

NUMERICAL INTEGRATORS FOR THE HAMILTONIAN MONTE CARLO METHOD

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I: THE PROBLEM

- Wish to sample from target pdf $\propto \exp(-V(q))$.
- Computational effort in HMC mostly spent when numerically integrating the Hamiltonian dynamics associated with the Hamiltonian function $H(q, p) = (1/2)p^2 + V(q)$, i.e. the differential system

$$(d/dt)q = p, \quad (d/dt)p = -\nabla V(q).$$

- Which integrator shall we use?

[N. Bou-Rabee & JMSS, Geometric integrators and the Hamiltonian Monte Carlo method, Acta Numerica, 2018.]

- Verlet is the algorithm of choice. For velocity form, one time-step is

$$p_{i+1/2} = p_i - \frac{h}{2} \nabla_q V(q_i), \quad (\text{kick})$$

$$q_{i+1} = q_i + h p_{i+1/2}, \quad (\text{drift})$$

$$p_{i+1} = p_{i+1/2} - \frac{h}{2} \nabla_q V(q_{i+1}). \quad (\text{kick})$$

- This is obviously a splitting integrator. Over one time step numerical solution is advanced by map

$$\psi_h = \varphi_{h/2}^B \circ \varphi_h^A \circ \varphi_{h/2}^B,$$

where φ^A , φ^B are exact solution maps (flows) of the (Hamiltonian) split systems:

$$(A) \quad (d/dt)q = p, \quad (d/dt)p = 0,$$

$$(B) \quad (d/dt)q = 0, \quad (d/dt)p = -\nabla V(q).$$

- ψ_h **volume preserving** as composition of volume-preserving flows.
- ψ_h **reversible** due to palindromic structure of composition.
- These properties allow for simple **accept-reject** rule. Proposal (q^*, p^*) accepted with probability

$$a^{(n)} = \min \left(1, \exp \left(H(q^{(n)}, p^{(n)}) - H(q^*, p^*) \right) \right).$$

$((q^{(n)}, p^{(n)}))$ current state of Markov chain).

[For useful dynamics that do not preserve volume see Y. Fang, JMSS & RD Skeel, Compressible generalized HMC, J. Chem. Phys. 2014.]

- Points to remember when choosing an integrator:

1. Interested in *energy errors* $\Delta(q, p)$ after I time-steps:

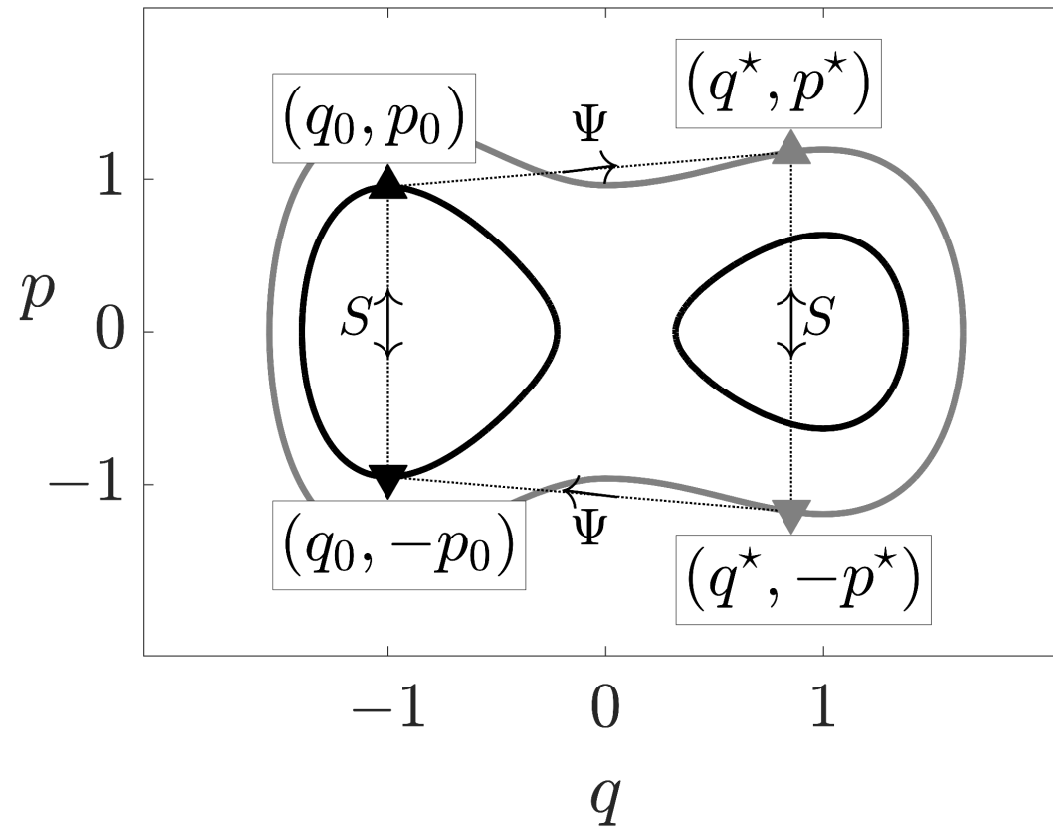
$$\Delta = H(\Psi_{h,I}(q, p)) - H(\varphi_{Ih}^H(q, p)) = H(\Psi_{h,I}(q, p)) - H(q, p),$$

as only these determine the acceptance probability.

2. High accuracy may not be required, unless *number of degrees of freedom is very high*. With an energy error $\Delta(q^{(n)}, p^{(n)}) = 1$ the proposal q^* will be accepted with probability $\exp(-1) > 36\%$. And for $\Delta(q^{(n)}, p^{(n)}) = 2$ the probability of acceptance is still larger than 13%.

3. The *sign* of the energy error matters: $\Delta(q^{(n)}, p^{(n)}) < 0$ leads to acceptance of the proposal.

- Conservation of volume and reversibility have an impact on energy errors:



- Expected energy error at stationarity of chain:

$$\mathbb{E}(\Delta) = \int_{\mathbb{R}^{2d}} \Delta(q, p) \exp(-H(q, p)) dq dp;$$

from figure we see $\mathbb{E}(\Delta)$ may also be written

$$- \int_{\mathbb{R}^{2d}} \Delta(q, p) \exp(-H(\Psi(q, p))) dq dp,$$

or, averaging both expressions,

$$\begin{aligned} & \frac{1}{2} \int_{\mathbb{R}^{2d}} \Delta(q, p) \left[\exp(-H(q, p)) - \exp(-H(\Psi(q, p))) \right] dq dp \\ &= \frac{1}{2} \int_{\mathbb{R}^{2d}} \Delta(q, p) \left[1 - \exp(-\Delta(q, p)) \right] \exp(-H(q, p)) dq dp. \end{aligned}$$

From here one may prove

$$0 \leq \mathbb{E}(\Delta) \leq \int_{\mathbb{R}^{2d}} \Delta(q, p)^2 \exp(-H(q, p)) dq dp.$$

Conclusions:

For a volume-preserving, reversible integrator, energy errors are, on average, much smaller than one would think.

Asymptotic properties in the limit $h \rightarrow 0$ (i.e. order, leading coefficients of local error expansion) of limited interest as in practice h will not be 'small'.

Hence: analyze integrators without assuming smallness of h .

But this is only possible for model problems . . .

II: A MODEL PROBLEM

- Harmonic oscillator:

$$H = \frac{1}{2}(p^2 + q^2), \quad q, p \in \mathbb{R},$$

$$\frac{d}{dt}q = -p, \quad \frac{d}{dt}p = q.$$

- From sampling point of view, target is the standard univariate Gaussian distribution. In matrix form, the solution flow is given by

$$\begin{bmatrix} q(t) \\ p(t) \end{bmatrix} = M_t \begin{bmatrix} q(0) \\ p(0) \end{bmatrix}, \quad M_t = \begin{bmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{bmatrix}.$$

- Then, *assuming stability*, the one-step numerical matrix is:

$$\tilde{M}_h = \begin{bmatrix} \cos \theta_h & \chi_h \sin \theta_h \\ -\chi_h^{-1} \sin \theta_h & \cos \theta_h \end{bmatrix}$$

and, over i steps:

$$\tilde{M}_h^i = \begin{bmatrix} \cos(i\theta_h) & \chi_h \sin(i\theta_h) \\ -\chi_h^{-1} \sin(i\theta_h) & \cos(i\theta_h) \end{bmatrix},$$

numerical solution stays on an ellipse.

- θ_h governs phase errors (here irrelevant).
- χ_h governs shape of numerical orbits/energy errors. $\chi_h \equiv 1$ would be ideal (then numerical solution stay on circles, no energy error).

The expectation of the random variable $\Delta(q_0, p_0)$ is given by:

[S. Blanes, F. Casas, JMSS, SIAM J. Sci. Comput. 2014]

$$\mathbb{E}(\Delta) = \sin^2(I\theta_h) \rho(h),$$

where

$$\rho(h) = \frac{1}{2} \left(\chi_h^2 + \frac{1}{\chi_h^2} - 2 \right) = \frac{1}{2} \left(\chi_h - \frac{1}{\chi_h} \right)^2 \geq 0.$$

Accordingly

$$0 \leq \mathbb{E}(\Delta) \leq \rho(h).$$

Illustration:

Velocity Verlet is stable for $0 < h < 2$, which is *optimal*.

For stable values of h :

$$\mathbb{E}(\Delta) \leq \frac{h^4}{32(1 - \frac{h^2}{4})}.$$

For $h \leq 1$ the expected energy error is $\leq 1/24$.

Halving h to $h \leq 1/2$, leads to an expected energy error $\leq 1/480$!

Extension: For a d -variate Gaussian target distribution (d coupled linear oscillators), assuming stability,

$$\mathbb{E}(\Delta) \leq \sum_{j=1}^d \rho(h\omega_j),$$

where ω_j are the angular frequencies of the oscillators (inverses of the standard deviations).

Note $h\omega_j$ is a *nondimensional* combination and stability requires $h\omega_j < 2$ for each j .

III: IMPROVING ON VERLET

- Split-step methods suggest themselves. Very easy implementation (sequence of drifts/kicks just as Verlet). They are symplectic, and, if palindromic, reversible.
- Many antecedents in literature: free parameters have been used to boost order and/or reduce error constants.
- Here we minimize

$$\|\rho\|_{(\bar{h})} = \max_{0 < h < \bar{h}} \rho(h),$$

where \bar{h} is suitable nondimensional maximum step-length ($\bar{h} \leq$ length of stability interval).

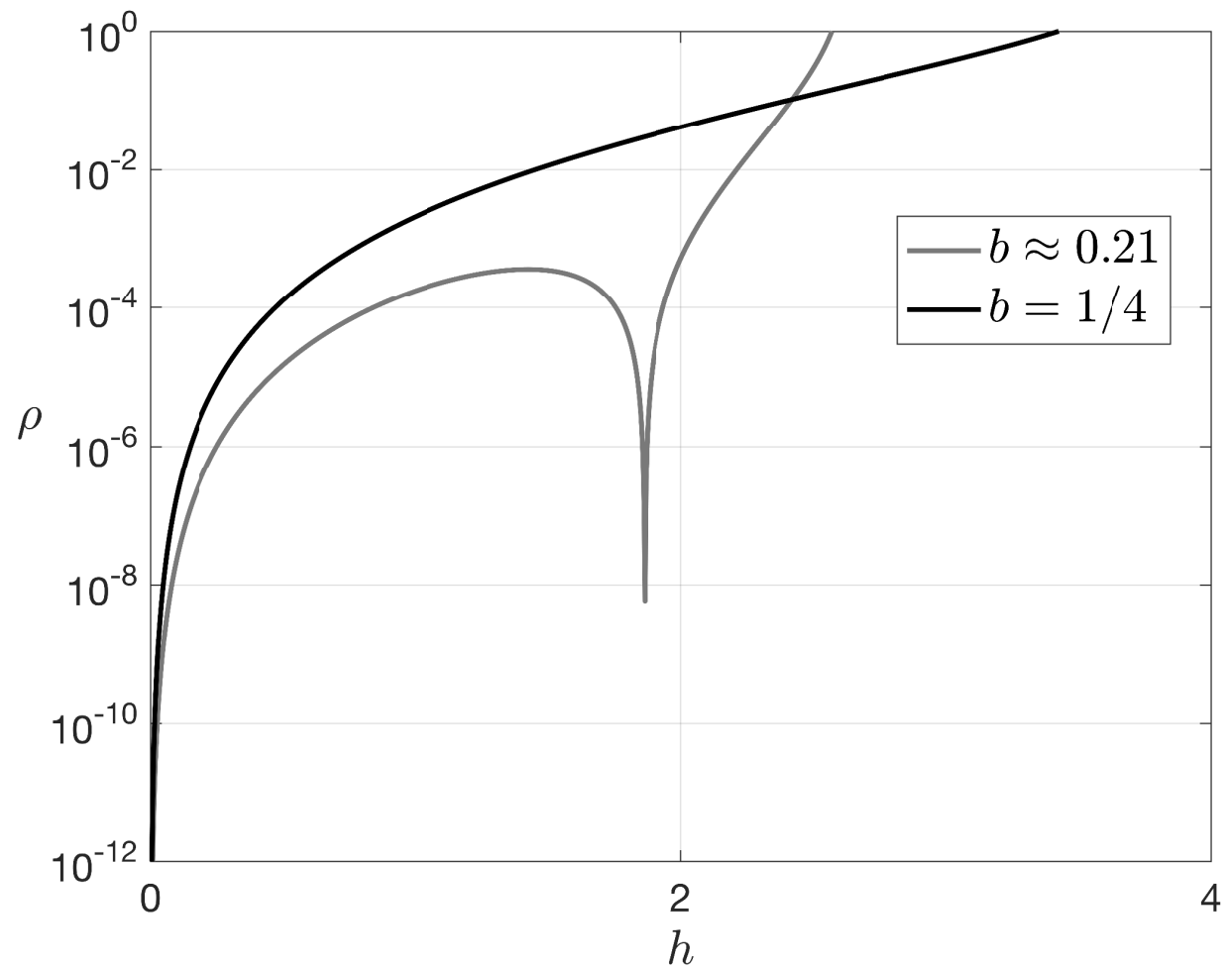
- If method uses r evaluations of ∇V per step, we choose $\bar{h} = r$, since Verlet works well with $h \approx 1$ for relevant numbers of degrees of freedom.

Two evaluations of ∇V per step:

- One-parameter family of palindromic formulae (three kicks, two drifts):

$$\psi_h = \varphi_{bh}^B \circ \varphi_{(1/2)h}^A \circ \varphi_{(1-2b)h}^B \circ \varphi_{(1/2)h}^A \circ \varphi_{bh}^B.$$

- When $b = 1/4$ method is concatenation of two-steps (of step-length $h/2$) of (position) Verlet method.
- All methods are second order accurate. Minimal error constant $b \approx 0.1932$. As b increases from 0.19 to 0.25 integrator may operate with larger values of h but is less accurate.
- Here a chosen to minimize $\max \rho(h)$, $0 < h < 2$. This leads to the optimal choice $b \approx 0.2118$.

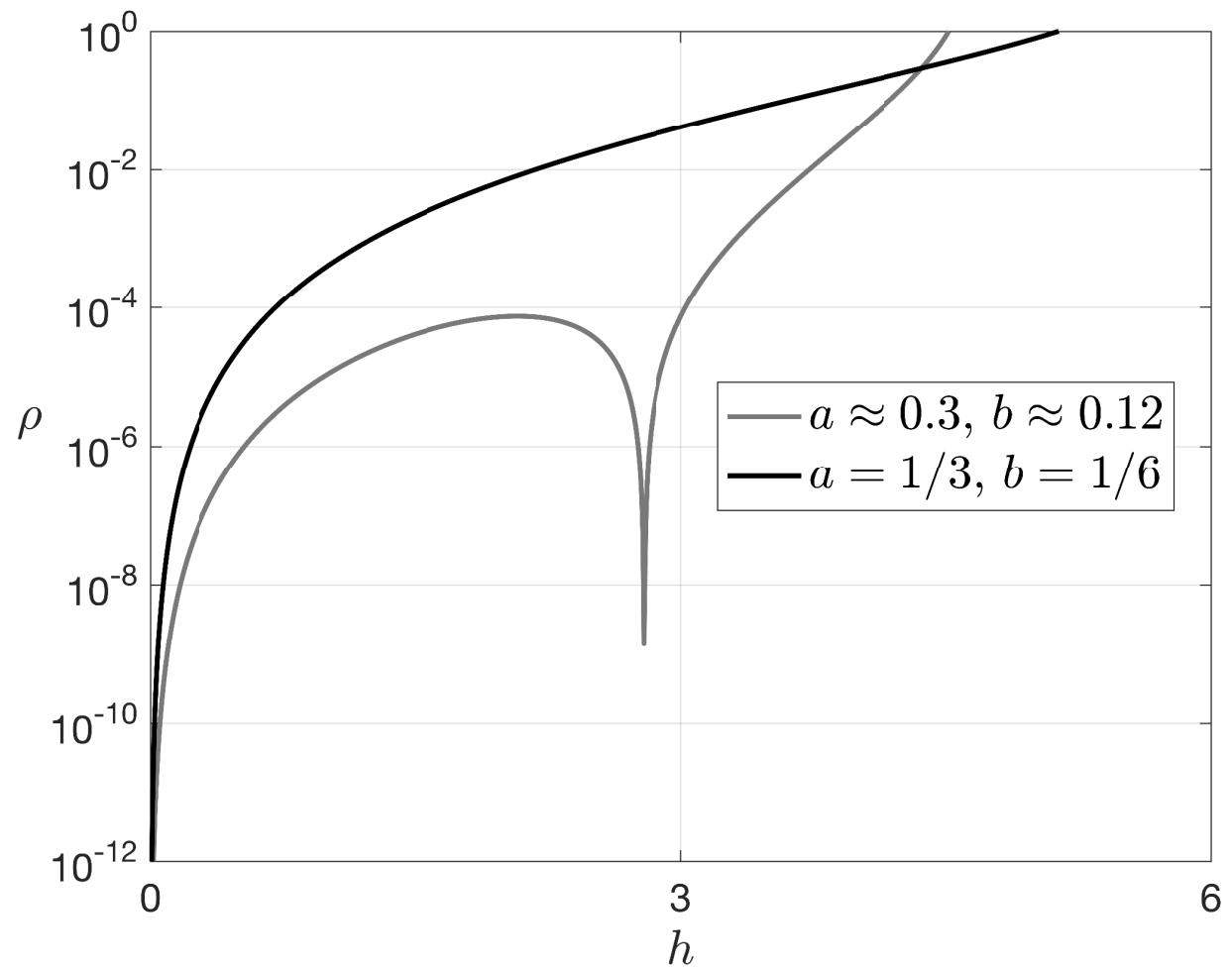


Three evaluations of ∇V per step:

- Two-parameter family of palindromic formulae (three kicks, two drifts):

$$\varphi_{bh}^B \circ \varphi_{ah}^A \circ \varphi_{(1/2-b)h}^B \circ \varphi_{(1-2a)h}^A \circ \varphi_{(1/2-b)h}^B \circ \varphi_{ah}^A \circ \varphi_{bh}^B.$$

- When $a = 1/3$ $b = 1/6$ method is concatenation of three-steps (of step-length $h/3$) of velocity Verlet method.
- Order *four* is possible and has been considered in this context.
- Here minimize $\max \rho(h)$, $0 < h < 3$. This is tricky: generically methods have stability intervals shorter than $0 < h < 3$. (The fourth-order method has stability interval $0 < h < 1.573$.)



Numerical comparison of three-stage algorithms:

- Canonical distribution for an alkane molecule with 27 degrees of freedom. (Not too many degrees of freedom and away from Gaussian model.)
- One force evaluation every 8 fs (good for Verlet).
- Average and standard deviation of acceptance rate:

Integrator	μ	σ
Verlet	77.7%	2.11%
Fourth order	0%	0%
Minimum ρ	96.7%	0.41%

AIA (adaptive integrator approach) [M Fernández-Pendás, E Akhmatskaya, JMSS, J. Comput. Phys. 2016]

Go back to two stage family. Above, free parameter b chosen once and for all to minimize ρ over $0 < h < 2$.

In AIA steplength chosen according to computational budget. Then estimate shortest interval $(0, h^*)$ that contains all products $h\omega_j$ and minimize ρ over $0 < h < h^*$.

Incorporated to molecular dynamics popular software GROMACS.

Sampling for a large biomolecule. If Δt is large, AIA chooses Verlet. If user may operate smaller values of Δt , AIA automatically picks an integrator with a shorter stability interval and enhanced accuracy.

