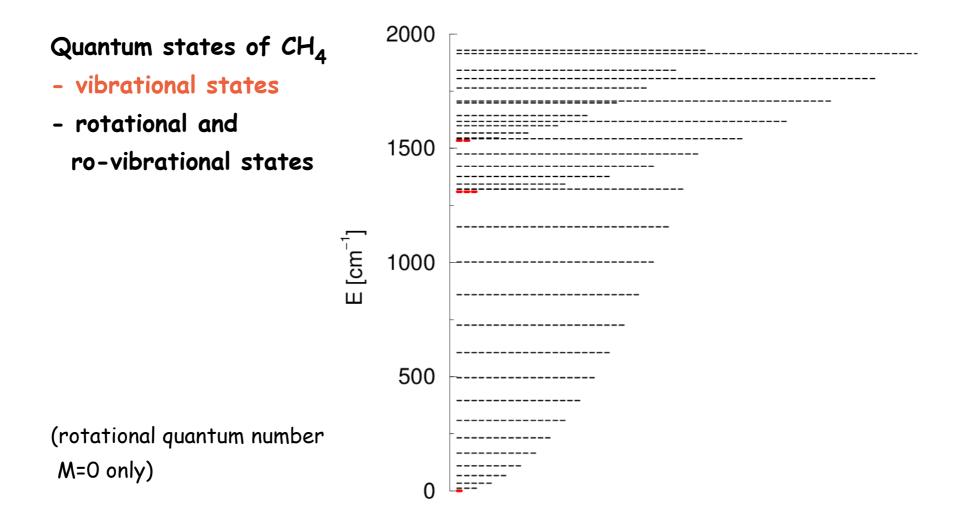
Symmetry and the Entangled Ro-vibrational Quantum States of a Fluxional Molecule

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Introduction: rotations and vibrations

Quantum states of isolated molecules: separation of rotation and vibration essential



Symmetry and the Entangled Ro-vibrational Quantum States of a Fluxional Molecule

Separation of rotation and vibrations

Molecular symmetry groups

Floppy molecules

The breakdown of separability: A_n and AB_n with n>4

A prominent example: CH_5^+

Separation of rotation and vibrations

Vibrational motion is described by coordinates Q in a body fixed frame

Rotational motion of the body fixed frame is described by the Euler angles a, $\beta,~\gamma$

Rotational invariance of the Hamiltonian:

$$\Psi_{J,M}(\alpha,\beta,\gamma,\mathbf{Q}) = \sum_{K=-J}^{J} \sqrt{\frac{2J+1}{8\pi^2}} D_{MK}^{J}(\alpha,\beta,\gamma) \cdot \psi_{J,K}(\mathbf{Q})$$

 $D_{MK}^J(\alpha,\beta,\gamma)$: Wigner rotation matrices

Separability of rotational and vibrational motion:

$$\Psi_{J,M}(\alpha,\beta,\gamma,\mathbf{Q}) = \left(\sum_{K=-J}^{J} \sqrt{\frac{2J+1}{8\pi^2}} D_{MK}^{J}(\alpha,\beta,\gamma) \cdot c_{J,K}\right) \cdot \psi(\mathbf{Q})$$

 $\psi(\mathbf{Q})$: vibrational wavefunction

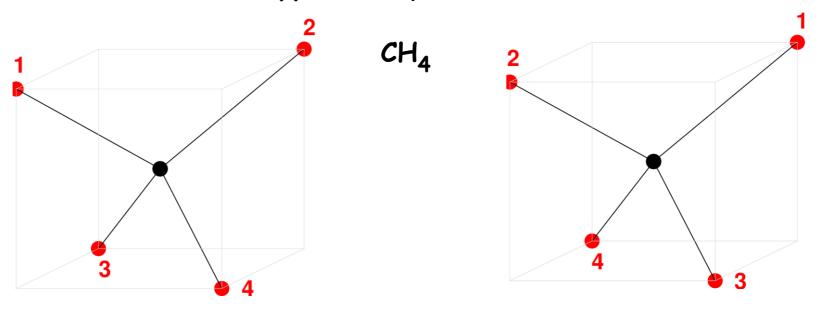
<u>Molecular symmetry groups</u>

Hamiltonian invariant with respect to inversion and permutation of identical atoms

Rigid or semirigid molecules: permutation-inversion symmetry mapped on point groups, vibrational wavefunctions transform according to the irreducible representations of the point group

Identical atoms used in the definition of the body fixed frame \rightarrow permutations affect rotational wavefunctions

Permutations are mapped on equivalent rotations



Floppy molecules

Molecules showing long range motion: identical nuclei can dynamically exchange their positions \rightarrow feasible permutations (and inversion)

Separation of rotional and vibrational motion: $\Psi(\alpha, \beta, \gamma, \mathbf{Q}) \approx \psi_{rot}(\alpha, \beta, \gamma) \cdot \psi_{vib}(\mathbf{Q})$

Vibrational wavefunction transforms according to the group of feasible permutations (and inversion).

Rotational wavefunction transforms according to the rotation group SO(3).

It must also transform according to the group of feasible permutations which affect the definition of the body fixed frame (\rightarrow equivalent rotations).

The breakdown of separability: An and ABn with n>4

All permutation dynamically feasible and relevant for the definition of the body fixed frame: A_3 , AB_3 : S_3 isomorphic to C_{3v} (\rightarrow subgroup of SO_3), triangle A_4 , AB_4 : S_4 isomorphic to T_d (\rightarrow subgroup of SO_3), tetrahedron A_5 , AB_5 : S_5 not isomorphic to any subgroup of SO_3 ... (analogous for all n > 4)

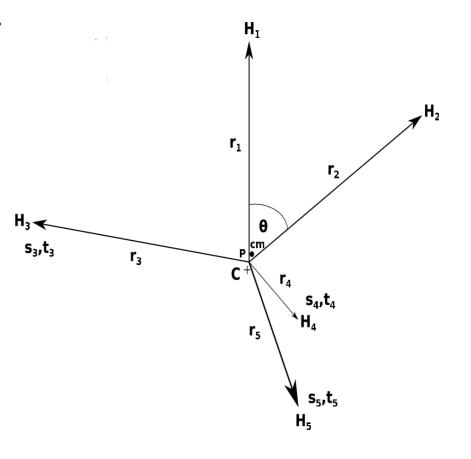
 \rightarrow rotational wavefunction of correct symmetry can not exist \rightarrow breakdown of separabily of rotational and vibrational motion

<u>A prominent example</u>: CH_5^+

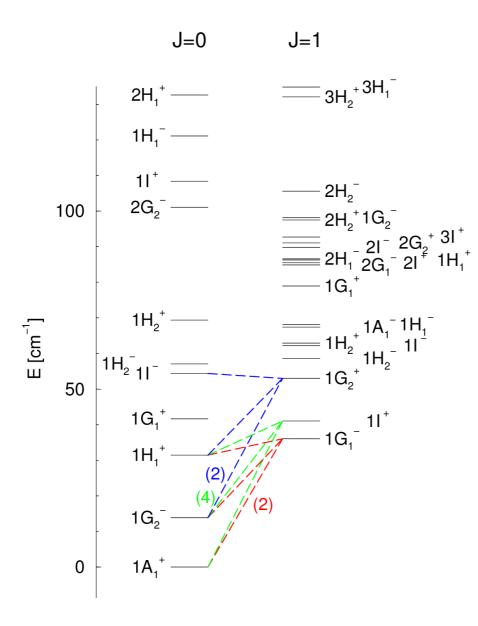
PES with 120 symmetry-equivalent minima separated by tiny barriers → delocalized quantum states

PES by Brown et al.

MCTDH calculations: iterative diagonalization approach adapted to multi-well systems, explizit symmetrization (incompletely converged)



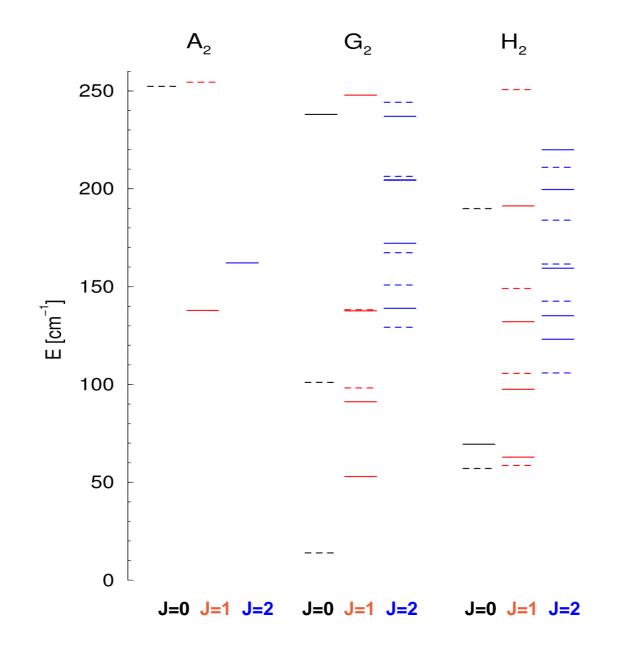
Ro-vibrational states of CH_5^+



numerical result: contributions from a small number of vibrational states dominate in the wavefunctions

Symmetry?

Pauli-allowed ro-vibrational states of CH_5^+



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