

Mixing in Noisy Nonlinear Oscillators

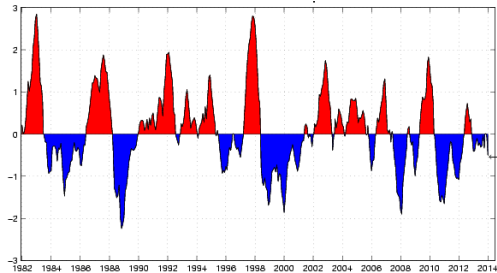
Application to Low-Frequency Climate Variability

Alexis Tantet, Mickael Chekroun, David Neelin, Valerio
Lucarini, Henk Dijkstra

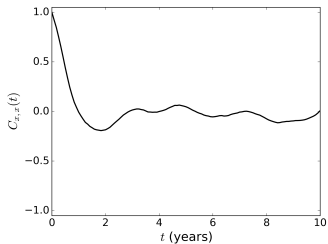
18th January 2017



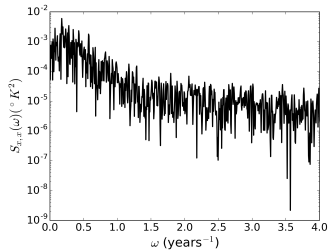
Motivation



(a) ???



(b) Sample correlation

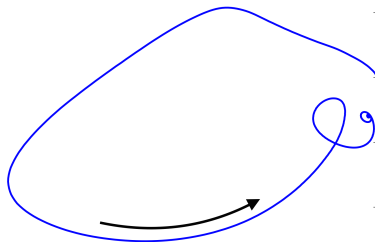
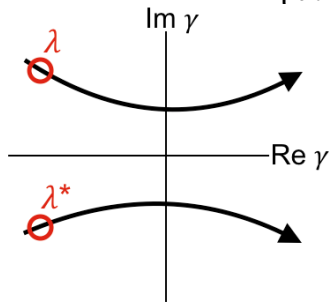


(c) Periodogram

Deterministic Hopf bifurcation

Normal Form ¹ of Hopf bifurcation:

$$\begin{cases} dr &= (\delta r - r^3)dt \\ d\theta &= (\gamma - \beta r^2)dt \end{cases}$$



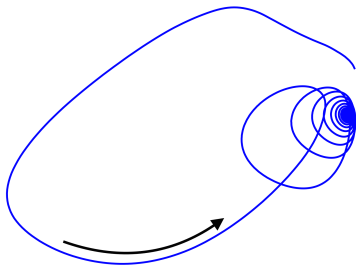
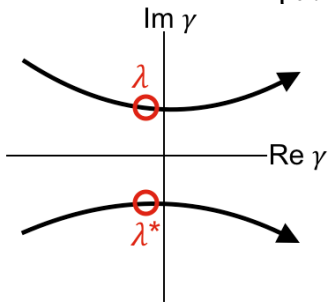
$\delta \ll \delta_c \rightarrow$ fast relaxation to fixed point

¹Guckenheimer and Holmes [1983]

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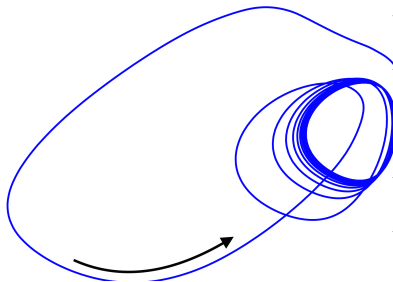
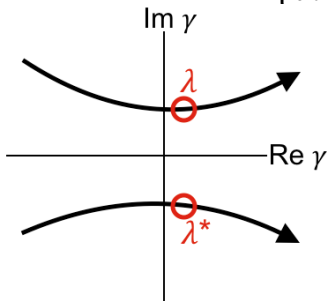
$\delta \approx \delta_c \rightarrow$ *Slowing Down*

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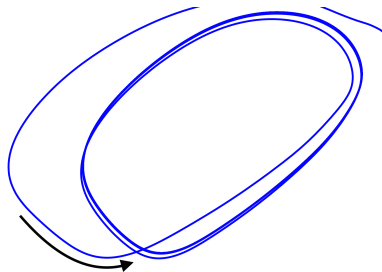
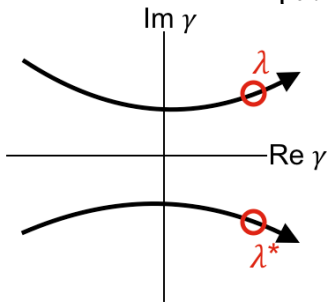
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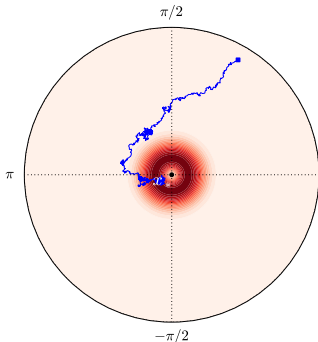
$\delta \gg \delta_c \rightarrow$ Fast relaxation to periodic orbit

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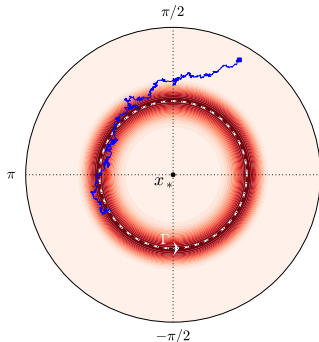
Stochastic Hopf equation

Perturbation of Hopf by white noise on x, y :

$$\begin{cases} dr &= (\delta r - r^3 + \frac{\epsilon^2}{2r})dt + \epsilon dW_r \\ d\theta &= (\gamma - \beta r^2)dt + \frac{\epsilon}{r} dW_\theta \end{cases}$$



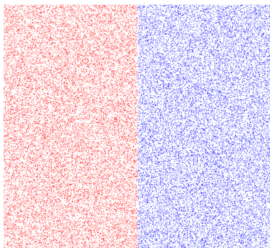
(a) $\delta < 0$



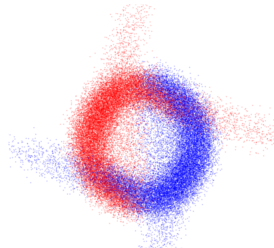
(b) $\delta > 0$

Ensemble mixing

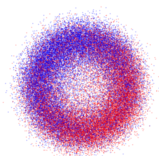
(a) $t = 0$



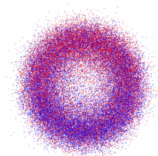
(b) $t = 1$



(c) $t = 5$



(d) $t = 10$



Markov semigroup

Process $X_t(\omega, x)$ governed by Itô SDE:

$$dX_t = F(X_t)dt + \Sigma(X)dW_t, \quad X_0 = x$$

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$$dX_t = F(X_t)dt + \Sigma(X)dW_t, \quad X_0 = x$$

Conditional expectations $u(x, t) = \mathbb{E}[f(X_t)|X_0 = x]$ governed by *Backward Kolmogorov Equation*

$$\partial_t u = \underbrace{F \cdot \nabla u + \frac{1}{2} \Sigma \Sigma^t : \nabla \nabla u}_{\mathcal{G}u}, \quad u(x, 0) = f(x)$$

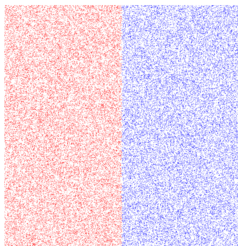
generating *Markov semigroup*

$$P_t u = e^{t\mathcal{G}} u, \quad u \in L^2_\mu(X)$$

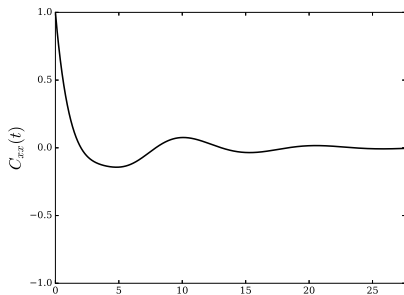
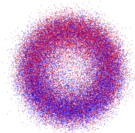
Mixing and correlations

Strong mixing² implies:

$$C_{f,g}(t) = \int f P_t g d\mu \xrightarrow{t \rightarrow \infty} 0$$



$\xrightarrow{\mathcal{L}_{t \rightarrow \infty}}$



Spectral decomposition on $\sigma(\mathcal{G})$

Decomposition of correlation function:

$$C_{f,g}(t) = \sum_{k \geq 1} e^{\lambda_k t} w_k$$

with $w_k = \int f \psi_k d\mu \int \psi_k^* g d\mu$

Spectral decomposition on $\sigma(\mathcal{G})$

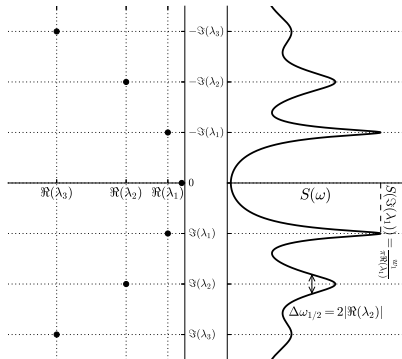
Decomposition of correlation function:

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with $w_k = \int f \psi_k d\mu \int \psi_k^* g d\mu$

Decomposition of power spectrum:

$$S_{f,g}(\omega) = \sum_{k \geq 1} \frac{w_k}{\pi} \frac{-\Re(\lambda_k)}{(\omega - \Im(\lambda_k))^2 + \Re(\lambda_k)^2}$$



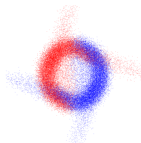
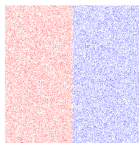
Stochastic Hopf

Hopf SDE:

$$\begin{cases} dr &= (\delta r - r^3 + \frac{\epsilon^2}{2r})dt + \epsilon dW_r \\ d\theta &= (\gamma - \beta r^2)dt + \frac{\epsilon}{r} dW_\theta \end{cases}$$

Backward Kolmogorov:

$$\partial_t u = \underbrace{\left(\delta r - r^3 + \frac{\epsilon^2}{2r} \right) \partial_r u + (\gamma - \beta r^2) \partial_\theta u}_{\mathcal{G}u} + \frac{\epsilon^2}{2} \partial_{rr}^2 u + \frac{\epsilon^2}{2r^2} \partial_{\theta\theta}^2 u$$



Small-noise expansion $\epsilon \ll 1$

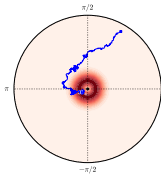
Expansion of the eigenvalues:

$$\lambda_k = \lambda_k^{(0)} + \epsilon \lambda_k^{(1)} + \dots$$

Rescaled deviations from deterministic trajectories:

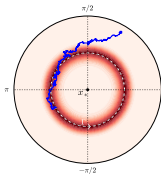
- $\delta < 0$

$$x' = \frac{x}{\epsilon}, \quad y' = \frac{y}{\epsilon}.$$



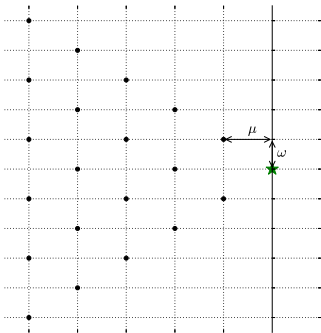
- $\delta > 0$

$$r' = \frac{r - \sqrt{\delta}}{\epsilon}, \quad \phi' = \phi - \omega t.$$



Spectrum for $\delta < 0$

$$\lambda_{ln} = (l+n)\delta - i(l-n)\gamma + \mathcal{O}(\epsilon^2), \quad l, n \in \mathbb{N}$$



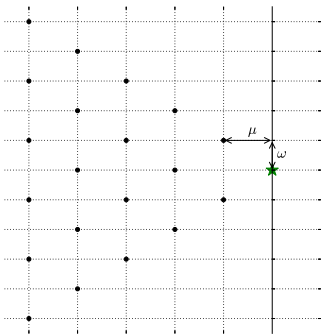
(a) Eigenvalues

Spectrum for $\delta < 0$

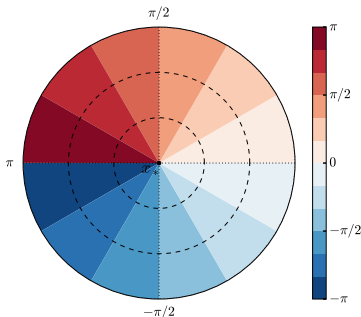
$$\lambda_{ln} = (l+n)\delta - i(l-n)\gamma + \mathcal{O}(\epsilon^2), \quad l, n \in \mathbb{N}$$

$$\psi_{ln}(r, \theta) \approx l! \left(\frac{\epsilon^2}{\delta}\right)^l e^{i(l-n)\theta} r^{n-l} L_l^{n-l}\left(-\frac{\delta r^2}{\epsilon^2}\right), \quad l < n$$

3



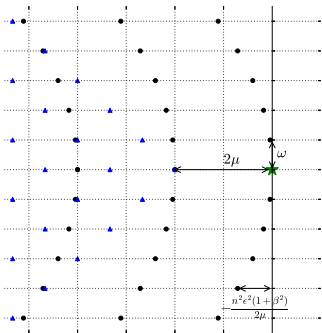
(a) Eigenvalues



(b) Eigenvector ψ_{01}

Spectrum for $\delta > 0$

$$\lambda_{ln} = -2l\delta - in(\gamma - \beta\delta) - \frac{n^2\epsilon^2(1 + \beta^2)}{2\delta} + o(\epsilon^3)$$

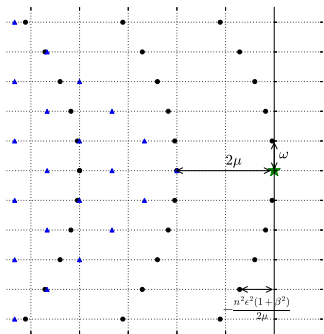


(a) Eigenvalues

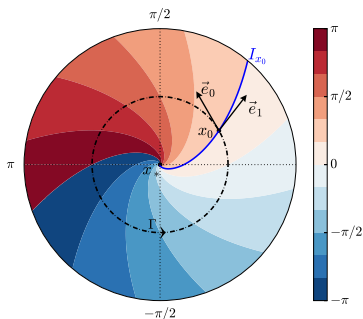
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$$\phi_{ln} \approx e^{in\left(\theta - \beta \log \frac{r}{\sqrt{\delta}}\right)} H_l \left(\frac{\sqrt{2\delta}}{\epsilon} \left(r - \sqrt{\delta} \right) \right)$$



(a) Eigenvalues



(b) Eigenvector ψ_{01}

Smoothing noise: geometric perspective

Hopf + only one radial forcing vector field $\epsilon\partial_r$:

$$\begin{cases} dr &= (\delta r - r^3)dt + \epsilon dW_r \\ d\theta &= (\gamma - \beta r^2)dt \end{cases}$$

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Test Hörmander's Lie bracket condition ⁴:

$$\begin{array}{ll} \text{span } \epsilon\partial_r = \mathbb{R}^2 ? & \text{If not } \rightarrow \mathcal{G} \text{ not elliptic} \\ \text{span } \{ \epsilon\partial_r, [F, \epsilon\partial_r] \} = \mathbb{R}^2 ? & \\ \dots & \text{If yes } \rightarrow \mathcal{G} \text{ hypoelliptic} \end{array}$$

⁴Hörmander [1968]

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$\text{span } \{\epsilon\partial_r, [F, \epsilon\partial_r]\} = \mathbb{R}^2$?

... If yes $\rightarrow \mathcal{G}$ hypoelliptic

$$[F, \epsilon\partial_r] = \sigma(\delta - 3r^2)\partial_r - \sigma\beta r\partial_\theta$$

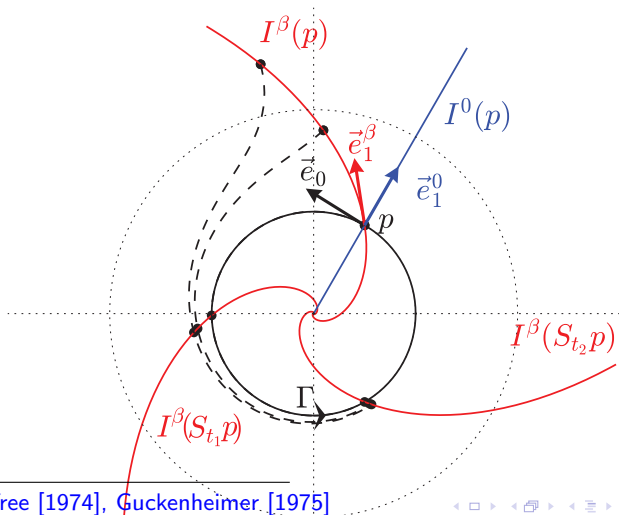
$$\Rightarrow \text{span } \{\epsilon\partial_r, [F, \epsilon\partial_r]\} = \mathbb{R}^2 \quad \text{iff } \beta \neq 0$$

⁴Hörmander [1968]

Twisting of the isochrons for $\beta \neq 0$

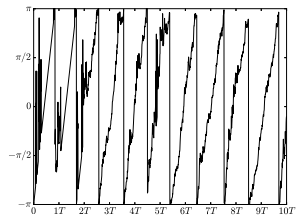
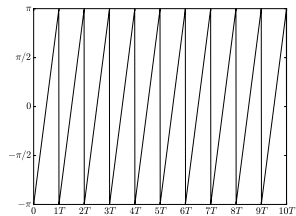
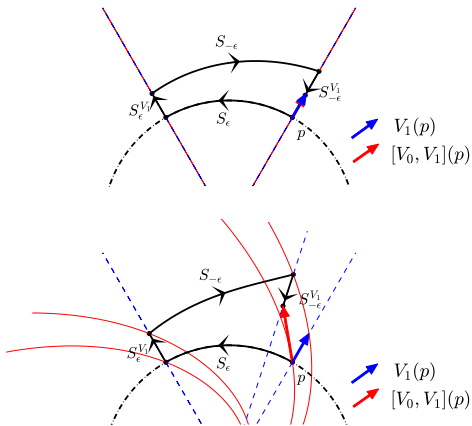
Leaves $I(p)$ of the stable manifold \rightarrow generalisation of phase ⁵

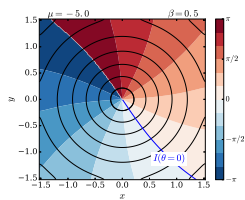
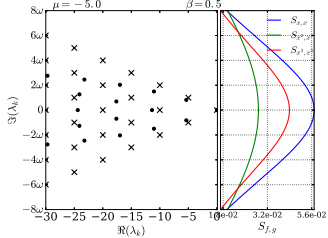
$$I(p) = \{q : \|p(t) - q(t)\| \xrightarrow[t \rightarrow \infty]{} 0\}, \quad p \in \Gamma$$



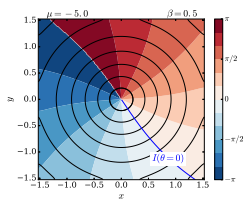
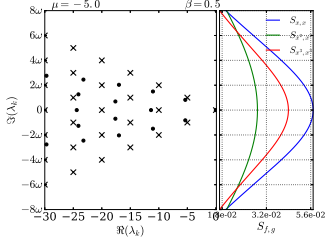
⁵Winfree [1974], Guckenheimer [1975]

Smoothing noise: geometric perspective

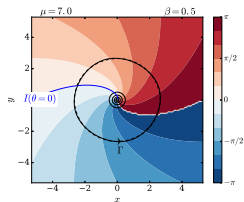
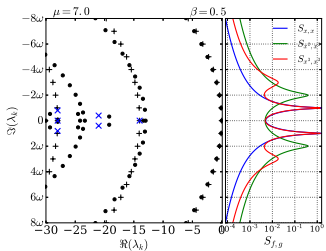




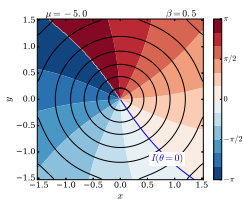
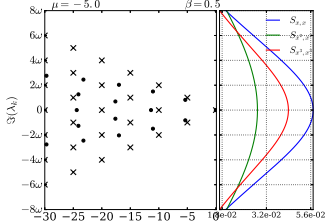
(a) $\delta < 0$



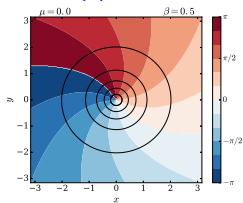
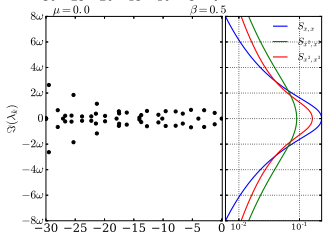
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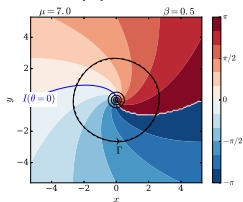
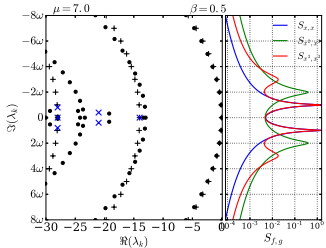
(c) $\delta > 0$



(a) $\delta < 0$



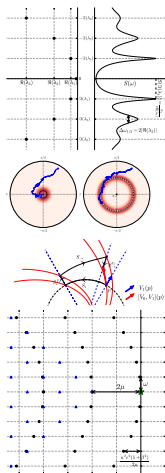
(b) $\delta = 0$



(c) $\delta > 0$

Conclusion

- *Mixing spectrum* relate correlations and power spectrum to the dynamics
- *Stochastic analysis* techniques for bifurcations
- *Geometric* approach to interaction of noise with the dynamics
- Small-noise expansions from *linear stability* of limit set



What about high-dimensional stochastic systems?

Reduced Markov operators

- Define reduced state space by $\mathcal{R} : X \rightarrow Y, \dim Y < \dim X$

⁶Kallenberg [2002]

⁷Chekroun et al. [2014]

Reduced Markov operators

- Define reduced state space by $\mathcal{R} : X \rightarrow Y$, $\dim Y < \dim X$
- Induced reduced function space $L_m^2(Y)$, with $\mathfrak{m} = \mathcal{R} * \mu$
- *Conditional measure*⁶ $\mu_y : L_\mu^2(X) \rightarrow L_m^2(Y)$, $y \in Y$ s.t.:

$$\int f d\mu = \int_Y \int_{\mathcal{R}^{-1}(y)} f d\mu_y d\mathfrak{m}$$

⁶Kallenberg [2002]

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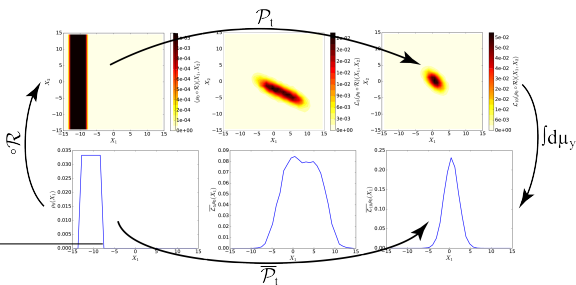
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$$\int f d\mu = \int_Y \int_{\mathcal{R}^{-1}(y)} f d\mu_y d\mathfrak{m}$$

- Define *Reduced Markov Operators* $\bar{P}_t : L_m^2(Y) \rightarrow L_m^2(Y)$ ⁷:

$$\bar{P}_t f = \int P_t(f \circ \mathcal{R}) d\mu_y$$



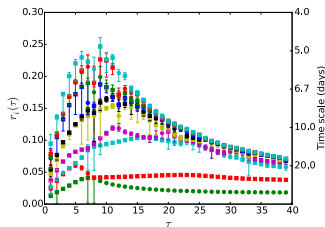
⁶Kallenberg [2002]

⁷Chekroun et al. [2014]

Applicability of reduction

Loss of information in reduction $\rightarrow \overline{P}_{t+s} \neq \overline{P}_t \overline{P}_s$

- Schütte [1999]: early work on almost-invariant sets
 - Bittracher et al. [2015]: pseudo-generators for short lags
 - Crommelin and Vanden-Eijnden [2011]: multi-scale systems (homogenization)
 - Froyland et al. [2014]: multi-scale systems (fiber dynamics)
-
- Tantet et al. [2015]: leading eigenvalues for long lags.



Estimation from time series

- Galerkin truncation on indicators (bounded domain)

$$(\mathbf{P}_\tau)_{ij} = \frac{\langle \overline{P}_\tau \mathbb{1}_{B_i}, \mathbb{1}_{B_j} \rangle_m}{m(B_j)}.$$

- ML Estimator from a *single long time series* $\{y_s\}_{1 \leq s \leq T}$

$$\widehat{(\mathbf{P}_\tau)}_{ij} = \frac{\#\{(y_s \in B_j) \wedge (y_{s+\tau} \in B_i)\}}{\#\{y_s \in B_j\}}, \quad (1)$$

- Get eigenvalues $\zeta_k(\tau) \in \mathbb{C}$ and left/right-eigenvectors ψ_k/ψ_k^*
- Convert to "generator" eigenvalues $\lambda_k(\tau)$ s.t. $e^{t\lambda_k(\tau)} = \zeta_k(\tau)$
- Reconstruct correlation functions for any observables

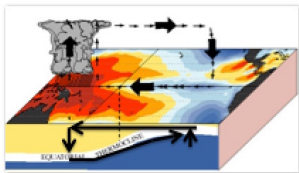
$$C_{f,g}(t) \approx (\mathbf{f} D(\mathbf{m}) \boldsymbol{\Psi}'_\tau) e^{t\Lambda_\tau} (\boldsymbol{\Psi}_\tau^* D(\mathbf{m}) \mathbf{g}') - (\mathbf{f} \mathbf{m})(\mathbf{m} \mathbf{g}')$$

Application to Hopf bifurcation in Cane-Zebiak

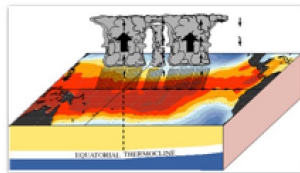
Model configuration:

- fully-coupled Cane-Zebiak model ⁸:
1.5 shallow-water ocean + steady-state atmosphere on β -plane with Galerkin projection (thousands of DOF),
- additive white noise wind-forcing ⁹,
- > 700 yr of simulation, spin-up removed,
- for different values of the coupling parameter δ around $\delta_c \approx 2.85$.

La Niña



El Niño

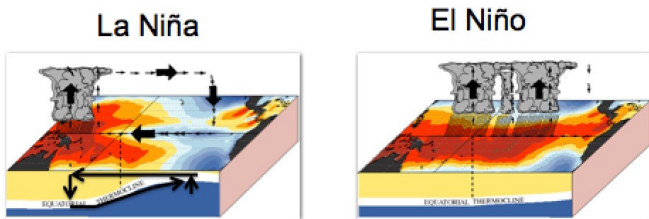


⁸van der Vaart et al. [2000]

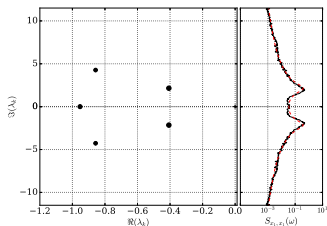
⁹Roulston and Neelin [2000]

Transition matrix estimation

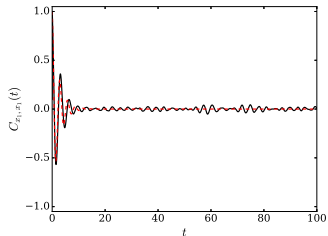
- reduced space (Easter SST, Western thermocline Depth),
- 100x100 boxes spanning $[-5, 3] \times [-4, 4]$ standard deviations,
- lag τ of 3 month.



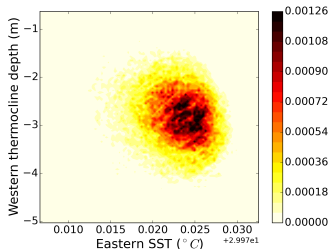
$$\delta = 2.5$$



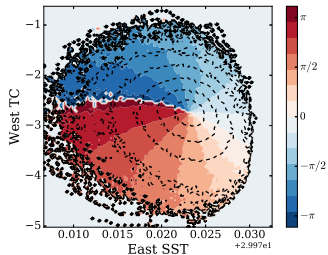
(a) Eigenval. (left), periodogram (black) and reconstruction (right)



(b) Sample correlation (black) and its reconstruction (right)

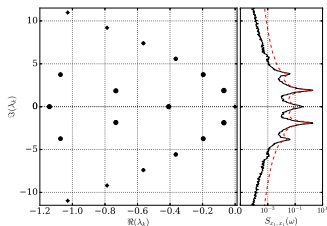


(c) Stationary density

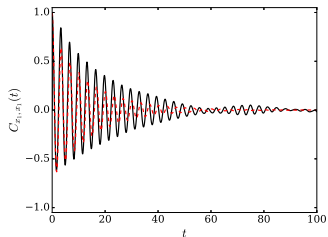


(d) Phase (filled) and amp. (line) of 2nd eigenvector

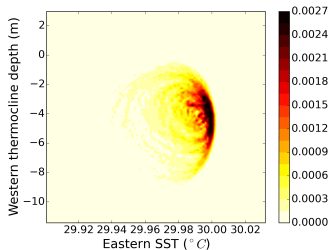
$$\delta = 2.8$$



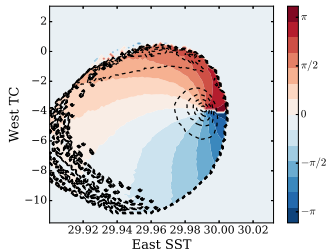
(a) Eigenval. (left), periodogram (black) and reconstruction (right)



(b) Sample correlation (black) and its reconstruction (right)

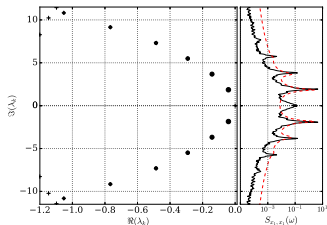


(c) Stationary density

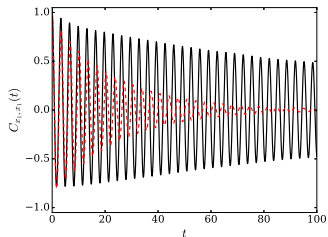


(d) Phase (filled) and amp. (line) of 2nd eigenvector

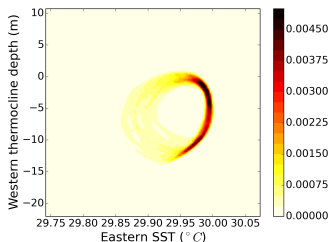
$$\delta = 2.9$$



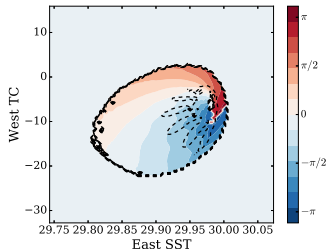
(a) Eigenval. (left), periodogram (black) and reconstruction (right)



(b) Sample correlation (black) and its reconstruction (right)

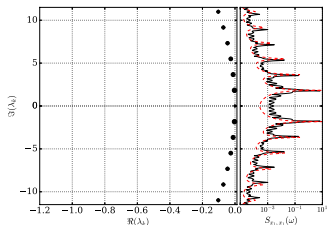


(c) Stationary density

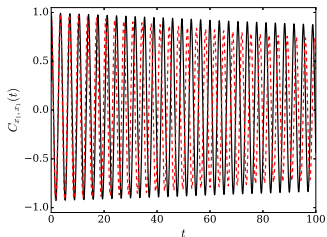


(d) Phase (filled) and amp. (line) of 2nd eigenvector

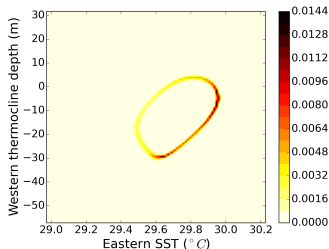
$$\delta = 3.5$$



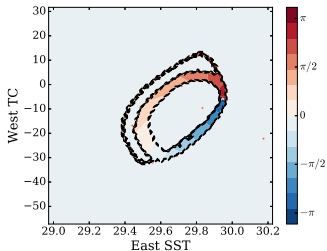
(a) Eigenval. (left), periodogram (black) and reconstruction (right)



(b) Sample correlation (black) and its reconstruction (right)



(c) Stationary density



(d) Phase (filled) and amp. (line) of 2nd eigenvector

Dealing with non-Markovianity

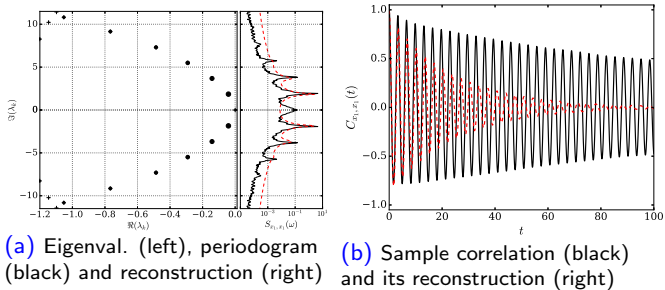
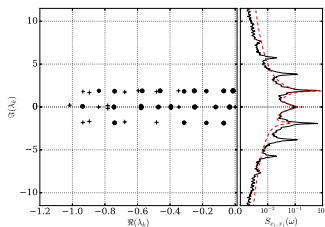
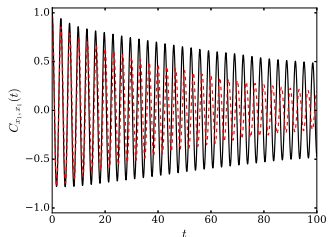


Figure: $\tau = 3$ months, $\delta = 2.9$

Dealing with non-Markovianity



(a) Eigenval. (left), periodogram (black) and reconstruction (right)



(b) Sample correlation (black) and its reconstruction (right)

Figure: $\tau = 20$ months, $\delta = 2.9$

Dealing with non-Markovianity

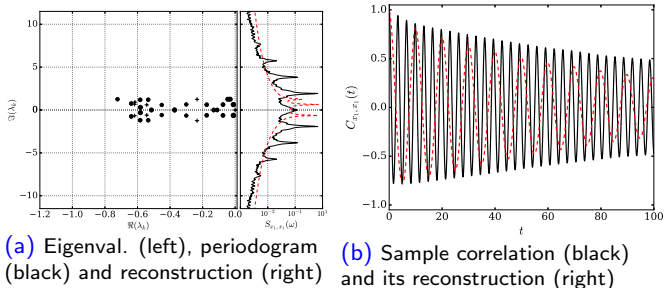


Figure: $\tau = 30$ months, $\delta = 2.9$

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