

# Principal eigenvalues for $k$ -Hessian operators by maximum principle methods

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# 1. Introduction

**Proposal:** Study maximum principles and principal eigenvalues for

$$(EVP) \quad \begin{cases} F(x, D^2u) + \lambda u|u|^{k-1} = 0 & \text{in } \Omega \in \mathbb{R}^N \\ u = 0 & \text{on } \partial\Omega \end{cases}$$

where  $F = F(x, A)$  is continuous with  $F(x, 0) = 0$  and

- homogeneous of degree  $k$  in  $A \in \mathcal{S}(N)$ ;
- elliptic in the sense of Krylov [TAMS'95]; increasing in  $A$  along  $\Theta(x) \subsetneq \mathcal{S}(N)$  an elliptic set for each  $x \in \Omega$

Define  $\lambda_1^-(F, \Theta)$  as the sup over  $\lambda \in \mathbb{R}$  for which there is a negative subsolution of (EVP).

- 1 Do suitably defined supersolutions satisfy a minimum principle for  $\lambda < \lambda_1^-(F, \Theta)$ ?
- 2 Exists  $\psi_1 < 0$  in  $\Omega$  corresponding to  $\lambda = \lambda_1^-(F, \Theta)$ ?

# Test case: $k$ -Hessian operators

For  $k = 1, 2, \dots, N$  consider  $F(D^2u) = S_k(D^2u)$  defined by

$$S_k(D^2u) := \sigma_k(\lambda(D^2u)) \quad \text{where}$$

$$\sigma_k(\lambda(A)) := \sum_{1 \leq i_1 < \dots < i_k \leq N} \lambda_{i_1} \cdots \lambda_{i_k} \quad \text{and}$$

$$\lambda(A) = (\lambda_1(A), \dots, \lambda_N(A)) \quad \text{for } A \in \mathcal{S}(N).$$

- $S_1(D^2u) = \text{tr}(D^2u)$ : “know everything” about  $\lambda_1^\pm(\Delta u)$  - [Berestycki-Nirenberg-Varadhan, CPAM'94]
- For each  $k$  there is a variational structure [Reilly, MMJ'73]
- $S_N(D^2u) = \det(D^2u)$ : variational description of  $\lambda_1^-(S_k(D^2u))$  simple w/ convex eigenfunction  $\psi_1 < 0$  on  $\Omega$  strictly convex w/  $\partial\Omega \in C^2$  - [P.L. Lions, AMPA'85]
- $k = 2, \dots, N$ : similar result for  $\Omega$  strictly  $(k-1)$ -convex and with  $k$ -convex  $\psi_1 < 0$  - [X.J. Wang, IUMJ'94]

# Objectives:

For  $k = 2, \dots, N$  on  $\Omega \in \mathbb{R}^N$  which is  $(k - 1)$ -convex and  $\partial\Omega \in C^2$

- 1 Characterize  $\lambda_1^-(S_k(D^2u))$  by the validity of a minimum principle.
- 2 Capture  $\psi_1$  by an iterative viscosity method for  $\lambda_n \nearrow \lambda_1^-$  a la [Birindelli-Demengel, CCAA'07]

In order to do this, we will:

- encode the needed notions of  $k$ -convexity into the language of elliptic sets  $\Theta \subsetneq \mathcal{S}(N)$ ;
- define suitable notions of **admissible viscosity supersolutions**;
- exploit the boundary convexity for constructing **suitable barriers**;
- follow the usual path of [BD].

## 2. Notions of $k$ -convexity

Consider the open convex cone (in  $\mathbb{R}^N$ ) with vertex at the origin

$$\Gamma_k := \{\lambda \in \mathbb{R}^N : \sigma_j(\lambda) > 0, j = 1, \dots, k\}$$

and define the closed cone in  $\mathcal{S}(N)$  by

$$\Theta_k := \{A \in \mathcal{S}(N) : \lambda(A) \in \bar{\Gamma}_k\}$$

where  $\lambda(A) = (\lambda_1(A), \dots, \lambda_N(A)) \in \mathbb{R}^N$  are the evals of  $A$

- $\Theta_k$  is an **elliptic set**; that is,  $\Theta_k \subsetneq \mathcal{S}(N)$  is closed, non empty and

$$A \in \Theta_k, P \geq 0 \Rightarrow A + P \in \Theta_k$$

- $S_k$  is increasing along  $\Theta_k$ ; that is, for each  $A \in \Theta_k, P \geq 0$

$$S_k(A + P) := \sigma_k(\lambda(A + P)) \geq \sigma_k(\lambda(A)) := S_k(A)$$

where

$$\sigma_k(\lambda(A)) := \sum_{1 \leq i_1 < \dots < i_k \leq N} \lambda_{i_1} \cdots \lambda_{i_k}$$

# $k$ -convex functions on $\Omega$

- For  $u \in C^2(\Omega)$  one asks that for each  $x \in \Omega$ ,

$$S_k(D^2u(x)) \in \Theta_k \quad (\Leftrightarrow \sigma_j(\lambda(D^2u(x))) \geq 0, j = 1, \dots, k)$$

**N.B.** For  $k = 1, N$ ,  $u$  is **subharmonic**, **convex** respectively.

- For  $u \in USC(\Omega)$  one uses a viscosity definition: for each  $x_0 \in \Omega$  and for each  $\varphi \in C^2(\Omega)$

$$u - \varphi \text{ has a local maximum in } x_0 \Rightarrow S_k(D^2\varphi(x_0)) \geq 0;$$

or equivalently, if  $(p, A) \in J^{2,+}u(x_0)$  then  $A \in \Theta_k$ .

## Lemma (Trudinger-Wang AM'99)

$u \in USC(\Omega)$  is  $k$ -convex in  $\Omega$  if and only if for each  $\Omega' \Subset \Omega$  and for each  $v \in C^2(\Omega') \cap C(\bar{\Omega})$  such that  $S_k(D^2v) \leq 0$  in  $\Omega'$

$$u \leq v \text{ on } \partial\Omega' \Rightarrow u \leq v \text{ in } \Omega'.$$

# $(k - 1)$ -convex domains $\Omega$

For  $\Omega \in \mathbb{R}^N$  with  $\partial\Omega \in C^2$  denote by  $(\kappa_1(y), \dots, \kappa_{N-1}(y))$  the principal curvatures at  $y \in \partial\Omega$ ; i.e. the eigenvalues of  $D^2\varphi(y')$  where  $\varphi : B_r(y') \subset \mathbb{R}^{N-1} \rightarrow \mathbb{R}$  locally defines  $\partial\Omega$  as a graph.

- $\Omega$  is strictly  $(k - 1)$ -convex if

$$\sigma_{k-1}(\kappa_1(y), \dots, \kappa_{N-1}(y)) > 0, \quad \text{for each } y \in \partial\Omega$$

**N.B.**  $(N - 1)$ -strict convexity is ordinary strict convexity.

- Since  $\partial\Omega$  is compact, there exists  $R > 0$  such that

$$\sigma_k(\kappa_1(y), \dots, \kappa_{N-1}(y), R) > 0, \quad \text{for each } y \in \partial\Omega;$$

i.e.  $(\kappa_1(y), \dots, \kappa_{N-1}(y), R) \in \Gamma_k$  for each  $y \in \partial\Omega$ .

- Equivalently  $\partial\Omega$  is strictly  $\overrightarrow{\Theta}_k$ -convex in the sense of [Harvey-Lawson, CPAM'09]; expressed in terms of a local defining function  $\rho : B_r(y) \subset \mathbb{R}^N \rightarrow \mathbb{R}$  for the boundary.

### 3. Minimum principle characterization of $\lambda_1^-$

With  $\Phi_k^-(\Omega) := \{\psi \in USC(\Omega) : \psi \text{ is } k\text{-convex and } \psi < 0 \text{ in } \Omega\}$  define the generalized principle eigenvalue  $\lambda_1^-(S_k, \Theta_k)$  as

$$\sup\{\lambda \in \mathbb{R} : \exists \psi \in \Phi_k^-(\Omega) \text{ with } S_k(D^2\psi) + \lambda\psi|\psi|^{k-1} \geq 0 \text{ in } \Omega\},$$

where the inequality is in the viscosity sense:  $\forall x \in \Omega, \varphi \in C^2(\Omega)$ :

$$\psi - \varphi \text{ w/ local max in } x \Rightarrow S_k(D^2\varphi(x)) + \lambda\psi(x)|\psi(x)|^{k-1} \geq 0.$$

Theorem (Birindelli-P.'17)

Let  $\Omega$  be a *strictly*  $(k-1)$ -convex domain in  $\mathbb{R}^N$  with  $k \in \{2, \dots, N\}$ . For every  $\lambda < \lambda_1^-(S_k, \Theta_k)$  and for every  $u \in LSC(\overline{\Omega})$  *admissible viscosity supersolution* of

$$S_k(D^2u) + \lambda u|u|^{k-1} = 0 \text{ in } \Omega \quad (1)$$

one has the following minimum principle

$$u \geq 0 \text{ on } \partial\Omega \Rightarrow u \geq 0 \text{ in } \Omega$$

# Admissible supersolutions of (1)

The admissibility is in the sense of [Krylov, TAMS'95]; that is,  $u \in LSC(\Omega)$  is an **admissible viscosity supersolution** of

$$S_k(D^2u) + \lambda u|u|^{k-1} = 0 \quad \text{in } \Omega$$

if for each  $x_0 \in \Omega$  and for each  $\varphi \in C^2(\Omega)$  such that  $u - \varphi$  has a local minimum (say zero) in  $x_0$  then

$$D^2\varphi(x_0) \notin \Theta_k^\circ \quad \text{or} \quad S_k(D^2\varphi(x_0)) + \lambda\varphi(x_0)|\varphi(x_0)|^{k-1} \leq 0. \quad (2)$$

hence

$$S_k(D^2\varphi(x_0)) + \lambda\varphi(x_0)|\varphi(x_0)|^{k-1} \leq 0 \quad (\text{if } D^2\varphi(x_0) \in \Theta_k^\circ). \quad (3)$$

- $\Theta_k^\circ$  corresponds to strict  $k$ -convexity.
- [Ishii-Lions, JDE'90] use the analog of (3) with  $D^2\varphi(x_0) \in \Theta_k$  for supersolutions to Monge-Ampère equations.
- (2) also reflects *duality* of [Harvey-Lawson, CPAM'09].

# Remarks on the minimum principle

- If  $k$  is odd, then so is  $S_k$  and one has a maximum principle characterization for  $\lambda_1^+(S_k, -\Theta_k)$  via  $k$ -concave functions.
- The minimum principle shows that  $\lambda_1^-(S_k, \Theta_k)$  agrees w/ the principal eigenvalue  $\lambda_1$  of Wang'94 (Lions'85 for  $k = N$ )

$$\lambda_1^k := \inf_{u \in \Phi_0^k(\Omega)} \left\{ - \int_{\Omega} u S_k(D^2 u) dx : \|u\|_{L^{k=1}(\Omega)} = 1 \right\}$$

–  $\Phi_0^k(\Omega)$  the set of strictly  $k$ -convex  $u \in C^2(\Omega)$  w/  $u|_{\partial\Omega} = 0$ .

**Proof** Since  $\lambda_1$  has a  $k$ -convex principal eigenfunction  $\psi_1$  with

$$\psi_1 < 0 \text{ in } \Omega \text{ and } \psi_1 = 0 \text{ on } \partial\Omega,$$

one has  $\lambda_1 \leq \lambda_1^-(S_k, \Theta_k)$  by definition. If  $\lambda_1 < \lambda_1^-(S_k, \Theta_k)$ , then  $\psi_1$  would be an admissible supersolution of (1) with  $\lambda = \lambda_1$  and hence  $\psi_1 \geq 0$  in  $\Omega$  by the minimum principle, which is absurd.

# Idea of proof for the minimum principle

Need  $u \geq 0$  on  $\Omega$  for **supersoln.** with  $0 < \lambda < \lambda_1(S_k, \Theta_k)$  of

$$S_k(D^2u) + \lambda u|u|^{k-1} = 0 \quad \text{in } \Omega. \quad (4)$$

Argue by contradiction and compare  $u$  with  $\gamma\psi$  where

$\psi < 0$  **subsoln.** of (4)  $\leftrightarrow \tilde{\lambda} \in (\lambda, \lambda_1^-)$  and  $\gamma \in \left(0, \gamma' := \sup_{\Omega} \frac{u}{\psi}\right)$

- $\psi$  exists: the set of  $\lambda$  competing for  $\lambda_1^-(S_k, \Theta_k)$  is an interval.
- $\gamma' < \infty$ : use semicontinuity of  $u, \psi$  away from  $\partial\Omega$  and construct barriers near  $\partial\Omega$ .

Find  $\tilde{x} \in \Omega$  such that  $u(\tilde{x}) < 0$  and

$$\lambda|u(\tilde{x})|^k \geq \gamma^k \tilde{\lambda} |\psi(\tilde{x})|^k; \quad \text{i.e.} \quad \frac{\lambda}{\tilde{\lambda}} \gamma^k \leq \left(\frac{u(\tilde{x})}{\psi(\tilde{x})}\right)^k \leq (\gamma')^k. \quad (5)$$

Pick  $\gamma > \gamma'(\lambda/\tilde{\lambda})^{1/k}$  to contradict (5).

# Barriers for $S_k$

For  $\delta > 0$  small enough, there exist  $C_1, C_2 > 0$  such that

$$\psi(x) \leq -C_1 d(x) \quad \text{and} \quad u(x) \geq -C_2 d(x),$$

in  $\Omega_\delta := \{x \in \Omega : d(x) = \text{dist}(x, \partial\Omega) < \delta\}$ .

- Compare  $\psi$  to  $w \in C^2(\Omega)$  standard radial function in an annular region touching  $\partial\Omega$  (Hopf lemma).
- Easy to calculate  $S_k$  on radial functions  $w(x) = h(|x - x_0|)$ .
- Compare  $u$  to  $v(x) = -M \log(1 + td(x))$  with  $t \geq 2R$  where  $R \sigma_{k-1}(\kappa_1(y), \dots, \kappa_{N-1}(y), R) > 0$  all  $y \in \partial\Omega$ .
- Easy to calculate  $S_k v$  for  $v = g \circ d$  in a *principal coordinate system* based at  $y_0 = y(x_0)$  with  $x_0 \in \Omega_{d_0}$ :

$$S_k(D^2 v(x_0)) = \sigma_k \left( \frac{-\kappa_1 g'(d)}{1 - \kappa_1 d}, \dots, \frac{-\kappa_{N-1} g'(d)}{1 - \kappa_{N-1} d}, g''(d) \right),$$

where  $\kappa_i = \kappa_i(y_0)$ ,  $d = d(x_0)$  and  $1 - \kappa_i d > 0$  for  $\delta$  small.

# Ishii's Lemma and admissibility

In order to find  $\tilde{x} \in \Omega$  such that (5) holds when comparing  $u, \gamma\psi$ , look at the maximum values of

$$\Psi_j(x, y) := \gamma\psi(x) - u(y) - \frac{j}{2}|x - y|^2, \quad (x, y) \in \bar{\Omega} \times \bar{\Omega}, j \in \mathbb{N}.$$

- $\Psi_j \leq 0$  on the complement of  $\Omega \times \Omega$ .
- $\Psi_j(\bar{x}, \bar{x}) \geq (\gamma - \gamma')\psi(\bar{x}) > 0$  where  $\min_{\Omega} u = u(\bar{x}) < 0$ , so  $\Psi_j$  has a positive maximum in  $(x_j, y_j) \in \Omega \times \Omega$ .
- By Ishii's lemma,  $\exists X_j, Y_j \in \mathcal{S}(N)$  such that

$$(j(x_j - y_j), X_j) \in \bar{J}^{2,+} \gamma\psi(x_j) \text{ and } (j(x_j - y_j), Y_j) \in \bar{J}^{2,-} \gamma u(y_j)$$

$$(x_j, y_j) \rightarrow (\tilde{x}, \tilde{x}) \text{ and } X_j \leq Y_j.$$

- $X_j \in \Theta_k$  since  $\psi$  is  $k$ -convex and hence  $Y_k \in \Theta_k$ , so

$$\tilde{\lambda} \gamma^k |\psi(x_j)|^k \leq S_k(X_j) \leq S_k(Y_j) \leq \lambda |u(y_j)|^k$$

and pass to the limit to get (5).

# Construction of a principal eigenfunction

We know that a negative  $k$ -convex eigenfunction  $\psi_1$  exists associated to  $\lambda_1 = \lambda_1^-(S_k, \Theta_k)$ , but to prepare for non variational perturbations of  $S_k$  seek a maximum principle approach.

**Idea:** [Birindelli-Demengel] Pick  $\{\lambda_n\}_{n \in \mathbb{N}}$  with  $0 < \lambda_n \nearrow \lambda_1^-$ .

- Start with  $u_0 = 0$  and solve inductively

$$\begin{cases} S_k(D^2 u_n) = 1 - \lambda_n u_{n-1} |u_{n-1}|^{k-1} := f_n & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases} \quad (6)$$

for  $\{u_n\}_{n \in \mathbb{N}} \subset C(\bar{\Omega})$  a decreasing sequence of  $k$ -convex solns.

- The PDE in (6) is proper as  $u_n$  does not appear explicitly.
- A strong comparison principle shows that  $u_n < 0$  in  $\Omega$ .
- Pass to the limit (along a subsequence) as  $n \rightarrow +\infty$  using a uniform Hölder bound on  $\|u_n\|_{C^{0,\gamma}(\bar{\Omega})}$  for each  $n \in \mathbb{N}$  and some  $\gamma \in (0, 1]$ .

# An auxiliary existence and regularity result

## Theorem (Birindelli-P.'17)

Let  $\Omega$  be strictly  $(k-1)$ -convex of class  $C^2$  and let  $f \in C(\Omega)$  be nonnegative and bounded. There exists a unique  $k$ -convex solution  $u \in C(\bar{\Omega})$  of the Dirichlet problem

$$S_k(D^2u) = f \text{ in } \Omega \quad \text{and} \quad u = 0 \text{ on } \partial\Omega.$$

Moreover,  $\forall \gamma \in (0, 1)$  there exists  $C = C(\Omega, \gamma, \|u\|_\infty, \|f\|_\infty)$  s.t.

$$|u(x) - u(x_0)| \leq C|x - x_0|^\gamma, \quad \forall x, x_0 \in \bar{\Omega}. \quad (7)$$

- Existence for  $\partial\Omega \in C^2$  follows from the main theorem of [Cirant-P., PM'17] since strict  $(k-1)$ -convexity implies the needed strict  $\vec{\Theta}_k$  and  $\vec{\tilde{\Theta}}_k$  convexity since

$$\vec{\Theta}_k = \Theta_k \quad \text{and} \quad \Theta_k \subset \vec{\tilde{\Theta}}_k := -\Theta_k^\circ.$$

# Hölder regularity via Ishii-Lions technique (JDE'90)

**Interior estimate:** Fix  $d_0 > 0$  for the boundary estimate (nice tubular neighbourhood) and work in  $\dot{B}_\delta(x_0) \Subset \Omega$  with  $2\delta < d_0$ .

- Compare  $u(x)$  with  $v_{x_0}(x) := u(x_0) + C|x - x_0|^\gamma$  where  $C\delta^\gamma \geq 2\|u\|_\infty$ .
- $u \leq v_{x_0}$  on  $\partial\dot{B}_\delta(x_0)$ .
- $S_k(D^2v_{x_0}(x)) = C^k\gamma^k C_{N,k}|x - x_0|^{k(\gamma-2)}[(\gamma-2)k + N]$  and  $u$  is  $k$ -convex s.t.  $S_k(D^2u) = f \geq 0$
- Use **Trudinger-Wang** if  $(\gamma-2)k + N \leq 0$  ( $k > N/2$ ) and  $u$  (sub)solution with  $f \geq 0$  otherwise.

**Boundary estimate:** In  $\Omega_{d_0}$  compare  $u(x)$  with  $v(x) := -Cd(x)^\gamma$  with suitable  $C = C(d_0(\Omega), \gamma, \|u\|_\infty, \|f\|_\infty)$  so that  $v$  is  $k$ -convex with

$$S_k(D^2v) > \|f\|_\infty \geq S_k(D^2u) \text{ in } \Omega_{d_0}.$$

Apply comparison for  $k$ -convex functions ( $u = 0 = v$  on  $\partial\Omega$ ).

# The existence theorem for $\psi_1$

## Theorem (Birindelli-P.'17)

Let  $\Omega$  be a strictly  $(k-1)$ -convex domain of class  $C^2$ . If  $\{u_n\}_{n \in \mathbb{N}}$  is the sequence of  $k$ -convex solutions to the iteration scheme (6) with  $0 < \lambda_n \nearrow \lambda_1^-$ , then the normalized sequence defined by

$$w_n := u_n / \|u_n\|_\infty$$

admits a subsequence which converges uniformly to an eigenfunction  $\psi_1 < 0$  of  $S_k$  associated to  $\lambda_1^-$ .

- Follow **Birindelli-Demengel** scheme.
- Monotonicity from **comparison principle** for  $k$ -convex functions.
- Hölder regularity above is the key.

# Concluding remarks

Where do we go from here?

- Elements of a Fredholm theory and eigenvalue estimates.
- Anti-maximum principles.
- Symmetry of solutions.
- Non variational perturbations of  $S_k(D^2u)$  like

$$S_k(D^2u + M(x)) + \lambda u|u|^{k-1} \quad \text{with} \quad M \in UC(\Omega; \mathcal{S}(N))$$

considered by [Cirant-P.] and [Y.Y. Li, CPAM'90].

- The “general case”  $F(x, D^2u) + \lambda u|u|^{k-1} = 0$  with  $F(x, A)$ 
  - continuous and  $F(x, 0) = 0$ ;
  - homogeneous of degree  $k$  in  $A \in \mathcal{S}(N)$ ;
  - $F(x, A)$  increasing in  $A$  along  $\Theta : \Omega \rightarrow \mathcal{E} \subset \mathcal{S}(N)$  a uniformly continuous elliptic map;
  - uniformly continuous in  $x \in \Omega$ .

# Thanks to one and all!!!

