

Stability and error analysis for a diffuse interface approach to an advection–diffusion equation on a moving surface

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Advanced Developments for Surface and Interface Dynamics
Analysis and Computation

Problem formulation

given $(\Gamma(t))_{t \in [0, T)} \subset \mathbb{R}^{n+1}$ family of evolving closed hypersurfaces

$$S_T := \bigcup_{t \in (0, T)} \Gamma(t) \times \{t\}$$

$v : S_T \rightarrow \mathbb{R}^{n+1}$ velocity field, $v \cdot \nu = V_\Gamma$

$$u_0 : \Gamma(0) \rightarrow \mathbb{R}.$$

find u such that

$$\partial_t^\bullet u + u \nabla_\Gamma \cdot v - \Delta_\Gamma u = 0 \quad \text{on } S_T \quad (1)$$

$$u(0) = u_0 \quad \text{on } \Gamma(0). \quad (2)$$

Existence and uniqueness

Theorem Suppose that $(\Gamma(t))_{t \in [0, T]}$ is smooth, $v \in C^1(\overline{S_T}, \mathbb{R}^{n+1})$ and $u_0 \in H^1(\Gamma(0))$. Then, (1), (2) has a unique weak solution $u \in H^1(S_T)$ such that $u(0) = u_0$ and

$$\int_{\Gamma(t)} \partial_t^\bullet u \varphi + \int_{\Gamma(t)} u \varphi \nabla_\Gamma \cdot v + \int_{\Gamma(t)} \nabla_\Gamma u \cdot \nabla_\Gamma \varphi = 0$$

for all $\varphi \in H^1(\Gamma(t))$ and a.a. $t \in (0, T)$. Furthermore:

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for all $\varphi \in H^1(\Gamma(t))$ and a.a. $t \in (0, T)$. Furthermore:

$$\int_{\Gamma(t)} u(\cdot, t) = \int_{\Gamma(0)} u_0, \quad 0 < t < T;$$
$$\frac{1}{2} \frac{d}{dt} \int_{\Gamma(t)} u^2 + \int_{\Gamma(t)} |\nabla_\Gamma u|^2 = -\frac{1}{2} \int_{\Gamma(t)} u^2 \nabla_\Gamma \cdot v.$$

Triangulated surfaces:

Dziuk & Elliott (ESFEM, '07,'12,'13), Lenz, Nemadjieu & Rumpf (FV, '08)

Eulerian approach, extended PDE:

Adalsteinsson & Sethian '03, Xu & Zhao '03, Adalsteinsson, Colella, Arkin & Onsum '05, Teigen, Li, Lowengrub, Wang & Voigt '09, Dziuk & Elliott '10, Elliott, Stinner, Styles & Welford '11, Petras & Ruuth '16

Restriction of bulk FEM, CutFEM:

Olshanskii, Reusken & Xu '14, Olshanskii & Reusken '14, Hansbo, Larson & Zahedi '15, Lehrenfeld, Olshanskii & Xu '17

Stationary surface $\Gamma = \{x \in \Omega \mid \phi(x) = 0\}$, $\nabla\phi(x) \neq 0$:

$$\nu = \frac{\nabla\phi}{|\nabla\phi|}$$

$$H = -\nabla \cdot \nu$$

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$$\Delta_{\phi}\eta = \nabla_{\phi} \cdot \nabla_{\phi}\eta$$

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$$\int_{\Omega} \nabla_{\phi} f |\nabla\phi| = - \int_{\Omega} f H \nu |\nabla\phi| \quad \text{supp } f \subset\subset \Omega.$$

Extension

Moving surfaces $\Gamma(t) = \{x \in \Omega \mid \phi(x, t) = 0\}, \nabla\phi(x, t) \neq 0;$

a) There exists an extension v of the velocity such that

$$\phi_t + v \cdot \nabla\phi = 0.$$

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a) There exists an extension v of the velocity such that

$$\phi_t + v \cdot \nabla\phi = 0.$$

b) Suppose that u is a solution of the surface PDE

$$\partial_t^\bullet u + u \nabla_\Gamma \cdot v - \Delta_\Gamma u = 0 \quad \text{on } S_T.$$

There exists an extension u^e of u such that $\nabla u^e \cdot \nabla\phi = 0$ and

$$\partial_t^\bullet u^e + u^e \nabla_\phi \cdot v - \Delta_\phi u^e = \phi R \quad \text{in } \Omega \times (0, T).$$

where $\partial_t^\bullet f = f_t + \nabla f \cdot v$.

Phase field function

For $\epsilon > 0$ define

$$\rho(x, t) := \sigma\left(\frac{\phi(x, t)}{\epsilon}\right),$$

where $\sigma \in C^{0,1}(\mathbb{R})$ is given by

$$\sigma(r) = \begin{cases} \frac{3}{4}(1 - r^2), & |r| \leq 1, \\ 0, & |r| > 1. \end{cases}$$

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$$\frac{1}{\epsilon} \int_{\Omega} f \rho |\nabla \phi| dx = \frac{1}{\epsilon} \int_{-\epsilon}^{\epsilon} \sigma\left(\frac{s}{\epsilon}\right) \int_{\{\phi=s\}} f d\mathcal{H}^n ds \approx \int_{\{\phi=0\}} f d\mathcal{H}^n.$$

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Note that

$$\nabla_{\phi} \rho = 0, \quad \partial_t^{\bullet} \rho = 0.$$

Weak formulation

Let $\eta \in H^1(\Omega)$:

$$\frac{d}{dt} \int_{\Omega} u^e \eta \rho |\nabla \phi| = \int_{\Omega} \partial_t^\bullet (u^e \eta \rho) |\nabla \phi| + \int_{\Omega} u^e \eta \nabla_{\phi} \cdot \nu \rho |\nabla \phi|$$

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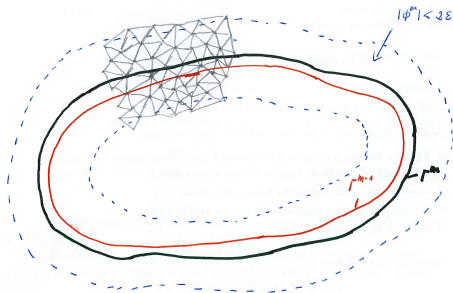
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Discretization

- ▶ Let \mathcal{T}_h be a regular triangulation of Ω , $t_m = m\tau$, $m = 0, 1, \dots$
- ▶ $D_h^m = \bigcup \{T \mid |\phi^m(x)| < 2\epsilon \text{ for some vertex } x \in T\}$.
- ▶ $V_h^m = \{\eta_h \in C^0(D_h^m) \mid \eta_h|_T \in P_1(T), T \subset D_h^m\}$.
- ▶ $\phi_h^m = I_h \phi^m$, $\rho_h^m = \sigma(\frac{\phi_h^m}{\epsilon})$.



Scheme: Find $u_h^m \in V_h^m$ such that for all $\eta_h \in V_h^m$

$$\begin{aligned} & \frac{1}{\tau} \left\{ \int_{\Omega} u_h^m \eta_h \rho_h^m |\nabla \phi_h^m| - \int_{\Omega} u_h^{m-1} \eta_h \rho_h^{m-1} |\nabla \phi_h^{m-1}| \right\} \\ & + \int_{\Omega} \nabla u_h^m \cdot \nabla \eta_h \rho_h^m |\nabla \phi_h^m| - \int_{\Omega} u_h^m (v^m \cdot \nabla \eta_h) \rho_h^m |\nabla \phi_h^m| \\ & + \int_{D_h^m} (\nabla u_h^m \cdot \nu_h^m) (\nabla v_h \cdot \nu_h^m) = 0 \end{aligned}$$

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Mass conservation, stability: For $m = 1, \dots, M$

$$(a) \quad \frac{1}{\epsilon} \int_{\Omega} u_h^m \rho_h^m |\nabla \phi_h^m| = \frac{1}{\epsilon} \int_{\Omega} u_h^0 \rho_h^0 |\nabla \phi_h^0|$$

$$(b) \quad \frac{1}{\epsilon} \int_{\Omega} |u_h^m|^2 \rho_h^m |\nabla \phi_h^m| + \tau \sum_{m=1}^M \frac{1}{\epsilon} \int_{\Omega} |\nabla u_h^m|^2 \rho_h^m |\nabla \phi_h^m| \leq C(u_0)$$

provided that $\epsilon = ch$ and $\tau \leq \gamma h$.

Sketch of the proof of (b)

To simplify: ϕ, ρ instead of ϕ_h, ρ_h ; $\phi(x, t) = d(x, t) = d_{\Gamma(t)}(x)$.

Choose $\eta_h = u_h^m$:

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Choose $\eta_h = u_h^m$:

$$\begin{aligned} & \frac{1}{2} \int_{\Omega} (u_h^m)^2 \rho^m - \frac{1}{2} \int_{\Omega} (u_h^{m-1})^2 \rho^{m-1} + \frac{1}{2} \int_{\Omega} (u_h^m - u_h^{m-1})^2 \rho^{m-1} \\ & \tau \int_{\Omega} |\nabla u_h^m|^2 \rho^m + \tau \int_{D_h^m} (\nabla u_h^m \cdot \nu^m)^2 \end{aligned}$$

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To simplify: ϕ, ρ instead of ϕ_h, ρ_h ; $\phi(x, t) = d(x, t) = d_{\Gamma(t)}(x)$.

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$$I = \tau \int_{\Omega} u_h^m (v^m \cdot \nabla u_h^m) \rho^m$$

$$I = \tau \underbrace{\int_{\Omega} u_h^m (v^m \cdot \nabla_{\phi} u_h^m) \rho^m}_{=I_1} + \tau \underbrace{\int_{\Omega} u_h^m (v^m \cdot \nu^m) (\nabla u_h^m \cdot \nu^m) \rho^m}_{=I_2}$$

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$$I_1 = \frac{1}{2} \tau \int_{\Omega} (\nabla_{\phi} (u_h^m)^2 \cdot v^m) \rho^m$$

$$= -\frac{1}{2} \tau \int_{\Omega} (u_h^m)^2 \nabla_{\phi} \cdot v^m \rho^m - \frac{1}{2} \tau \int_{\Omega} (u_h^m)^2 H^m \underbrace{v^m \cdot \nu^m}_{=-d_t^m} \rho^m;$$

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$$I_2 = -\tau \int_{\Omega} u_h^m (\nabla u_h^m \cdot \nu^m) d_t^m \rho^m.$$

$$H = -\frac{1}{2} \int_{\Omega} (u_h^m)^2 (\rho^m - \rho^{m-1})$$

$$\rho_t = \frac{1}{\epsilon} \sigma' \left(\frac{d}{\epsilon} \right) d_t = \frac{1}{\epsilon} \sigma' \left(\frac{d}{\epsilon} \right) \underbrace{\nabla d \cdot \nu}_{=1} d_t = \nabla \rho \cdot \nu d_t.$$

$$II = -\frac{1}{2} \int_{\Omega} (u_h^m)^2 (\rho^m - \rho^{m-1})$$

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$$II = -\frac{1}{2} \int_{t_{m-1}}^{t_m} \int_{\Omega} (u_h^m)^2 \rho_t = -\frac{1}{2} \int_{t_{m-1}}^{t_m} \int_{\Omega} (u_h^m)^2 \nabla \rho \cdot \nu d_t$$

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since $\nu \cdot \nabla d_t = \nabla d \cdot \nabla d_t = \frac{1}{2} \partial_t |\nabla d|^2 = 0$.

Recall $\frac{1}{2} \frac{d}{dt} \int_{\Gamma(t)} u^2 + \int_{\Gamma(t)} |\nabla_{\Gamma} u|^2 = -\frac{1}{2} \int_{\Gamma(t)} u^2 \nabla_{\Gamma} \cdot \nu$

$$\begin{aligned} & \frac{1}{2} \int_{\Omega} (u_h^m)^2 \rho^m - \frac{1}{2} \int_{\Omega} (u_h^{m-1})^2 \rho^{m-1} + \tau \int_{\Omega} |\nabla u_h^m|^2 \rho^m \\ & + \tau \int_{D_h^m} (\nabla u_h^m \cdot \nu^m)^2 \leq -\frac{1}{2} \tau \int_{\Omega} (u_h^m)^2 (\nabla \phi \cdot \nu^m) \rho^m \\ & + \underbrace{\int_{t_{m-1}}^{t_m} \int_{\Omega} ((u_h^m)^2 r + u_h^m \nabla u_h^m \cdot \tilde{r})}_{=S} \end{aligned}$$

where

$$r = \frac{1}{2} (H^m d_t^m \rho^m - H d_t \rho), \quad \tilde{r} = d_t \rho \nu - d_t^m \rho^m \nu^m.$$

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where

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$$|S| \leq C\tau \int_{\Omega} (u_h^m)^2 \rho^m + \tau \left(\frac{1}{2} + C\epsilon^2 \right) \int_{D_h^m} (\nabla u_h^m \cdot \nu^m)^2.$$

Theorem (Error bound)

Let u be the solution of the surface PDE, $u_h^m \in V_h^m$, $m = 0, \dots, M$ the discrete solution. Then

$$\max_m \int_{\Gamma(t_m)} |u^m - u_h^m|^2 + \tau \sum_{m=1}^M \int_{\Gamma(t_m)} |\nabla_{\Gamma}(u^m - u_h^m)|^2 \leq Ch^2,$$

provided that $\epsilon = ch$, $\tau \leq \epsilon^2$.

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Work in progress

- ▶ Error bound under time step restriction $\tau \leq c\epsilon$;
- ▶ Analysis of a scheme with

$$I_h\left[\sigma\left(\frac{\phi}{\epsilon}\right)\right] \quad \text{instead of} \quad \sigma\left(\frac{I_h\phi}{\epsilon}\right).$$