

Thin Trees

Nima Anari



based on joint work with



Shayan Oveis Gharan

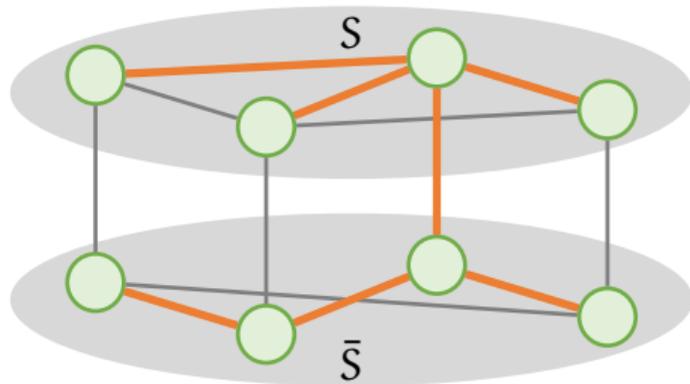
Thin Tree Recap

Thinness

T is α -thin w.r.t. G iff

$$|T(S, \bar{S})| \leq \alpha \cdot |G(S, \bar{S})|,$$

for every subset of vertices S .



Thin Tree Recap

Thinness

T is α -thin w.r.t. G iff

$$|T(S, \bar{S})| \leq \alpha \cdot |G(S, \bar{S})|,$$

for every subset of vertices S .

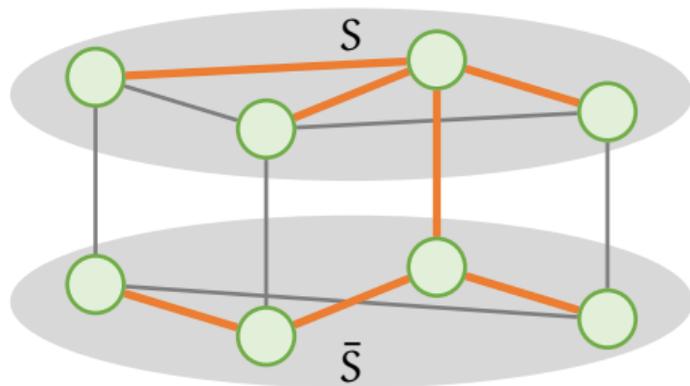
Spectral Thinness

T is α -spectrally thin w.r.t. G iff

$$L_T \preceq \alpha \cdot L_G,$$

or in other words for every $x \in \mathbb{R}^n$,

$$x^T L_T x \leq \alpha x^T L_G x.$$



Thin Tree Recap

Thinness

T is α -thin w.r.t. G iff

$$|T(S, \bar{S})| \leq \alpha \cdot |G(S, \bar{S})|,$$

for every subset of vertices S .

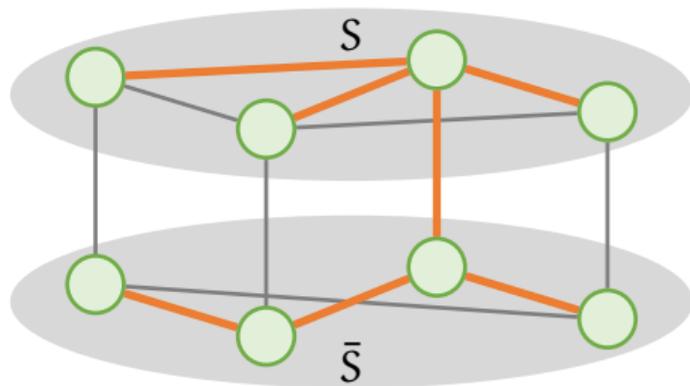
Spectral Thinness

T is α -spectrally thin w.r.t. G iff

$$L_T \preceq \alpha \cdot L_G,$$

or in other words for every $x \in \mathbb{R}^n$,

$$x^T L_T x \leq x^T L_G x.$$



α -spectrally thin
 \implies α -thin

Thin Tree Conjecture

Strong Form of [Goddyn]

Every k -edge connected graph has $O(1/k)$ -thin spanning tree.

Thin Tree Conjecture

Strong Form of [Goddyn]

Every k -edge connected graph has $O(1/k)$ -thin spanning tree.

- ▶ This implies $O(1)$ upper bound for integrality gap of LP relaxation for ATSP.

Thin Tree Conjecture

Strong Form of [Goddyn]

Every k -edge connected graph has $O(1/k)$ -thin spanning tree.

- ▶ This implies $O(1)$ upper bound for integrality gap of LP relaxation for ATSP.
- ▶ Existence of $f(n)/k$ -thin trees implies $O(f(n))$ upper bound for integrality gap of LP relaxation for ATSP.

Thin Tree Conjecture

Strong Form of [Goddyn]

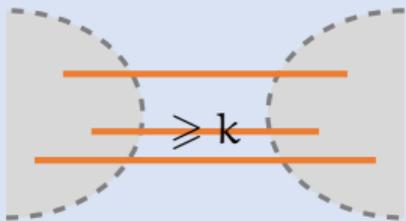
Every k -edge connected graph has $O(1/k)$ -thin spanning tree.

- ▶ This implies $O(1)$ upper bound for integrality gap of LP relaxation for ATSP.
- ▶ Existence of $f(n)/k$ -thin trees implies $O(f(n))$ upper bound for integrality gap of LP relaxation for ATSP.
- ▶ $O(1)$ integrality gap already proved [Svensson-Tarnawski-Végh'17], but thin tree remains open.

Spectral Thinness

Edge Connectivity

$$|G(S, \bar{S})| \geq k$$



Goal

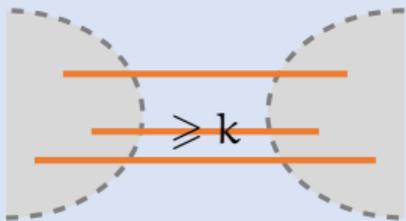
Thin Tree

$$|T(S, \bar{S})| \leq \alpha \cdot |G(S, \bar{S})|$$

Spectral Thinness

Edge Connectivity

$$|G(S, \bar{S})| \geq k$$



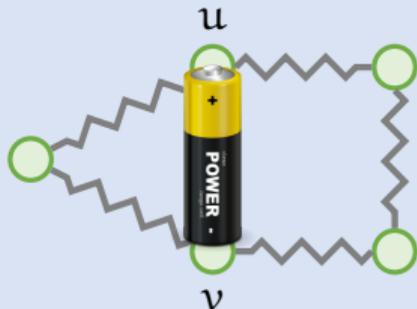
Goal

Thin Tree

$$|T(S, \bar{S})| \leq \alpha \cdot |G(S, \bar{S})|$$

Electrical Connectivity

$$R_{\text{eff}}(u, v) \leq \frac{1}{k}$$



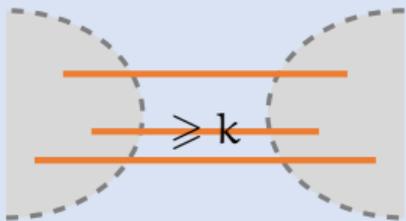
Spectrally Thin Tree

$$x^T L_T x \leq \alpha \cdot x^T L_G x$$

Spectral Thinness

Edge Connectivity

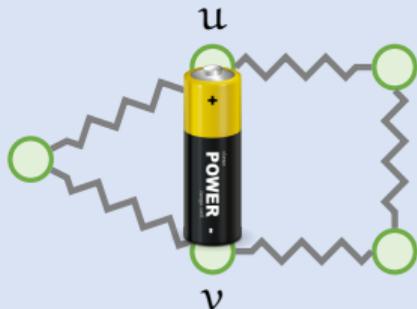
$$|G(S, \bar{S})| \geq k$$



Electrical Connectivity

$$R_{\text{eff}}(u, v) \leq \frac{1}{k}$$

[Harvey-Olver'14,
Marcus-Spielman-Srivastava'14]



Thin Tree

$$|T(S, \bar{S})| \leq \alpha \cdot |G(S, \bar{S})|$$

Spectrally Thin Tree

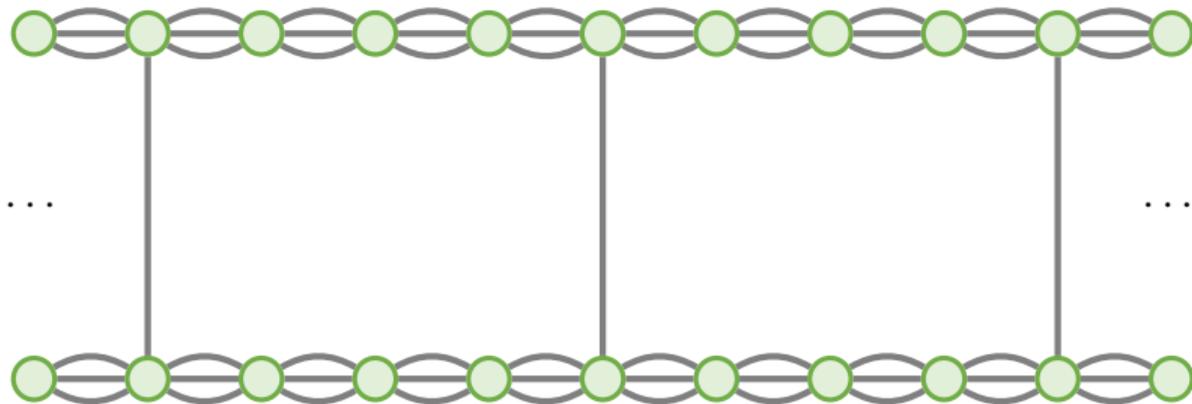
$$x^T L_T x \leq \alpha \cdot x^T L_G x$$

Goal



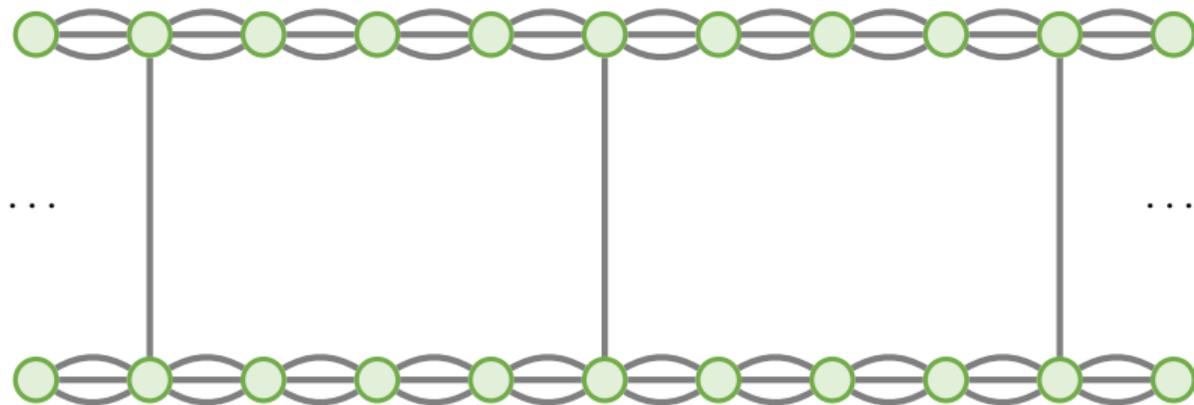
Obstacles

▶ **Problem:** Edge connectivity does not imply electrical connectivity.



Obstacles

► **Problem:** Edge connectivity does not imply electrical connectivity.



► **Problem:** Electrical connectivity is needed for the existence of spectrally thin trees. For any $e = (u, v) \in T$:

$$1 \geq \text{Reff}_T(u, v) = e^T L_T^{-1} b_e \geq \frac{1}{\alpha} \cdot b_e^T L_G^{-1} b_e = \frac{1}{\alpha} \cdot \text{Reff}_G(u, v).$$

Key Idea : Well-condition the graph spectrally
without changing cuts much.

Well-Conditioning Scheme

▶ Add “graph” H to G ensuring

$$|H(S, \bar{S})| \leq O(1) \cdot |G(S, \bar{S})|.$$

Well-Conditioning Scheme

- ▶ Add “graph” H to G ensuring

$$|H(S, \bar{S})| \leq O(1) \cdot |G(S, \bar{S})|.$$

- ▶ If $G + H$ admits an α -spectrally thin tree T , then

$$|T(S, \bar{S})| = \mathbf{1}_S^T L_T \mathbf{1}_S \leq \alpha \cdot \mathbf{1}_S^T (L_G + L_H) \mathbf{1}_S = O(\alpha) \cdot |G(S, \bar{S})|$$

Well-Conditioning Scheme

- ▶ Add “graph” H to G ensuring

$$|H(S, \bar{S})| \leq O(1) \cdot |G(S, \bar{S})|.$$

- ▶ If $G + H$ admits an α -spectrally thin tree T , then

$$|T(S, \bar{S})| = \mathbf{1}_S^T L_T \mathbf{1}_S \leq \alpha \cdot \mathbf{1}_S^T (L_G + L_H) \mathbf{1}_S = O(\alpha) \cdot |G(S, \bar{S})|$$

- ▶ **Goal:** Find H that brings Reff down.

Well-Conditioning Scheme

- ▶ Add “graph” H to G ensuring

$$|H(S, \bar{S})| \leq O(1) \cdot |G(S, \bar{S})|.$$

- ▶ If $G + H$ admits an α -spectrally thin tree T , then

$$|T(S, \bar{S})| = \mathbf{1}_S^T L_T \mathbf{1}_S \leq \alpha \cdot \mathbf{1}_S^T (L_G + L_H) \mathbf{1}_S = O(\alpha) \cdot |G(S, \bar{S})|$$

- ▶ **Goal:** Find H that brings Reff down.
- ▶ **Problem 1:** How do we ensure T does not use any newly added edges?

Well-Conditioning Scheme

- ▶ Add “graph” H to G ensuring

$$|H(S, \bar{S})| \leq O(1) \cdot |G(S, \bar{S})|.$$

- ▶ If $G + H$ admits an α -spectrally thin tree T , then

$$|T(S, \bar{S})| = \mathbf{1}_S^T L_T \mathbf{1}_S \leq \alpha \cdot \mathbf{1}_S^T (L_G + L_H) \mathbf{1}_S = O(\alpha) \cdot |G(S, \bar{S})|$$

- ▶ **Goal:** Find H that brings Reff down.
- ▶ **Problem 1:** How do we ensure T does not use any newly added edges?
- ▶ **Problem 2:** How do we certify H is $O(1)$ -thin w.r.t. G ?

Ensuring only original edges are picked ...

Extension to Interlacing Families

[Harvey-Olver'14, Marcus-Spielman-Srivastava'14]

If for every edge e in a graph G

$$\text{Reff}(e) \leq \alpha,$$

then G has an $O(\alpha)$ -spectrally thin tree.

Extension to Interlacing Families

[Harvey-Olver'14, Marcus-Spielman-Srivastava'14]

If for every edge e in a graph G

$$\text{Reff}(e) \leq \alpha,$$

then G has an $O(\alpha)$ -spectrally thin tree.

[A-Oveis Gharan'15]

Let F be a subset of edges in G . If for every $e \in F$,

$$\text{Reff}_G(e) \leq \alpha,$$

and F is k -edge-connected, then G has a $O(\alpha + 1/k)$ -spectrally thin tree $T \subseteq F$.

Extension to Interlacing Families

[Harvey-Olver'14, Marcus-Spielman-Srivastava'14]

If for every edge e in a graph G

$$\text{Reff}(e) \leq \alpha,$$

then G has an $O(\alpha)$ -spectrally thin tree.

[A-Oveis Gharan'15]

Let F be a subset of edges in G . If for every $e \in F$,

$$\text{Reff}_G(e) \leq \alpha,$$

and F is k -edge-connected, then G has a $O(\alpha + 1/k)$ -spectrally thin tree $T \subseteq F$.

[on board ...]

Ensuring cuts do not blow up ...

Idea 1: Using Shortcuts

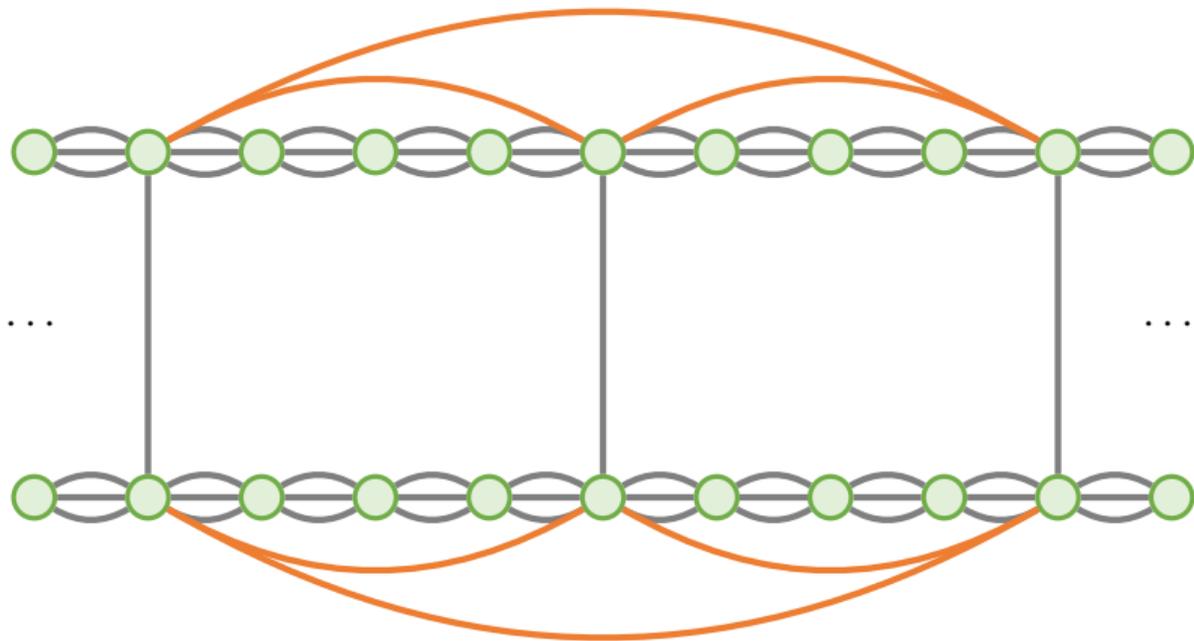
▶ If H can be routed over G with congestion $O(1)$, then for every S

$$H(S, \bar{S}) \leq O(1) \cdot G(S, \bar{S}).$$

Idea 1: Using Shortcuts

▷ If H can be routed over G with congestion $O(1)$, then for every S

$$H(S, \bar{S}) \leq O(1) \cdot G(S, \bar{S}).$$



Idea 2: Check All Constraints

- Instead of L_H , we can add any PSD matrix D , as long as for all S

$$\mathbf{1}_S^T D \mathbf{1}_S \leq |G(S, \bar{S})|.$$

Idea 2: Check All Constraints

- ▶ Instead of L_H , we can add any PSD matrix D , as long as for all S

$$\mathbf{1}_S^T D \mathbf{1}_S \leq |G(S, \bar{S})|.$$

- ▶ Just turn the problem into an exponential-sized semidefinite program:

$$\min_{D \succeq 0} \left\{ \max_{e \in G} \text{Reff}_D(e) \mid \forall S : \mathbf{1}_S^T D \mathbf{1}_S \leq \mathbf{1}_S^T L_G \mathbf{1}_S \right\}$$

Idea 2: Check All Constraints

- ▶ Instead of L_H , we can add any PSD matrix D , as long as for all S

$$\mathbf{1}_S^T D \mathbf{1}_S \leq |G(S, \bar{S})|.$$

- ▶ Just turn the problem into an exponential-sized semidefinite program:

$$\min_{D \succeq 0} \left\{ \max_{e \in G} \text{Reff}_D(e) \mid \forall S : \mathbf{1}_S^T D \mathbf{1}_S \leq \mathbf{1}_S^T L_G \mathbf{1}_S \right\}$$

- ▶ **Pro:** Can use duality to facilitate analysis.

Idea 2: Check All Constraints

- ▶ Instead of L_H , we can add any PSD matrix D , as long as for all S

$$\mathbf{1}_S^T D \mathbf{1}_S \leq |G(S, \bar{S})|.$$

- ▶ Just turn the problem into an exponential-sized semidefinite program:

$$\min_{D \succeq 0} \left\{ \max_{e \in G} \text{Reff}_D(e) \mid \forall S : \mathbf{1}_S^T D \mathbf{1}_S \leq \mathbf{1}_S^T L_G \mathbf{1}_S \right\}$$

- ▶ **Pro:** Can use duality to facilitate analysis.
- ▶ **Con:** Adds another obstacle to making the construction algorithmic.

Puzzle Interlude: Degree-thinness ...

Degree-Thin Trees (Toy Example)

Suppose that we want a tree which is thin only in degree cuts, i.e.,

$$|T(S, \bar{S})| \leq \alpha \cdot |G(S, \bar{S})|,$$

for all singletons S .

Degree-Thin Trees (Toy Example)

Suppose that we want a tree which is thin only in degree cuts, i.e.,

$$|T(S, \bar{S})| \leq \alpha \cdot |G(S, \bar{S})|,$$

for all singletons S .

- ▶ There has been lots of work on special families of cuts, including degree cuts [Olver-Zenklusen'13, Fürer-Raghavachari'94, ...], nevertheless ...

Degree-Thin Trees (Toy Example)

Suppose that we want a tree which is thin only in degree cuts, i.e.,

$$|T(S, \bar{S})| \leq \alpha \cdot |G(S, \bar{S})|,$$

for all singletons S .

- ▶ There has been lots of work on special families of cuts, including degree cuts [Olver-Zenklusen'13, Fürer-Raghavachari'94, ...], nevertheless ...
- ▶ Is there an easy well-conditioner H ?

Degree-Thin Trees (Toy Example)

Suppose that we want a tree which is thin only in degree cuts, i.e.,

$$|T(S, \bar{S})| \leq \alpha \cdot |G(S, \bar{S})|,$$

for all singletons S .

- ▶ There has been lots of work on special families of cuts, including degree cuts [Olver-Zenklusen'13, Fürer-Raghavachari'94, ...], nevertheless ...
- ▶ Is there an easy well-conditioner H ?
- ▶ An **expander**!

[on board ...]

Do well-conditioners always exist?

► What is the worst possible answer to the convex program?

$$\min_{D \succeq 0} \left\{ \max_{e \in G} \text{Reff}_D(e) \mid \forall S : \mathbf{1}_S^T D \mathbf{1}_S \leq \mathbf{1}_S^T L_G \mathbf{1}_S \right\}$$

- ▶ What is the worst possible answer to the convex program?

$$\min_{D \succeq 0} \left\{ \max_{e \in E} \text{Reff}_D(e) \mid \forall S : \mathbf{1}_S^T D \mathbf{1}_S \leq \mathbf{1}_S^T L_G \mathbf{1}_S \right\}$$

- ▶ **Bad News:** There are k -edge-connected graphs where the answer is $\Omega(1)$.

- ▶ What is the worst possible answer to the convex program?

$$\min_{D \succeq 0} \left\{ \max_{e \in G} \text{Reff}_D(e) \mid \forall S : \mathbf{1}_S^T D \mathbf{1}_S \leq \mathbf{1}_S^T L_G \mathbf{1}_S \right\}$$

- ▶ **Bad News:** There are k -edge-connected graphs where the answer is $\Omega(1)$.
- ▶ **New Strategy:** Change the objective to average effective resistance in cuts

$$\max_S \mathbb{E}[\text{Reff}_D(e) \mid e \in G(S, \bar{S})].$$

- ▶ What is the worst possible answer to the convex program?

$$\min_{D \succeq 0} \left\{ \max_{e \in G} \text{Reff}_D(e) \mid \forall S : \mathbf{1}_S^T D \mathbf{1}_S \leq \mathbf{1}_S^T L_G \mathbf{1}_S \right\}$$

- ▶ **Bad News:** There are k -edge-connected graphs where the answer is $\Omega(1)$.
- ▶ **New Strategy:** Change the objective to average effective resistance in cuts

$$\max_S \mathbb{E}[\text{Reff}_D(e) \mid e \in G(S, \bar{S})].$$

- ▶ **Bad News:** There are still bad examples.

- ▶ What is the worst possible answer to the convex program?

$$\min_{D \succeq 0} \left\{ \max_{e \in E} \text{Reff}_D(e) \mid \forall S : \mathbf{1}_S^T D \mathbf{1}_S \leq \mathbf{1}_S^T L_G \mathbf{1}_S \right\}$$

- ▶ **Bad News:** There are k -edge-connected graphs where the answer is $\Omega(1)$.
- ▶ **New Strategy:** Change the objective to average effective resistance in cuts

$$\max_S \mathbb{E}[\text{Reff}_D(e) \mid e \in G(S, \bar{S})].$$

- ▶ **Bad News:** There are still bad examples.

Averages in Degree Cuts [A-Oveis Gharan'15]

For every k -edge-connected graph G there is a 1 -thin matrix $D \succeq 0$ such that for every singleton S

$$\mathbb{E}[\text{Reff}_D(e) \mid e \in G(S, \bar{S})] \leq \frac{(\log \log n)^{O(1)}}{k}.$$

When Degree Cuts are Enough

In expanders, degree cuts are enough.

When Degree Cuts are Enough

In expanders, degree cuts are enough.

- ▶ Assume average R_{eff} in degree cuts is low. By Markov's inequality $> 99\%$ of each degree cut has low effective resistance.

When Degree Cuts are Enough

In expanders, degree cuts are enough.

- ▶ Assume average R_{eff} in degree cuts is low. By Markov's inequality $> 99\%$ of each degree cut has low effective resistance.
- ▶ If a cut has few low-effective-resistance edges, its expansion must be low.

When Degree Cuts are Enough

In expanders, degree cuts are enough.

- ▶ Assume average R_{eff} in degree cuts is low. By Markov's inequality $> 99\%$ of each degree cut has low effective resistance.
- ▶ If a cut has few low-effective-resistance edges, its expansion must be low.

Not every graph is an expander but,

When Degree Cuts are Enough

In expanders, degree cuts are enough.

- ▶ Assume average R_{eff} in degree cuts is low. By Markov's inequality $> 99\%$ of each degree cut has low effective resistance.
- ▶ If a cut has few low-effective-resistance edges, its expansion must be low.

Not every graph is an expander but,

Informal Lemma

Every graph has weakly expanding induced subgraphs.

When Degree Cuts are Enough

In expanders, degree cuts are enough.

- ▶ Assume average R_{eff} in degree cuts is low. By Markov's inequality $> 99\%$ of each degree cut has low effective resistance.
- ▶ If a cut has few low-effective-resistance edges, its expansion must be low.

Not every graph is an expander but,

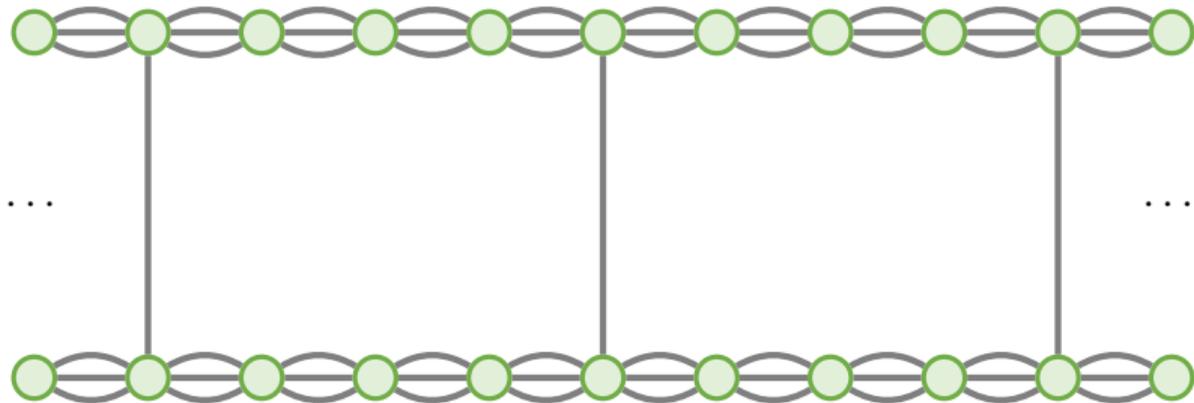
Informal Lemma

Every graph has weakly expanding induced subgraphs.

Plan: Contract this subgraph, and repeat to get a hierarchical decomposition.
Lower average R_{eff} in degree cuts of each expander simultaneously.

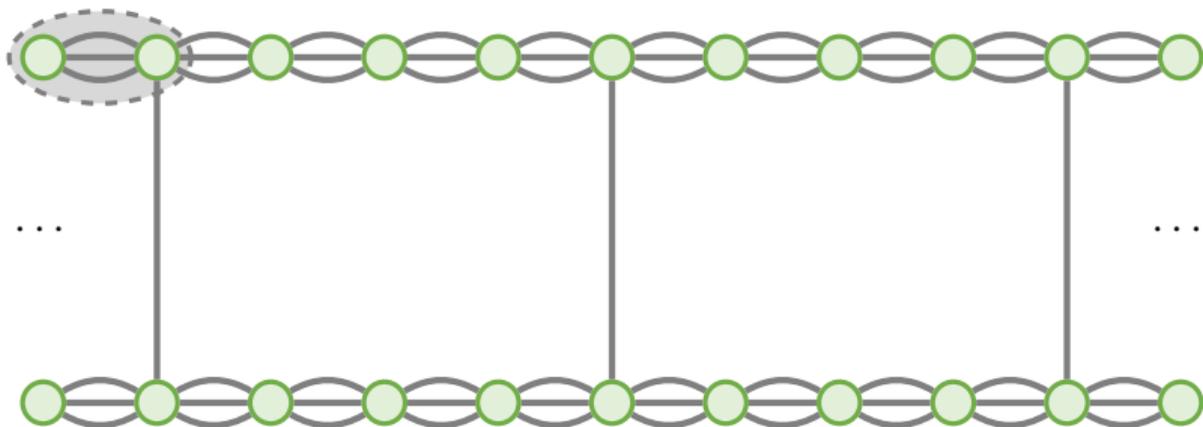
Example: Planar Graphs

If G is planar, there are vertices u and v connected by $\Omega(k)$ edges.



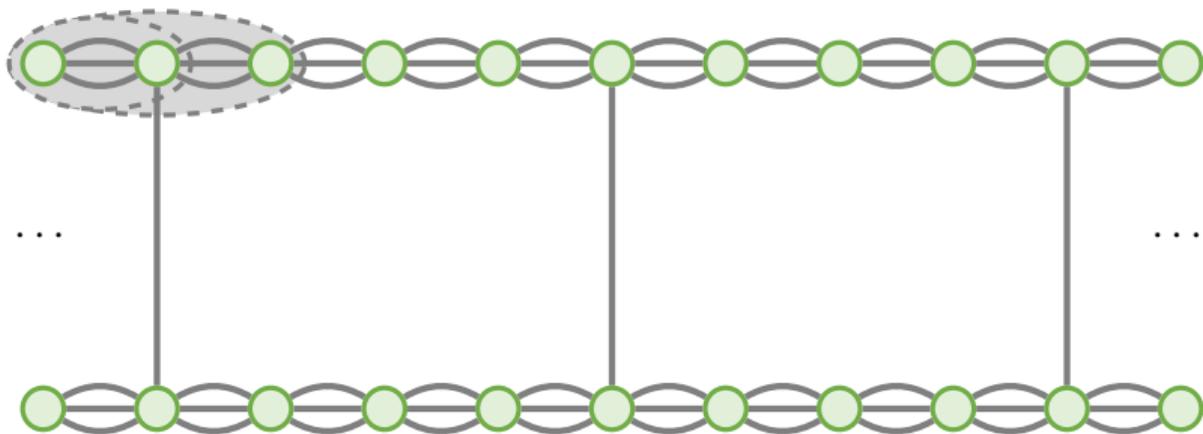
Example: Planar Graphs

If G is planar, there are vertices u and v connected by $\Omega(k)$ edges.



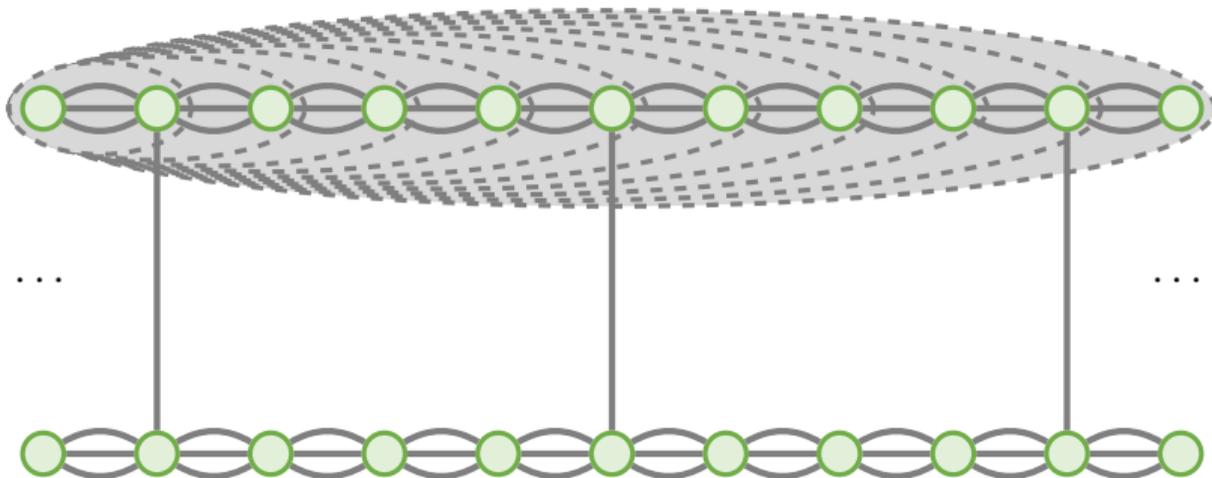
Example: Planar Graphs

If G is planar, there are vertices u and v connected by $\Omega(k)$ edges.



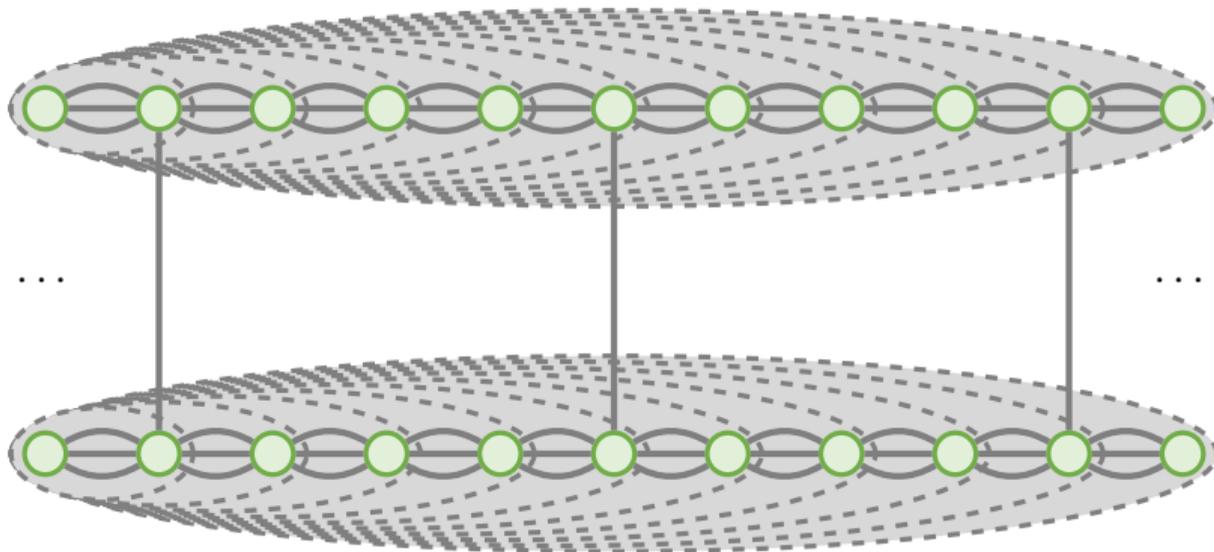
Example: Planar Graphs

If G is planar, there are vertices u and v connected by $\Omega(k)$ edges.



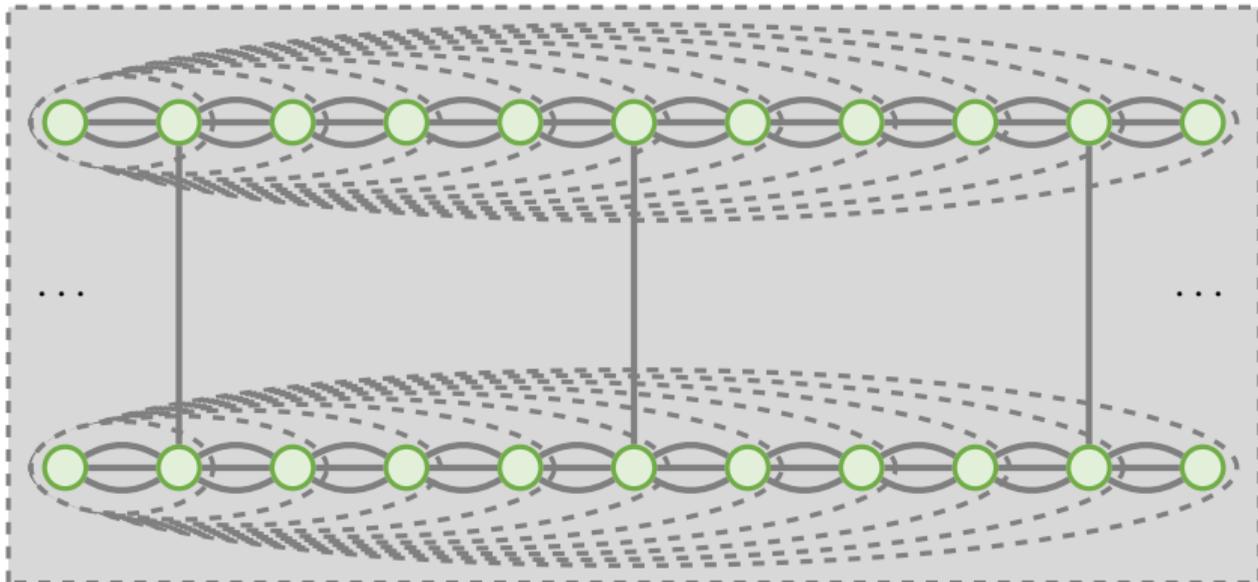
Example: Planar Graphs

If G is planar, there are vertices u and v connected by $\Omega(k)$ edges.



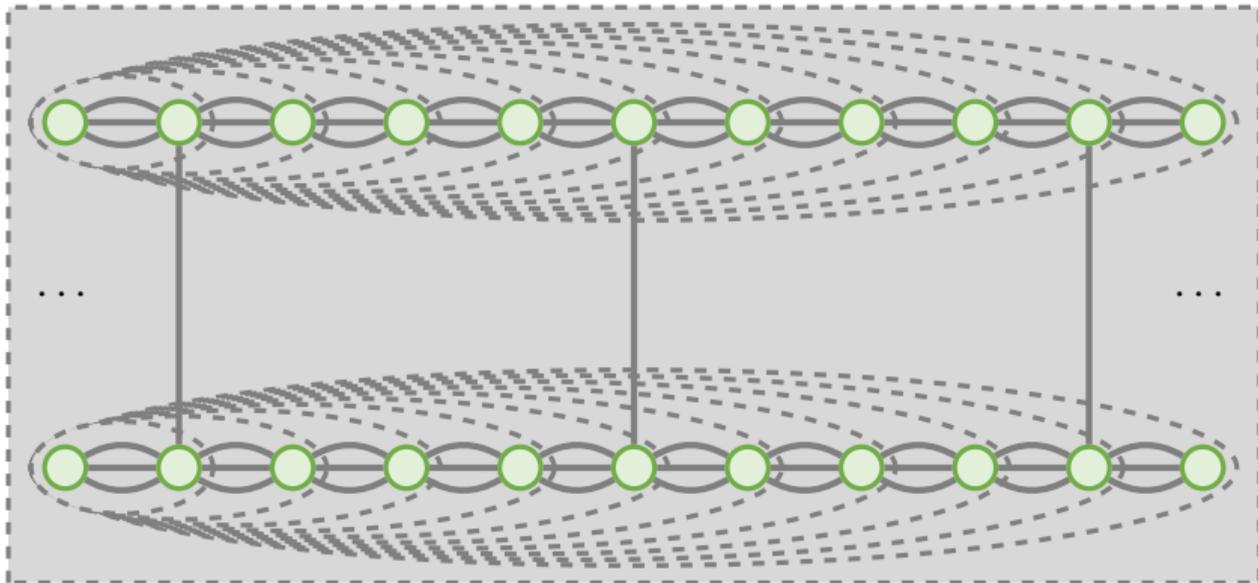
Example: Planar Graphs

If G is planar, there are vertices u and v connected by $\Omega(k)$ edges.



Example: Planar Graphs

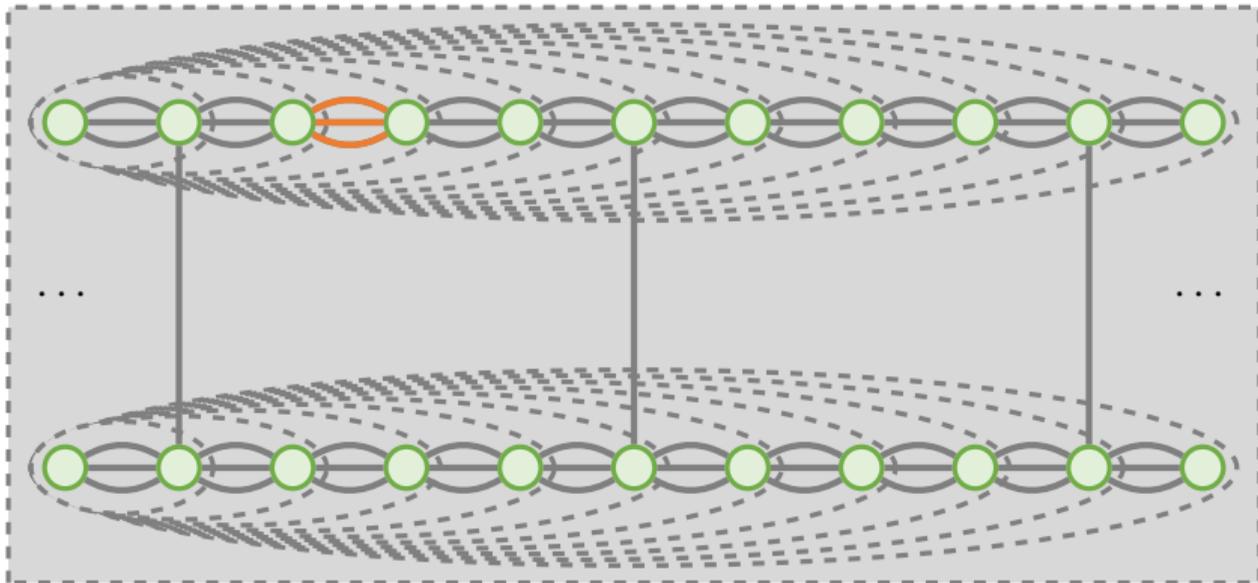
If G is planar, there are vertices u and v connected by $\Omega(k)$ edges.



Reduce average R_{eff} in **degree cuts** of hierarchy simultaneously.

Example: Planar Graphs

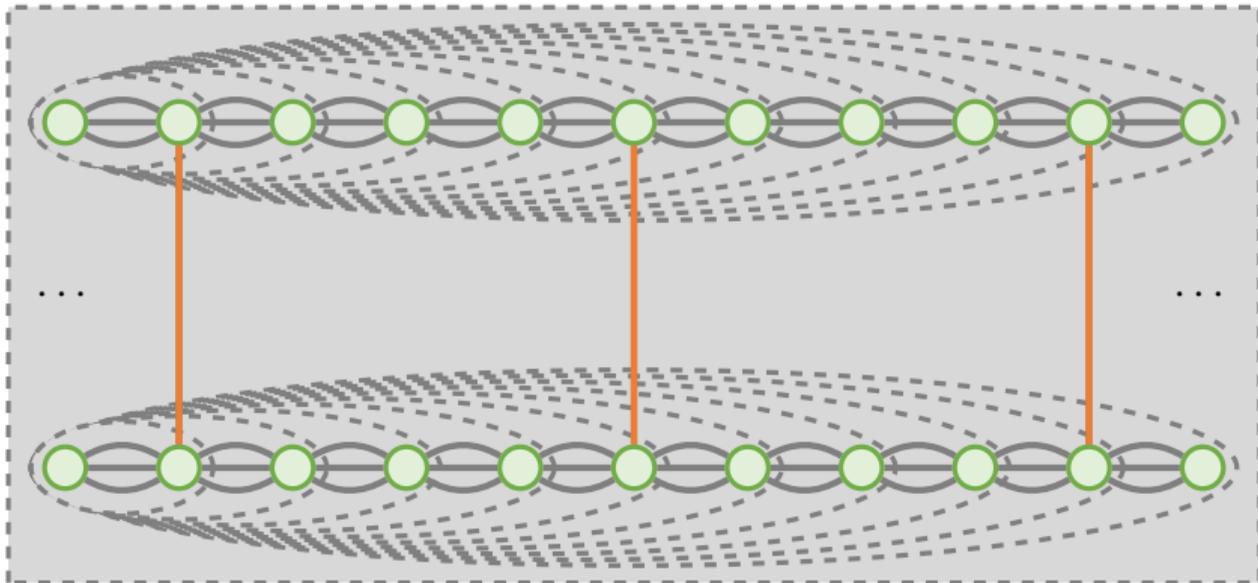
If G is planar, there are vertices u and v connected by $\Omega(k)$ edges.



Reduce average R_{eff} in **degree cuts** of hierarchy simultaneously.

Example: Planar Graphs

If G is planar, there are vertices u and v connected by $\Omega(k)$ edges.



Reduce average R_{eff} in **degree cuts** of hierarchy simultaneously.

Rest of the Ideas

- ▶ There is always a $\Omega(k)$ -edge-connected $1/\log n$ -expanding induced subgraph. Using this, build the hierarchical decomposition.

Rest of the Ideas

- ▶ There is always a $\Omega(k)$ -edge-connected $1/\log n$ -expanding induced subgraph. Using this, build the hierarchical decomposition.
- ▶ Reduce average effective resistance of degree cuts in the hierarchy.

Rest of the Ideas

- ▶ There is always a $\Omega(k)$ -edge-connected $1/\log n$ -expanding induced subgraph. Using this, build the hierarchical decomposition.
- ▶ Reduce average effective resistance of degree cuts in the hierarchy.
- ▶ Contract k -edge-connected components formed of low R_{eff} edges.

Rest of the Ideas

- ▶ There is always a $\Omega(k)$ -edge-connected $1/\log n$ -expanding induced subgraph. Using this, build the hierarchical decomposition.
- ▶ Reduce average effective resistance of degree cuts in the hierarchy.
- ▶ Contract k -edge-connected components formed of low R_{eff} edges.
- ▶ **Key Observation:** Expansion goes up by a constant factor after contracting.

Rest of the Ideas

- ▶ There is always a $\Omega(k)$ -edge-connected $1/\log n$ -expanding induced subgraph. Using this, build the hierarchical decomposition.
- ▶ Reduce average effective resistance of degree cuts in the hierarchy.
- ▶ Contract k -edge-connected components formed of low R_{eff} edges.
- ▶ **Key Observation:** Expansion goes up by a constant factor after contracting.
- ▶ Repeat this $\log \log n$ times until expansion is $\Omega(1)$.

Conclusion

► Every k -edge-connected graph has an α -thin tree for

$$\alpha = \frac{(\log \log n)^{O(1)}}{k}.$$

Conclusion

- ▶ Every k -edge-connected graph has an α -thin tree for

$$\alpha = \frac{(\log \log n)^{O(1)}}{k}.$$

- ▶ Can we build thin trees efficiently?

Conclusion

- ▶ Every k -edge-connected graph has an α -thin tree for

$$\alpha = \frac{(\log \log n)^{O(1)}}{k}.$$

- ▶ Can we build thin trees efficiently?
- ▶ Can we remove the dependence on n ?

Conclusion

- ▶ Every k -edge-connected graph has an α -thin tree for

$$\alpha = \frac{(\log \log n)^{O(1)}}{k}.$$

- ▶ Can we build thin trees efficiently?
- ▶ Can we remove the dependence on n ?
- ▶ What happens if we look at thinness w.r.t. a family of cuts? For what families is it easy to construct well-conditioners?

Conclusion

- ▶ Every k -edge-connected graph has an α -thin tree for

$$\alpha = \frac{(\log \log n)^{O(1)}}{k}.$$

- ▶ Can we build thin trees efficiently?
- ▶ Can we remove the dependence on n ?
- ▶ What happens if we look at thinness w.r.t. a family of cuts? For what families is it easy to construct well-conditioners?

Thank you!