

Consistent and Flexible Thermodynamics using Thermodynamic Potentials

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Motivation I: consistency

Approximations to moist thermodynamics are often inconsistent between different components of the same model, or inconsistent with the laws of thermodynamics. e.g.,

- effect of composition on specific heat capacity;
- $C_p^v \neq C^l$ implies $L^v \neq \text{const}$;

• use of an empirical formula for p^{sat} rather than deriving p^{sat} from the EoS etc for water.

These kinds of inconsistency can lead to errors in the global energy budget of a typical weather or climate model of order 1 Wm^{-2} (Martin Willett, pers. comm.)



Motivation II: flexibility

It may be desirable to use the same model (or dycore) with different EoS e.g.

- Remove current approximations to quantify their effect
- More accurate EoS for air + water to improve tropical tropopause region
- Comparison with rotating annulus experiments
- Ocean and atmosphere with the same dycore!?
- Variable composition:
 - thermosphere for space weather forecasting;
 - exoplanets: non-dilute condensate; gas giant interior; ...

Typically the EoS is hard-coded into many different code segments, making it very difficult to make such changes (consistently).



Consistency via a thermodynamic potential

Recall the four standard thermodynamic potentials

Specific internal energy: $e(\alpha, \eta, q)$ Specific enthalpy: $h(p, \eta, q) = e + \alpha p$ Gibbs function: $g(p, T, q) = e + \alpha p - \eta T$ Helmholtz free energy: $f(\alpha, T, q) = e - \eta T$

where

lpha=1/
ho is specific volume, q is total specific humidity,

 η is specific entropy.



Here (initially) we use the Gibbs function

- It is already used by oceanographers see TEOS10;
- The conditions for equilibrium between phases are equal p, equal T, and equal g; if we work in terms of p and T then two conditions are satisfied more or less automatically.



E.g. Gibbs function for wet air

$$g(p, T, q) = (1 - q)g^d + (q - q^l)g^v + q^l g^l$$

where

$$g^{d} = -C_{p}^{d}T\ln\left(\frac{T}{T_{0}}\right) + R^{d}T\ln\left(\frac{p^{d}}{p_{0}^{d}}\right),$$

$$g^{v} = -C_{p}^{v}T\ln\left(\frac{T}{T_{0}}\right) + R^{v}T\ln\left(\frac{p^{v}}{p_{0}^{v}}\right) + L_{0}^{v}\left(1 - \frac{T}{T_{0}}\right),$$

$$g^{l} = -C^{l}\ln\left(\frac{T}{T_{0}}\right) + \alpha^{l}\left(p - p_{0}^{\text{sat}}\frac{T}{T_{0}}\right),$$

and

 $p^d = \frac{\varepsilon a p}{(1+a(\varepsilon-1))}, \ p^v = \frac{(1-a)p}{(1+a(\varepsilon-1))},$ $a = (1-q)/(1-q^l)$ is the mass fraction of dry air in the gaseous part, and $T_0, \ p_0^d, \ p_0^v, \ p_0^{sat}, \ L_0^v, \ \alpha^l$ and $\varepsilon = R^d/R^v$ are constants.



E.g. Gibbs function for wet air

To evaluate the previous expressions we must determine q^l from the condition for equilibrium between phases:

either

 $q^l > 0$ and $g^v = g^l$

or

 $q^{l} = 0.$



How do we use this idea in practice?

We do not *predict* g. Rather, given p, T and q, we can use the expression for g to compute any thermodynamic quantity we like. E.g.

$$egin{aligned} &lpha &= g_p; &\eta &= -g_T; \ &C_p &= -Tg_{TT}; &C_v &= rac{T(g_{pT}^2 - g_{pp}g_{TT})}{g_p p}; \ &h &= g - Tg_T; &e &= g - pg_p - Tg_T; \ &L^v &= h^v - h^l; &rac{1}{c^2} &= rac{g_{pT}^2 - g_{pp}g_{TT}}{g_p^2 g_{TT}}. \end{aligned}$$



How do we use this idea in practice?

Because these quantities are derived from a thermodynamic potential they are guaranteed to be **consistent** with each other and with the laws of thermodynamics.

We can approximate the Gibbs function; all derived quantities inherit the approximation consistently.

Note the analogy with deriving the dynamical equations from a Lagrangian or Hamiltonian.



What if my model doesn't predict p and T?

E.g. ENDGame predicts ρ and a quantitiv related to η .

Then we must solve

$$1/\rho = g_p(p, T, q), \qquad \eta = -g_T(p, T, q), \qquad (*)$$

for p and T.



Hmmm... 'sounds complicated?

Given a reasonable first guess for p and T, which we will usually have, one or two Newton iterations will suffice to solve (*) accurately.

Even better, for a semi-implicit dynamical core, the solution of (*) can be combined with the iterative semi-implicit solver; this leads to a familiar standard Helmholtz problem for the pressure increments! (Details in T17.)

For an incompressible fluid (*) does not determine p. However, the semi-implict solution method still works! (The Helmholtz problem reduces to a Poisson problem because $1/c^2 = 0$.)



Implementation for flexibility

A single subroutine or set of subroutines computes the Gibbs function and its derivatives.

The rest of the code is generic.

Thus, the EoS can be modified by changing only a small number of routines (and the EoS can easily be made switchable).



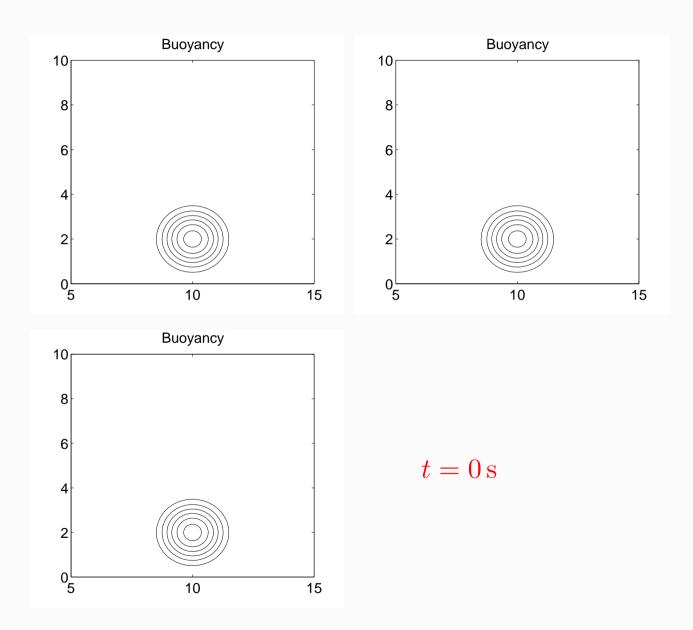
Example (T17)

BF02 2D buoyant bubble test case

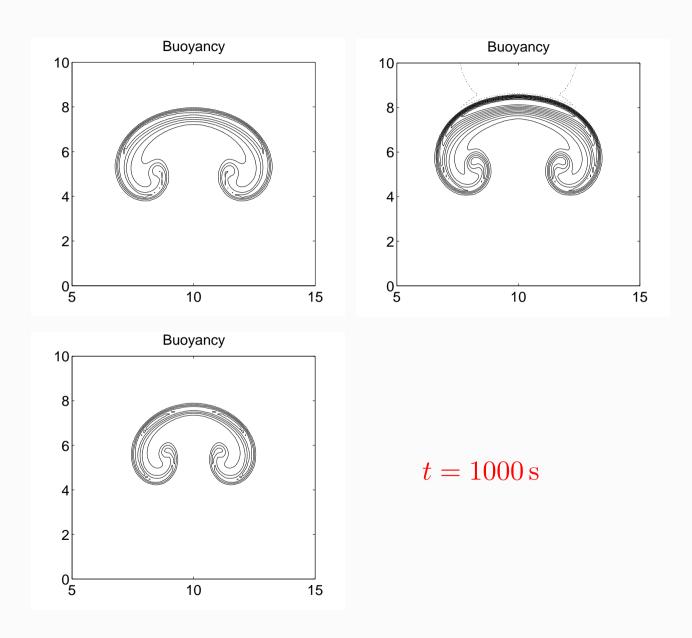
Dry air Saturated air

Quasiincompressible





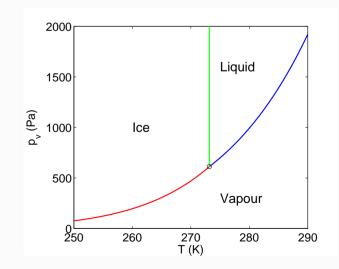






Limitations

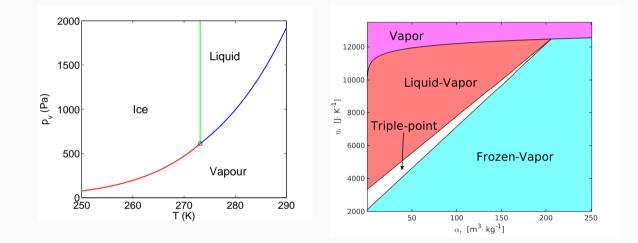
- T17 assumed equilibrium between different phases/components, but **non-equilibrium** processes are important. E.g.,
 - supercooled liquid water,
 - evaporation of rain into subsaturated air,
 - precipitation at different temperature from surrounding air, ...
- If three phases of water are present,
 p, *T* and *q* are not enough to
 determine the fractions of each
 phase.





Current work

- 1. Use internal energy $e(\alpha, \eta, q)$ as the thermodynamic potential.
- The triple point in (p, T)space expands to a triangle in (α, η) space.



- We want to predict (something like) α and η .
- e is more familiar to most meteorologists than g.
- However, determining equilibrium is now more complicated $(7 \times 7 \text{ system for three})$ water phases plus dry air).



Current work

2. Want to remove the equilibrium assumption and replace it by relaxation to equilibrium on specified time scales.

It should be implemented in a way that recovers the equilibrium case as the timescales go to zero.

Entropy sources should be calculated consistently for the non-equilibrium processes.



Next steps

1. Reproduce the results of T17 using a formulation based on e instead of g.

2. Derive governing equations for the non-equilibrium case that reduce to the equilibrium case in the appropriate limit.



Summary

- Deriving all thermodynamic quantities and relations from a potential ensures **consistency** between model components and with the laws of thermodynamics.
- The idea can be implemented in a way that permits **flexibility** in the choice of EoS.
- Feasibility has been demonstrated using the Gibbs function for the case of equilibrium thermodynamics with two water phases.
- We are reformulating the approach in terms of **internal energy** in order to apply it to the case of three water phases...
- ... and extending it to handle **non-equilibrium** thermodynamic processes.



References

BF02: Bryan GH and Fritsch JM, 2002: A benchmark simulation for moist nonhydrostatic numerical models. *Mon. Wea. Rev.*, **130**, 2917-2928.

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T17: Thuburn J, 2017: Use of the Gibbs thermodynamic potential to express the equation of state in atmospheric models. *QJRMS*, **143**, 1185-1196.