# Time domain interpretation of sum rules in electromagnetism 

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Thanks to the organizers of the BIRS Herglotz-Nevanlinna workshop!


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## Introduction



## Motivation

We have had success with deriving sum rules and interpreting them in the frequency domain. One example is for the transmission coefficient of a low pass slab:

$$
\int_{0}^{\infty} \frac{\operatorname{Re}\{1-T(\omega)\}}{\omega^{2}} \mathrm{~d} \omega=\frac{\pi \gamma}{4 A c}
$$

where $\operatorname{Re}\{2 A(1-T)\}=\sigma_{\text {ext }}$ is the extinction cross section of the slab.
But not all sum rules are easy to interpret. For instance, we can derive the following for the reflection coefficient of a PEC backed slab:

$$
\int_{0}^{\infty} \frac{\operatorname{Re}\{1+R(\omega)\}}{\omega^{2}} \mathrm{~d} \omega=\pi\left(1+\frac{\gamma_{\mathrm{m}}}{2 A d}\right) \frac{d}{c}=\pi \mu_{\mathrm{s}} \frac{d}{c}
$$

But what is the physical relevance of $\operatorname{Re}\{1+R(\omega)\}$ ? If we do not find something in the frequency domain, then maybe in time domain?

## Integral identities for Herglotz functions

Consider Herglotz functions with the symmetry $h(z)=-h^{*}\left(-z^{*}\right)$ (real-valued in the time domain), having asymptotic expansions ( $N_{0} \geq 0$ and $N_{\infty} \geq 0$ )

$$
\begin{cases}h(z)=\sum_{n=0}^{N_{0}} a_{2 n-1} z^{2 n-1}+\mathrm{o}\left(z^{2 N_{0}-1}\right) & \text { as } z \hat{\rightarrow} 0 \\ h(z)=\sum_{n=0}^{N_{\infty}} b_{1-2 n} z^{1-2 n}+\mathrm{o}\left(z^{1-2 N_{\infty}}\right) & \text { as } z \hat{\rightarrow} \infty\end{cases}
$$


where $\rightarrow$ denotes limits in the Stoltz domain $0<\theta \leq \arg (z) \leq \pi-\theta$. They satisfy the identities $\left(1-N_{\infty} \leq n \leq N_{0}\right)$

$$
\lim _{\varepsilon \rightarrow 0^{+}} \lim _{y \rightarrow 0^{+}} \frac{2}{\pi} \int_{\varepsilon}^{\frac{1}{\varepsilon}} \frac{\operatorname{Im} h(x+\mathrm{i} y)}{x^{2 n}} \mathrm{~d} x=a_{2 n-1}-b_{2 n-1}= \begin{cases}-b_{2 n-1} & n<0 \\ a_{-1}-b_{-1} & n=0 \\ a_{1}-b_{1} & n=1 \\ a_{2 n-1} & n>1\end{cases}
$$

Bernland, Luger, Gustafsson, Sum rules and constraints on passive systems, J. Phys. A: Math. Theor., 2011.
Warm thanks to Mats, Annemarie, Sven, Lars, Yevhen, Mitja for all the collaborations!

## Physical bounds

Given that $\operatorname{Im} h(x) / x^{2 n}=P(x) \geq 0$, we can estimate the integrals as

$$
\int_{0}^{\infty} P(x) \mathrm{d} x \geq \int_{x_{1}}^{x_{2}} P(x) \mathrm{d} x \geq\left(x_{2}-x_{1}\right) \min _{x \in\left[x_{1}, x_{2}\right]} P(x)
$$

This implies

$$
\left(x_{2}-x_{1}\right) \min _{x \in\left[x_{1}, x_{2}\right]} P(x) \leq \frac{\pi}{2}\left(a_{1}-b_{1}\right)
$$

With the interpretations

- $x_{2}-x_{1}=$ bandwidth (in frequency or wavelength)
- $\min _{x \in\left[x_{1}, x_{2}\right]} P(x)=$ performance level (application specific)
we see that a physical interpretation of the sum rule is that
the product of bandwidth and performance level is bounded from above by lowand high-frequency asymptotics, independent of specific behavior in between!
Further interpretation can be possible when $h$ and the application are specified.


## Notation

In this presentation, notation is abused in at least the following ways:

- $h$ is used to denote both a Herglotz function in frequency domain, and a time domain impulse response.
- The presentation is based more on positive real functions than Herglotz functions:
- Time convention $\mathrm{e}^{\mathrm{j} \omega t}$ is used instead of $\mathrm{e}^{-\mathrm{i} \omega t}$.
- In the stated sum rules, we typically write $\operatorname{Re}\{H(\omega)\}$ instead of $\operatorname{Im}\{\mathrm{i} H(\omega)\}$, where $H(\omega)$ is a transfer function.
- The word "slab" should be interpreted as a planar structure with internal microstructure, although the examples at the end will be for homogeneous slabs due to computational simplicity.


## Scattering problems



## Scattering problems

A plane wave $E^{\mathrm{i}}(\boldsymbol{r})=E_{0} \mathrm{e}^{-\mathrm{j} k \cdot \boldsymbol{r}}, \boldsymbol{H}^{\mathrm{i}}(\boldsymbol{r})=\frac{1}{\eta_{0}} \hat{\boldsymbol{k}} \times \boldsymbol{E}^{\mathrm{i}}(\boldsymbol{r})$, impinges on a scattering object enclosed by a surface $S$.


The interaction with the scatterer results in absorption and scattering. The extincted power is $P_{\text {ext }}=P_{\mathrm{abs}}+P_{\mathrm{sca}}$, and the extinction cross section is $\sigma_{\mathrm{ext}}=\frac{P_{\mathrm{ext}}}{\left|E_{0}\right|^{2} /\left(2 \eta_{0}\right)}$.

## Sum rules in scattering theory

Using the optical theorem, the extinction cross section can be written
1D: $\quad \sigma_{\text {ext }}=\operatorname{Re}\{-2 A(T-1)\} \quad T=$ transmission coefficient
2D : $\quad \sigma_{\text {ext }}=\operatorname{Re}\left\{-\frac{4 b}{\mathrm{jk}} \frac{\boldsymbol{E}_{0}^{*} \cdot \boldsymbol{f}}{\left|\boldsymbol{E}_{0}\right|^{2}}\right\} \quad f=\frac{\mathrm{j} k}{4 b} \hat{\boldsymbol{k}} \times \int_{0}^{b} \oint_{C}\left[\hat{\boldsymbol{k}} \times\left(\hat{\boldsymbol{n}} \times \eta_{0} \boldsymbol{H}^{\mathrm{s}}\right)+\boldsymbol{E}^{\mathrm{s}} \times \hat{\boldsymbol{n}}\right] \mathrm{e}^{\mathrm{j} \boldsymbol{k} \cdot \boldsymbol{r}} \mathrm{d} \ell \mathrm{d} z$
3D : $\quad \sigma_{\text {ext }}=\operatorname{Re}\left\{-\frac{4 \pi}{j k} \frac{\boldsymbol{E}_{0}^{*} \cdot \boldsymbol{F}}{\left|\boldsymbol{E}_{0}\right|^{2}}\right\} \quad \boldsymbol{F}=\frac{\mathrm{j} k}{4 \pi} \hat{\boldsymbol{k}} \times \int_{S}\left[\hat{\boldsymbol{k}} \times\left(\hat{\boldsymbol{n}} \times \eta_{0} \boldsymbol{H}^{\mathrm{s}}\right)+\boldsymbol{E}^{\mathrm{s}} \times \hat{\boldsymbol{n}}\right] \mathrm{e}^{\mathrm{j} \boldsymbol{k} \cdot \boldsymbol{r}} \mathrm{d} S$
Thus, the extinction cross section (proportional to power, square of field strength) can be evaluated using forward scattering coefficients (proportional to field strength, being transfer functions). This enables the derivation of a forward scattering sum rule:

$$
\int_{0}^{\infty} \frac{\sigma_{\mathrm{ext}}(\omega)}{\omega^{2}} \mathrm{~d} \omega=\frac{\pi \gamma}{4 A c}
$$

where $\sigma_{\mathrm{ext}}=\sigma_{\mathrm{abs}}+\sigma_{\text {sca }}$ and $\gamma$ is the static polarizability of the scatterer.

## Scattering problem, periodic surfaces



$$
\left\{\begin{array} { l } 
{ \nabla \times \boldsymbol { E } + \mathrm { jkc } \mu \boldsymbol { H } = \mathbf { 0 } } \\
{ \nabla \times \boldsymbol { H } - \mathrm { jkc } \epsilon \boldsymbol { E } = \mathbf { 0 } }
\end{array} \quad \left\{\begin{array}{l}
\hat{\boldsymbol{n}} \times \boldsymbol{E}=\mathbf{0} \text { on } \partial \Omega, \boldsymbol{E}, \boldsymbol{H} \text { periodic in } x y \\
\text { input/output Floquet ports at } z= \pm \infty
\end{array}\right.\right.
$$

## Scattering problem, periodic surfaces



## How to compute the polarizabilities

The electric polarizability $\gamma_{\mathrm{e}}$ is computed from the static Maxwell's equations:

$$
\nabla \times \boldsymbol{E}=\mathbf{0}, \quad \nabla \cdot \boldsymbol{D}=0, \quad \boldsymbol{D}(\boldsymbol{r})=\boldsymbol{\epsilon}(\boldsymbol{r}) \cdot \boldsymbol{E}(\boldsymbol{r})
$$

The excitation is from a uniform field $E_{0}$,

$$
E(r) \rightarrow E_{0}, \quad|r| \rightarrow \infty
$$

For periodic structures periodic boundary conditions may apply in one or two dimensions. The polarizability tensor $\overline{\bar{\gamma}}_{\mathrm{e}}$ is defined from the dipole moment

$$
\boldsymbol{p}=\int_{U}\left(\boldsymbol{\epsilon}(\boldsymbol{r})-\epsilon_{0} \mathbf{I}\right) \cdot \boldsymbol{E}(\boldsymbol{r}) \mathrm{d} V=\epsilon_{0} \overline{\bar{\gamma}}_{\mathrm{e}} \cdot \boldsymbol{E}_{0}
$$

and the scalar $\gamma_{e}$ is the diagonal element

$$
\gamma_{\mathrm{e}}=\frac{\boldsymbol{E}_{0} \cdot \overline{\bar{\gamma}}_{\mathrm{e}} \cdot \boldsymbol{E}_{0}}{\left|E_{0}\right|^{2}}
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$$

This is very similar to classical homogenization theory, which has periodic boundary conditions in all dimensions.

## How to estimate the polarizability

The electrostatic problem can be solved using two different potentials (with $D_{0}=\epsilon_{0} \boldsymbol{E}_{0}$ ):

$$
\begin{aligned}
\nabla \times \boldsymbol{E}=\mathbf{0} & \Rightarrow & \boldsymbol{E} & =\boldsymbol{E}_{0}-\nabla \varphi \\
\nabla \cdot \boldsymbol{D} & =0 & \Rightarrow & \boldsymbol{D}
\end{aligned}=\boldsymbol{D}_{0}+\nabla \times \boldsymbol{F}
$$

This provides two different expressions for the energy:

$$
\begin{aligned}
J\left(\varphi, \boldsymbol{E}_{0}\right) & =\int\left[\left(\boldsymbol{E}_{0}-\nabla \varphi\right) \cdot \boldsymbol{\epsilon}(\boldsymbol{r}) \cdot\left(\boldsymbol{E}_{0}-\nabla \varphi\right)-\epsilon_{0}\left|\boldsymbol{E}_{0}\right|^{2}\right] \mathrm{d} V \\
K\left(\boldsymbol{F}, \boldsymbol{D}_{0}\right) & =\int\left[\left(\boldsymbol{D}_{0}+\nabla \times \boldsymbol{F}\right) \cdot \boldsymbol{\epsilon}(\boldsymbol{r})^{-1} \cdot\left(\boldsymbol{D}_{0}+\nabla \times \boldsymbol{F}\right)-\epsilon_{0}^{-1}\left|\boldsymbol{D}_{0}\right|^{2}\right] \mathrm{d} V
\end{aligned}
$$

It can be shown that for all test functions $\varphi$ and $F$ (with correct boundary conditions and unit background energy density $\left.\epsilon_{0}\left|E_{0}\right|^{2}=\epsilon_{0}^{-1}\left|\boldsymbol{D}_{0}\right|^{2}=1\right)$

$$
-K\left(\boldsymbol{F}, \boldsymbol{D}_{0}\right) \leq \gamma_{\mathrm{e}} \leq J\left(\varphi, \boldsymbol{E}_{0}\right)
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Equality is obtained for the unique minimizing potentials $\varphi_{0}$ and $F_{0}$, which are the solutions to the electrostatic equations.

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K\left(\boldsymbol{F}, \boldsymbol{D}_{0}\right) & =\int\left[\left(\boldsymbol{D}_{0}+\nabla \times \boldsymbol{F}\right) \cdot \boldsymbol{\epsilon}(\boldsymbol{r})^{-1} \cdot\left(\boldsymbol{D}_{0}+\nabla \times \boldsymbol{F}\right)-\epsilon_{0}^{-1}\left|\boldsymbol{D}_{0}\right|^{2}\right] \mathrm{d} V
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$$

Equality is obtained for the unique minimizing potentials $\varphi_{0}$ and $F_{0}$, which are the solutions to the electrostatic equations. If we can guess $\varphi$ and $F$ based on limited information, we can bound $\gamma_{\mathrm{e}}$ !

## Application to absorption

## Low pass case

Since $\sigma^{\text {ext }}=\sigma^{\text {sca }}+\sigma^{\text {abs }} \geq \sigma^{\text {abs }}$, we have

$$
\left(\lambda_{2}-\lambda_{1}\right) \frac{\sigma_{\min }^{\mathrm{abs}}}{A} \leq \pi^{2} \frac{\gamma_{\mathrm{e}}+\gamma_{\mathrm{m}}}{A}
$$

where $\sigma_{\min }^{\mathrm{abs}} / A$ is the minimum allowed absorption cross section per unit cell area in the band.

## Ground plane backing

Rozanov showed in 2000, using the same analytical properties, that

$$
\left(\lambda_{2}-\lambda_{1}\right) \Gamma_{0} \leq 172 \mu_{\mathrm{s}} d
$$

where $\Gamma_{0}=\min _{\lambda \in\left(\lambda_{1}, \lambda_{2}\right)}\left|\Gamma_{\mathrm{dB}}(\lambda)\right|$ is the minimum allowed return loss in dB . Logarithmic metric instead of linear.

The result is that the product of bandwidth and absorption performance is bounded by the polarizability per unit area.

## Other applications

## Transmission blockage

Low pass structure:

$$
\left(\lambda_{2}-\lambda_{1}\right) \ln \frac{1}{T_{0}} \leq \pi^{2} \frac{\gamma_{\mathrm{e}}+\gamma_{\mathrm{m}}}{2 A}
$$



High impedance surfaces
PEC ground plane backing, $Z_{s} \geq 2 Z_{0}$ :

$$
\frac{\lambda_{2}-\lambda_{1}}{d} \leq \pi
$$



## Sum rules in the time domain



## Sum rules in the time domain

Let $\sigma_{\text {ext }}=\operatorname{Re}\{H\}$, where $H(\omega)$ is a transfer function corresponding to a real, causal impulse response $h(t)=\left[\mathcal{F}^{-1} H\right](t)$. Since $\operatorname{Im}\{H(\omega)\}$ is odd in $\omega$, we have

$$
\int_{0}^{\infty} \frac{\operatorname{Re}\{H(\omega)\}}{\omega^{2}} \mathrm{~d} \omega=\frac{1}{2} \int_{-\infty}^{\infty} \frac{\operatorname{Re}\{H(\omega)\}}{\omega^{2}} \mathrm{~d} \omega=\left.\frac{1}{2} \int_{-\infty}^{\infty} \frac{H(\omega)}{\omega^{2}} \mathrm{e}^{\mathrm{j} \omega t} \mathrm{~d} \omega\right|_{t=0}
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=\frac{1}{2}\left[2 \pi\left(\mathcal{F}^{-1} H(\omega)\right) *\left(\mathcal{F}^{-1} \frac{1}{\omega^{2}}\right)\right]_{t=0} & =\left.\pi \int_{-\infty}^{\infty} h\left(t^{\prime}\right)\left(-\frac{1}{2}\left|t-t^{\prime}\right|\right) \mathrm{d} t^{\prime}\right|_{t=0}
\end{aligned}
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\end{aligned}
$$

Summarizing, we have

$$
\int_{0}^{\infty} \frac{\operatorname{Re}\{H(\omega)\}}{\omega^{2}} \mathrm{~d} \omega=-\frac{\pi}{2} \int_{0}^{\infty} \operatorname{th}(t) \mathrm{d} t
$$

Generalizing, it can be shown that sum rules with weight factors $1 / \omega^{2 n}$ correspond to moments $t^{2 n-1}$ of the impulse response.

## Interpretation

The negative of the first moment of the impulse response,

$$
t_{h}=-\int_{0}^{\infty} t h(t) \mathrm{d} t
$$

can be seen as a delay (known as Elmore delay in electronic circuits).

- Delay is an important quantity in filters, communication channels, logic circuits etc.
- When $h(t) \leq 0$, we have $t_{h}=\int_{0}^{\infty} t|h(t)| \mathrm{d} t$ and the delay interpretation is clear.
- When $h(t)$ has alternating signs, we have $t_{h} \leq \int_{0}^{\infty} t|h(t)| \mathrm{d} t$, and the delay interpretation is less clear, but is sometimes used as a definition.
Thus, the time domain version of the forward scattering sum rules in 1D, 2D, 3D, is

$$
t_{h}=(\text { expression proportional to } \gamma)
$$

meaning
the delay in forward transmission through any linear, time-invariant, passive scattering system is given by the static polarizability $\gamma$.
For propagation through rain or fog, $\gamma$ is related to the volume of water in the air.

## Impulse forward scattering

The impulse forward scattering in different dimensions is
1D : $h(t)=-2 A(\mathcal{T}(t)-\delta(t))$
2D : $\quad h(t)=-\hat{\boldsymbol{k}} \times \int_{0}^{b} \oint_{C}\left[\hat{\boldsymbol{k}} \times\left(\hat{\boldsymbol{n}} \times \eta_{0} \boldsymbol{H}^{\mathrm{s}}(\boldsymbol{r}, \boldsymbol{t}+\hat{\boldsymbol{k}} \cdot \boldsymbol{r} / c)\right)+\boldsymbol{E}^{\mathrm{s}}(\boldsymbol{r}, \boldsymbol{t}+\hat{\boldsymbol{k}} \cdot \boldsymbol{r} / c) \times \hat{\boldsymbol{n}}\right] \mathrm{d} \ell \mathrm{d} z$
3D : $h(t)=-\hat{\boldsymbol{k}} \times \int_{S}\left[\hat{\boldsymbol{k}} \times\left(\hat{\boldsymbol{n}} \times \eta_{0} \boldsymbol{H}^{\mathrm{s}}(\boldsymbol{r}, t+\hat{\boldsymbol{k}} \cdot \boldsymbol{r} / c)\right)+\boldsymbol{E}^{\mathrm{s}}(\boldsymbol{r}, t+\hat{\boldsymbol{k}} \cdot \boldsymbol{r} / c) \times \hat{\boldsymbol{n}}\right] \mathrm{d} S$

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Consider the 1D case for simplicity:

$$
\frac{\pi \gamma}{4 A c}=\int_{0}^{\infty} \frac{\operatorname{Re}\{1-T(\omega)\}}{\omega^{2}} \mathrm{~d} \omega=\frac{\pi}{2} \int_{0}^{\infty} t(\mathcal{T}(t)-\delta(t)) \mathrm{d} t=\frac{\pi}{2} \int_{0}^{\infty} t \mathcal{T}(t) \mathrm{d} t=\frac{\pi}{2} t_{-\mathcal{T}}
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$3 \mathrm{D}: \quad h(t)=-\hat{\boldsymbol{k}} \times \int_{S}\left[\hat{\boldsymbol{k}} \times\left(\hat{\boldsymbol{n}} \times \eta_{0} \boldsymbol{H}^{\mathrm{S}}(\boldsymbol{r}, t+\hat{\boldsymbol{k}} \cdot \boldsymbol{r} / c)\right)+\boldsymbol{E}^{\mathrm{S}}(\boldsymbol{r}, t+\hat{\boldsymbol{k}} \cdot \boldsymbol{r} / c) \times \hat{\boldsymbol{n}}\right] \mathrm{d} S$
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$$

For a non-dispersive slab with refractive index $n$ and thickness $d$ we have

$$
t_{-\mathcal{T}}=\frac{\gamma}{2 A c}=\frac{A d\left(n^{2}-1\right)}{2 A c}=\frac{d(n-1)(n+1)}{2 c}=t_{\mathrm{d}} \frac{n+1}{2}=t_{\mathrm{d}}+t_{\mathrm{d}} \frac{n-1}{2}
$$

where $t_{\mathrm{d}}=(n-1) d / c$ is the one-pass delay through the slab. The delay as measured by $t_{-} \mathcal{T}$ takes into account additional multiple reflections inside the slab.

## Power series of the forward scattering

To indicate the generalization to higher moments, consider the 3D forward scattering:

$$
H(\omega)=-\frac{E_{0}^{*}}{\left|\boldsymbol{E}_{0}\right|^{2}} \cdot \hat{\boldsymbol{k}} \times \int_{S}\left[\hat{\boldsymbol{k}} \times\left(\hat{\boldsymbol{n}} \times \eta_{0} \boldsymbol{H}^{\mathrm{s}}\right)+\boldsymbol{E}^{\mathrm{s}} \times \hat{\boldsymbol{n}}\right] \mathrm{e}^{\mathrm{j} \cdot \boldsymbol{r}} \mathrm{~d} S
$$

With the power series (a being the radius of a sphere enclosing the scatterer)

$$
\boldsymbol{E}^{\mathrm{s}}=\sum_{n=0}^{\infty}(\mathrm{j} k a)^{n} \boldsymbol{E}_{n}^{\mathrm{s}} \quad \boldsymbol{H}^{\mathrm{s}}=\sum_{n=0}^{\infty}(\mathrm{j} k a)^{n} \boldsymbol{H}_{n}^{\mathrm{s}} \quad \mathrm{e}^{\mathrm{j} \boldsymbol{k} \cdot \boldsymbol{r}}=\sum_{n=0}^{\infty}(\mathrm{j} k a)^{n} \frac{(\hat{\boldsymbol{k}} \cdot \boldsymbol{r} / a)^{n}}{n!}
$$

we have

$$
\begin{aligned}
H(\omega) & =-\sum_{n=0}^{\infty} \sum_{m=0}^{\infty}(\mathrm{j} k a)^{m+n} \frac{\boldsymbol{E}_{0}^{*}}{\left|\boldsymbol{E}_{0}\right|^{2}} \cdot \hat{\boldsymbol{k}} \times \int_{S}\left[\hat{\boldsymbol{k}} \times\left(\hat{\boldsymbol{n}} \times \eta_{0} \boldsymbol{H}_{n}^{\mathrm{s}}\right)+\boldsymbol{E}_{n}^{\mathrm{s}} \times \hat{\boldsymbol{n}}\right] \frac{(\hat{\boldsymbol{k}} \cdot \boldsymbol{r} / a)^{m}}{m!} \mathrm{d} S \\
& =-\sum_{n=0}^{\infty}(\mathrm{j} k a)^{n} \sum_{m=0}^{n} \frac{\boldsymbol{E}_{0}^{*}}{\left|\boldsymbol{E}_{0}\right|^{2}} \cdot \hat{\boldsymbol{k}} \times \int_{S}\left[\hat{\boldsymbol{k}} \times\left(\hat{\boldsymbol{n}} \times \eta_{0} \boldsymbol{H}_{m}^{\mathrm{s}}\right)+\boldsymbol{E}_{m}^{\mathrm{s}} \times \hat{\boldsymbol{n}}\right] \frac{(\hat{\boldsymbol{k}} \cdot \boldsymbol{r} / a)^{n-m}}{(n-m)!} \mathrm{d} S
\end{aligned}
$$

The expansion terms (moments of the scattered field distribution) correspond to the derivatives $\left.H^{(n)}\right|_{\omega=0}$, or the moments $\int_{0}^{\infty} t^{n} h(t) \mathrm{d} t$.

## Examples



## Transmission through a non-dispersive slab



Multiple reflections inside the slab gives a sequence of exponentially decaying delta pulses as impulse response:

$$
\begin{gathered}
\mathcal{T}(t)=\sum_{n=0}^{\infty}\left(1-\rho^{2}\right) \rho^{2 n} \delta\left(t-n 2 t_{0}-t_{0}+t_{\mathrm{b}}\right) \\
t_{0}=\sqrt{\epsilon_{\mathrm{r}} \mu_{\mathrm{r}}} \frac{d}{c} \quad t_{\mathrm{b}}=\frac{d}{c} \quad \rho=\frac{\eta_{\mathrm{r}}-1}{\eta_{\mathrm{r}}+1} \quad \eta_{\mathrm{r}}=\sqrt{\frac{\mu_{\mathrm{r}}}{\epsilon_{\mathrm{r}}}}
\end{gathered}
$$

The sum rule is $\int_{0}^{\infty} \frac{\operatorname{Re}\{1-T(\omega)\}}{\omega^{2}} \mathrm{~d} \omega=\frac{\pi \gamma}{4 A c}$, with $\gamma=\operatorname{Ad}\left(\epsilon_{\mathrm{r}}-1+\mu_{\mathrm{r}}-1\right)$.

## Verifying the sum rule

Given $\mathcal{T}(t)=\sum_{n=0}^{\infty}\left(1-\rho^{2}\right) \rho^{2 n} \delta\left(t-n 2 t_{0}-t_{0}+t_{\mathrm{b}}\right)$, the first moment is

$$
\int_{0}^{\infty} t \mathcal{T}(t) \mathrm{d} t=\sum_{n=0}^{\infty}\left(1-\rho^{2}\right) \rho^{2 n}\left(n 2 t_{0}+t_{0}-t_{\mathrm{b}}\right)
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& =\left(1-\rho^{2}\right)\left(2 t_{0} \sum_{n=0}^{\infty} n \rho^{2 n}+\left(t_{0}-t_{\mathrm{b}}\right) \sum_{n=0}^{\infty} \rho^{2 n}\right)
\end{aligned}
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& =\left(1-\rho^{2}\right)\left(2 t_{0} \frac{\rho^{2}}{\left(1-\rho^{2}\right)^{2}}+\left(t_{0}-t_{\mathrm{b}}\right) \frac{1}{1-\rho^{2}}\right)
\end{aligned}
$$

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& =2 t_{0} \frac{\rho^{2}}{1-\rho^{2}}+t_{0}-t_{\mathrm{b}}
\end{aligned}
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& =2 t_{0} \frac{\rho^{2}}{1-\rho^{2}}+t_{0}-t_{\mathrm{b}}=\cdots=
\end{aligned}
$$

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& =\left(1-\rho^{2}\right)\left(2 t_{0} \frac{\rho^{2}}{\left(1-\rho^{2}\right)^{2}}+\left(t_{0}-t_{\mathrm{b}}\right) \frac{1}{1-\rho^{2}}\right) \\
& =2 t_{0} \frac{\rho^{2}}{1-\rho^{2}}+t_{0}-t_{\mathrm{b}}=\cdots=\frac{d}{c} \frac{\epsilon_{\mathrm{r}}+\mu_{\mathrm{r}}-2}{2}
\end{aligned}
$$

## Verifying the sum rule

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& =2 t_{0} \frac{\rho^{2}}{1-\rho^{2}}+t_{0}-t_{\mathrm{b}}=\cdots=\frac{d}{c} \frac{\epsilon_{\mathrm{r}}+\mu_{\mathrm{r}}-2}{2}
\end{aligned}
$$

Hence, we have

$$
\int_{0}^{\infty} t \mathcal{T}(t) \mathrm{d} t=\frac{d}{c} \frac{\epsilon_{\mathrm{r}}+\mu_{\mathrm{r}}-2}{2}=\frac{1}{2 A c} \operatorname{Ad}\left(\epsilon_{\mathrm{r}}-1+\mu_{\mathrm{r}}-1\right)=\frac{\gamma}{2 A c}
$$

and the sum rule is verified.

## Reflection from a grounded non-dispersive slab



With $\epsilon_{\mathrm{r}}>\mu_{\mathrm{r}} \geq 1$ we have $\rho<0$ and alternating signs in reflections.

$$
\begin{gathered}
\mathcal{R}(t)=\rho \delta(t)-\sum_{n=1}^{\infty}\left(1-\rho^{2}\right) \rho^{n-1} \delta\left(t-n 2 t_{0}\right) \\
\int_{0}^{\infty} \frac{\operatorname{Re}\{1+R(\omega)\}}{\omega^{2}} \mathrm{~d} \omega=\pi \mu_{\mathrm{r}} \frac{d}{c} \Rightarrow-\int_{0}^{\infty} t \mathcal{R}(t) \mathrm{d} t=2 \mu_{\mathrm{r}} \frac{d}{c}
\end{gathered}
$$

This can be explicitly verified in the same way as the previous sum rule.

## Reflection from a Salisbury absorber



The reflection $\rho=\frac{-1}{1+2 / G}, G=\sigma d_{\mathrm{s}} \sqrt{\mu_{0} / \epsilon_{0}}$, from a resistive sheet has the same sign from both directions, leading to non-alternating signs of reflections.

$$
\begin{aligned}
\mathcal{R}(t)=\rho \delta(t) & -\sum_{n=1}^{\infty}(1+\rho)^{2}(-\rho)^{n-1} \delta\left(t-n 2 t_{0}\right) \\
& -\int_{0}^{\infty} t \mathcal{R}(t) \mathrm{d} t=2 \frac{d}{c}
\end{aligned}
$$

Note the delay only depends on thickness! True for any non-magnetic absorber.

## Fabry-Perot resonator

resistive sheets



$$
\begin{aligned}
& \mathcal{T}(t)=\sum_{n=0}^{\infty}(1+\rho)^{2} \rho^{2 n} \delta\left(t-n 2 t_{0}\right) \\
& \mathcal{R}(t)=\rho \delta(t)+\sum_{n=1}^{\infty}(1+\rho)^{2} \rho^{2 n-1} \delta\left(t-n 2 t_{0}\right)
\end{aligned}
$$

## Fabry-Perot resonator

$$
\begin{aligned}
& \xrightarrow{\delta(t)} \text { resistive sheets } \\
& \mathcal{R}(t)=\sum_{n=0}^{\infty}(1+\rho)^{2} \rho^{2 n} \delta\left(t-n 2 t_{0}\right) \quad \mathcal{T}(t) \\
& \mathcal{R}(t)=\rho \delta(t)+\sum_{n=1}^{\infty}(1+\rho)^{2} \rho^{2 n-1} \delta\left(t-n 2 t_{0}\right) \quad-\int_{0}^{\infty} t \mathcal{T}(t) \mathrm{d}(t) \mathrm{d} t=\frac{t_{0}}{2} \frac{1}{(1+1 / G)^{2}} \frac{t_{0}}{2} \frac{1+2 / G}{(1+1 / G)^{2}}
\end{aligned}
$$

## Fabry-Perot resonator

$$
\begin{gathered}
\text { resistive sheets } \\
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\mathcal{R}(t)=\rho \delta(t)+\sum_{n=1}^{\infty}(1+\rho)^{2} \rho^{2 n-1} \delta\left(t-n 2 t_{0}\right) \quad-\int_{0}^{\infty} t \mathcal{T}(t) \mathrm{d}(t) \mathrm{d} t=\frac{t_{0}}{2} \frac{1}{(1+1 / G)^{2}} \frac{t_{0}}{2} \frac{1+2 / G}{(1+1 / G)^{2}}
\end{gathered}
$$

The Fabry-Perot resonator is neither low pass, nor backed by a ground plane. Hence the previous sum rules do not apply.

## Impulse moments using bandlimited signals

Explicit impulse responses are very rare. In numerical or experimental approaches, the exciting signal is bandlimited. Consider the input signal $x(t)$ and output signal $y(t)$ :

$$
y(t)=\int_{0}^{\infty} h\left(t-t^{\prime}\right) x\left(t^{\prime}\right) \mathrm{d} t^{\prime}
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The negative first moment of the bandlimited signal is

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t_{y}=-\int_{0}^{\infty} t y(t) \mathrm{d} t=-\int_{t=0}^{\infty} t \int_{t^{\prime}=0}^{\infty} h\left(t-t^{\prime}\right) x\left(t^{\prime}\right) \mathrm{d} t^{\prime} \mathrm{d} t
$$

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& =-\int_{t^{\prime}=0}^{\infty} x\left(t^{\prime}\right) \int_{t=0}^{\infty} t h\left(t-t^{\prime}\right) \mathrm{d} t \mathrm{~d} t^{\prime}=-\int_{t^{\prime}=0}^{\infty} x\left(t^{\prime}\right)\left[\mathrm{j} \frac{\partial}{\partial \omega} H(\omega) \mathrm{e}^{-\mathrm{j} \omega t^{\prime}}\right]_{\omega=0} \mathrm{~d} t^{\prime}
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& =-\int_{t^{\prime}=0}^{\infty} x\left(t^{\prime}\right) \int_{t=0}^{\infty} t h\left(t-t^{\prime}\right) \mathrm{d} t \mathrm{~d} t^{\prime}=-\int_{t^{\prime}=0}^{\infty} x\left(t^{\prime}\right)\left[\mathrm{j} \frac{\partial}{\partial \omega} H(\omega) \mathrm{e}^{-\mathrm{j} \omega t^{\prime}}\right]_{\omega=0} \mathrm{~d} t^{\prime} \\
& =-\int_{t^{\prime}=0}^{\infty} x\left(t^{\prime}\right)\left[\mathrm{j} H^{\prime}(0)+t^{\prime} H(0)\right] \mathrm{d} t^{\prime}=-\int_{t^{\prime}=0}^{\infty} x\left(t^{\prime}\right)\left[\int_{0}^{\infty} t h(t) \mathrm{d} t+t^{\prime} H(0)\right] \mathrm{d} t^{\prime}
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\begin{aligned}
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&=-\int_{t^{\prime}=0}^{\infty} x\left(t^{\prime}\right) \int_{t=0}^{\infty} t h\left(t-t^{\prime}\right) \mathrm{d} t \mathrm{~d} t^{\prime}=-\int_{t^{\prime}=0}^{\infty} x\left(t^{\prime}\right)\left[\mathrm{j} \frac{\partial}{\partial \omega} H(\omega) \mathrm{e}^{-\mathrm{j} \omega t^{\prime}}\right]_{\omega=0} \mathrm{~d} t^{\prime} \\
&=-\int_{t^{\prime}=0}^{\infty} x\left(t^{\prime}\right)\left[\mathrm{j} H^{\prime}(0)+t^{\prime} H(0)\right] \mathrm{d} t^{\prime}=-\int_{t^{\prime}=0}^{\infty} x\left(t^{\prime}\right)\left[\int_{0}^{\infty} t h(t) \mathrm{d} t+t^{\prime} H(0)\right] \mathrm{d} t^{\prime} \\
& \quad=t_{h} X(0)+t_{x} H(0)
\end{aligned}
$$

where $X(0)=\int_{0}^{\infty} x(t) \mathrm{d} t$ is the zeroth moment of $x(t)$.

## Impulse moments using bandlimited signals

Apply two different input signals $x_{1}(t)$ and $x_{2}(t)$ :

$$
\begin{aligned}
& t_{y_{1}}=t_{h} X_{1}(0)+t_{x_{1}} H(0) \\
& t_{y_{2}}=t_{h} X_{2}(0)+t_{x_{2}} H(0)
\end{aligned}
$$

and solve for impulse response moments $H(0)$ and $t_{h}$ in terms of bandlimited data:

$$
\begin{aligned}
H(0) & =\frac{t_{y_{1}} X_{2}(0)-t_{y_{2}} X_{1}(0)}{t_{x_{1}} X_{2}(0)-t_{x_{2}} X_{1}(0)} \\
t_{h} & =\frac{t_{y_{1}} t_{x_{2}}-t_{y_{2}} t_{x_{1}}}{t_{x_{2}} X_{1}(0)-t_{x_{1}} X_{2}(0)}
\end{aligned}
$$

This has been verified by explicit calculations for the Salisbury screen, and implemented numerically as follows. This may prove to be a useful tool also for experimental work, but requires input signals with a DC component.

## Verifying the sum rule for a dispersive slab

Maxwell's equations for a 1D-problem were solved numerically in the time domain using finite differences.



## Verifying the sum rule for a dispersive slab

Maxwell's equations for a 1D-problem were solved numerically in the time domain using finite differences.

$$
\xrightarrow{y(t)} \xrightarrow{x(t)} \stackrel{\begin{array}{c}
\epsilon_{\mathrm{r}} \\
\mu_{\mathrm{r}} \\
\sigma
\end{array}}{\underset{d}{ }} \quad\left\{\begin{array}{l}
\partial_{z} E+\mu \partial_{t} H=0 \\
\partial_{z} H+\epsilon \partial_{t} E+\sigma E=0
\end{array}\right.
$$



$$
\begin{array}{cc|cccccc} 
& \epsilon_{\mathrm{r}} & 1 & 2 & 1 & 1 & 1 & 2 \\
t_{\mathcal{R}}=2 \mu_{\mathrm{r}} \frac{d}{c} & \mu_{\mathrm{r}} & 1 & 1 & 2 & 1 & 1 & 1 \\
& \sigma & 0 & 0 & 0 & 0.01 & 0 & 0.01 \\
& d / c & 1 & 1 & 1 & 1 & 2 & 1 \\
\hline & -\int_{0}^{t_{\max }} t \mathcal{R}(t) \mathrm{d} t & & & & &
\end{array}
$$

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\mu_{\mathrm{r}} \\
\sigma
\end{array} \quad\left\{\begin{array}{l}
\partial_{z} E+\mu \partial_{t} H=0 \\
\partial_{z} H+\epsilon \partial_{t} E+\sigma E=0
\end{array}\right.
$$



$$
\begin{array}{cc|cccccc} 
& \epsilon_{\mathrm{r}} & 1 & 2 & 1 & 1 & 1 & 2 \\
t_{\mathcal{R}}=2 \mu_{\mathrm{r}} \frac{d}{c} & \mu_{\mathrm{r}} & 1 & 1 & 2 & 1 & 1 & 1 \\
& \sigma & 0 & 0 & 0 & 0.01 & 0 & 0.01 \\
\cline { 2 - 7 } & d / c & 1 & 1 & 1 & 1 & 2 & 1 \\
\hline & -\int_{0}^{t_{\max }} t \mathcal{R}(t) \mathrm{d} t & 1.999 & 2.000 & 4.000 & 1.999 & 3.999 & 2.000 \\
25 / 27
\end{array}
$$

## Conclusions



## Conclusions

- The frequency domain sum rules were rewritten in terms of the time domain impulse response.
- The sum rules become restrictions on the moments of impulse response.
- The first moment is (at least sometimes) associated with the average delay through the system. This quantity is of interest in many applications, like filters, communication channels, and electrical networks.
- The static polarizability may be directly linked to physically interesting quantities, like the volume of water in the air.
- A few time domain sum rules were verified by explicit calculations and numerical simulations.
- A means of extracting moments of the impulse response using bandlimited data was demonstrated.


