

# Almost tight lower bounds on regular resolution refutations of Tseitin Formulas for all constant-degree graphs

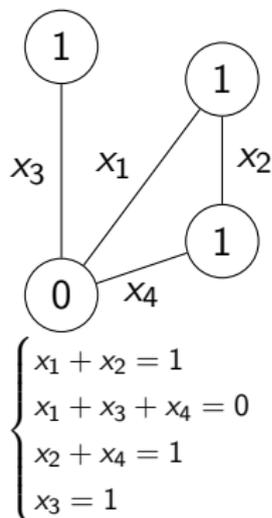
Dmitry Itsykson<sup>1</sup>   Artur Riazanov<sup>1</sup>   Danil Sagunov<sup>1</sup>  
Petr Smirnov<sup>2</sup>

<sup>1</sup>Steklov institute of Mathematics at St. Petersburg  
<sup>2</sup> St. Petersburg State University

Proof Complexity Workshop  
Banff International Research Station  
January 23, 2020

# Tseitin formulas

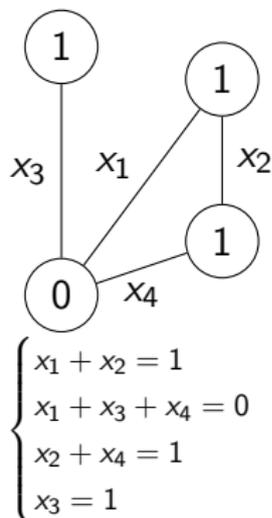
- ▶ Let  $G(V, E)$  be an undirected graph.
- ▶  $f : V \rightarrow \{0, 1\}$  is a charging function.
- ▶ Edge  $e \in E \mapsto$  variable  $x_e$ .
- ▶  $T(G, f) = \bigwedge_{v \in V} \text{Parity}(v)$ , where  $\text{Parity}(v) = \left( \sum_{e \text{ is incident to } v} x_e = f(v) \pmod{2} \right)$ .
- ▶  $T(G, f)$  is represented in CNF.



- ▶ [Urquhart, 1987]  $T(G, f)$  is satisfiable  $\iff$  for every connected component  $U \subseteq V$ ,  $\sum_{v \in U} f(v) = 0$ .

# Tseitin formulas

- ▶ Let  $G(V, E)$  be an undirected graph.
- ▶  $f : V \rightarrow \{0, 1\}$  is a charging function.
- ▶ Edge  $e \in E \mapsto$  variable  $x_e$ .
- ▶  $T(G, f) = \bigwedge_{v \in V} \text{Parity}(v)$ , where  $\text{Parity}(v) = \left( \sum_{e \text{ is incident to } v} x_e = f(v) \pmod{2} \right)$ .
- ▶  $T(G, f)$  is represented in CNF.



- ▶ [Urquhart, 1987]  $T(G, f)$  is satisfiable  $\iff$  for every connected component  $U \subseteq V$ ,  $\sum_{v \in U} f(v) = 0$ .

## Resolution and its subsystems

- ▶ Resolution refutation of a CNF formula  $\phi$ 
  - ▶ **Resolution rule**  $\frac{C \vee x, D \vee \neg x}{C \vee D}$ ,
  - ▶ A refutation of  $\phi$  is a sequence of clauses  $C_1, C_2, \dots, C_s$  such that
    - ▶ for every  $i$ ,  $C_i$  is either a clause of  $\phi$  or is obtained by the resolution rule from previous.
    - ▶  $C_s$  is an empty clause.
- ▶ **Regular resolution**: for any path in the proof-graph no variable is used twice in a resolution rule.
- ▶ **Tree-like resolution**: the proof-graph is a tree.

$$S(\phi) \leq S_{reg}(\phi) \leq S_T(\phi)$$

- ▶ **Resolution width** The width of a clause is the number of literals in it. The width of a refutation is the maximal width of a clause in it.  $w(\phi)$  is the minimal possible width of resolution refutation of  $\phi$ .

# Tseitin formulas and resolution

- ▶ Lower bounds for particular graphs
  - ▶  $S_{reg}(T(\boxplus_n, f)) = n^{\omega(1)}$  where  $\boxplus_n$  is  $n \times n$  grid (Tseitin, 1968).
  - ▶  $S(T(\boxplus_n, f)) = 2^{\Omega(n)}$  (Dantchev, Riis, 2001)
  - ▶  $S(T(G, f)) = 2^{\Omega(n)}$  for an expander  $G$  with  $n$  vertices (Urquhart, 1987, Ben-Sasson, Wigderson, 2001).
- ▶ Upper bound (Alekhnovich, Razborov, 2011)
  - ▶  $S_{reg}(T(G, f)) = 2^{O(w(T(G, f)))} \text{poly}(|V|)$ , where  $w(\phi)$  is a resolution width of  $\phi$ .
- ▶ **Urquhart's conjecture.** Regular resolution polynomially simulates general resolution on Tseitin formulas.
- ▶ **Stronger conjecture.**  $S(T(G, f)) = 2^{\Omega(w(T(G, f)))}$



- ▶ It is false for star graph  $S_n$ ,  
 $S(T(S_n, f)) = O(n)$ , while  $w(T(S_n, f)) = n$ .
- ▶ Perhaps, the conjecture is true for constant-degree graphs.

# Tseitin formulas and resolution

- ▶ Lower bounds for particular graphs
  - ▶  $S_{reg}(T(\boxplus_n, f)) = n^{\omega(1)}$  where  $\boxplus_n$  is  $n \times n$  grid (Tseitin, 1968).
  - ▶  $S(T(\boxplus_n, f)) = 2^{\Omega(n)}$  (Dantchev, Riis, 2001)
  - ▶  $S(T(G, f)) = 2^{\Omega(n)}$  for an expander  $G$  with  $n$  vertices (Urquhart, 1987, Ben-Sasson, Wigderson, 2001).
- ▶ Upper bound (Alekhnovich, Razborov, 2011)
  - ▶  $S_{reg}(T(G, f)) = 2^{O(w(T(G, f)))} \text{poly}(|V|)$ , where  $w(\phi)$  is a resolution width of  $\phi$ .
- ▶ **Urquhart's conjecture.** Regular resolution polynomially simulates general resolution on Tseitin formulas.
- ▶ **Stronger conjecture.**  $S(T(G, f)) = 2^{\Omega(w(T(G, f)))}$



- ▶ It is false for star graph  $S_n$ ,  
 $S(T(S_n, f)) = O(n)$ , while  $w(T(S_n, f)) = n$ .
- ▶ Perhaps, the conjecture is true for constant-degree graphs.

# Tseitin formulas and resolution

- ▶ Lower bounds for particular graphs
  - ▶  $S_{reg}(T(\boxplus_n, f)) = n^{\omega(1)}$  where  $\boxplus_n$  is  $n \times n$  grid (Tseitin, 1968).
  - ▶  $S(T(\boxplus_n, f)) = 2^{\Omega(n)}$  (Dantchev, Riis, 2001)
  - ▶  $S(T(G, f)) = 2^{\Omega(n)}$  for an expander  $G$  with  $n$  vertices (Urquhart, 1987, Ben-Sasson, Wigderson, 2001).
- ▶ Upper bound (Alekhnovich, Razborov, 2011)
  - ▶  $S_{reg}(T(G, f)) = 2^{O(w(T(G, f)))} \text{poly}(|V|)$ , where  $w(\phi)$  is a resolution width of  $\phi$ .
- ▶ **Urquhart's conjecture.** Regular resolution polynomially simulates general resolution on Tseitin formulas.
- ▶ **Stronger conjecture.**  $S(T(G, f)) = 2^{\Omega(w(T(G, f)))}$



- ▶ It is false for star graph  $S_n$ ,  
 $S(T(S_n, f)) = O(n)$ , while  $w(T(S_n, f)) = n$ .
- ▶ Perhaps, the conjecture is true for constant-degree graphs.

# Tseitin formulas and resolution

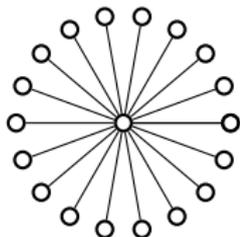
- ▶ Lower bounds for particular graphs
  - ▶  $S_{reg}(T(\boxplus_n, f)) = n^{\omega(1)}$  where  $\boxplus_n$  is  $n \times n$  grid (Tseitin, 1968).
  - ▶  $S(T(\boxplus_n, f)) = 2^{\Omega(n)}$  (Dantchev, Riis, 2001)
  - ▶  $S(T(G, f)) = 2^{\Omega(n)}$  for an expander  $G$  with  $n$  vertices (Urquhart, 1987, Ben-Sasson, Wigderson, 2001).
- ▶ Upper bound (Alekhnovich, Razborov, 2011)
  - ▶  $S_{reg}(T(G, f)) = 2^{O(w(T(G, f)))} \text{poly}(|V|)$ , where  $w(\phi)$  is a resolution width of  $\phi$ .
- ▶ **Urquhart's conjecture.** Regular resolution polynomially simulates general resolution on Tseitin formulas.
- ▶ **Stronger conjecture.**  $S(T(G, f)) = 2^{\Omega(w(T(G, f)))}$



- ▶ It is false for star graph  $S_n$ ,  
 $S(T(S_n, f)) = O(n)$ , while  $w(T(S_n, f)) = n$ .
- ▶ Perhaps, the conjecture is true for constant-degree graphs.

# Tseitin formulas and resolution

- ▶ Lower bounds for particular graphs
  - ▶  $S_{reg}(T(\boxplus_n, f)) = n^{\omega(1)}$  where  $\boxplus_n$  is  $n \times n$  grid (Tseitin, 1968).
  - ▶  $S(T(\boxplus_n, f)) = 2^{\Omega(n)}$  (Dantchev, Riis, 2001)
  - ▶  $S(T(G, f)) = 2^{\Omega(n)}$  for an expander  $G$  with  $n$  vertices (Urquhart, 1987, Ben-Sasson, Wigderson, 2001).
- ▶ Upper bound (Alekhnovich, Razborov, 2011)
  - ▶  $S_{reg}(T(G, f)) = 2^{O(w(T(G, f)))} \text{poly}(|V|)$ , where  $w(\phi)$  is a resolution width of  $\phi$ .
- ▶ **Urquhart's conjecture.** Regular resolution polynomially simulates general resolution on Tseitin formulas.
- ▶ **Stronger conjecture.**  $S(T(G, f)) = 2^{\Omega(w(T(G, f)))}$



- ▶ It is false for star graph  $S_n$ ,  
 $S(T(S_n, f)) = O(n)$ , while  $w(T(S_n, f)) = n$ .
- ▶ Perhaps, the conjecture is true for constant-degree graphs.

# Tseitin formulas and resolution

- ▶ Lower bounds for particular graphs
  - ▶  $S_{reg}(T(\boxplus_n, f)) = n^{\omega(1)}$  where  $\boxplus_n$  is  $n \times n$  grid (Tseitin, 1968).
  - ▶  $S(T(\boxplus_n, f)) = 2^{\Omega(n)}$  (Dantchev, Riis, 2001)
  - ▶  $S(T(G, f)) = 2^{\Omega(n)}$  for an expander  $G$  with  $n$  vertices (Urquhart, 1987, Ben-Sasson, Wigderson, 2001).
- ▶ Upper bound (Alekhnovich, Razborov, 2011)
  - ▶  $S_{reg}(T(G, f)) = 2^{O(w(T(G, f)))} \text{poly}(|V|)$ , where  $w(\phi)$  is a resolution width of  $\phi$ .
- ▶ **Urquhart's conjecture.** Regular resolution polynomially simulates general resolution on Tseitin formulas.
- ▶ **Stronger conjecture.**  $S(T(G, f)) = 2^{\Omega(w(T(G, f)))}$



- ▶ It is false for star graph  $S_n$ ,  
 $S(T(S_n, f)) = O(n)$ , while  $w(T(S_n, f)) = n$ .
- ▶ Perhaps, the conjecture is true for constant-degree graphs.

## Constant degree graphs

- ▶ (Galesi et al. 2018)  $w(T(G, f)) = \Theta(\text{tw}(G))$  for  $O(1)$ -degree graphs.
- ▶ The inequality  $S(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$  is known for following  $O(1)$ -degree graphs:
  - ▶ (Size-width relation): graphs with large treewidth:  
 $\text{tw}(G) = \Omega(n)$
  - ▶ (Alekhovich, Razborov, 2011): graphs with bounded cyclicity
  - ▶ (xorification): graphs with doubled edges
- ▶ **Grid Minor Theorem** (Robertson, Seymour 1986), (Chuzhoy 2015): Every graph  $G$  has a grid minor of size  $t \times t$ , where  $t = \Omega(\text{tw}(G)^\delta)$ .
  - ▶ Known for  $\delta = 1/10$ . Necessary:  $\delta \leq \frac{1}{2}$ .
  - ▶ (Håstad, 2017) Let  $S$  be the size of the shortest  $d$ -depth Frege proof of  $T(\boxplus_n, f)$ . Then  $S \geq 2^{n^{\Omega(1/d)}}$  for  $d \leq \frac{C \log n}{\log \log n}$
  - ▶ For resolution this method gives  $S(T(G, f)) \geq 2^{\text{tw}(G)^\delta}$ .
- ▶ Tree-like resolution
  - ▶  $S_T(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$  (size-width relation)
  - ▶  $S_T(T(G, f)) \leq 2^{\Omega(\text{tw}(G) \log |V|)}$  (Beame, Beck, Impagliazzo, 2013, I., Oparin, 2013)

## Constant degree graphs

- ▶ (Galesi et al. 2018)  $w(T(G, f)) = \Theta(\text{tw}(G))$  for  $O(1)$ -degree graphs.
- ▶ The inequality  $S(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$  is known for following  $O(1)$ -degree graphs:
  - ▶ (Size-width relation): graphs with large treewidth:  
 $\text{tw}(G) = \Omega(n)$
  - ▶ (Alekhovich, Razborov, 2011): graphs with bounded cyclicity
  - ▶ (xorification): graphs with doubled edges
- ▶ **Grid Minor Theorem** (Robertson, Seymour 1986), (Chuzhoy 2015): Every graph  $G$  has a grid minor of size  $t \times t$ , where  $t = \Omega(\text{tw}(G)^\delta)$ .
  - ▶ Known for  $\delta = 1/10$ . Necessary:  $\delta \leq \frac{1}{2}$ .
  - ▶ (Håstad, 2017) Let  $S$  be the size of the shortest  $d$ -depth Frege proof of  $T(\boxplus_n, f)$ . Then  $S \geq 2^{n^{\Omega(1/d)}}$  for  $d \leq \frac{C \log n}{\log \log n}$
  - ▶ For resolution this method gives  $S(T(G, f)) \geq 2^{\text{tw}(G)^\delta}$ .
- ▶ Tree-like resolution
  - ▶  $S_T(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$  (size-width relation)
  - ▶  $S_T(T(G, f)) \leq 2^{\Omega(\text{tw}(G) \log |V|)}$  (Beame, Beck, Impagliazzo, 2013, I., Oparin, 2013)

## Constant degree graphs

- ▶ (Galesi et al. 2018)  $w(T(G, f)) = \Theta(\text{tw}(G))$  for  $O(1)$ -degree graphs.
- ▶ The inequality  $S(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$  is known for following  $O(1)$ -degree graphs:
  - ▶ (Size-width relation): graphs with large treewidth:  
 $\text{tw}(G) = \Omega(n)$ 
    - ▶ (Alekhovich, Razborov, 2011): graphs with bounded cyclicity
    - ▶ (xorification): graphs with doubled edges
  - ▶ **Grid Minor Theorem** (Robertson, Seymour 1986), (Chuzhoy 2015): Every graph  $G$  has a grid minor of size  $t \times t$ , where  $t = \Omega(\text{tw}(G)^\delta)$ .
    - ▶ Known for  $\delta = 1/10$ . Necessary:  $\delta \leq \frac{1}{2}$ .
    - ▶ (Håstad, 2017) Let  $S$  be the size of the shortest  $d$ -depth Frege proof of  $T(\boxplus_n, f)$ . Then  $S \geq 2^{n^{\Omega(1/d)}}$  for  $d \leq \frac{C \log n}{\log \log n}$
    - ▶ For resolution this method gives  $S(T(G, f)) \geq 2^{\text{tw}(G)^\delta}$ .
- ▶ Tree-like resolution
  - ▶  $S_T(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$  (size-width relation)
  - ▶  $S_T(T(G, f)) \leq 2^{\Omega(\text{tw}(G) \log |V|)}$  (Beame, Beck, Impagliazzo, 2013, I., Oparin, 2013)

## Constant degree graphs

- ▶ (Galesi et al. 2018)  $w(T(G, f)) = \Theta(\text{tw}(G))$  for  $O(1)$ -degree graphs.
- ▶ The inequality  $S(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$  is known for following  $O(1)$ -degree graphs:
  - ▶ (Size-width relation): graphs with large treewidth:  
 $\text{tw}(G) = \Omega(n)$
  - ▶ (Alekhnovich, Razborov, 2011): graphs with bounded cyclicity
    - ▶ (xorification): graphs with doubled edges
- ▶ **Grid Minor Theorem** (Robertson, Seymour 1986), (Chuzhoy 2015): Every graph  $G$  has a grid minor of size  $t \times t$ , where  $t = \Omega(\text{tw}(G)^\delta)$ .
  - ▶ Known for  $\delta = 1/10$ . Necessary:  $\delta \leq \frac{1}{2}$ .
  - ▶ (Håstad, 2017) Let  $S$  be the size of the shortest  $d$ -depth Frege proof of  $T(\boxplus_n, f)$ . Then  $S \geq 2^{n^{\Omega(1/d)}}$  for  $d \leq \frac{C \log n}{\log \log n}$
  - ▶ For resolution this method gives  $S(T(G, f)) \geq 2^{\text{tw}(G)^\delta}$ .
- ▶ Tree-like resolution
  - ▶  $S_T(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$  (size-width relation)
  - ▶  $S_T(T(G, f)) \leq 2^{\Omega(\text{tw}(G) \log |V|)}$  (Beame, Beck, Impagliazzo, 2013, I., Oparin, 2013)

## Constant degree graphs

- ▶ (Galesi et al. 2018)  $w(T(G, f)) = \Theta(\text{tw}(G))$  for  $O(1)$ -degree graphs.
- ▶ The inequality  $S(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$  is known for following  $O(1)$ -degree graphs:
  - ▶ (Size-width relation): graphs with large treewidth:  
 $\text{tw}(G) = \Omega(n)$
  - ▶ (Alekhovich, Razborov, 2011): graphs with bounded cyclicity
  - ▶ (xorification): graphs with doubled edges
- ▶ **Grid Minor Theorem** (Robertson, Seymour 1986), (Chuzhoy 2015): Every graph  $G$  has a grid minor of size  $t \times t$ , where  $t = \Omega(\text{tw}(G)^\delta)$ .
  - ▶ Known for  $\delta = 1/10$ . Necessary:  $\delta \leq \frac{1}{2}$ .
  - ▶ (Håstad, 2017) Let  $S$  be the size of the shortest  $d$ -depth Frege proof of  $T(\boxplus_n, f)$ . Then  $S \geq 2^{n^{\Omega(1/d)}}$  for  $d \leq \frac{C \log n}{\log \log n}$
  - ▶ For resolution this method gives  $S(T(G, f)) \geq 2^{\text{tw}(G)^\delta}$ .
- ▶ Tree-like resolution
  - ▶  $S_T(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$  (size-width relation)
  - ▶  $S_T(T(G, f)) \leq 2^{\Omega(\text{tw}(G) \log |V|)}$  (Beame, Beck, Impagliazzo, 2013, I., Oparin, 2013)

## Constant degree graphs

- ▶ (Galesi et al. 2018)  $w(T(G, f)) = \Theta(\text{tw}(G))$  for  $O(1)$ -degree graphs.
- ▶ The inequality  $S(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$  is known for following  $O(1)$ -degree graphs:
  - ▶ (Size-width relation): graphs with large treewidth:  
 $\text{tw}(G) = \Omega(n)$
  - ▶ (Alekhovich, Razborov, 2011): graphs with bounded cyclicity
  - ▶ (xorification): graphs with doubled edges
- ▶ **Grid Minor Theorem** (Robertson, Seymour 1986), (Chuzhoy 2015): Every graph  $G$  has a grid minor of size  $t \times t$ , where  $t = \Omega(\text{tw}(G)^\delta)$ .
  - ▶ Known for  $\delta = 1/10$ . Necessary:  $\delta \leq \frac{1}{2}$ .
  - ▶ (Håstad, 2017) Let  $S$  be the size of the shortest  $d$ -depth Frege proof of  $T(\boxplus_n, f)$ . Then  $S \geq 2^{n^{\Omega(1/d)}}$  for  $d \leq \frac{C \log n}{\log \log n}$
  - ▶ For resolution this method gives  $S(T(G, f)) \geq 2^{\text{tw}(G)^\delta}$ .
- ▶ Tree-like resolution
  - ▶  $S_T(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$  (size-width relation)
  - ▶  $S_T(T(G, f)) \leq 2^{\Omega(\text{tw}(G) \log |V|)}$  (Beame, Beck, Impagliazzo, 2013, I., Oparin, 2013)

## Constant degree graphs

- ▶ (Galesi et al. 2018)  $w(T(G, f)) = \Theta(\text{tw}(G))$  for  $O(1)$ -degree graphs.
- ▶ The inequality  $S(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$  is known for following  $O(1)$ -degree graphs:
  - ▶ (Size-width relation): graphs with large treewidth:  
 $\text{tw}(G) = \Omega(n)$
  - ▶ (Alekhovich, Razborov, 2011): graphs with bounded cyclicity
  - ▶ (xorification): graphs with doubled edges
- ▶ **Grid Minor Theorem** (Robertson, Seymour 1986), (Chuzhoy 2015): Every graph  $G$  has a grid minor of size  $t \times t$ , where  $t = \Omega(\text{tw}(G)^\delta)$ .
  - ▶ Known for  $\delta = 1/10$ . Necessary:  $\delta \leq \frac{1}{2}$ .
  - ▶ (Håstad, 2017) Let  $S$  be the size of the shortest  $d$ -depth Frege proof of  $T(\boxplus_n, f)$ . Then  $S \geq 2^{n^{\Omega(1/d)}}$  for  $d \leq \frac{C \log n}{\log \log n}$
  - ▶ For resolution this method gives  $S(T(G, f)) \geq 2^{\text{tw}(G)^\delta}$ .
- ▶ Tree-like resolution
  - ▶  $S_T(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$  (size-width relation)
  - ▶  $S_T(T(G, f)) \leq 2^{\Omega(\text{tw}(G) \log |V|)}$  (Beame, Beck, Impagliazzo, 2013, I., Oparin, 2013)

## Constant degree graphs

- ▶ (Galesi et al. 2018)  $w(T(G, f)) = \Theta(\text{tw}(G))$  for  $O(1)$ -degree graphs.
- ▶ The inequality  $S(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$  is known for following  $O(1)$ -degree graphs:
  - ▶ (Size-width relation): graphs with large treewidth:  
 $\text{tw}(G) = \Omega(n)$
  - ▶ (Alekhovich, Razborov, 2011): graphs with bounded cyclicity
  - ▶ (xorification): graphs with doubled edges
- ▶ **Grid Minor Theorem** (Robertson, Seymour 1986), (Chuzhoy 2015): Every graph  $G$  has a grid minor of size  $t \times t$ , where  $t = \Omega(\text{tw}(G)^\delta)$ .
  - ▶ Known for  $\delta = 1/10$ . Necessary:  $\delta \leq \frac{1}{2}$ .
  - ▶ (Galesi et. al., 2019) Let  $S$  be the size of the shortest  $d$ -depth Frege proof of  $T(G, f)$ . Then  $S \geq 2^{\text{tw}(G)^{\Omega(1/d)}}$  for  $d \leq \frac{C \log n}{\log \log n}$ .
  - ▶ For resolution this method gives  $S(T(G, f)) \geq 2^{\text{tw}(G)^\delta}$ .
- ▶ Tree-like resolution
  - ▶  $S_T(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$  (size-width relation)
  - ▶  $S_T(T(G, f)) \leq 2^{\Omega(\text{tw}(G) \log |V|)}$  (Beame, Beck, Impagliazzo, 2013, I., Oparin, 2013)

## Constant degree graphs

- ▶ (Galesi et al. 2018)  $w(T(G, f)) = \Theta(\text{tw}(G))$  for  $O(1)$ -degree graphs.
- ▶ The inequality  $S(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$  is known for following  $O(1)$ -degree graphs:
  - ▶ (Size-width relation): graphs with large treewidth:  
 $\text{tw}(G) = \Omega(n)$
  - ▶ (Alekhovich, Razborov, 2011): graphs with bounded cyclicity
  - ▶ (xorification): graphs with doubled edges
- ▶ **Grid Minor Theorem** (Robertson, Seymour 1986), (Chuzhoy 2015): Every graph  $G$  has a grid minor of size  $t \times t$ , where  $t = \Omega(\text{tw}(G)^\delta)$ .
  - ▶ Known for  $\delta = 1/10$ . Necessary:  $\delta \leq \frac{1}{2}$ .
  - ▶ (Galesi et. al., 2019) Let  $S$  be the size of the shortest  $d$ -depth Frege proof of  $T(G, f)$ . Then  $S \geq 2^{\text{tw}(G)^{\Omega(1/d)}}$  for  $d \leq \frac{C \log n}{\log \log n}$ .
  - ▶ For resolution this method gives  $S(T(G, f)) \geq 2^{\text{tw}(G)^\delta}$ .
- ▶ Tree-like resolution
  - ▶  $S_T(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$  (size-width relation)
  - ▶  $S_T(T(G, f)) \leq 2^{\Omega(\text{tw}(G) \log |V|)}$  (Beame, Beck, Impagliazzo, 2013, I., Oparin, 2013)

## Constant degree graphs

- ▶ (Galesi et al. 2018)  $w(T(G, f)) = \Theta(\text{tw}(G))$  for  $O(1)$ -degree graphs.
- ▶ The inequality  $S(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$  is known for following  $O(1)$ -degree graphs:
  - ▶ (Size-width relation): graphs with large treewidth:  
 $\text{tw}(G) = \Omega(n)$
  - ▶ (Alekhovich, Razborov, 2011): graphs with bounded cyclicity
  - ▶ (xorification): graphs with doubled edges
- ▶ **Grid Minor Theorem** (Robertson, Seymour 1986), (Chuzhoy 2015): Every graph  $G$  has a grid minor of size  $t \times t$ , where  $t = \Omega(\text{tw}(G)^\delta)$ .
  - ▶ Known for  $\delta = 1/10$ . Necessary:  $\delta \leq \frac{1}{2}$ .
  - ▶ (Galesi et. al., 2019) Let  $S$  be the size of the shortest  $d$ -depth Frege proof of  $T(G, f)$ . Then  $S \geq 2^{\text{tw}(G)^{\Omega(1/d)}}$  for  $d \leq \frac{C \log n}{\log \log n}$ .
  - ▶ For resolution this method gives  $S(T(G, f)) \geq 2^{\text{tw}(G)^\delta}$ .
- ▶ Tree-like resolution
  - ▶  $S_T(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$  (size-width relation)
  - ▶  $S_T(T(G, f)) \leq 2^{\Omega(\text{tw}(G) \log |V|)}$  (Beame, Beck, Impagliazzo, 2013, I., Oparin, 2013)

## Our results

**Main theorem.**  $S_{reg}(T(G, f)) \geq 2^{\Omega(\text{tw}(G)/\log |V|)}$ .

### Plan of the proof

1. If  $S_{reg}(T(G, f)) = S$ , then there exists a 1-BP computing satisfiable Tseitin formula  $T(G, f')$  of size  $S^{O(\log |V|)}$ .  
If  $S_T(T(G, f)) = S$ , then there exists a 1-BP computing satisfiable Tseitin formula  $T(G, f')$  of size  $S$ .

2.  $1\text{-BP}(T(G, f')) \geq 2^{\Omega(\text{tw}(G))}$

from previous result (Laskin, 2014)

$2^{\Omega(\text{tw}(G)/\log |V|)} \geq 1\text{-BP}(T(G, f')) \geq 2^{\Omega(\text{tw}(G))}$ , where the last constant from Grid Minor Theorem.

**Example.** There exist  $O(1)$ -degree graphs  $G_n(V_n, E_n)$  such that  $1\text{-BP}(T(G_n, c)) \geq 2^{\Omega(\text{tw}(G_n) \log |V_n|)}$  and  $\text{tw}(G_n) = n^{\Omega(1)}$ .

- ▶  $S_T(T(G_n, c)) \geq 2^{\Omega(\text{tw}(G_n) \log |V_n|)}$ ,  $S_{reg}(T(G_n, c)) = 2^{\Theta(\text{tw}(G_n))}$ .

## Our results

**Main theorem.**  $S_{reg}(T(G, f)) \geq 2^{\Omega(\text{tw}(G)/\log|V|)}$ .

### Plan of the proof

1. If  $S_{reg}(T(G, f)) = S$ , then there exists a 1-BP computing **satisfiable** Tseitin formula  $T(G, f')$  of size  $S^{O(\log|V|)}$ .

▶ If  $S_T(T(G, f)) = S$ , then there exists a 1-BP computing satisfiable Tseitin formula  $T(G, f')$  of size  $S$ .

▶ Remark: it is not true for decision trees. Let  $P_n$  be a path with doubled edges. Then  $S_T(T(P_n, f)) = O(n^2)$  but any decision tree computing satisfiable  $T(P_n, f)$  has size at least  $2^n$ .

2.  $1\text{-BP}(T(G, f')) \geq 2^{\Omega(\text{tw}(G))}$

▶ Previous result: (Glinskih, I., 2019)

$2^{O(\text{tw}(G)\log|V|)} \geq 1\text{-BP}(T(G, f')) \geq 2^{\Omega(\text{tw}(G)^\delta)}$ , where  $\delta$  is a constant from Grid Minor Theorem.

**Example.** There exist  $O(1)$ -degree graphs  $G_n(V_n, E_n)$  such that  $1\text{-BP}(T(G_n, c)) \geq 2^{\Omega(\text{tw}(G_n)\log|V_n|)}$  and  $\text{tw}(G_n) = n^{\Omega(1)}$ .

▶  $S_T(T(G_n, c)) \geq 2^{\Omega(\text{tw}(G_n)\log|V_n|)}$ ,  $S_{reg}(T(G_n, c)) = 2^{\Theta(\text{tw}(G_n))}$ .

## Our results

**Main theorem.**  $S_{reg}(T(G, f)) \geq 2^{\Omega(\text{tw}(G)/\log|V|)}$ .

### Plan of the proof

1. If  $S_{reg}(T(G, f)) = S$ , then there exists a 1-BP computing **satisfiable** Tseitin formula  $T(G, f')$  of size  $S^{O(\log|V|)}$ .

▶ If  $S_T(T(G, f)) = S$ , then there exists a 1-BP computing satisfiable Tseitin formula  $T(G, f')$  of size  $S$ .

▶ Remark: it is not true for decision trees. Let  $P_n$  be a path with doubled edges. Then  $S_T(T(P_n, f)) = O(n^2)$  but any decision tree computing satisfiable  $T(P_n, f)$  has size at least  $2^n$ .

2.  $1\text{-BP}(T(G, f')) \geq 2^{\Omega(\text{tw}(G))}$

▶ Previous result: (Glinskih, I., 2019)

$2^{O(\text{tw}(G)\log|V|)} \geq 1\text{-BP}(T(G, f')) \geq 2^{\Omega(\text{tw}(G)^\delta)}$ , where  $\delta$  is a constant from Grid Minor Theorem.

**Example.** There exist  $O(1)$ -degree graphs  $G_n(V_n, E_n)$  such that  $1\text{-BP}(T(G_n, c)) \geq 2^{\Omega(\text{tw}(G_n)\log|V_n|)}$  and  $\text{tw}(G_n) = n^{\Omega(1)}$ .

▶  $S_T(T(G_n, c)) \geq 2^{\Omega(\text{tw}(G_n)\log|V_n|)}$ ,  $S_{reg}(T(G_n, c)) = 2^{\Theta(\text{tw}(G_n))}$ .

## Our results

**Main theorem.**  $S_{reg}(T(G, f)) \geq 2^{\Omega(\text{tw}(G)/\log|V|)}$ .

### Plan of the proof

1. If  $S_{reg}(T(G, f)) = S$ , then there exists a 1-BP computing **satisfiable** Tseitin formula  $T(G, f')$  of size  $S^{O(\log|V|)}$ .
  - ▶ If  $S_T(T(G, f)) = S$ , then there exists a 1-BP computing satisfiable Tseitin formula  $T(G, f')$  of size  $S$ .
    - ▶ Remark: it is not true for decision trees. Let  $P_n$  be a path with doubled edges. Then  $S_T(T(P_n, f)) = O(n^2)$  but any decision tree computing satisfiable  $T(P_n, f)$  has size at least  $2^n$ .
2.  $1\text{-BP}(T(G, f')) \geq 2^{\Omega(\text{tw}(G))}$ 
  - ▶ Previous result: (Glinskih, I., 2019)  
 $2^{O(\text{tw}(G)\log|V|)} \geq 1\text{-BP}(T(G, f')) \geq 2^{\Omega(\text{tw}(G)^\delta)}$ , where  $\delta$  is a constant from Grid Minor Theorem.

**Example.** There exist  $O(1)$ -degree graphs  $G_n(V_n, E_n)$  such that  $1\text{-BP}(T(G_n, c)) \geq 2^{\Omega(\text{tw}(G_n)\log|V_n|)}$  and  $\text{tw}(G_n) = n^{\Omega(1)}$ .

- ▶  $S_T(T(G_n, c)) \geq 2^{\Omega(\text{tw}(G_n)\log|V_n|)}$ ,  $S_{reg}(T(G_n, c)) = 2^{\Theta(\text{tw}(G_n))}$ .

## Our results

**Main theorem.**  $S_{reg}(T(G, f)) \geq 2^{\Omega(\text{tw}(G)/\log|V|)}$ .

### Plan of the proof

1. If  $S_{reg}(T(G, f)) = S$ , then there exists a 1-BP computing **satisfiable** Tseitin formula  $T(G, f')$  of size  $S^{O(\log|V|)}$ .
  - ▶ If  $S_T(T(G, f)) = S$ , then there exists a 1-BP computing satisfiable Tseitin formula  $T(G, f')$  of size  $S$ .
    - ▶ Remark: it is not true for decision trees. Let  $P_n$  be a path with doubled edges. Then  $S_T(T(P_n, f)) = O(n^2)$  but any decision tree computing satisfiable  $T(P_n, f)$  has size at least  $2^n$ .
2.  $1\text{-BP}(T(G, f')) \geq 2^{\Omega(\text{tw}(G))}$ 
  - ▶ Previous result: (Glinskih, I., 2019)  
 $2^{O(\text{tw}(G)\log|V|)} \geq 1\text{-BP}(T(G, f')) \geq 2^{\Omega(\text{tw}(G)^\delta)}$ , where  $\delta$  is a constant from Grid Minor Theorem.

**Example.** There exist  $O(1)$ -degree graphs  $G_n(V_n, E_n)$  such that  $1\text{-BP}(T(G_n, c)) \geq 2^{\Omega(\text{tw}(G_n)\log|V_n|)}$  and  $\text{tw}(G_n) = n^{\Omega(1)}$ .

- ▶  $S_T(T(G_n, c)) \geq 2^{\Omega(\text{tw}(G_n)\log|V_n|)}$ ,  $S_{reg}(T(G_n, c)) = 2^{\Theta(\text{tw}(G_n))}$ .

## Our results

**Main theorem.**  $S_{reg}(T(G, f)) \geq 2^{\Omega(\text{tw}(G)/\log|V|)}$ .

### Plan of the proof

1. If  $S_{reg}(T(G, f)) = S$ , then there exists a 1-BP computing **satisfiable** Tseitin formula  $T(G, f')$  of size  $S^{O(\log|V|)}$ .
  - ▶ If  $S_T(T(G, f)) = S$ , then there exists a 1-BP computing satisfiable Tseitin formula  $T(G, f')$  of size  $S$ .
    - ▶ Remark: it is not true for decision trees. Let  $P_n$  be a path with doubled edges. Then  $S_T(T(P_n, f)) = O(n^2)$  but any decision tree computing satisfiable  $T(P_n, f)$  has size at least  $2^n$ .
2.  $1\text{-BP}(T(G, f')) \geq 2^{\Omega(\text{tw}(G))}$ 
  - ▶ Previous result: (Glinskih, I., 2019)  
 $2^{O(\text{tw}(G)\log|V|)} \geq 1\text{-BP}(T(G, f')) \geq 2^{\Omega(\text{tw}(G)^\delta)}$ , where  $\delta$  is a constant from Grid Minor Theorem.

**Example.** There exist  $O(1)$ -degree graphs  $G_n(V_n, E_n)$  such that  $1\text{-BP}(T(G_n, c)) \geq 2^{\Omega(\text{tw}(G_n)\log|V_n|)}$  and  $\text{tw}(G_n) = n^{\Omega(1)}$ .

- ▶  $S_T(T(G_n, c)) \geq 2^{\Omega(\text{tw}(G_n)\log|V_n|)}$ ,  $S_{reg}(T(G_n, c)) = 2^{\Theta(\text{tw}(G_n))}$ .

## Our results

**Main theorem.**  $S_{reg}(T(G, f)) \geq 2^{\Omega(\text{tw}(G)/\log|V|)}$ .

### Plan of the proof

1. If  $S_{reg}(T(G, f)) = S$ , then there exists a 1-BP computing **satisfiable** Tseitin formula  $T(G, f')$  of size  $S^{O(\log|V|)}$ .
  - ▶ If  $S_T(T(G, f)) = S$ , then there exists a 1-BP computing satisfiable Tseitin formula  $T(G, f')$  of size  $S$ .
    - ▶ Remark: it is not true for decision trees. Let  $P_n$  be a path with doubled edges. Then  $S_T(T(P_n, f)) = O(n^2)$  but any decision tree computing satisfiable  $T(P_n, f)$  has size at least  $2^n$ .
2.  $1\text{-BP}(T(G, f')) \geq 2^{\Omega(\text{tw}(G))}$ 
  - ▶ Previous result: (Glinskih, I., 2019)  
 $2^{O(\text{tw}(G)\log|V|)} \geq 1\text{-BP}(T(G, f')) \geq 2^{\Omega(\text{tw}(G)^\delta)}$ , where  $\delta$  is a constant from Grid Minor Theorem.

**Example.** There exist  $O(1)$ -degree graphs  $G_n(V_n, E_n)$  such that  $1\text{-BP}(T(G_n, c)) \geq 2^{\Omega(\text{tw}(G_n)\log|V_n|)}$  and  $\text{tw}(G_n) = n^{\Omega(1)}$ .

- ▶  $S_T(T(G_n, c)) \geq 2^{\Omega(\text{tw}(G_n)\log|V_n|)}$ ,  $S_{reg}(T(G_n, c)) = 2^{\Theta(\text{tw}(G_n))}$ .

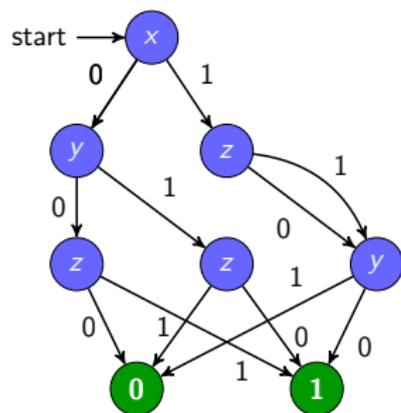
# Our results

**Main theorem.**  $S_{reg}(T(G, f)) \geq 2^{\Omega(\text{tw}(G)/\log |V|)}$ .

Plan of the proof

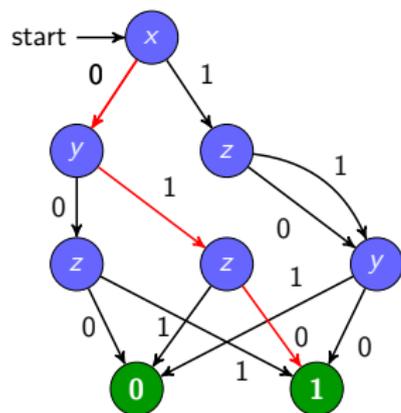
1. If  $S_{reg}(T(G, f)) = S$ , then there exists a 1-BP computing satisfiable Tseitin formula  $T(G, f')$  of size  $S^{O(\log |V|)}$ .
2.  $1\text{-BP}(T(G, f')) \geq 2^{\Omega(\text{tw}(G))}$

# 1-BP



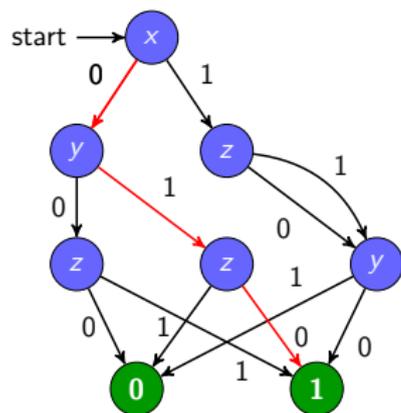
- ▶  $f : \{0, 1\}^n \rightarrow X$  is represented by a DAG with the unique source.
- ▶ Sinks are labeled with distinct elements of  $X$ . Each non-sink node is labeled with a variable and has two outgoing edges: 0-edge and 1-edge.
- ▶ Given an assignment  $\xi$  a branching program returns the label of the sink at the end of the path corresponding to  $\xi$ .
- ▶ Read-once branching program (1-BP): in every path every variable appears at most once.
- ▶ In 1-BP:  $u \xrightarrow{a} v$ , and  $u$  is labeled with  $x$ . If  $u$  computes  $f_u$  and  $v$  computes  $f_v$ , then  $f_v = f_u|_{x=a}$ .

# 1-BP



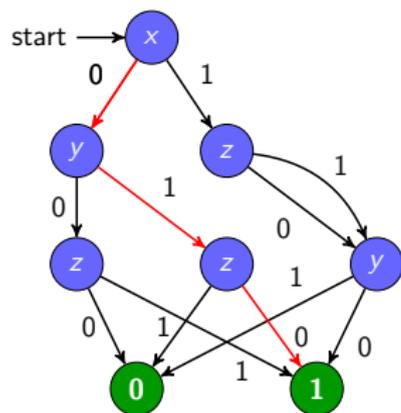
- ▶  $f : \{0, 1\}^n \rightarrow X$  is represented by a DAG with the unique source.
  - ▶ Sinks are labeled with distinct elements of  $X$ . Each non-sink node is labeled with a variable and has two outgoing edges: 0-edge and 1-edge.
  - ▶ Given an assignment  $\xi$  a branching program returns the label of the sink at the end of the path corresponding to  $\xi$ .
- 
- ▶ Read-once branching program (1-BP): in every path every variable appears at most once.
  - ▶ In 1-BP:  $u \xrightarrow{a} v$ , and  $u$  is labeled with  $x$ . If  $u$  computes  $f_u$  and  $v$  computes  $f_v$ , then  $f_v = f_u|_{x=a}$ .

# 1-BP



- ▶  $f : \{0, 1\}^n \rightarrow X$  is represented by a DAG with the unique source.
- ▶ Sinks are labeled with distinct elements of  $X$ . Each non-sink node is labeled with a variable and has two outgoing edges: 0-edge and 1-edge.
- ▶ Given an assignment  $\xi$  a branching program returns the label of the sink at the end of the path corresponding to  $\xi$ .
- ▶ Read-once branching program (1-BP): in every path every variable appears at most once.
- ▶ In 1-BP:  $u \xrightarrow{a} v$ , and  $u$  is labeled with  $x$ . If  $u$  computes  $f_u$  and  $v$  computes  $f_v$ , then  $f_v = f_u|_{x=a}$ .

# 1-BP



- ▶  $f : \{0, 1\}^n \rightarrow X$  is represented by a DAG with the unique source.
- ▶ Sinks are labeled with distinct elements of  $X$ . Each non-sink node is labeled with a variable and has two outgoing edges: 0-edge and 1-edge.
- ▶ Given an assignment  $\xi$  a branching program returns the label of the sink at the end of the path corresponding to  $\xi$ .
- ▶ Read-once branching program (1-BP): in every path every variable appears at most once.
- ▶ In 1-BP:  $u \xrightarrow{a} v$ , and  $u$  is labeled with  $x$ . If  $u$  computes  $f_u$  and  $v$  computes  $f_v$ , then  $f_v = f_u|_{x=a}$ .

# SearchVertex

- ▶  $\text{Search}_\phi$ : Let  $\phi$  be an unsatisfiable CNF. Given an assignment  $\sigma$ , find a **clause of  $\phi$**  falsified by  $\sigma$ .
- ▶ **Theorem (folklore)**.  $\phi$  has a regular resolution refutation of size  $S$  iff there exists a 1-BP of size  $S$  computing  $\text{Search}_\phi$ .
- ▶ For an **unsatisfiable** formula  $T(G, f)$ :
  - ▶  $\text{Search}_{T(G, f)}$ : given an assignment, find a falsified **clause of  $T(G, f)$** .
  - ▶  $\text{SearchVertex}(G, f)$ : given an assignment, find a **vertex of  $G$**  with violated parity condition.
- ▶ **Simple observation**  
 $1\text{-BP}(\text{Search}_{T(G, f)}) \geq 1\text{-BP}(\text{SearchVertex}(G, f))$ .
- ▶ We are going to prove that  
 $1\text{-BP}(T(G, f')) \leq 1\text{-BP}(\text{SearchVertex}(G, f))^{\mathcal{O}(\log |V|)}$ .

# SearchVertex

- ▶  $\text{Search}_\phi$ : Let  $\phi$  be an unsatisfiable CNF. Given an assignment  $\sigma$ , find a **clause of  $\phi$**  falsified by  $\sigma$ .
- ▶ **Theorem (folklore)**.  $\phi$  has a regular resolution refutation of size  $S$  iff there exists a 1-BP of size  $S$  computing  $\text{Search}_\phi$ .
- ▶ For an **unsatisfiable** formula  $T(G, f)$ :
  - ▶  $\text{Search}_{T(G, f)}$ : given an assignment, find a falsified **clause of  $T(G, f)$** .
  - ▶  $\text{SearchVertex}(G, f)$ : given an assignment, find a **vertex of  $G$**  with violated parity condition.
- ▶ **Simple observation**  
 $1\text{-BP}(\text{Search}_{T(G, f)}) \geq 1\text{-BP}(\text{SearchVertex}(G, f))$ .
- ▶ We are going to prove that  
 $1\text{-BP}(T(G, f')) \leq 1\text{-BP}(\text{SearchVertex}(G, f))^{\mathcal{O}(\log |V|)}$ .

# SearchVertex

- ▶  $\text{Search}_\phi$ : Let  $\phi$  be an unsatisfiable CNF. Given an assignment  $\sigma$ , find a **clause of  $\phi$**  falsified by  $\sigma$ .
- ▶ **Theorem (folklore)**.  $\phi$  has a regular resolution refutation of size  $S$  iff there exists a 1-BP of size  $S$  computing  $\text{Search}_\phi$ .
- ▶ For an **unsatisfiable** formula  $T(G, f)$ :
  - ▶  $\text{Search}_{T(G, f)}$ : given an assignment, find a falsified **clause of  $T(G, f)$** .
  - ▶  $\text{SearchVertex}(G, f)$ : given an assignment, find a **vertex of  $G$**  with violated parity condition.
- ▶ **Simple observation**  
 $1\text{-BP}(\text{Search}_{T(G, f)}) \geq 1\text{-BP}(\text{SearchVertex}(G, f))$ .
- ▶ We are going to prove that  
 $1\text{-BP}(T(G, f')) \leq 1\text{-BP}(\text{SearchVertex}(G, f))^{\mathcal{O}(\log |V|)}$ .

# SearchVertex

- ▶  $\text{Search}_\phi$ : Let  $\phi$  be an unsatisfiable CNF. Given an assignment  $\sigma$ , find a **clause of  $\phi$**  falsified by  $\sigma$ .
- ▶ **Theorem (folklore)**.  $\phi$  has a regular resolution refutation of size  $S$  iff there exists a 1-BP of size  $S$  computing  $\text{Search}_\phi$ .
- ▶ For an **unsatisfiable** formula  $T(G, f)$ :
  - ▶  $\text{Search}_{T(G, f)}$ : given an assignment, find a falsified **clause of  $T(G, f)$** .
  - ▶  $\text{SearchVertex}(G, f)$ : given an assignment, find a **vertex of  $G$**  with violated parity condition.
- ▶ **Simple observation**  
 $1\text{-BP}(\text{Search}_{T(G, f)}) \geq 1\text{-BP}(\text{SearchVertex}(G, f))$ .
- ▶ We are going to prove that  
 $1\text{-BP}(T(G, f')) \leq 1\text{-BP}(\text{SearchVertex}(G, f))^{O(\log |V|)}$ .

# SearchVertex

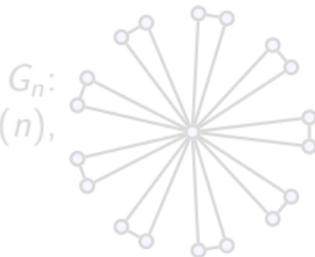
- ▶  $\text{Search}_\phi$ : Let  $\phi$  be an unsatisfiable CNF. Given an assignment  $\sigma$ , find a **clause of  $\phi$**  falsified by  $\sigma$ .
- ▶ **Theorem (folklore)**.  $\phi$  has a regular resolution refutation of size  $S$  iff there exists a 1-BP of size  $S$  computing  $\text{Search}_\phi$ .
- ▶ For an **unsatisfiable** formula  $T(G, f)$ :
  - ▶  $\text{Search}_{T(G, f)}$ : given an assignment, find a falsified **clause of  $T(G, f)$** .
  - ▶  $\text{SearchVertex}(G, f)$ : given an assignment, find a **vertex of  $G$**  with violated parity condition.
- ▶ **Simple observation**  
 $1\text{-BP}(\text{Search}_{T(G, f)}) \geq 1\text{-BP}(\text{SearchVertex}(G, f))$ .
- ▶ We are going to prove that  
 $1\text{-BP}(T(G, f')) \leq 1\text{-BP}(\text{SearchVertex}(G, f))^{\mathcal{O}(\log |V|)}$ .

## SearchVertex( $G, f$ ) vs Search $_T(G, f)$

- ▶ SearchVertex( $G, f$ ) and Search $_T(G, f)$  are equivalent for decision trees.
- ▶ For 1-BP:

**Unrestricted degrees.**

1. 1-BP(SearchVertex( $G_n, f$ )) =  $O(n)$ , while Search $_T(G_n, f) = 2^{\Omega(n)}$ .



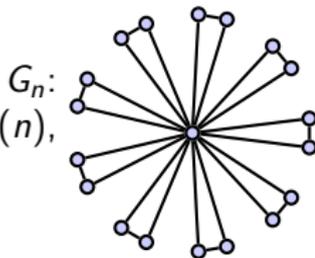
2. **Logarithmic degrees.**  $K_{\log n}$ :  
1-BP(SearchVertex( $K_{\log n}, f$ )) =  $O(n)$ , while  
1-BP(Search $_T(K_{\log n}, f)$ ) =  $2^{\Omega(\log^2 n)}$  by size-width relation.
3. **Constant degrees.** We conjecture that for  $O(1)$ -degree graphs two problems are polynomially equivalent. But this conjecture implies stronger inequality  
 $S_{reg}(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$ .
  - ▶ Xorification:  $S(\phi^\oplus) \geq 2^{\Omega(w(\phi))}$ .
  - ▶ For Tseitin formulas xorification = doubling of edges.
  - ▶ It improves bound on Search $_T(G_n, f)^\oplus$  but 1-BP for SearchVertex increases in at most a constant.

## SearchVertex( $G, f$ ) vs Search $_T(G, f)$

- ▶ SearchVertex( $G, f$ ) and Search $_T(G, f)$  are equivalent for decision trees.
- ▶ For 1-BP:

### Unrestricted degrees.

1. 1-BP(SearchVertex( $G_n, f$ )) =  $O(n)$ , while Search $_T(G_n, f) = 2^{\Omega(n)}$ .



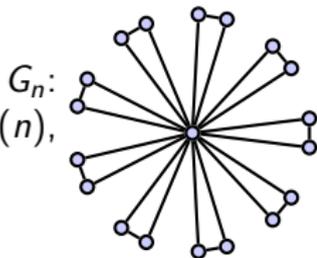
2. **Logarithmic degrees.**  $K_{\log n}$ :  
1-BP(SearchVertex( $K_{\log n}, f$ )) =  $O(n)$ , while  
1-BP(Search $_T(K_{\log n}, f)$ ) =  $2^{\Omega(\log^2 n)}$  by size-width relation.
3. **Constant degrees.** We conjecture that for  $O(1)$ -degree graphs two problems are polynomially equivalent. But this conjecture implies stronger inequality  
 $S_{reg}(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$ .
  - ▶ Xorification:  $S(\phi^\oplus) \geq 2^{\Omega(w(\phi))}$ .
  - ▶ For Tseitin formulas xorification = doubling of edges.
  - ▶ It improves bound on Search $_T(G_n, f)^\oplus$  but 1-BP for SearchVertex increases in at most a constant.

## SearchVertex( $G, f$ ) vs Search $_T(G, f)$

- ▶ SearchVertex( $G, f$ ) and Search $_T(G, f)$  are equivalent for decision trees.
- ▶ For 1-BP:

### Unrestricted degrees.

1. 1-BP(SearchVertex( $G_n, f$ )) =  $O(n)$ , while Search $_T(G_n, f) = 2^{\Omega(n)}$ .



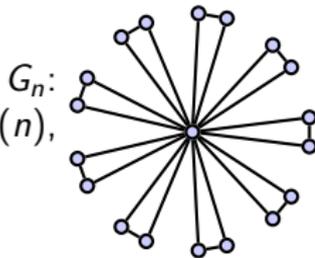
2. **Logarithmic degrees.**  $K_{\log n}$ :  
1-BP(SearchVertex( $K_{\log n}, f$ )) =  $O(n)$ , while  
1-BP(Search $_T(K_{\log n}, f)$ ) =  $2^{\Omega(\log^2 n)}$  by size-width relation.
3. **Constant degrees.** We conjecture that for  $O(1)$ -degree graphs two problems are polynomially equivalent. But this conjecture implies stronger inequality  
 $S_{reg}(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$ .
  - ▶ Xorification:  $S(\phi^\oplus) \geq 2^{\Omega(w(\phi))}$ .
  - ▶ For Tseitin formulas xorification = doubling of edges.
  - ▶ It improves bound on Search $_T(G_n, f)^\oplus$  but 1-BP for SearchVertex increases in at most a constant.

## SearchVertex( $G, f$ ) vs Search $_T(G, f)$

- ▶ SearchVertex( $G, f$ ) and Search $_T(G, f)$  are equivalent for decision trees.
- ▶ For 1-BP:

### Unrestricted degrees.

1. 1-BP(SearchVertex( $G_n, f$ )) =  $O(n)$ ,  
while Search $_T(G_n, f) = 2^{\Omega(n)}$ .



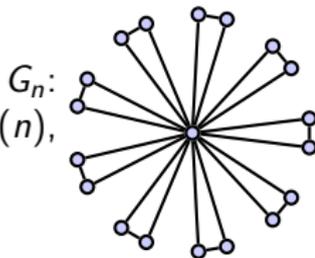
2. **Logarithmic degrees.**  $K_{\log n}$ :  
1-BP(SearchVertex( $K_{\log n}, f$ )) =  $O(n)$ , while  
1-BP(Search $_T(K_{\log n}, f)$ ) =  $2^{\Omega(\log^2 n)}$  by size-width relation.
3. **Constant degrees.** We conjecture that for  $O(1)$ -degree graphs two problems are polynomially equivalent. But this conjecture implies stronger inequality  
 $S_{reg}(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$ .
  - ▶ Xorification:  $S(\phi^\oplus) \geq 2^{\Omega(w(\phi))}$ .
  - ▶ For Tseitin formulas xorification = doubling of edges.
  - ▶ It improves bound on Search $_T(G_n, f)^\oplus$  but 1-BP for SearchVertex increases in at most a constant.

## SearchVertex( $G, f$ ) vs Search $_T(G, f)$

- ▶ SearchVertex( $G, f$ ) and Search $_T(G, f)$  are equivalent for decision trees.
- ▶ For 1-BP:

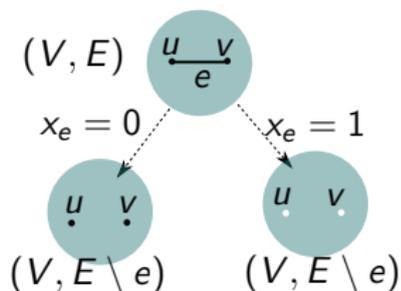
### Unrestricted degrees.

1. 1-BP(SearchVertex( $G_n, f$ )) =  $O(n)$ , while Search $_T(G_n, f) = 2^{\Omega(n)}$ .

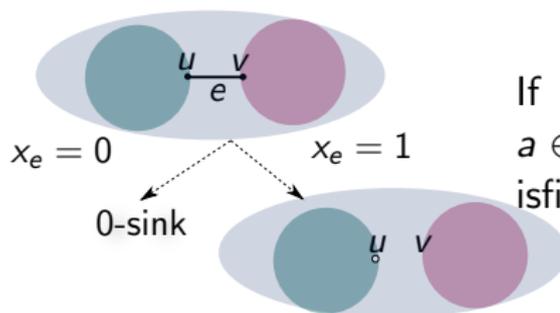


2. **Logarithmic degrees.**  $K_{\log n}$ :  
1-BP(SearchVertex( $K_{\log n}, f$ )) =  $O(n)$ , while  
1-BP(Search $_T(K_{\log n}, f)$ ) =  $2^{\Omega(\log^2 n)}$  by size-width relation.
3. **Constant degrees.** We conjecture that for  $O(1)$ -degree graphs two problems are polynomially equivalent. But this conjecture implies stronger inequality  
 $S_{reg}(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$ .
  - ▶ Xorification:  $S(\phi^\oplus) \geq 2^{\Omega(w(\phi))}$ .
  - ▶ For Tseitin formulas xorification = doubling of edges.
  - ▶ It improves bound on Search $_T(G_n, f)^\oplus$  but 1-BP for SearchVertex increases in at most a constant.

# Structure of a 1-BP computing a satisfiable $\mathbb{T}(G, f)$

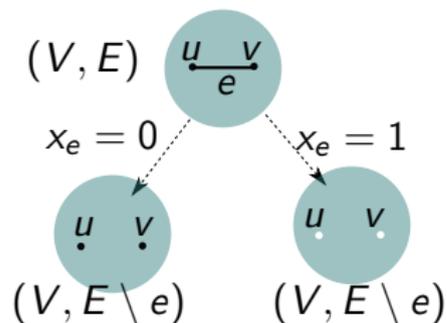


$$\mathbb{T}(H, f)|_{x_e=a} = \mathbb{T}(H - e, f + a(\mathbf{1}_u + \mathbf{1}_v)), \text{ where } e = (u, v).$$

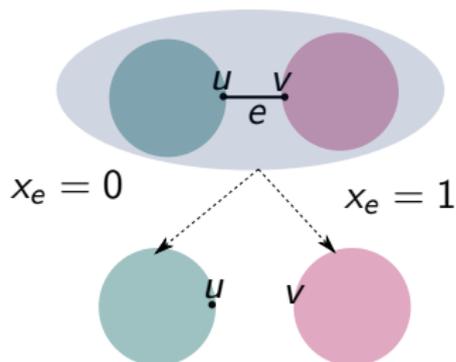


If  $e$  is a bridge, then for some  $a \in \{0, 1\}$ ,  $\mathbb{T}(H, f)|_{x_e=a}$  is unsatisfiable.

## Structure of a 1-BP computing SearchVertex

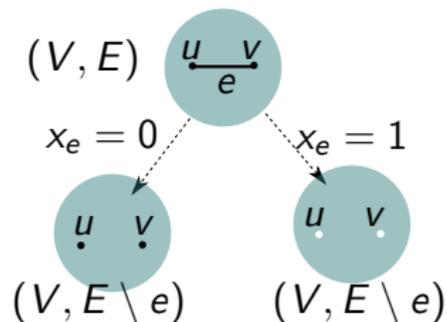


- ▶ Let  $D$  be a minimum-size 1-BP computing  $\text{SearchVertex}(G, f)$ . Let  $s$  be a node of  $D$  computing  $\text{SearchVertex}(H, g)$  labeled by  $X_e$ . Then the children of  $s$  compute  $\text{SearchVertex}(H - e, g_0)$  and  $\text{SearchVertex}(H - e, g_1)$ .

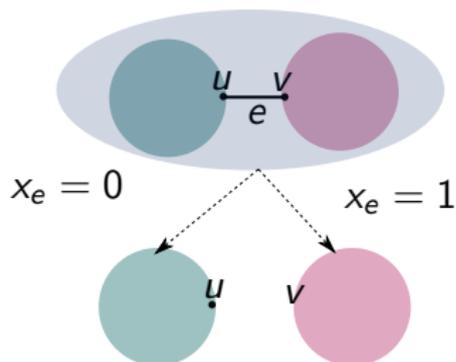


- ▶ **Structural lemma.** If  $e$  is a bridge of  $H$  and  $H - e = C_1 \sqcup C_2$  for two connected components  $C_1$  and  $C_2$ , then the children of  $s$  compute  $\text{SearchVertex}(C_1, g_0)$  and  $\text{SearchVertex}(C_2, g_1)$ .

## Structure of a 1-BP computing SearchVertex



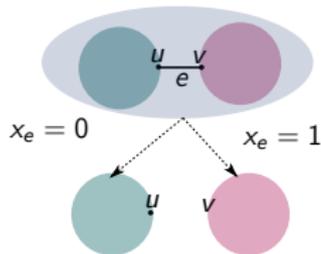
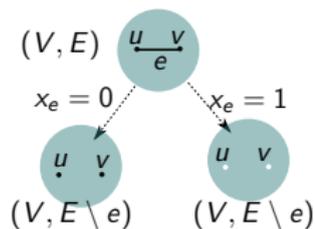
- ▶ Let  $D$  be a minimum-size 1-BP computing  $\text{SearchVertex}(G, f)$ . Let  $s$  be a node of  $D$  computing  $\text{SearchVertex}(H, g)$  labeled by  $X_e$ . Then the children of  $s$  compute  $\text{SearchVertex}(H - e, g_0)$  and  $\text{SearchVertex}(H - e, g_1)$ .



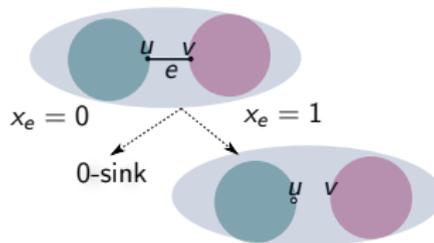
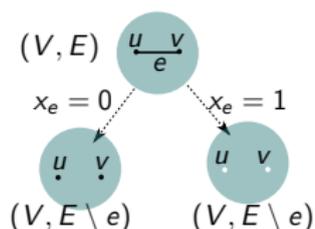
- ▶ **Structural lemma.** If  $e$  is a bridge of  $H$  and  $H - e = C_1 \sqcup C_2$  for **two connected components**  $C_1$  and  $C_2$ , then the children of  $s$  compute  $\text{SearchVertex}(C_1, g_0)$  and  $\text{SearchVertex}(C_2, g_1)$ .

# Transformation

SearchVertex( $G, f$ )



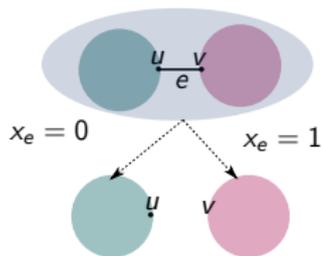
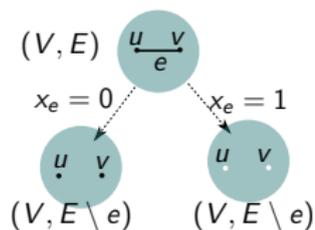
$T(G, f')$



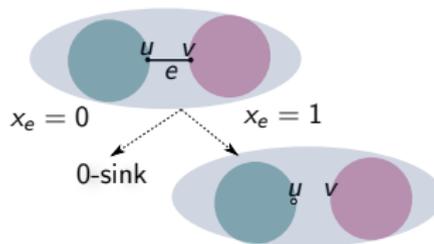
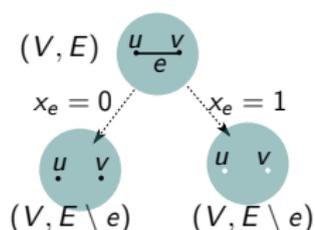
Let  $D$  be a 1-BP computing SearchVertex( $G, f$ ). By induction (from sinks) for every node  $s \in D$  computing SearchVertex( $H, c$ ) and every  $w \in V(H)$ , we construct a node  $s \setminus w$  computing  $T(H, c + \mathbf{1}_w)$ .

# Transformation

SearchVertex( $G, f$ )

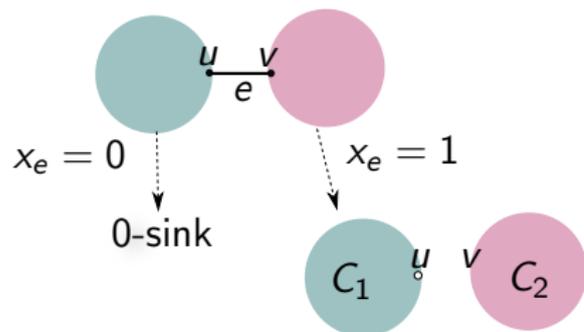


$T(G, f')$

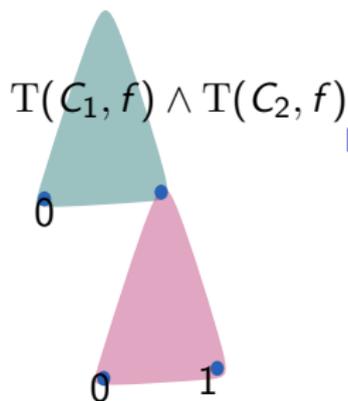
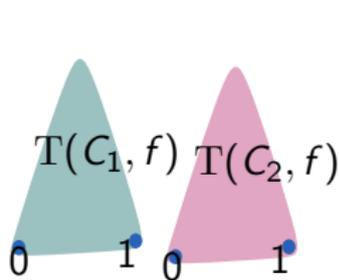


Let  $D$  be a 1-BP computing SearchVertex( $G, f$ ). By induction (from sinks) for every node  $s \in D$  computing SearchVertex( $H, c$ ) and every  $w \in V(H)$ , we construct a node  $s$  computing  $T(H, c + \mathbf{1}_w)$ .

# Transformation



$$T(C_1 \cup C_2, f) = T(C_1, f) \wedge T(C_2, f)$$



- ▶ Nontrivial case:  $e$  is a bridge.
- ▶ By induction hypothesis we have node  $s_1$  computing  $T(C_1, f)$  and  $s_2$  computing  $T(C_2, f)$  but we need a node computing  $T(C_1 \cup C_2, f) = T(C_1, f) \wedge T(C_2, f)$ .
- ▶ Make a copy of subprogram of  $s_1$  where all edges to 1-sink redirected to  $s_2$ .
- ▶ The necessity to copy one of the subdiagrams results in a quasipolynomial  $(S \mapsto S^{O(\log |V|)})$  blowup.

# Our results

**Main theorem.**  $S_{reg}(T(G, f)) \geq 2^{\Omega(\text{tw}(G)/\log|V|)}$ .

## Plan of the proof

1. If  $S_{reg}(T(G, f)) = S$ , then there exists a 1-BP computing satisfiable Tseitin formula  $T(G, f')$  of size  $S^{O(\log|V|)}$ .
2.  $1\text{-BP}(T(G, f')) \geq 2^{\Omega(\text{tw}(G))}$ 
  - ▶ Minimal 1-BP for  $(T(G, f))$  is OBDD (in every path variables appear in the same order).
  - ▶  $\text{OBDD}(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$ .

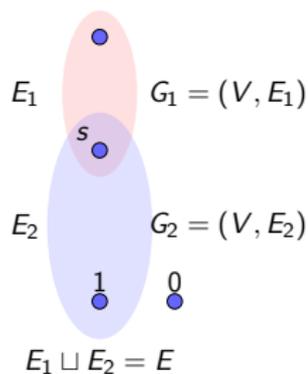
# Our results

**Main theorem.**  $S_{reg}(T(G, f)) \geq 2^{\Omega(\text{tw}(G)/\log|V|)}$ .

## Plan of the proof

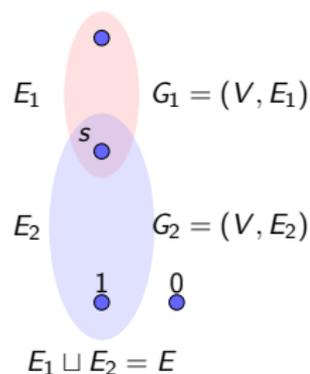
1. If  $S_{reg}(T(G, f)) = S$ , then there exists a 1-BP computing satisfiable Tseitin formula  $T(G, f')$  of size  $S^{O(\log|V|)}$ .
2.  $1\text{-BP}(T(G, f')) \geq 2^{\Omega(\text{tw}(G))}$ 
  - ▶ Minimal 1-BP for  $(T(G, f))$  is OBDD (in every path variables appear in the same order).
  - ▶  $\text{OBDD}(T(G, f)) \geq 2^{\Omega(\text{tw}(G))}$ .

## Number of acc. paths passing a node of 1-BP



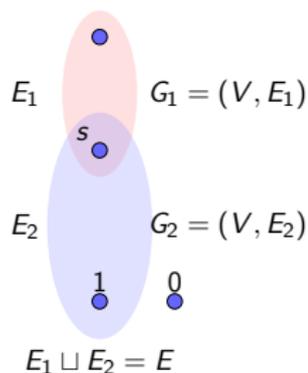
- ▶ Let  $s$  computes  $T(G_2, c_2)$ , where  $G_2 = (V, E_2)$ . Hence, there are exactly  $\#T(G_2, c_2)$  paths from  $s$  to 1-sink.
  - ▶ Every path from the source to  $s$  is a sat. assignment of  $T(G_1, c_1)$ , where  $G_1 = (V, E_1)$ . Hence, there are at most  $\#T(G_1, c_1)$  paths from the source to  $s$ .
  - ▶ In minimal OBDD all paths starts with  $E_1$ , hence all sat. assignments of  $T(G_1, c_1)$  can be realized. Hence there are exactly  $\#T(G_1, c_1)$  paths from the source to  $s$ .
- ▶ In 1-BP: at most  $\#T(G_1, c_1) \times \#T(G_2, c_2)$  accepting passing  $s$ .
  - ▶ In minimal OBDD: exactly  $\#T(G_1, c_1) \times \#T(G_2, c_2)$  accepting paths passing  $s$ .

## Number of acc. paths passing a node of 1-BP



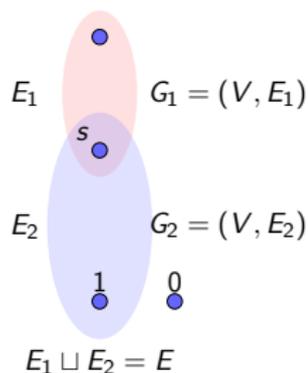
- ▶ Let  $s$  compute  $T(G_2, c_2)$ , where  $G_2 = (V, E_2)$ . Hence, there are exactly  $\#T(G_2, c_2)$  paths from  $s$  to 1-sink.
  - ▶ Every path from the source to  $s$  is a sat. assignment of  $T(G_1, c_1)$ , where  $G_1 = (V, E_1)$ . Hence, there are at most  $\#T(G_1, c_1)$  paths from the source to  $s$ .
  - ▶ In minimal OBDD all paths start with  $E_1$ , hence all sat. assignments of  $T(G_1, c_1)$  can be realized. Hence there are exactly  $\#T(G_1, c_1)$  paths from the source to  $s$ .
- ▶ In 1-BP: at most  $\#T(G_1, c_1) \times \#T(G_2, c_2)$  accepting paths passing  $s$ .
  - ▶ In minimal OBDD: exactly  $\#T(G_1, c_1) \times \#T(G_2, c_2)$  accepting paths passing  $s$ .

## Number of acc. paths passing a node of 1-BP



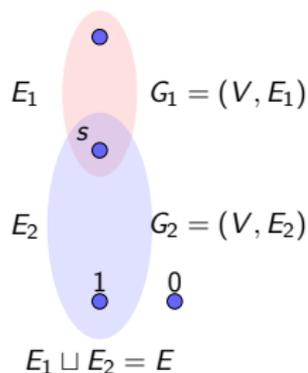
- ▶ Let  $s$  compute  $T(G_2, c_2)$ , where  $G_2 = (V, E_2)$ . Hence, there are exactly  $\#T(G_2, c_2)$  paths from  $s$  to 1-sink.
  - ▶ Every path from the source to  $s$  is a sat. assignment of  $T(G_1, c_1)$ , where  $G_1 = (V, E_1)$ . Hence, there are at most  $\#T(G_1, c_1)$  paths from the source to  $s$ .
  - ▶ In minimal OBDD all paths start with  $E_1$ , hence all sat. assignments of  $T(G_1, c_1)$  can be realized. Hence there are exactly  $\#T(G_1, c_1)$  paths from the source to  $s$ .
- ▶ In 1-BP: at most  $\#T(G_1, c_1) \times \#T(G_2, c_2)$  accepting paths passing  $s$ .
- ▶ In minimal OBDD: exactly  $\#T(G_1, c_1) \times \#T(G_2, c_2)$  accepting paths passing  $s$ .

## Number of acc. paths passing a node of 1-BP



- ▶ Let  $s$  compute  $T(G_2, c_2)$ , where  $G_2 = (V, E_2)$ . Hence, there are exactly  $\#T(G_2, c_2)$  paths from  $s$  to 1-sink.
- ▶ Every path from the source to  $s$  is a sat. assignment of  $T(G_1, c_1)$ , where  $G_1 = (V, E_1)$ . Hence, there are at most  $\#T(G_1, c_1)$  paths from the source to  $s$ .
- ▶ In minimal OBDD all paths start with  $E_1$ , hence all sat. assignments of  $T(G_1, c_1)$  can be realized. Hence there are exactly  $\#T(G_1, c_1)$  paths from the source to  $s$ .
- ▶ In 1-BP: at most  $\#T(G_1, c_1) \times \#T(G_2, c_2)$  accepting paths passing  $s$ .
- ▶ In minimal OBDD: exactly  $\#T(G_1, c_1) \times \#T(G_2, c_2)$  accepting paths passing  $s$ .

## Number of acc. paths passing a node of 1-BP



- ▶ Let  $s$  compute  $T(G_2, c_2)$ , where  $G_2 = (V, E_2)$ . Hence, there are exactly  $\#T(G_2, c_2)$  paths from  $s$  to 1-sink.
  - ▶ Every path from the source to  $s$  is a sat. assignment of  $T(G_1, c_1)$ , where  $G_1 = (V, E_1)$ . Hence, there are at most  $\#T(G_1, c_1)$  paths from the source to  $s$ .
  - ▶ In minimal OBDD all paths start with  $E_1$ , hence all sat. assignments of  $T(G_1, c_1)$  can be realized. Hence there are exactly  $\#T(G_1, c_1)$  paths from the source to  $s$ .
- ▶ In 1-BP: at most  $\#T(G_1, c_1) \times \#T(G_2, c_2)$  accepting paths passing  $s$ .
  - ▶ In minimal OBDD: exactly  $\#T(G_1, c_1) \times \#T(G_2, c_2)$  accepting paths passing  $s$ .

# Optimal 1-BP computing a Tseitin formula is OBDD

**Theorem.**  $1\text{-BP}(T(G, c)) \geq \text{OBDD}(T(G, c))$ .

- ▶ Let  $D$  be a minimal 1-BP computing  $T(G, c)$ .
- ▶ Let  $a_s$  be the number of accepting paths passing  $s$ .
- ▶ For an accepting path  $p$  we denote by  $\gamma(p) = \sum_{s \in p} \frac{1}{a_s}$ .
- ▶ Let  $\mathcal{P}$  be the set of accepting paths in  $D$ ;  $|\mathcal{P}| = \#T(G, c)$ .
- ▶  $|D| - 1 = \sum_{p \in \mathcal{P}} \gamma(p) \geq |\mathcal{P}| \min_{p \in \mathcal{P}} \gamma(p) = |\mathcal{P}| \gamma(p^*)$ .
- ▶ Let  $D'$  be a minimal OBDD for  $T(G, c)$  in order corresponding  $p^*$ .
- ▶ For  $D'$  we define  $a'_s$  and  $\gamma'(p)$ .  $a'_s$  depends only on the distance from the source. Hence,  $\gamma'(p)$  does not depend on accepting path. We know that  $\gamma(p^*) \geq \gamma'(p^*)$ .
- ▶  $|D| - 1 \geq |\mathcal{P}| \gamma(p^*) = \#T(G, c) \gamma(p^*) \geq \#T(G, c) \gamma'(p^*) = |D'| - 1$ .

# Optimal 1-BP computing a Tseitin formula is OBDD

**Theorem.**  $1\text{-BP}(T(G, c)) \geq \text{OBDD}(T(G, c))$ .

- ▶ Let  $D$  be a minimal 1-BP computing  $T(G, c)$ .
- ▶ Let  $a_s$  be the number of accepting paths passing  $s$ .
- ▶ For an accepting path  $p$  we denote by  $\gamma(p) = \sum_{s \in p} \frac{1}{a_s}$ .
- ▶ Let  $\mathcal{P}$  be the set of accepting paths in  $D$ ;  $|\mathcal{P}| = \#T(G, c)$ .
- ▶  $|D| - 1 = \sum_{p \in \mathcal{P}} \gamma(p) \geq |\mathcal{P}| \min_{p \in \mathcal{P}} \gamma(p) = |\mathcal{P}| \gamma(p^*)$ .
- ▶ Let  $D'$  be a minimal OBDD for  $T(G, c)$  in order corresponding  $p^*$ .
- ▶ For  $D'$  we define  $a'_s$  and  $\gamma'(p)$ .  $a'_s$  depends only on the distance from the source. Hence,  $\gamma'(p)$  does not depend on accepting path. We know that  $\gamma(p^*) \geq \gamma'(p^*)$ .
- ▶  $|D| - 1 \geq |\mathcal{P}| \gamma(p^*) = \#T(G, c) \gamma(p^*) \geq \#T(G, c) \gamma'(p^*) = |D'| - 1$ .

# Optimal 1-BP computing a Tseitin formula is OBDD

**Theorem.**  $1\text{-BP}(T(G, c)) \geq \text{OBDD}(T(G, c))$ .

- ▶ Let  $D$  be a minimal 1-BP computing  $T(G, c)$ .
- ▶ Let  $a_s$  be the number of accepting paths passing  $s$ .
- ▶ For an accepting path  $p$  we denote by  $\gamma(p) = \sum_{s \in p} \frac{1}{a_s}$ .
- ▶ Let  $\mathcal{P}$  be the set of accepting paths in  $D$ ;  $|\mathcal{P}| = \#T(G, c)$ .
- ▶  $|D| - 1 = \sum_{p \in \mathcal{P}} \gamma(p) \geq |\mathcal{P}| \min_{p \in \mathcal{P}} \gamma(p) = |\mathcal{P}| \gamma(p^*)$ .
- ▶ Let  $D'$  be a minimal OBDD for  $T(G, c)$  in order corresponding  $p^*$ .
- ▶ For  $D'$  we define  $a'_s$  and  $\gamma'(p)$ .  $a'_s$  depends only on the distance from the source. Hence,  $\gamma'(p)$  does not depend on accepting path. We know that  $\gamma(p^*) \geq \gamma'(p^*)$ .
- ▶  $|D| - 1 \geq |\mathcal{P}| \gamma(p^*) = \#T(G, c) \gamma(p^*) \geq \#T(G, c) \gamma'(p^*) = |D'| - 1$ .

# Optimal 1-BP computing a Tseitin formula is OBDD

**Theorem.**  $1\text{-BP}(T(G, c)) \geq \text{OBDD}(T(G, c))$ .

- ▶ Let  $D$  be a minimal 1-BP computing  $T(G, c)$ .
- ▶ Let  $a_s$  be the number of accepting paths passing  $s$ .
- ▶ For an accepting path  $p$  we denote by  $\gamma(p) = \sum_{s \in p} \frac{1}{a_s}$ .
- ▶ Let  $\mathcal{P}$  be the set of accepting paths in  $D$ ;  $|\mathcal{P}| = \#T(G, c)$ .
- ▶  $|D| - 1 = \sum_{p \in \mathcal{P}} \gamma(p) \geq |\mathcal{P}| \min_{p \in \mathcal{P}} \gamma(p) = |\mathcal{P}| \gamma(p^*)$ .
- ▶ Let  $D'$  be a minimal OBDD for  $T(G, c)$  in order corresponding  $p^*$ .
- ▶ For  $D'$  we define  $a'_s$  and  $\gamma'(p)$ .  $a'_s$  depends only on the distance from the source. Hence,  $\gamma'(p)$  does not depend on accepting path. We know that  $\gamma(p^*) \geq \gamma'(p^*)$ .
- ▶  $|D| - 1 \geq |\mathcal{P}| \gamma(p^*) = \#T(G, c) \gamma(p^*) \geq \#T(G, c) \gamma'(p^*) = |D'| - 1$ .

# Optimal 1-BP computing a Tseitin formula is OBDD

**Theorem.**  $1\text{-BP}(T(G, c)) \geq \text{OBDD}(T(G, c))$ .

- ▶ Let  $D$  be a minimal 1-BP computing  $T(G, c)$ .
- ▶ Let  $a_s$  be the number of accepting paths passing  $s$ .
- ▶ For an accepting path  $p$  we denote by  $\gamma(p) = \sum_{s \in p} \frac{1}{a_s}$ .
- ▶ Let  $\mathcal{P}$  be the set of accepting paths in  $D$ ;  $|\mathcal{P}| = \#T(G, c)$ .
- ▶  $|D| - 1 = \sum_{p \in \mathcal{P}} \gamma(p) \geq |\mathcal{P}| \min_{p \in \mathcal{P}} \gamma(p) = |\mathcal{P}| \gamma(p^*)$ .
- ▶ Let  $D'$  be a minimal OBDD for  $T(G, c)$  in order corresponding  $p^*$ .
- ▶ For  $D'$  we define  $a'_s$  and  $\gamma'(p)$ .  $a'_s$  depends only on the distance from the source. Hence,  $\gamma'(p)$  does not depend on accepting path. We know that  $\gamma(p^*) \geq \gamma'(p^*)$ .
- ▶  $|D| - 1 \geq |\mathcal{P}| \gamma(p^*) = \#T(G, c) \gamma(p^*) \geq \#T(G, c) \gamma'(p^*) = |D'| - 1$ .

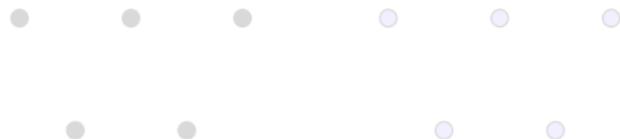
## OBDD and component width

- ▶ The number of satisfying assignments of a satisfiable  $T(G, f)$  is  $2^{|E|-|V|+cc(G)}$ .
  - ▶ Fix a spanning forest, take arbitrary values to all edges out of it. The value of edges from the spanning forest will be uniquely determined.
- ▶ Consider a node  $s$  of a minimal OBDD  $D$  computing  $T(G, f)$ . The number of nodes on level  $\ell$  equals  $\frac{\#T(G, f)}{\#T(G_1, f_1)\#T(G_2, f_2)} = 2^{|V|+cc(G)-cc(G_1)-cc(G_2)}$ .
- ▶ Bob plays the following game:  $G_1 = G$ ,  $G_2$  is the empty graph on  $V$ . Every his move, Bob remove one edge from  $G_1$  and add it to  $G_2$ . Bob calculates a value  $\alpha = cc(G_1) + cc(G_2)$ . Initially  $\alpha_0 = |V| + cc(G)$ . Bob pays the maximal value of  $\alpha_0 - \alpha$ . The component width of  $G$  ( $compw(G)$ ) is the minimum possible Bob's payout.



## OBDD and component width

- ▶ The number of satisfying assignments of a satisfiable  $T(G, f)$  is  $2^{|E|-|V|+cc(G)}$ .
- ▶ Consider a node  $s$  of a minimal OBDD  $D$  computing  $T(G, f)$ . The number of nodes on level  $\ell$  equals 
$$\frac{\#T(G, f)}{\#T(G_1, f_1)\#T(G_2, f_2)} = 2^{|V|+cc(G)-cc(G_1)-cc(G_2)}.$$
- ▶ Bob plays the following game:  $G_1 = G$ ,  $G_2$  is the empty graph on  $V$ . Every his move, Bob remove one edge from  $G_1$  and add it to  $G_2$ . Bob calculates a value  $\alpha = cc(G_1) + cc(G_2)$ . Initially  $\alpha_0 = |V| + cc(G)$ . Bob pays the maximal value of  $\alpha_0 - \alpha$ . The component width of  $G$  ( $compw(G)$ ) is the minimum possible Bob's payout.



## OBDD and component width

- ▶ The number of satisfying assignments of a satisfiable  $T(G, f)$  is  $2^{|E|-|V|+cc(G)}$ .
- ▶ Consider a node  $s$  of a minimal OBDD  $D$  computing  $T(G, f)$ . The number of nodes on level  $\ell$  equals 
$$\frac{\#T(G, f)}{\#T(G_1, f_1)\#T(G_2, f_2)} = 2^{|V|+cc(G)-cc(G_1)-cc(G_2)}.$$
- ▶ Bob plays the following game:  $G_1 = G$ ,  $G_2$  is the empty graph on  $V$ . Every his move, Bob remove one edge from  $G_1$  and add it to  $G_2$ . Bob calculates a value  $\alpha = cc(G_1) + cc(G_2)$ . Initially  $\alpha_0 = |V| + cc(G)$ . Bob pays the maximal value of  $\alpha_0 - \alpha$ . The component width of  $G$  ( $compw(G)$ ) is the minimum possible Bob's payout.



## OBDD and component width

- ▶ The number of satisfying assignments of a satisfiable  $T(G, f)$  is  $2^{|E|-|V|+cc(G)}$ .
- ▶ Consider a node  $s$  of a minimal OBDD  $D$  computing  $T(G, f)$ . The number of nodes on level  $\ell$  equals  $\frac{\#T(G, f)}{\#T(G_1, f_1)\#T(G_2, f_2)} = 2^{|V|+cc(G)-cc(G_1)-cc(G_2)}$ .
- ▶ Bob plays the following game:  $G_1 = G$ ,  $G_2$  is the empty graph on  $V$ . Every his move, Bob remove one edge from  $G_1$  and add it to  $G_2$ . Bob calculates a value  $\alpha = cc(G_1) + cc(G_2)$ . Initially  $\alpha_0 = |V| + cc(G)$ . Bob pays the maximal value of  $\alpha_0 - \alpha$ . The component width of  $G$  ( $compw(G)$ ) is the minimum possible Bob's payout.

$$\alpha_0 = 6 \quad \alpha_{min} = 6$$



## OBDD and component width

- ▶ The number of satisfying assignments of a satisfiable  $T(G, f)$  is  $2^{|E|-|V|+cc(G)}$ .
- ▶ Consider a node  $s$  of a minimal OBDD  $D$  computing  $T(G, f)$ . The number of nodes on level  $\ell$  equals  $\frac{\#T(G, f)}{\#T(G_1, f_1)\#T(G_2, f_2)} = 2^{|V|+cc(G)-cc(G_1)-cc(G_2)}$ .
- ▶ Bob plays the following game:  $G_1 = G$ ,  $G_2$  is the empty graph on  $V$ . Every his move, Bob remove one edge from  $G_1$  and add it to  $G_2$ . Bob calculates a value  $\alpha = cc(G_1) + cc(G_2)$ . Initially  $\alpha_0 = |V| + cc(G)$ . Bob pays the maximal value of  $\alpha_0 - \alpha$ . The component width of  $G$  ( $compw(G)$ ) is the minimum possible Bob's payout.

$$\alpha_0 = 6 \quad \alpha_{min} = 5$$



## OBDD and component width

- ▶ The number of satisfying assignments of a satisfiable  $T(G, f)$  is  $2^{|E|-|V|+cc(G)}$ .
- ▶ Consider a node  $s$  of a minimal OBDD  $D$  computing  $T(G, f)$ . The number of nodes on level  $\ell$  equals  $\frac{\#T(G, f)}{\#T(G_1, f_1)\#T(G_2, f_2)} = 2^{|V|+cc(G)-cc(G_1)-cc(G_2)}$ .
- ▶ Bob plays the following game:  $G_1 = G$ ,  $G_2$  is the empty graph on  $V$ . Every his move, Bob remove one edge from  $G_1$  and add it to  $G_2$ . Bob calculates a value  $\alpha = cc(G_1) + cc(G_2)$ . Initially  $\alpha_0 = |V| + cc(G)$ . Bob pays the maximal value of  $\alpha_0 - \alpha$ . The component width of  $G$  ( $compw(G)$ ) is the minimum possible Bob's payout.

$$\alpha_0 = 6 \quad \alpha_{min} = 4$$



## OBDD and component width

- ▶ The number of satisfying assignments of a satisfiable  $T(G, f)$  is  $2^{|E|-|V|+cc(G)}$ .
- ▶ Consider a node  $s$  of a minimal OBDD  $D$  computing  $T(G, f)$ . The number of nodes on level  $\ell$  equals 
$$\frac{\#T(G, f)}{\#T(G_1, f_1)\#T(G_2, f_2)} = 2^{|V|+cc(G)-cc(G_1)-cc(G_2)}$$
.
- ▶ Bob plays the following game:  $G_1 = G$ ,  $G_2$  is the empty graph on  $V$ . Every his move, Bob remove one edge from  $G_1$  and add it to  $G_2$ . Bob calculates a value  $\alpha = cc(G_1) + cc(G_2)$ . Initially  $\alpha_0 = |V| + cc(G)$ . Bob pays the maximal value of  $\alpha_0 - \alpha$ . The component width of  $G$  ( $compw(G)$ ) is the minimum possible Bob's payout.

$$\alpha_0 = 6 \quad \alpha_{min} = 4$$



## OBDD and component width

- ▶ The number of satisfying assignments of a satisfiable  $T(G, f)$  is  $2^{|E|-|V|+cc(G)}$ .
- ▶ Consider a node  $s$  of a minimal OBDD  $D$  computing  $T(G, f)$ . The number of nodes on level  $\ell$  equals 
$$\frac{\#T(G, f)}{\#T(G_1, f_1)\#T(G_2, f_2)} = 2^{|V|+cc(G)-cc(G_1)-cc(G_2)}$$
.
- ▶ Bob plays the following game:  $G_1 = G$ ,  $G_2$  is the empty graph on  $V$ . Every his move, Bob remove one edge from  $G_1$  and add it to  $G_2$ . Bob calculates a value  $\alpha = cc(G_1) + cc(G_2)$ . Initially  $\alpha_0 = |V| + cc(G)$ . Bob pays the maximal value of  $\alpha_0 - \alpha$ . The component width of  $G$  ( $compw(G)$ ) is the minimum possible Bob's payout.

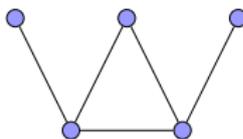
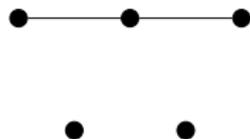
$$\alpha_0 = 6 \quad \alpha_{min} = 3$$



## OBDD and component width

- ▶ The number of satisfying assignments of a satisfiable  $T(G, f)$  is  $2^{|E|-|V|+cc(G)}$ .
- ▶ Consider a node  $s$  of a minimal OBDD  $D$  computing  $T(G, f)$ . The number of nodes on level  $\ell$  equals  $\frac{\#T(G, f)}{\#T(G_1, f_1)\#T(G_2, f_2)} = 2^{|V|+cc(G)-cc(G_1)-cc(G_2)}$ .
- ▶ Bob plays the following game:  $G_1 = G$ ,  $G_2$  is the empty graph on  $V$ . Every his move, Bob remove one edge from  $G_1$  and add it to  $G_2$ . Bob calculates a value  $\alpha = cc(G_1) + cc(G_2)$ . Initially  $\alpha_0 = |V| + cc(G)$ . Bob pays the maximal value of  $\alpha_0 - \alpha$ . The component width of  $G$  ( $compw(G)$ ) is the minimum possible Bob's payout.

$$\alpha_0 = 6 \quad \alpha_{min} = 3$$



## OBDD and component width

- ▶ The number of satisfying assignments of a satisfiable  $T(G, f)$  is  $2^{|E|-|V|+cc(G)}$ .
- ▶ Consider a node  $s$  of a minimal OBDD  $D$  computing  $T(G, f)$ . The number of nodes on level  $\ell$  equals 
$$\frac{\#T(G, f)}{\#T(G_1, f_1)\#T(G_2, f_2)} = 2^{|V|+cc(G)-cc(G_1)-cc(G_2)}$$
.
- ▶ Bob plays the following game:  $G_1 = G$ ,  $G_2$  is the empty graph on  $V$ . Every his move, Bob remove one edge from  $G_1$  and add it to  $G_2$ . Bob calculates a value  $\alpha = cc(G_1) + cc(G_2)$ . Initially  $\alpha_0 = |V| + cc(G)$ . Bob pays the maximal value of  $\alpha_0 - \alpha$ . The component width of  $G$  ( $compw(G)$ ) is the minimum possible Bob's payout.

$$\alpha_0 = 6 \quad \alpha_{min} = 3$$



## OBDD and component width

- ▶ The number of satisfying assignments of a satisfiable  $T(G, f)$  is  $2^{|E|-|V|+cc(G)}$ .
- ▶ Consider a node  $s$  of a minimal OBDD  $D$  computing  $T(G, f)$ . The number of nodes on level  $\ell$  equals 
$$\frac{\#T(G, f)}{\#T(G_1, f_1)\#T(G_2, f_2)} = 2^{|V|+cc(G)-cc(G_1)-cc(G_2)}$$
.
- ▶ Bob plays the following game:  $G_1 = G$ ,  $G_2$  is the empty graph on  $V$ . Every his move, Bob remove one edge from  $G_1$  and add it to  $G_2$ . Bob calculates a value  $\alpha = cc(G_1) + cc(G_2)$ . Initially  $\alpha_0 = |V| + cc(G)$ . Bob pays the maximal value of  $\alpha_0 - \alpha$ . The component width of  $G$  ( $compw(G)$ ) is the minimum possible Bob's payout.

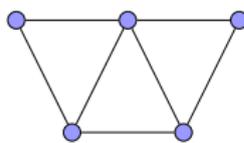
$$\alpha_0 = 6 \quad \alpha_{min} = 3 \quad \text{payout} = 3$$



## OBDD and component width

- ▶ The number of satisfying assignments of a satisfiable  $T(G, f)$  is  $2^{|E|-|V|+cc(G)}$ .
- ▶ Consider a node  $s$  of a minimal OBDD  $D$  computing  $T(G, f)$ . The number of nodes on level  $\ell$  equals  $\frac{\#T(G, f)}{\#T(G_1, f_1)\#T(G_2, f_2)} = 2^{|V|+cc(G)-cc(G_1)-cc(G_2)}$ .
- ▶ Bob plays the following game:  $G_1 = G$ ,  $G_2$  is the empty graph on  $V$ . Every his move, Bob remove one edge from  $G_1$  and add it to  $G_2$ . Bob calculates a value  $\alpha = cc(G_1) + cc(G_2)$ . Initially  $\alpha_0 = |V| + cc(G)$ . Bob pays the maximal value of  $\alpha_0 - \alpha$ . The component width of  $G$  ( $compw(G)$ ) is the minimum possible Bob's payout.

$$\alpha_0 = 6 \quad \alpha_{min} = 3 \quad \text{payout} = 3$$



- ▶ **Proposition.**  $|E|2^{\text{compw}(G)} \geq \text{OBDD}(T(G, f)) \geq 2^{\text{compw}(G)}$ .
- ▶ **Theorem.**  $\text{pw}(G) + 1 \geq \text{compw}(G) \geq \frac{1}{2}(\text{tw}(G) - 1)$ .

## Open problems

- ▶ Is it possible to prove that  $S_R(\mathcal{T}(G, c)) \geq 2^{\Omega(\text{tw}(G))}$ ?
- ▶ Is it possible to prove a similar lower bound for unrestricted resolution?
- ▶ Is it possible to separate  $\text{Search}_{\mathcal{T}(G, c)}$  and  $\text{SearchVertex}_{G, c}$  for constant degree graphs?