

# Algebra and Arithmetic of Plane Binary Trees: Theory & Applications of Mapped Regular Pavings

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Main Idea & Motivation

Motivating Examples

Why MRPs?

Theory of Regular Pavings (RPs)

Theory of Mapped Regular Pavings (MRPs)

Theory of Real Mapped Regular Pavings ( $\mathbb{R}$ -MRPs)

Applications of Mapped Regular Pavings (MRPs)

Randomized Algorithms for  $\mathbb{IR}$ -MRPs

Conclusions and References

# Extending Arithmetic:

reals  $\rightarrow$  intervals  $\rightarrow$  mapped partitions of interval

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4. – **by** exploiting the *algebraic structure of partitions formed by finite-rooted-binary (frb) trees*

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3. **Our Main Idea:**
  - is to further naturally extend to arithmetic over mapped partitions of an interval called *Mapped Regular Pavings (MRPs)*
4. – **by** exploiting the *algebraic structure of partitions formed by finite-rooted-binary (frb) trees*
5. – **thereby** provide algorithms for several algebras and their inclusions over frb tree partitions

# arithmetic from intervals to their frb-tree partitions

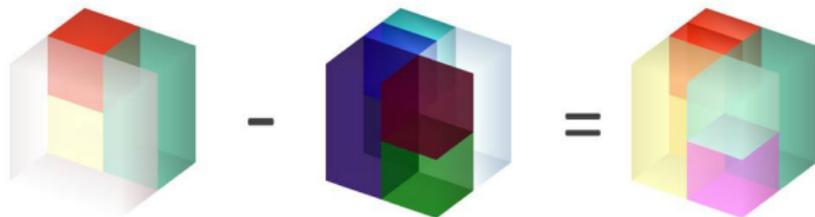


Figure : Arithmetic with coloured spaces.

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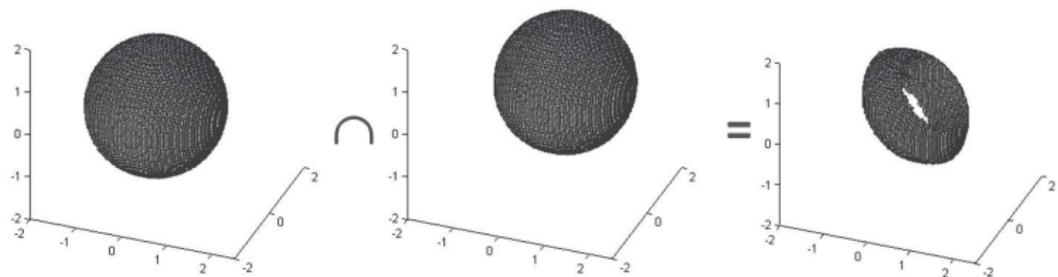


Figure : Intersection of enclosures of two hollow spheres.

# arithmetic from intervals to their frb-tree partitions

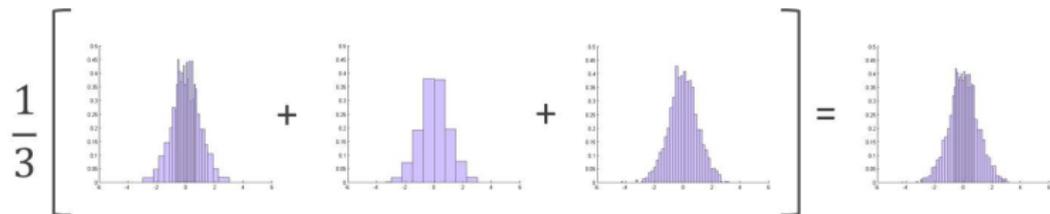


Figure : Histogram averaging.

# Why Mapped Regular pavings (MRPs)?

MRPs allow any arithmetic defined over elements in  $\mathbb{Y}$  to be extended point-wise to  $\mathbb{Y}$ -MRPs.

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2. Exploiting the tree-based structure to obtain interval enclosures of real-valued functions efficiently
3. Statistical set-processing operations like marginal density, conditional density and highest coverage regions, visualization, etc
4. **Other Possibilities: “Tree’d” Contractor Programs and Constraint Propagators (Bounded-error Robotics)**

# An RP tree a root interval $\mathbf{x}_\rho \in \mathbb{IR}^d$

The **regularly paved boxes** of  $\mathbf{x}_\rho$  can be represented by nodes of **finite rooted binary (frb-trees)** of **geometric group theory**

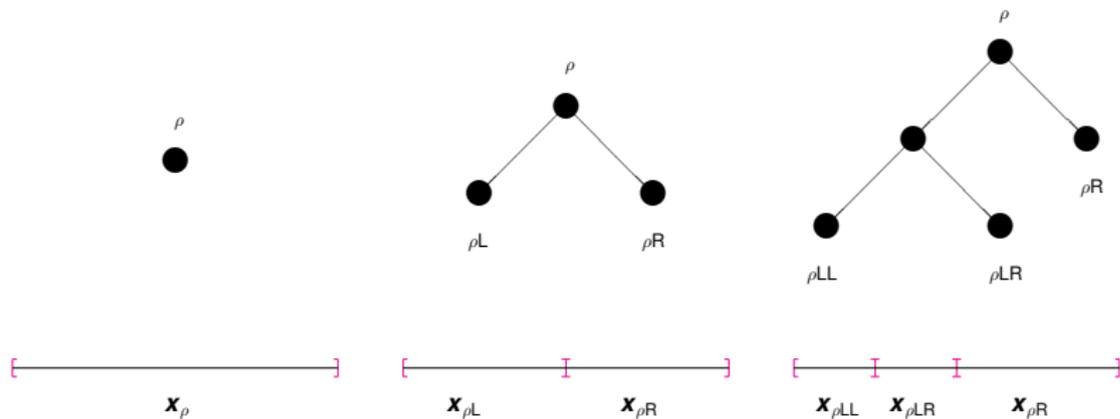
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# An RP tree a root interval $\mathbf{x}_\rho \in \mathbb{I}\mathbb{R}^d$

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An operation of bisection on a box is equivalent to performing the operation on its corresponding node in the tree:

Leaf boxes of RP tree partition the root interval  $\mathbf{x}_\rho \in \mathbb{I}\mathbb{R}^1$

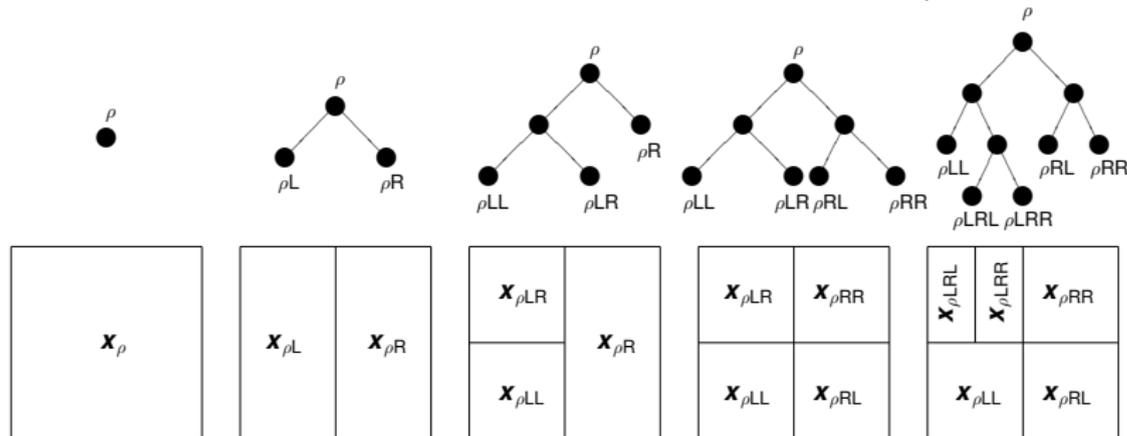


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Leaf boxes of RP tree partition the root interval  $\mathbf{x}_\rho \in \mathbb{I}\mathbb{R}^2$

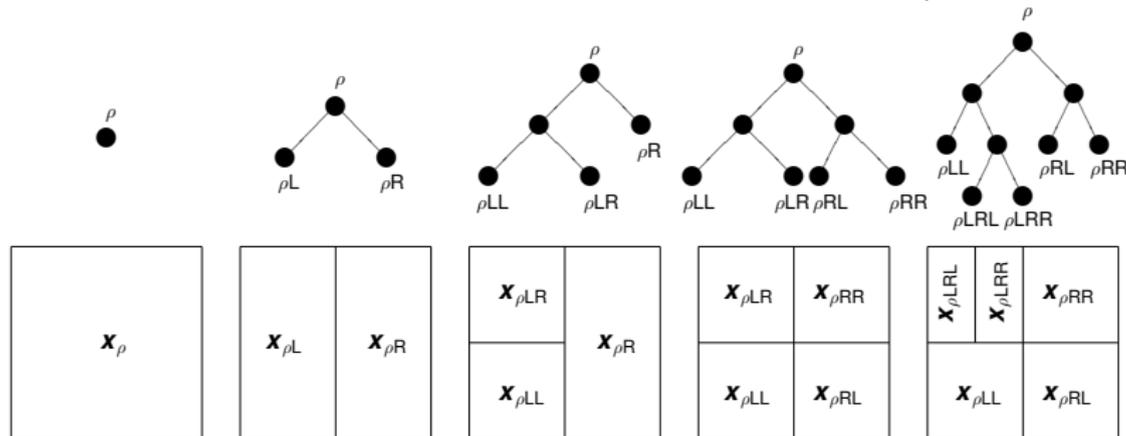


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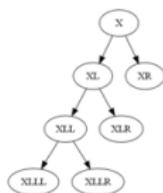
Leaf boxes of RP tree partition the root interval  $\mathbf{x}_\rho \in \mathbb{I}\mathbb{R}^2$



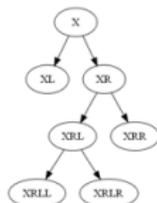
By this “RP Peano’s curve” frb-trees encode partitions of  $\mathbf{x}_\rho \in \mathbb{I}\mathbb{R}^d$

# Algebraic Structure and Combinatorics of RPs

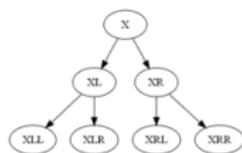
## Leaf-depth encoded RPs



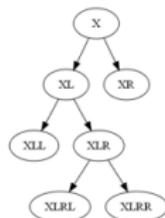
(3, 3, 2, 1)



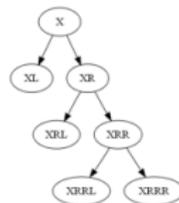
(1, 3, 3, 2)



(2, 2, 2, 2)

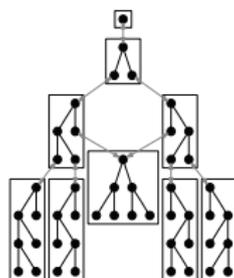


(2, 3, 3, 1)

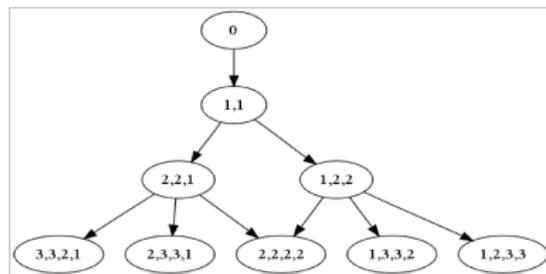


(1, 2, 3, 3)

There are  $C_k$  RPs with  $k$  splits

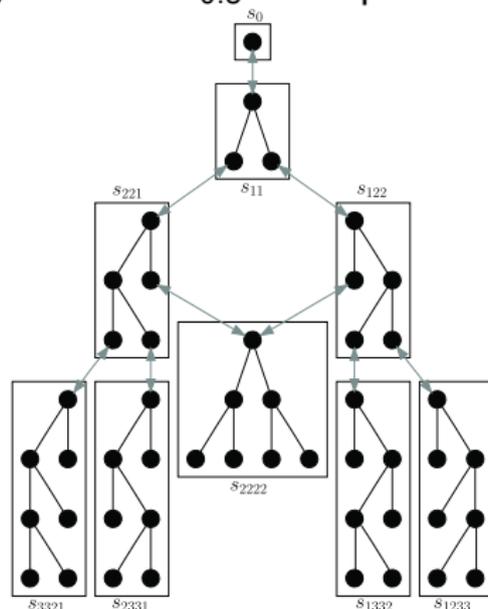


|          |   |                          |
|----------|---|--------------------------|
| $C_0$    | = | 1                        |
| $C_1$    | = | 1                        |
| $C_2$    | = | 2                        |
| $C_3$    | = | 5                        |
| $C_4$    | = | 14                       |
| $C_5$    | = | 42                       |
| ...      | = | ...                      |
| $C_k$    | = | $\frac{(2k)!}{(k+1)!k!}$ |
| ...      | = | ...                      |
| $C_{15}$ | = | 9694845                  |
| ...      | = | ...                      |
| $C_{20}$ | = | 6564120420               |
| ...      | = | ...                      |



# Hasse (transition) Diagram of Regular Pavings

Transition diagram over  $\mathbb{S}_{0:3}$  with split/reunion operations

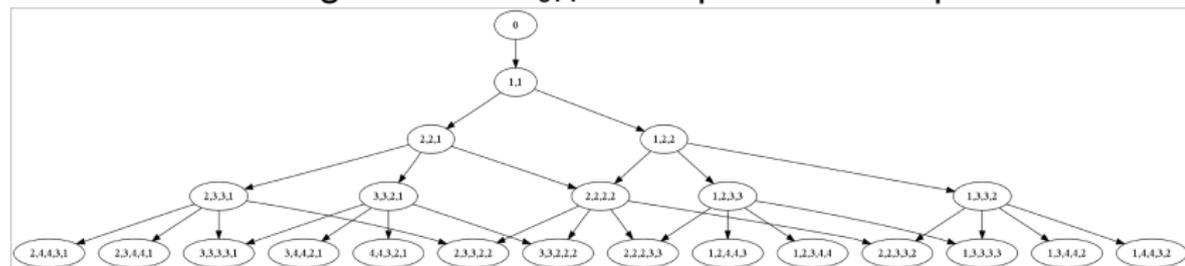


RS, W.Taylor and G.Teng, [Catalan Coefficients, Sequence A185155 in The On-Line Encyclopedia of Integer](#)

[Sequences, 2012](#), <http://oeis.org>

# Hasse (transition) Diagram of Regular Pavings

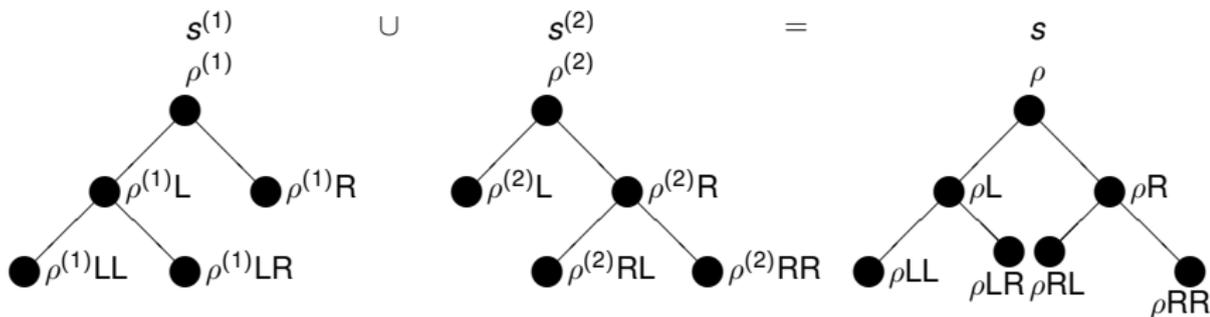
Transition diagram over  $\mathbb{S}_{0:4}$  with split/reunion operations



1. The above state space is denoted by  $\mathbb{S}_{0:4}$
2. Number of RPs with  $k$  splits is the Catalan number  $C_k$
3. There is more than one way to reach a RP by  $k$  splits
4. Randomized enclosure algorithms are Markov chains on  $\mathbb{S}_{0:\infty}$

# RPs are closed under union operations

$s^{(1)} \cup s^{(2)} = s$  is union of two RPs  $s^{(1)}$  and  $s^{(2)}$  of  $\mathbf{x}_\rho \in \mathbb{R}^2$ .



|                             |                            |
|-----------------------------|----------------------------|
| $\mathbf{x}_{\rho^{(1)}LR}$ | $\mathbf{x}_{\rho^{(1)}R}$ |
| $\mathbf{x}_{\rho^{(1)}LL}$ |                            |

|                            |                             |
|----------------------------|-----------------------------|
| $\mathbf{x}_{\rho^{(2)}L}$ | $\mathbf{x}_{\rho^{(2)}RR}$ |
|                            | $\mathbf{x}_{\rho^{(2)}RL}$ |

|                        |                        |
|------------------------|------------------------|
| $\mathbf{x}_{\rho LR}$ | $\mathbf{x}_{\rho RR}$ |
| $\mathbf{x}_{\rho LL}$ | $\mathbf{x}_{\rho RL}$ |

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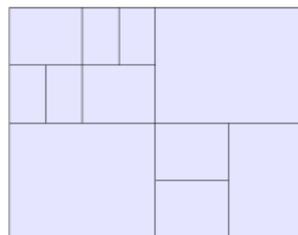
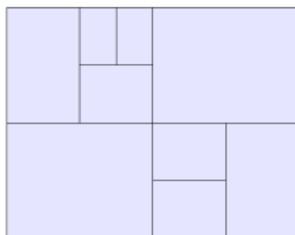
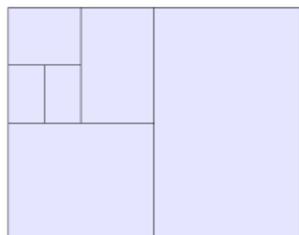
**Lemma 1:** The algebraic structure of frb-trees (underlying Thompson's group) is closed under union operations.

# RPs are closed under union operations

**Lemma 1:** The algebraic structure of frb-trees (underlying Thompson's group) is closed under union operations.

**Proof:** by a “transparency overlay process” argument (cf. Meier 2008).

$s^{(1)} \cup s^{(2)} = s$  is union of two RPs  $s^{(1)}$  and  $s^{(2)}$  of  $\mathbf{x}_\rho \in \mathbb{R}^2$ .



---

## Algorithm 1: $\text{RPUnion}(\rho^{(1)}, \rho^{(2)})$

---

**input** : Root nodes  $\rho^{(1)}$  and  $\rho^{(2)}$  of RPs  $s^{(1)}$  and  $s^{(2)}$ , respectively, with root box  $\mathbf{x}_{\rho^{(1)}} = \mathbf{x}_{\rho^{(2)}}$

**output** : Root node  $\rho$  of RP  $s = s^{(1)} \cup s^{(2)}$

**if**  $\text{IsLeaf}(\rho^{(1)}) \ \& \ \text{IsLeaf}(\rho^{(2)})$  **then**

$\rho \leftarrow \text{Copy}(\rho^{(1)})$

**return**  $\rho$

**end**

**else if**  $!\text{IsLeaf}(\rho^{(1)}) \ \& \ \text{IsLeaf}(\rho^{(2)})$  **then**

$\rho \leftarrow \text{Copy}(\rho^{(1)})$

**return**  $\rho$

**end**

**else if**  $\text{IsLeaf}(\rho^{(1)}) \ \& \ !\text{IsLeaf}(\rho^{(2)})$  **then**

$\rho \leftarrow \text{Copy}(\rho^{(2)})$

**return**  $\rho$

**end**

**else**

$!\text{IsLeaf}(\rho^{(1)}) \ \& \ !\text{IsLeaf}(\rho^{(2)})$

**end**

Make  $\rho$  as a node with  $\mathbf{x}_{\rho} \leftarrow \mathbf{x}_{\rho^{(1)}}$

Graft onto  $\rho$  as left child the node  $\text{RPUnion}(\rho^{(1)}\text{L}, \rho^{(2)}\text{L})$

Graft onto  $\rho$  as right child the node  $\text{RPUnion}(\rho^{(1)}\text{R}, \rho^{(2)}\text{R})$

**return**  $\rho$

---

Note: this is not the minimal union of the (Boolean mapped) RPs of Jaulin et. al. 2001

## Dfn: Mapped Regular Paving (MRP)

- ▶ Let  $s \in \mathbb{S}_{0:\infty}$  be an RP with root node  $\rho$  and root box  $\mathbf{x}_\rho \in \mathbb{IR}^d$

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- ▶ Let  $s \in \mathbb{S}_{0:\infty}$  be an RP with root node  $\rho$  and root box  $\mathbf{x}_\rho \in \mathbb{IR}^d$
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- ▶ Let  $\mathbb{V}(s)$  and  $\mathbb{L}(s)$  denote the sets all nodes and leaf nodes of  $s$ , respectively.
- ▶ Let  $f : \mathbb{V}(s) \rightarrow \mathbb{Y}$  map each node of  $s$  to an element in  $\mathbb{Y}$  as follows:

$$\{\rho\mathbf{v} \mapsto f_{\rho\mathbf{v}} : \rho\mathbf{v} \in \mathbb{V}(s), f_{\rho\mathbf{v}} \in \mathbb{Y}\} .$$

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- ▶ Such a map  $f$  is called a  $\mathbb{Y}$ -mapped regular paving ( $\mathbb{Y}$ -MRP).

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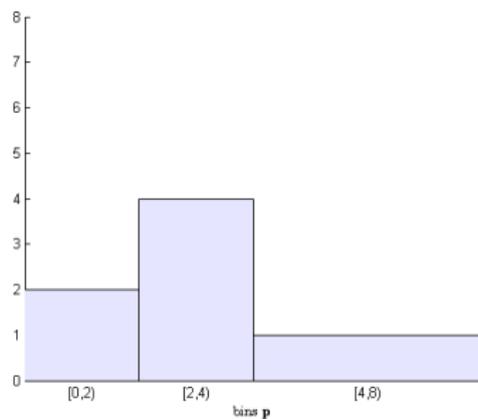
$$\{\rho\mathbf{v} \mapsto f_{\rho\mathbf{v}} : \rho\mathbf{v} \in \mathbb{V}(s), f_{\rho\mathbf{v}} \in \mathbb{Y}\} .$$

- ▶ Such a map  $f$  is called a  $\mathbb{Y}$ -mapped regular paving ( $\mathbb{Y}$ -MRP).
- ▶ Thus, a  $\mathbb{Y}$ -MRP  $f$  is obtained by augmenting each node  $\rho\mathbf{v}$  of the RP tree  $s$  with an additional data member  $f_{\rho\mathbf{v}}$ .

# Examples of $\mathbb{Y}$ -MRPs

If  $\mathbb{Y} = \mathbb{R}$

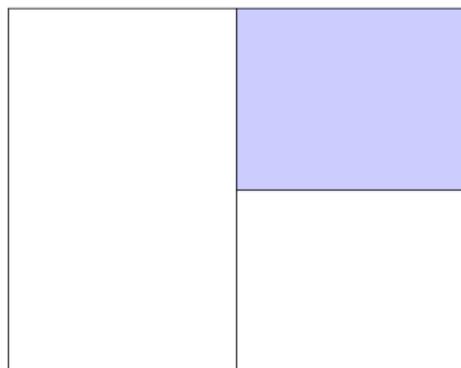
$\mathbb{R}$ -MRP over  $s_{221}$  with  $x_\rho = [0, 8]$



# Examples of $\mathbb{Y}$ -MRPs

If  $\mathbb{Y} = \mathbb{B}$

$\mathbb{B}$ -MRP over  $s_{122}$  with  $x_\rho = [0, 1]^2$  (e.g. Jaulin et. al. 2001)

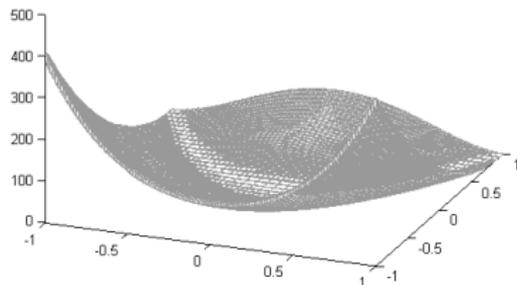


# Examples of $\mathbb{Y}$ -MRPs

If  $\mathbb{Y} = \mathbb{IR}$

– frb tree representation for interval inclusion algebra

$\mathbb{IR}$ -MRP enclosure of the Rosenbrock function with  
 $x_\rho = [-1, 1]^2$

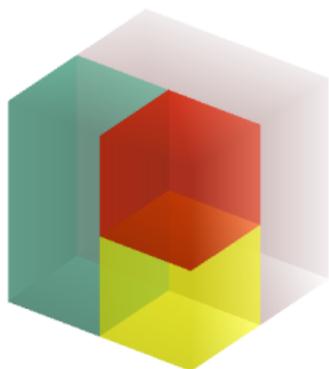


# Examples of $\mathbb{Y}$ -MRPs

If  $\mathbb{Y} = [0, 1]^3$

– R G B colour maps

$[0, 1]^3$ -MRP over  $s_{3321}$  with  $x_\rho = [0, 1]^3$

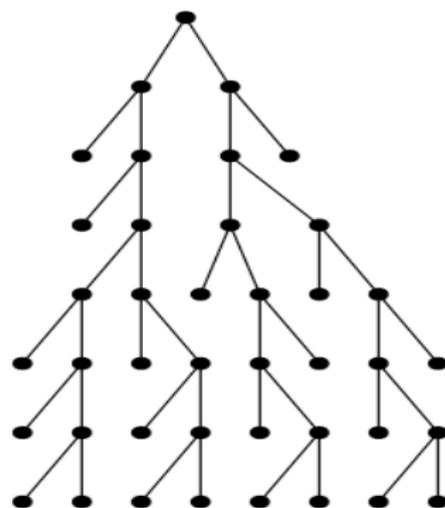
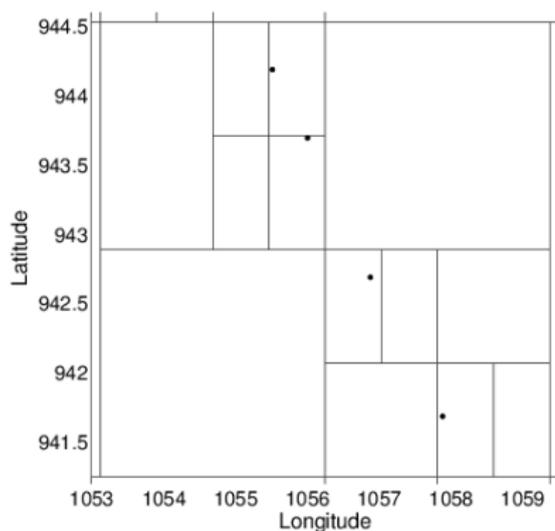


# Examples of $\mathbb{Y}$ -MRPs

If  $\mathbb{Y} = \mathbb{Z}_+ := \{0, 1, 2, \dots\}$

– radar-measured aircraft trajectory data

$\mathbb{Z}_+$ -MRP trajectory of an aircraft and its tree

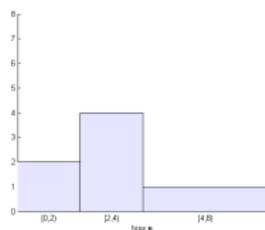


# $\mathbb{Y}$ -MRP Arithmetic

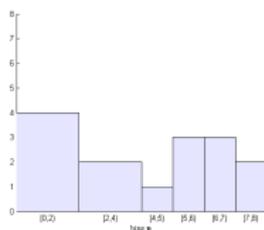
If  $\star : \mathbb{Y} \times \mathbb{Y} \rightarrow \mathbb{Y}$  then we can extend  $\star$  point-wise to two  $\mathbb{Y}$ -MRPs  $f$  and  $g$  with root nodes  $\rho^{(1)}$  and  $\rho^{(2)}$  via  $\text{MRPOperate}(\rho^{(1)}, \rho^{(2)}, \star)$ .

This is done using  $\text{MRPOperate}(\rho^{(1)}, \rho^{(2)}, +)$

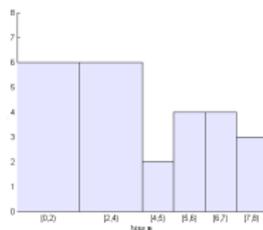
$f$



$g$



$f + g$



## $\mathbb{R}$ -MRP Addition by $\text{MRPOperate}(\rho^{(1)}, \rho^{(2)}, +)$

adding two piece-wise constant functions or  $\mathbb{R}$ -MRPs

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## Algorithm 2: MRPOperate( $\rho^{(1)}, \rho^{(2)}, \star$ )

---

**input** : two root nodes  $\rho^{(1)}$  and  $\rho^{(2)}$  with same root box  $\mathbf{x}_{\rho^{(1)}} = \mathbf{x}_{\rho^{(2)}}$  and binary operation  $\star$ .

**output** : the root node  $\rho$  of  $\mathbb{Y}$ -MRP  $h = f \star g$ .

Make a new node  $\rho$  with box and image

$\mathbf{x}_{\rho} \leftarrow \mathbf{x}_{\rho^{(1)}}; h_{\rho} \leftarrow f_{\rho^{(1)}} \star g_{\rho^{(2)}}$

**if** IsLeaf( $\rho^{(1)}$ ) & !IsLeaf( $\rho^{(2)}$ ) **then**

    Make temporary nodes  $L', R'$

$\mathbf{x}_{L'} \leftarrow \mathbf{x}_{\rho^{(1)}L}; \mathbf{x}_{R'} \leftarrow \mathbf{x}_{\rho^{(1)}R}$

$f_{L'} \leftarrow f_{\rho^{(1)}}, f_{R'} \leftarrow f_{\rho^{(1)}}$

    Graft onto  $\rho$  as left child the node MRPOperate( $L', \rho^{(2)}L, \star$ )

    Graft onto  $\rho$  as right child the node MRPOperate( $R', \rho^{(2)}R, \star$ )

**end**

**else if** !IsLeaf( $\rho^{(1)}$ ) & IsLeaf( $\rho^{(2)}$ ) **then**

    Make temporary nodes  $L', R'$

$\mathbf{x}_{L'} \leftarrow \mathbf{x}_{\rho^{(2)}L}; \mathbf{x}_{R'} \leftarrow \mathbf{x}_{\rho^{(2)}R}$

$g_{L'} \leftarrow g_{\rho^{(2)}}, g_{R'} \leftarrow g_{\rho^{(2)}}$

    Graft onto  $\rho$  as left child the node MRPOperate( $\rho^{(1)}L, L', \star$ )

    Graft onto  $\rho$  as right child the node MRPOperate( $\rho^{(1)}R, R', \star$ )

**end**

**else if** !IsLeaf( $\rho^{(1)}$ ) & !IsLeaf( $\rho^{(2)}$ ) **then**

    Graft onto  $\rho$  as left child the node MRPOperate( $\rho^{(1)}L, \rho^{(2)}L, \star$ )

    Graft onto  $\rho$  as right child the node MRPOperate( $\rho^{(1)}R, \rho^{(2)}R, \star$ )

**end**

**return**  $\rho$

---

# Unary transformations are easy too

Let  $\text{MRPTransform}(\rho, \tau)$  apply the unary transformation  $\tau : \mathbb{R} \rightarrow \mathbb{R}$  to a given  $\mathbb{R}$ -MRP  $f$  with root node  $\rho$  as follows:

- ▶ copy  $f$  to  $g$
- ▶ recursively set  $f_{\rho v} = \tau(f_{\rho v})$  for each node  $\rho v$  in  $g$
- ▶ return  $g$  as  $\tau(f)$

# Minimal Representation of $\mathbb{R}$ -MRP

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## Algorithm 3: MinimiseLeaves( $\rho$ )

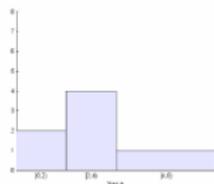
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**input** :  $\rho$ , the root node of  $\mathbb{R}$ -MRP  $f$ .

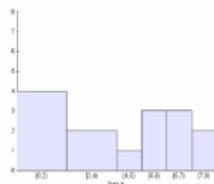
**output** : Modify  $f$  into  $\succ(f)$ , the unique  $\mathbb{R}$ -MRP with fewest leaves.

```
if !IsLeaf( $\rho$ ) then
  MinimiseLeaves( $\rho$ L)
  MinimiseLeaves( $\rho$ R)
  if IsCherry( $\rho$ ) & (  $f_{\rho L} = f_{\rho R}$  ) then
     $f_{\rho} \leftarrow f_{\rho L}$ 
    Prune( $\rho$ L)
    Prune( $\rho$ R)
  end
end
end
```

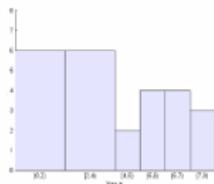
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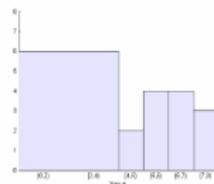
(a)  $f$



(b)  $g$



(c)  $f + g$



(d)  $\succ(f + g)$

Thus, we can obtain arithmetical expressions specified by finitely many sub-expressions in a **directed acyclic graph** whose:

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Thus, we can obtain arithmetical expressions specified by finitely many sub-expressions in a **directed acyclic graph** whose:

- ▶ inputs and output **nodes** are themselves  $\mathbb{R}$ -MRPs
- ▶ and whose **edges** involve:
  1. a binary arithmetic operation  $\star \in \{+, -, \cdot, /\}$  over two  $\mathbb{R}$ -MRPs,
  2. a standard transformation of  $\mathbb{R}$ -MRP by elements of  $\mathcal{G} := \{\exp, \sin, \cos, \tan, \dots\}$  and
  3. their compositions.

# Stone-Wierstrass Theorem: $\mathbb{R}$ -MRPs Dense in $C(\mathbf{x}_\rho, \mathbb{R})$

## Theorem

*Let  $\mathcal{F}$  be the class of  $\mathbb{R}$ -MRPs with the same root box  $\mathbf{x}_\rho$ . Then  $\mathcal{F}$  is dense in  $C(\mathbf{x}_\rho, \mathbb{R})$ , the algebra of real-valued continuous functions on  $\mathbf{x}_\rho$ .*

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## Proof:

Since  $\mathbf{x}_\rho \in \mathbb{R}^d$  is a compact Hausdorff space, by the Stone-Weierstrass theorem we can establish that  $\mathcal{F}$  is dense in  $C(\mathbf{x}_\rho, \mathbb{R})$  with the topology of uniform convergence, provided that  $\mathcal{F}$  is a sub-algebra of  $C(\mathbf{x}_\rho, \mathbb{R})$  that separates points in  $\mathbf{x}_\rho$  and which contains a non-zero constant function.

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We will show all these conditions are satisfied by  $\mathcal{F}$

## Stone-Wierstrass Theorem Contd.: $\mathbb{R}$ -MRPs Dense in $C(\mathbf{x}_\rho, \mathbb{R})$

- ▶  $\mathcal{F}$  is a sub-algebra of  $C(\mathbf{x}_\rho, \mathbb{R})$  since it is closed under addition and scalar multiplication.

## Stone-Wierstrass Theorem Contd.: $\mathbb{R}$ -MRPs Dense in $C(\mathbf{x}_\rho, \mathbb{R})$

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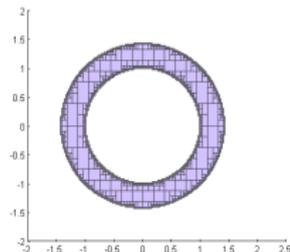
## Stone-Wierstrass Theorem Contd.: $\mathbb{R}$ -MRPs Dense in $C(\mathbf{x}_\rho, \mathbb{R})$

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- ▶ Q.E.D.

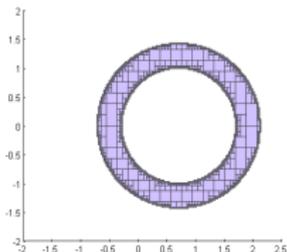
# $\mathbb{B}$ -MRP arithmetic – **contractors, propagators & collaborators** (bounded-error robotics)

Two Boolean-mapped regular pavings  $A_1$  and  $A_2$  and Boolean arithmetic operations with  $+$  for set union,  $-$  for symmetric set difference,  $\times$  for set intersection, and  $\div$  for set difference.

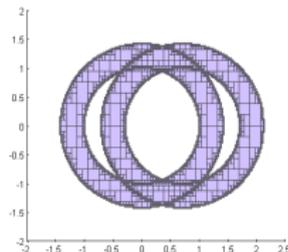
$A_1$



$A_2$



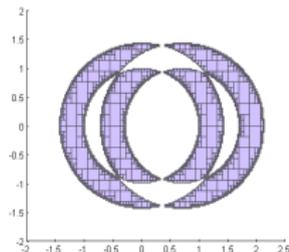
$A_1 + A_2$



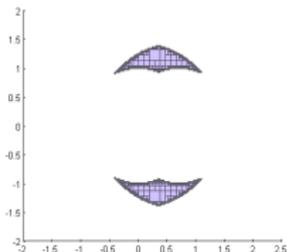
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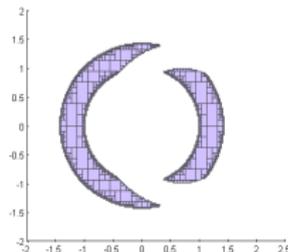
$$A_1 - A_2$$



$$A_1 \times A_2$$

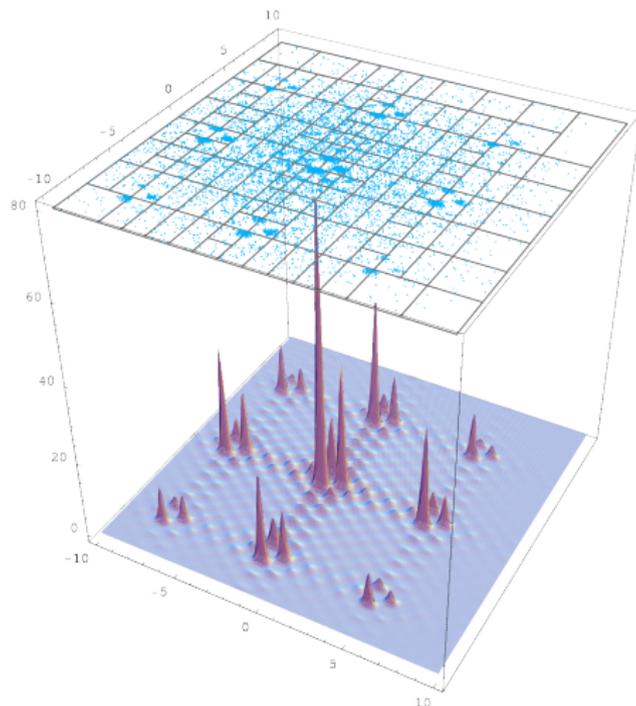


$$A_1 \div A_2$$



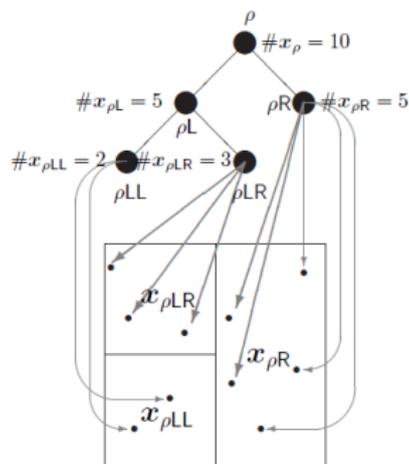
# Nonparametric Density Estimation

Problem: Take **samples** from an unknown density  $f$  and consistently reconstruct  $f$

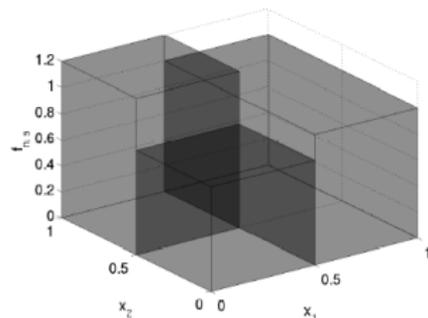
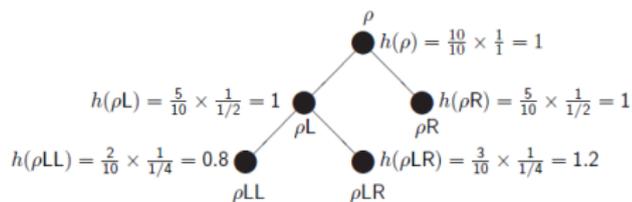


# Nonparametric Density Estimation

Approach: Use **statistical regular paving** to get  **$\mathbb{R}$ -MRP data-adaptive histogram**



(a) An SRP tree and its constituents.

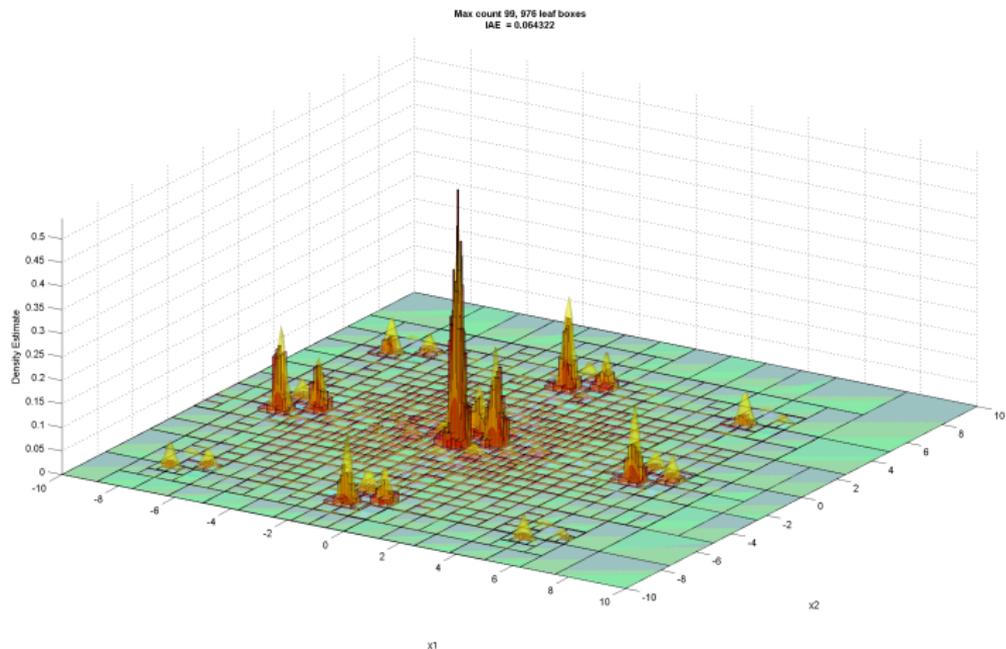


(b) An SRP histogram and its tree.

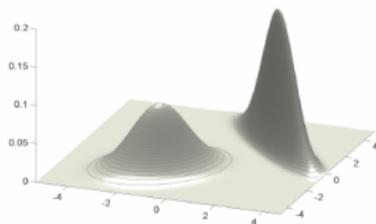
# Nonparametric Density Estimation

Solution:  $\mathbb{R}$ -MRP histogram averaging allows us to produce a consistent Bayesian estimate of the density (up to 10 dimensions)

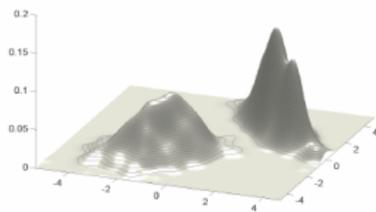
(Teng, Harlow, Lee and S., *ACM Trans. Mod. & Comp. Sim.*, [r. 2] 2012)



# Kernel Density Estimate (visualization of a procedure)

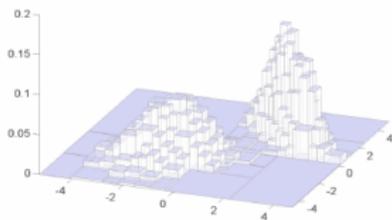


(a) True density.

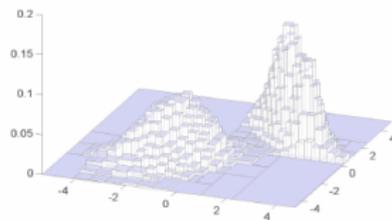


(c) MCMC bandwidth KDE.

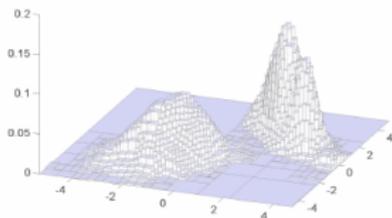
# Approximating Kernel Density Estimates by $\mathbb{R}$ -MRPs



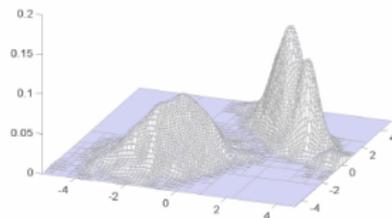
(a)  $\bar{\psi} = 0.001$  (187 leaves).



(b)  $\bar{\psi} = 0.005$  (316 leaves).



(c)  $\bar{\psi} = 0.0001$  (919 leaves).



(d)  $\bar{\psi} = 0.00001$  (4420 leaves).

# Approximating Kernel Density Estimates by $\mathbb{R}$ -MRPs

Table J.4: 5- $d$  case: estimated errors for KDE and RMRP-KDE approximations.

|                          | $\hat{d}_{KL}$ | $\hat{L}_1$ error | Time (s)    | Leaves  |
|--------------------------|----------------|-------------------|-------------|---------|
| KDE ( $n_K = 2,000$ )    | 0.41           | 0.66              | 7,350–8,880 | $n/a$   |
| RMRP-KDE approximations  |                |                   |             |         |
| $\bar{\psi} = 0.0001$    | 5.06           | 0.96              | 1.0         | 2,363   |
| $\bar{\psi} = 0.00005$   | 4.85           | 0.91              | 2.3         | 4,639   |
| $\bar{\psi} = 0.00001$   | 4.51           | 0.85              | 8.7         | 17,759  |
| $\bar{\psi} = 0.000005$  | 4.49           | 0.84              | 17.2        | 31,335  |
| $\bar{\psi} = 0.000001$  | 3.33           | 0.76              | 66.1        | 133,493 |
| $\bar{\psi} = 0.0000005$ | 3.31           | 0.75              | 131.0       | 237,561 |
| $\bar{\psi} = 0.0000001$ | 3.54           | 0.74              | 470.0       | 895,012 |

# Finding image of $\mathbb{R}$ -MRP is by fast look-ups

---

## Algorithm 4: PointWiseImage( $\rho, x$ )

---

**input** :  $\rho$  with box  $x_\rho$ , the root node of  $\mathbb{R}$ -MRP  $f$  with RP  $s$ , and a point  $x \in x_\rho$ .  
**output** : Return  $f_{\eta(x)}$  at the leaf node  $\eta(x)$  that is associated with the box  $x_{\eta(x)}$  containing  $x$ .

```
if IsLeaf( $\rho$ ) then
  | return  $f_\rho$ 
end
else
  | if  $x \in x_{\rho R}$  then
  | | PointWiseImage( $\rho R, x$ )
  | end
  | else
  | | PointWiseImage( $\rho L, x$ )
  | end
end
```

---

# Finding image of $\mathbb{R}$ -MRP is by fast look-ups

---

## Algorithm 5: `PointWiseImage( $\rho, x$ )`

---

**input** :  $\rho$  with box  $\mathbf{x}_\rho$ , the root node of  $\mathbb{R}$ -MRP  $f$  with RP  $s$ , and a point  $x \in \mathbf{x}_\rho$ .  
**output** : Return  $f_{\eta(x)}$  at the leaf node  $\eta(x)$  that is associated with the box  $\mathbf{x}_{\eta(x)}$  containing  $x$ .

```
if IsLeaf( $\rho$ ) then
  | return  $f_\rho$ 
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else
  | if  $x \in \mathbf{x}_{\rho R}$  then
  | | PointWiseImage( $\rho R, x$ )
  | end
  | else
  | | PointWiseImage( $\rho L, x$ )
  | end
end
end
```

- 
- ▶ Cost of KDE image  $\sim O(n)$  **KFLOPs** (FLOPs for kernel evaluation procedure)

# Finding image of $\mathbb{R}$ -MRP is by fast look-ups

---

## Algorithm 6: `PointWiseImage( $\rho, x$ )`

---

**input** :  $\rho$  with box  $\mathbf{x}_\rho$ , the root node of  $\mathbb{R}$ -MRP  $f$  with RP  $s$ , and a point  $x \in \mathbf{x}_\rho$ .  
**output** : Return  $f_{\eta(x)}$  at the leaf node  $\eta(x)$  that is associated with the box  $\mathbf{x}_{\eta(x)}$  containing  $x$ .

```
if IsLeaf( $\rho$ ) then
  | return  $f_\rho$ 
end
else
  | if  $x \in \mathbf{x}_{\rho R}$  then
  | | PointWiseImage( $\rho R, x$ )
  | end
  | else
  | | PointWiseImage( $\rho L, x$ )
  | end
end
end
```

---

- ▶ Cost of KDE image  $\sim O(n)$  **KFLOPs** (FLOPs for kernel evaluation procedure)
- ▶ 10-fold CV cost  $\sim 10 \times O\left(\frac{1}{10}n\frac{9}{10}n\right) = O(n^2)$  **KFLOPs**

# Finding image of $\mathbb{R}$ -MRP is by fast look-ups

---

## Algorithm 7: PointWiseImage( $\rho, x$ )

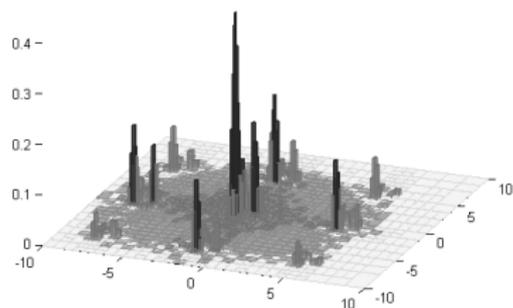
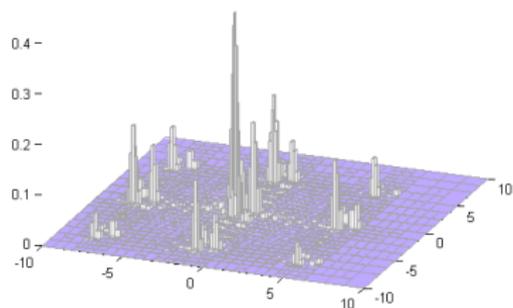
---

**input** :  $\rho$  with box  $\mathbf{x}_\rho$ , the root node of  $\mathbb{R}$ -MRP  $f$  with RP  $s$ , and a point  $x \in \mathbf{x}_\rho$ .  
**output** : Return  $f_{\eta(x)}$  at the leaf node  $\eta(x)$  that is associated with the box  $\mathbf{x}_{\eta(x)}$  containing  $x$ .

```
if IsLeaf( $\rho$ ) then
  | return  $f_\rho$ 
end
else
  | if  $x \in \mathbf{x}_{\rho R}$  then
  | | PointWiseImage( $\rho R, x$ )
  | end
  | else
  | | PointWiseImage( $\rho L, x$ )
  | end
end
end
```

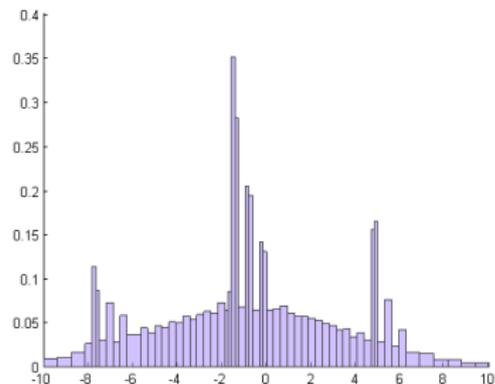
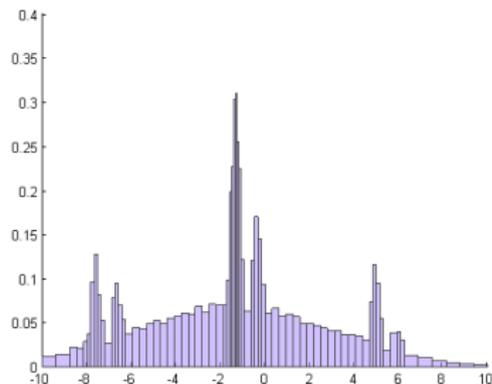
- 
- ▶ Cost of KDE image  $\sim O(n)$  **KFLOPs** (FLOPs for kernel evaluation procedure)
  - ▶ 10-fold CV cost  $\sim 10 \times O\left(\frac{1}{10} n \frac{9}{10} n\right) = O(n^2)$  **KFLOPs**
  - ▶ But using  $\mathbb{R}$ -MRP approximation to KDE requires  $10 \times O\left(\frac{1}{10} n \lg\left(\frac{9}{10} n\right)\right) = O(n \lg(n))$  **tree-look-ups**

# Coverage, Marginal & Slice Operators of $\mathbb{R}$ -MRP



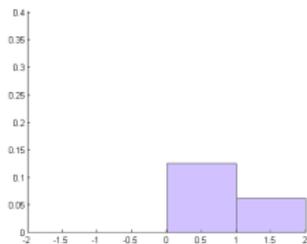
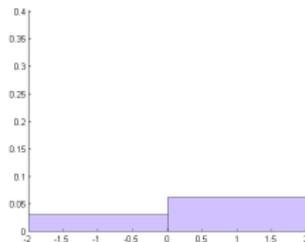
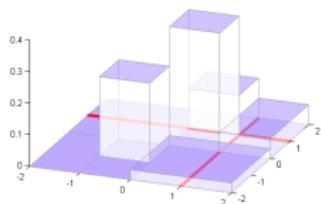
$\mathbb{R}$ -MRP approximation to Levy density and its coverage regions with  $\alpha = 0.9$  (light gray),  $\alpha = 0.5$  (dark gray) and  $\alpha = 0.1$  (black)

# Coverage, Marginal & Slice Operators of $\mathbb{R}$ -MRP



Marginal densities  $f^{\{1\}}(x_1)$  and  $f^{\{2\}}(x_2)$  along each coordinate of  $\mathbb{R}$ -MRP approximation

# Coverage, Marginal & Slice Operators of $\mathbb{R}$ -MRP



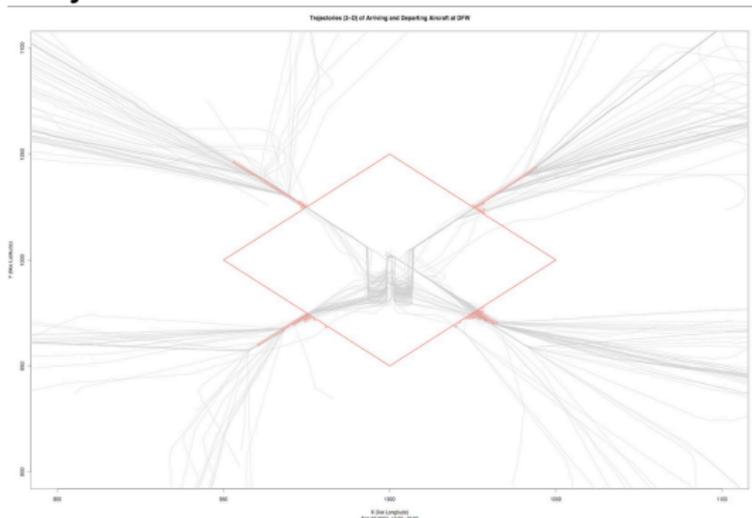
The slices of a simple  $\mathbb{R}$ -MRP in 2D

— “non-parametric regression arithmetic”

# Air Traffic “Arithmetic” → dynamic air-space configuration

(G. Teng, K. Kuhn and RS, *J. Aerospace Comput., Inf. & Com.*, 9:1, 14–25, 2012.)

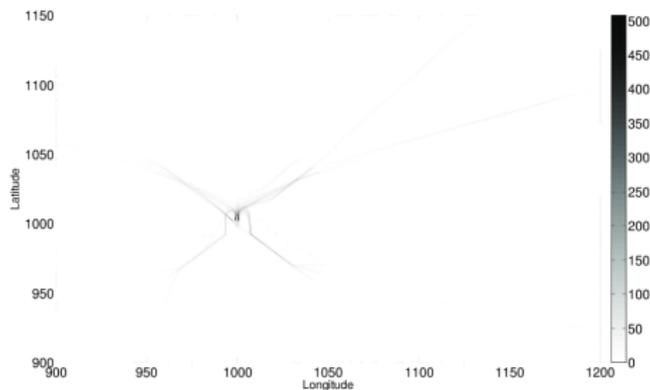
## On a Good Day



# Air Traffic “Arithmetic” → dynamic air-space configuration

(G. Teng, K. Kuhn and RS, *J. Aerospace Comput., Inf. & Com.*, 9:1, 14–25, 2012.)

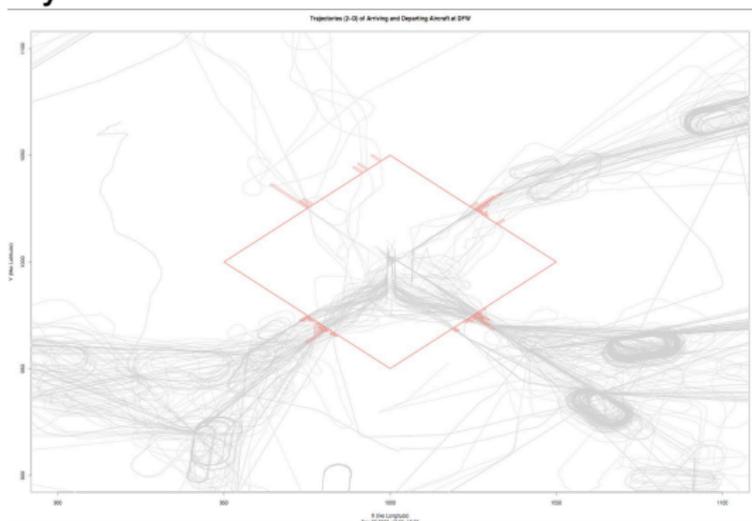
## $\mathbb{Z}_+$ -MRP On a Good Day



# Air Traffic “Arithmetic” → dynamic air-space configuration

(G. Teng, K. Kuhn and RS, *J. Aerospace Comput., Inf. & Com.*, 9:1, 14–25, 2012.)

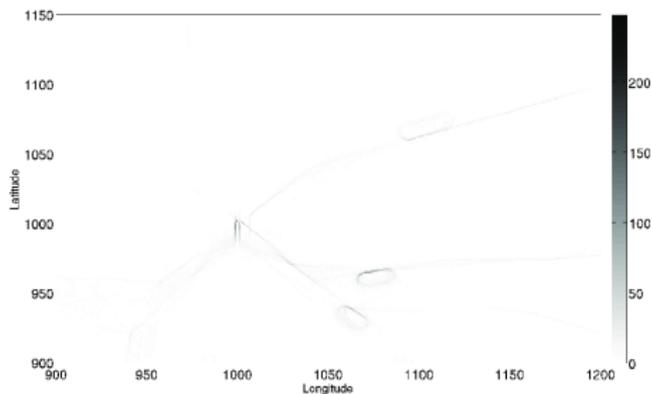
## On a Bad Day



# Air Traffic “Arithmetic” → dynamic air-space configuration

(G. Teng, K. Kuhn and RS, *J. Aerospace Comput., Inf. & Com.*, 9:1, 14–25, 2012.)

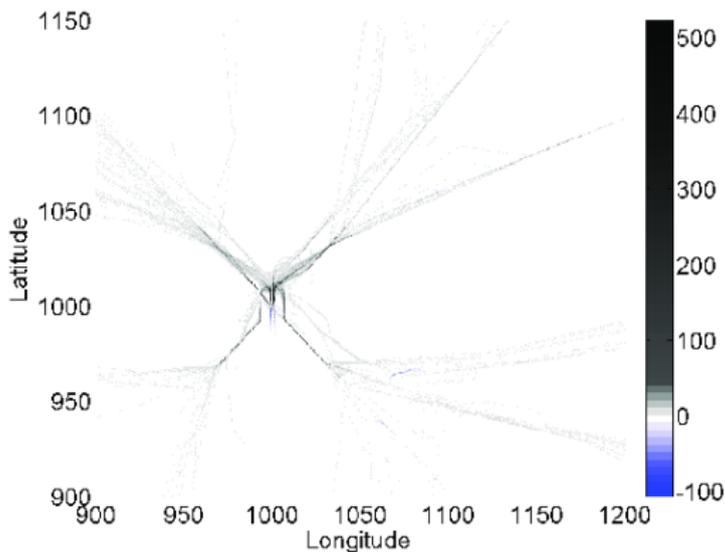
## $\mathbb{Z}_+$ -MRP On a Bad Day



# Air Traffic “Arithmetic” → dynamic air-space configuration

(G. Teng, K. Kuhn and RS, *J. Aerospace Comput., Inf. & Com.*, 9:1, 14–25, 2012.)

$\mathbb{Z}_+$ -MRP pattern for Good Day – Bad Day



## Example – Prioritised Splitting

inclusion function:  $\mathbf{g}(\mathbf{x}) = \mathbf{x}^2 + (\mathbf{x} + 1) \sin(10\pi\mathbf{x})^2 \cos(3\pi\mathbf{x})^2$

priority function:  $\psi(\rho\mathbf{v}) = \text{vol}(\rho\mathbf{v})\text{wid}(\mathbf{g}(\mathbf{x}_{\rho\mathbf{v}}))$

To 50 leaves by

$\text{RPQEnclose}^\nabla(\rho, \mathbf{g}, \psi, \bar{\ell} = 50)$

To 100 leaves by

$\text{RPQEnclose}^\nabla(\rho, \mathbf{g}, \psi, \bar{\ell} = 100)$

---

**Algorithm 8:**  $\text{RPQEnclose}^\nabla(\rho, \mathbf{g}, \psi, \bar{\ell})$ 

---

**input** :  $\rho$ , the root node of  $\mathbb{I}\mathbb{R}$ -MRP  $\mathbf{f}$  with RP  $s$ , root box  $\mathbf{x}_\rho$  and

$$\mathbf{f}_\rho = \mathbf{g}(\mathbf{x}_\rho),$$

$\psi : \mathbb{L}(s) \rightarrow \mathbb{R}$  such that

$$\psi(\rho\mathbf{v}) = \text{vol}(\mathbf{x}_{\rho\mathbf{v}}) (\mathbf{g}(\mathbf{x}_{\rho\mathbf{v}}) - 0.5(\mathbf{g}(\mathbf{x}_{\rho\mathbf{v}\mathbf{L}}) + \mathbf{g}(\mathbf{x}_{\rho\mathbf{v}\mathbf{R}}))),$$

$\bar{\ell}$  the maximum number of leaves.

**output** :  $\mathbf{f}$  with modified RP  $s$  such that  $|\mathbb{L}(s)| = \bar{\ell}$

**if**  $|\mathbb{L}(s)| < \bar{\ell}$  **then**

$$\rho\mathbf{v} \leftarrow \text{random\_sample} \left( \underset{\rho\mathbf{v} \in \mathbb{L}(s)}{\text{argmax}} \psi(\rho\mathbf{v}) \right)$$

Split  $\rho\mathbf{v}$ :  $\nabla(\rho\mathbf{v}) = \{\rho\mathbf{v}\mathbf{L}, \rho\mathbf{v}\mathbf{R}\}$  // split the sampled node

$$\mathbf{f}_{\rho\mathbf{v}\mathbf{L}} \leftarrow \mathbf{g}(\square(\mathbf{x}_{\rho\mathbf{v}\mathbf{L}}))$$

$$\mathbf{f}_{\rho\mathbf{v}\mathbf{R}} \leftarrow \mathbf{g}(\square(\mathbf{x}_{\rho\mathbf{v}\mathbf{L}}))$$

$\text{RPQEnclose}^\nabla(\rho, \psi, \bar{\ell})$

**end**

---

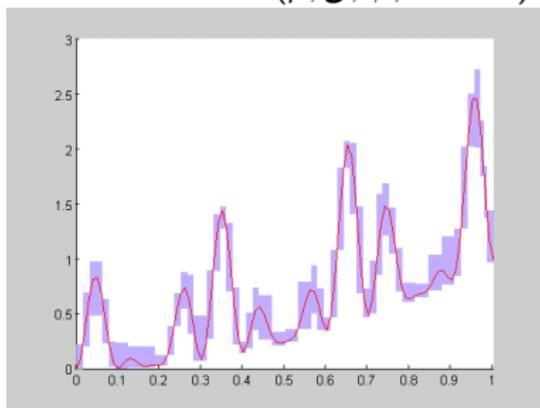
# Example - Prioritised Splitting Continued

inclusion function:  $\mathbf{g}(\mathbf{x}) = \mathbf{x}^2 + (\mathbf{x} + 1) \sin(10\pi\mathbf{x})^2 \cos(3\pi\mathbf{x})^2$

priority function:  $\psi(\rho\nu) = \text{vol}(\rho\nu)\text{wid}(\mathbf{g}(\mathbf{x}_{\rho\nu}))$

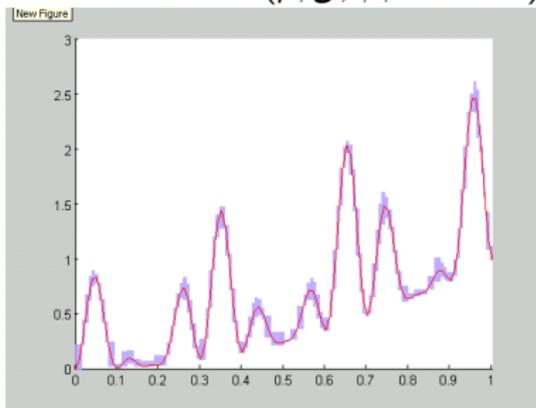
To 50 leaves by

$\text{RPQEnclose}^\nabla(\rho, \mathbf{g}, \psi, \bar{\ell} = 50)$



To 100 leaves by

$\text{RPQEnclose}^\nabla(\rho, \mathbf{g}, \psi, \bar{\ell} = 100)$



Can we get tighter enclosures using only 50 leaves by propagating the interval hull of 100-leaved  $\mathbb{IR}$ -MRP up the tree and then doing a prioritised merging of the cherries?

# Hull Propagate up the tree via $\text{HullPropagate}(\rho)$

---

**Algorithm 9:**  $\text{HullPropagate}(\rho)$ 

---

**input** :  $\rho$ , the root node of  $\mathbb{IR}$ -MRP  $\mathbf{f}$  with RP  $s$ .

**output** : Modify input MRP  $\mathbf{f}$ .

**if**  $\text{!IsLeaf}(\rho)$  **then**

$\text{HullPropagate}(\rho\text{L})$

$\text{HullPropagate}(\rho\text{R})$

$\mathbf{f}_\rho \leftarrow \mathbf{f}_{\rho\text{L}} \sqcup \mathbf{f}_{\rho\text{R}}$

**end**

---

By calling  $\text{HullPropagate}(\rho)$  on our  $\mathbb{IR}$ -MRP of Example constructed by  $\text{RPQEnclose}^\nabla(\rho, \mathbf{g}, \psi, \bar{\ell} = 100)$  we would have tightened the range enclosures of  $\mathbf{g}$  in the internal nodes.

# Prioritised Merging via $\text{RPQEnclose}^\Delta(\rho, \psi, \bar{\ell}')$

---

**Algorithm 10:**  $\text{RPQEnclose}^\Delta(\rho, \psi, \bar{\ell}')$

---

**input** :  $\rho$ , the root node of  $\mathbb{IR}$ -MRP  $\mathbf{f}$  with RP  $s$ , box  $\mathbf{x}_\rho$ ,  
 $\psi : \mathbb{C}(s) \rightarrow \mathbb{R}$  as  $\psi(\rho\mathbf{v}) = \text{vol}(\mathbf{x}_{\rho\mathbf{v}}) (\mathbf{f}_{\rho\mathbf{v}} - 0.5(\mathbf{f}_{\rho\mathbf{vL}} + \mathbf{f}_{\rho\mathbf{vR}}))$ ,  
 $\bar{\ell}'$  the maximum number of leaves.

**output** : modified  $\mathbf{f}$  with RP  $s$  such that  $|\mathbb{L}(s)| = \bar{\ell}'$  or  $\mathbb{C}(s) = \emptyset$ .

**if**  $|\mathbb{L}(s)| \geq \bar{\ell}'$  &  $\mathbb{C}(s) \neq \emptyset$  **then**

$\rho\mathbf{v} \leftarrow \text{random\_sample}(\text{argmin}_{\rho\mathbf{v} \in \mathbb{C}(s)} \psi(\rho\mathbf{v}))$  // choose a  
    random node with smallest  $\psi$

    Prune( $\rho\mathbf{L}$ )

    Prune( $\rho\mathbf{R}$ )

$\text{RPQEnclose}^\Delta(\rho, \psi, \bar{\ell}')$

**end**

---

# Example – Split, Propogating & Prune

Yes we can!

```
RPQEnclose $\nabla$ ( $\rho, \mathbf{g}, \psi, \bar{\ell} = 100$ ); HullPropagate( $\rho$ ); RPQEnclose $\Delta$ ( $\rho, \psi, \bar{\ell}' = 50$ )
```

# Conclusions

- ▶  $\mathbb{Y}$ -MRPs provide frb-tree partition arithmetic
- ▶  $\mathbb{Y}$ -MRPs allow efficient arithmetic for Neumaier's inclusion algebras
- ▶  $\mathbb{Y}$  can be  $\mathbb{IR}$  for  $\mathbf{f} : \mathbb{IR}^d \rightarrow \mathbb{IR}$
- ▶  $\mathbb{Y}$  can be  $\mathbb{IR}^m$  for  $\mathbf{f} : \mathbb{IR}^d \rightarrow \mathbb{IR}^m$
- ▶  $\mathbb{Y}$  can be  $(\mathbb{IR}, \mathbb{IR}^m, \mathbb{IR}^{m^2})$  for range, gradient & Hessian of  $\mathbf{f} : \mathbb{IR}^d \rightarrow \mathbb{IR}$
- ▶ Other obvious extensions include arithmetic over Taylor polynomial inclusion algebras
- ▶ In general the domain and range of  $\mathbf{f}$  can be complete lattices with intervals and bisection operations
- ▶ We have seen several statistical applications of  $\mathbb{Y}$ -MRPs
- ▶ CODE: *mrs: a C++ class library for statistical set processing* by Bycroft, Harlow, Sainudiin, Teng and York.

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