

Optimization of Lyapunov Exponents

RDS and MET Workshop at BIRS, Banff, Canada

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Joint work with
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Plan of the talk

- 1 Thanks to the organizers.
- 2 “Classical” ergodic optimization
- 3 Non-commutative ergodic optimization: what we would like to do
- 4 Setting: One-step cocycles and domination
- 5 A useful tool: Barabanov functions
- 6 The main result
- 7 Strategy of the proof

ERGODIC OPTIMIZATION:
FROM BIRKHOFF AVERAGES TO LYAPUNOV EXPONENTS

Ref.: Survey by O. Jenkinson (DCDS, 2006)

“Classical” ergodic optimization

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Given a continuous function $f: X \rightarrow \mathbb{R}$, let

$$M(f) := \sup_{\mu \in \mathcal{M}(T)} \int f d\mu.$$

An invariant measure for which the sup is attained is called *maximizing* for f . (They always exist.)

“Classical” Ergodic Optimization is concerned about determining $M(f)$, describing the maximizing measures μ , their properties etc.

Rem.: Connections with Classical Mechanics (Aubry–Mather...), Thermodynamical Formalism (zero temperature limits), Multifractal Analysis ...

The place where maximizing measures live

Theorem (Many authors(*), 90's, 00's)

Suppose $T: X \rightarrow X$ is “*hyperbolic*” and f is *Hölder* continuous. Then there exists a compact T -invariant set $K \subset X$ (called a “*Mather set*”) such that:

$$\mu \in \mathcal{M}(T) \text{ is maximizing} \iff \text{supp } \mu \subset K.$$

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N.B.: The result is false for C^0 functions; in this case there are examples where the maximizing measure is unique and has full support.

Proof of the existence of Mather sets

Suppose \tilde{f} is cohomologous to f , i.e.,

$$\tilde{f} = f + h \circ T - h \quad \text{for some } h$$

Then

$$M(f) = \sup_{\mu \in \mathcal{M}(T)} \int f d\mu = \sup_{\mu \in \mathcal{M}(T)} \int \tilde{f} d\mu = M(\tilde{f}).$$

μ is maximizing for $f \iff \mu$ is maximizing for \tilde{f} .

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Theorem (Mañé(*) Lemma or Revelation Lemma)

Suppose $T: X \rightarrow X$ is “**hyperbolic**” and f is **Hölder** continuous. Then $\exists \tilde{f}$ cohomologous to f such that $\tilde{f} \leq M(\tilde{f})$.

Then the maximizing measures are exactly those who live in the (Mather set) $K := \{x \in X; \tilde{f}(x) = M(\tilde{f})\}$.

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If T is “expanding” then for **generic** Lipschitz functions f :

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Related results on periodicity of maximizing measures by:

Hunt–Ott’96 (experimental), Yuan–Hunt’99, Contreras–Lopes-Thieullen’01, Bousch’01, Quas–Siefken’12. The latter deals with spaces of *super-continuous* functions over the shift.

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Theorem (B.–Zhang, preprint ArXiv 2015)

On spaces of sufficiently super-continuous functions, the conclusion of Quas–Siefken–Contreras is not only topologically generic but **prevalent** (has “full probability”).

Non-commutative Ergodic Optimization

What if instead of optimizing integrals (Birkhoff averages), we optimize Lyapunov exponents instead?

Lyapunov exponents (2×2 case)

Let $T: X \rightarrow X$ be a homeomorphism of a compact space. Let $A: X \rightarrow \text{GL}(2, \mathbb{R})$ be continuous. The pair (T, A) is called a *cocycle*. Consider “Birkhoff-like” products:

$$A^{(n)}(x) := A(T^{n-1}x) \cdots A(Tx)A(x).$$

Lyapunov exponents (2×2 case)

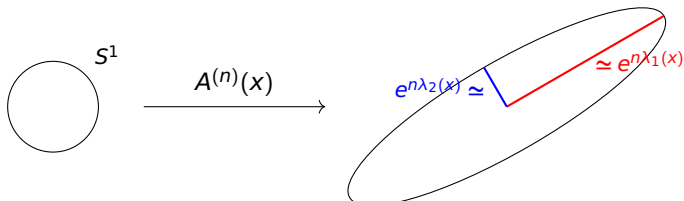
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The *upper and lower Lyapunov exponents* at the point x (if they exist) are:

$$\lambda_1(x) := \lim_{n \rightarrow +\infty} \frac{1}{n} \log \|A^{(n)}(x)\|$$

$$\lambda_2(x) := \lim_{n \rightarrow +\infty} \frac{1}{n} \log \|[A^{(n)}(x)]^{-1}\|^{-1}$$



Oseledets Theorem

Theorem (Invertible 2×2 Oseledets)

Let μ be an ergodic probability measure for T . Then there exist $\lambda_1(\mu) \geq \lambda_2(\mu)$ such that $\lambda_i(x) = \lambda_i(\mu)$ for μ -a.e. x .

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Moreover, if $\lambda_1(\mu) > \lambda_2(\mu)$ then there exists an “Oseledets splitting” $\mathbb{R}^2 = E_1(x) \oplus E_2(x)$, defined for μ -a.e. x and such that for each $i = 1, 2$:

- the spaces E_i vary measurably w.r.t. x ;
- the spaces E_i are equivariant: $A(x)(E_i(x)) = E_i(Tx)$;
- $\lim_{n \rightarrow \pm\infty} \frac{1}{n} \log \|A^{(n)}(x)v\| = \lambda_i(\mu), \quad \forall v \in E_i(x) \setminus \{0\} \quad (i = 1, 2).$

Optimization of Lyapunov exponents

Fixed cocycle (T, A) as above, let:

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- Are they unique?
- Are they characterized by their support?

Summary of the main result (B., Rams)

We will exhibit a natural open class of 2×2 cocycles for which the Lyapunov-maximizing and -minimizing measures have zero entropy.

An important source of ideas:

paper by T. Bousch, J. Mairesse (JAMS, 2002).

A SPECIAL SITUATION:
ONE-STEP COCYCLES

One-step cocycles

A cocycle (T, A) is *one-step* if:

- $T: X \rightarrow X$ is the two-sided full shift on $k \geq 2$ symbols, so

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- $A: X \rightarrow \text{GL}(2, \mathbb{R})$ only depends on the zeroth symbol. In other words, there is a list of matrices A_1, \dots, A_k such that

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(In particular, A is locally constant.)

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Equivalent setting: *Linear IFS's (iterated function systems)*.

Joint spectral radius and subradius

Equivalent *elementary* definitions of λ_1^\top , λ_1^\perp **for one-step cocycles**:

$$\lambda_1^\top = \lim_{n \rightarrow \infty} \frac{1}{n} \log \sup_{i_1, \dots, i_n} \|A_{i_1} \dots A_{i_n}\|,$$

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For one-step cocycles, the numbers $e^{\lambda_1^\top}$ and $e^{\lambda_1^\perp}$ are known as *joint spectral radius* (Rota, Strang 1960) and *joint spectral subradius* (Gurvits, 1995) of the set of matrices $\{A_1, \dots, A_k\}$.

Applications in wavelets, control theory ...

The finiteness conjecture on the Joint spectral radius

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The conjecture was shown to be **false** by Bousch and Mairesse (2002); their counterexamples are pairs of matrices in $GL(2, \mathbb{R})$ such that the maximizing measures are **sturmian** but not periodic.

Domination for one-step cocycles

An one-step cocycle is called *dominated* if the Lyapunov exponents are uniformly separated, for all invariant measures. In other words,

$$(\lambda_1 - \lambda_2)^+(A) := \inf_{\mu \in \mathcal{M}_{\text{erg}}(T)} (\lambda_1(A, \mu) - \lambda_2(A, \mu))$$

is positive.


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Example (Perron–Frobenius theorem)

Each A_i is an (entrywise) **positive** matrix \Rightarrow the cocycle is dominated.

Domination for one-step cocycles: notes

Recall: An one-step cocycle is called *dominated* if $(\lambda_1 - \lambda_2)^\perp > 0$.

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- In the area-preserving case (2×2 matrices with determinant ± 1), domination is equivalent to the familiar notion of *uniform hyperbolicity*.
- Domination is a natural weakening of uniform hyperbolicity and is important smooth dynamics (e.g. in partial hyperbolicity).
- It's also weaker than exponential dichotomy.

Domination for one-step cocycles: geometrical viewpoint

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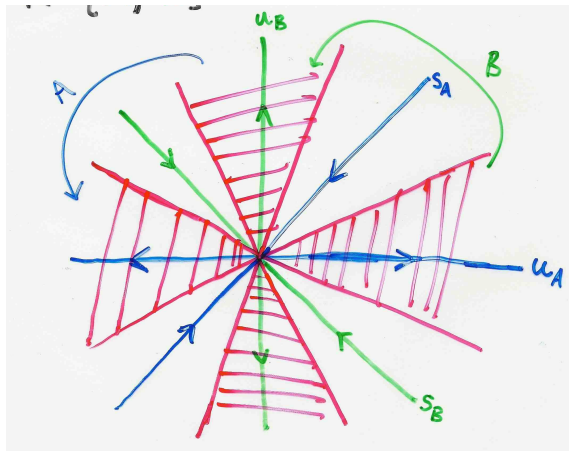
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Theorem (Avila, B., Yoccoz)

An one-step cocycle is dominated IFF it has a multicone.

Consequence: domination is an open condition. (This is also true for more general cocycles.)

The simplest example where the multicone cannot be taken as a cone is:



$$A_1 = A, A_2 = B.$$

Examples with complicated combinatorics: see [Avila-B.-Yoccoz]

BARABANOV FUNCTIONS
FOR DOMINATED ONE-STEP COCYCLES:
An analogue of the Mañé revelation lemma

Barabanov functions

Assume given an one-step dominated cocycle, with a multicone M . Let $\vec{M} := \{v \in \mathbb{R}^2; v = 0 \text{ or } \mathbb{R} \cdot v \in M\}$ be the “support” of M .

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Proposition (Existence of a Barabanov function)

There exists a continuous function $\|\cdot\|: \vec{M} \rightarrow [0, \infty)$ such that for every $v \in \vec{M}$, $t \in \mathbb{R}$ we have

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We call $\|\cdot\|$ an *upper Barabanov function*.

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Consequence: For any $v \in \vec{M}$, we can find recursively symbols $i_1, i_2, \dots \in \{1, \dots, k\}$ such that

$$\|A_{i_n} \cdots A_{i_1}(v)\| = e^{n\lambda_1^\top} \|v\|.$$

Barabanov functions

Upper Barabanov function:

$$\|tv\| = |t| \|v\|, \quad \max_{i \in \{1, \dots, k\}} \|A_i v\| = e^{\lambda_1^\top} \|v\|.$$

- Actually (even without domination) there is a true norm $\|\cdot\|$ in \mathbb{R}^2 with the properties above; it is called *Barabanov norm* (1988).

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- Actually (even without domination) there is a true norm $\|\cdot\|$ in \mathbb{R}^2 with the properties above; it is called *Barabanov norm* (1988).
- There is also a *lower Barabanov function* $\|\cdot\|'$ such that

$$\|tv\|' = |t| \|v\|', \quad \min_{i \in \{1, \dots, k\}} \|A_i v\|' = e^{\lambda_1^\dagger} \|v\|'.$$

In this case the domination hypothesis is really needed.

- Higher dimension: see [B.–Morris, Proc. LMS (to appear)].

Proof of existence of Barabanov functions

We apply Schauder fixed point theorem to an appropriate space of Lipschitz functions (with respect to the Hilbert metric) on the multicone . . .

BTW, this proof also gives a Lipschitz property for $\|\cdot\|$, which is also useful.

Mather sets

Proposition

If an one-step cocycle is **dominated** then there are nonempty compact shift-invariant sets $K^\top, K^\perp \subset k^\mathbb{Z}$ s.t. for every shift-invariant measure μ ,

$$\text{supp } \mu \subset K^\top \Leftrightarrow \lambda_1(\mu) = \lambda_1^\top, \quad \text{supp } \mu \subset K^\perp \Leftrightarrow \lambda_1(\mu) = \lambda_1^\perp$$

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(In particular, there exist Lyapunov-optimizing measures.)

Proof:

$$K^\top := \left\{ \xi \in X; u \in E_1(\xi), n \in \mathbb{Z} \Rightarrow \|A^{(n)}(\xi)(u)\| = e^{n\lambda_1^\top} \|u\| \right\}.$$

Rem.: The proposition above should also follow from the “classical” (commutative) theory applied to the function $f := \log \|A|E_1\|$. Anyway, our Barabanov functions will be fundamental for what we will do next.

OUR MAIN RESULT

Non-overlapping condition

We say that the matrices A_1, \dots, A_k satisfy *forward nonoverlapping condition* (NOC⁺) if they admit a multicone M such that

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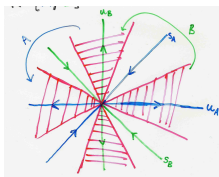
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We say that the matrices A_1, \dots, A_k satisfy *backwards nonoverlapping condition* (NOC^-) if $\{A_1^{-1}, \dots, A_k^{-1}\}$ satisfy the forward nonoverlapping condition.

If both conditions hold then we say that the matrices satisfy the *nonoverlapping condition* (NOC).



Example: The one in a previous figure:

The main theorem

Theorem (B., Rams)

If an **one-step** cocycle is **dominated** and satisfies the **non-overlapping** condition

The main theorem

Theorem (B., Rams)

If an **one-step** cocycle is **dominated** and satisfies the **non-overlapping** condition then the sets K^+ , K^- have **zero topological entropy**.

In particular, the optimizing measures have zero entropy.

Remarks

- The zero entropy measures that appear in the theorem are **not necessarily supported on periodic orbits** (\exists examples by Bousch–Mairesse and others).
- Neither they are necessarily unique.
- The non-overlapping condition is indeed required: for example, if $A_1 = A_2$ then there are optimal measures with positive entropy.
- We think that a more general theorem holds, with $T =$ subshift of finite type, $A =$ locally constant cocycle, but we haven't checked the details.

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In other words, does a matrix version of Contreras theorem hold?
- What about **higher dimension**?

There is much more to be done in this subject!

PROOF OF THE THEOREM

Oseledets directions

Given a bi-infinite word $\xi \in X = k^{\mathbb{Z}}$, split it as $\xi = (\xi_-, \xi_+) \in k^{\mathbb{Z}_-} \times k^{\mathbb{Z}_+}$, where $\mathbb{Z}_- = \{\dots, -2, -1\}$ and $\mathbb{Z}_+ = \{0, 1, \dots\}$.

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The first Oseledets direction only depends on the past, while the second one only depends on the future:

$$E_1(\xi) = E_1(\xi_-), \quad E_2(\xi) = E_2(\xi_+).$$

Some facts about the sets of directions

$$C_1 := \{E_1(\xi_-); \xi \in k^{\mathbb{Z}^-}\}, \quad C_2 := \{E_2(\xi_+); \xi \in k^{\mathbb{Z}^+}\}.$$

$$M \text{ is a multicone} \Rightarrow C_1 = \bigcap_{n=1}^{\infty} \bigcup_{i_1, \dots, i_n} A_{i_1} \cdots A_{i_n}(M) \quad (\text{nested})$$

Proof: $E_1(\xi_-)$ appears when we take $i_j = \xi_{-j}$.

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forward non-overlapping condition (NOC⁺)



$E_1: k^{\mathbb{Z}^-} \rightarrow C_1$ **is a bijection.**



C_1 **is a Cantor set.**

Analogously for $E_2: k^{\mathbb{Z}^+} \rightarrow C_1$.

Main proposition

Proposition (E_1 determines E_2 a.s.)

Suppose that the cocycle satisfies the forward non-overlapping condition (NOC^+).

Let μ be an ergodic measure such that $\lambda_1(\mu) = \lambda_1^\top$ or λ_1^\perp .

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Let μ be an ergodic measure such that $\lambda_1(\mu) = \lambda_1^\top$ or λ_1^\perp . Then for μ -a.e. $\xi \in X$, the direction $E_1(\xi_-)$ is uniquely determined the direction $E_2(\xi_+)$.

Main Proposition \Rightarrow Theorem

Suppose that the cocycle satisfies the non-overlapping condition ($\text{NOC}^+ + \text{NOC}^-$). Let μ be an ergodic measure supported in K^\top , that is, $\lambda_1(\mu) = \lambda_1^\top$.

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Then **for μ -a.e. $\xi \in X$, the past ξ_- uniquely the future ξ_+ :**

$$\begin{array}{ccc} \xi_- & & \xi_+ \\ \downarrow & & \uparrow \text{NOC}^- \\ E_1(\xi_-) & \xrightarrow[\text{NOC}^+]{\text{Proposition}} & E_2(\xi_+) \end{array}$$

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This implies that $h(\mu) = 0$, for all μ supported in K^\top .

By the Entropy Variational Principle, $h_{\text{top}}(K^\top) = 0$. Analogously for K^\perp .

This proves the Theorem modulo the Proposition.

PROOF OF THE MAIN PROPOSITION

Cross ratio

Given nonzero vectors $u, v, u', v' \in \mathbb{R}^2$, (no three of them being collinear), we define their *cross ratio*:

$$[u, v; u', v'] := \frac{u \times u'}{u \times v'} \cdot \frac{v \times v'}{v \times u'} \in \mathbb{R} \cup \{\infty\},$$

where \times is the cross product on \mathbb{R}^2 (that is, determinant).

Actually the value above only depends on the directions determined by the vectors. So we can define the cross ratio of four points in \mathbb{P}^1 .

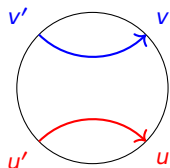
The cross ratio is invariant by linear isomorphisms.

Configurations of four points in \mathbb{P}^1

Let $u, v, u', v' \in \mathbb{P}^1$ be distinct. The configuration is called *co-parallel*, *crossing* or *anti-parallel* according to the value of the cross ratio $[u, v; u', v']$ as follows:

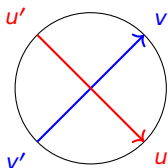
Co-parallel

$$0 < [u, v; u', v'] < 1$$



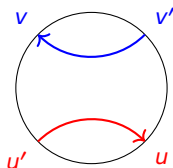
Crossing

$$[u, v; u', v'] > 1$$



Anti-parallel

$$[u, v; u', v'] < 0$$



Restrictions among the Oseledets directions

Lemma (Geometrical Lemma)

$K^T, K^\perp =$ Mather sets of an 1-step dominated cocycle.

$$\begin{aligned} \text{Then } \xi, \eta \in K^T &\Rightarrow |[E_1(\xi), E_1(\eta); E_2(\xi), E_2(\eta)]| \geq 1, \\ \xi, \eta \in K^\perp &\Rightarrow |[E_1(\xi), E_1(\eta); E_2(\xi), E_2(\eta)]| \leq 1. \end{aligned}$$

In particular:

Restrictions among the Oseledets directions

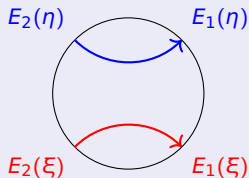
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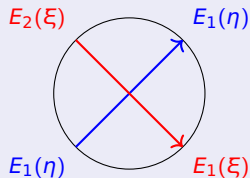
$$\begin{aligned} \text{Then } \xi, \eta \in K^\top &\Rightarrow |[E_1(\xi), E_1(\eta); E_2(\xi), E_2(\eta)]| \geq 1, \\ \xi, \eta \in K^\perp &\Rightarrow |[E_1(\xi), E_1(\eta); E_2(\xi), E_2(\eta)]| \leq 1. \end{aligned}$$

In particular:

co-parallel configuration
is **forbidden** in K^\top :



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Consequences of the Geometrical Lemma

Consider the set $G := \{(E_1(\xi), E_2(\xi)); \xi \in K^\top\} \subset \mathbb{P}^1 \times \mathbb{P}^1$.

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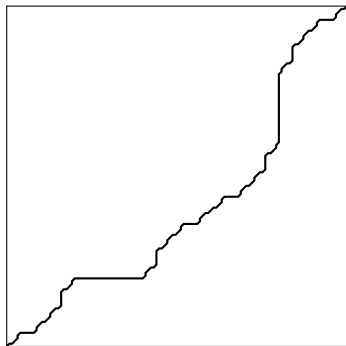
Since the co-parallel configuration is forbidden, the set G has a **monotonicity property**: if E_1 moves clockwise then so does E_2 .

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Since the co-parallel configuration is forbidden, the set G has a **monotonicity property**: if E_1 moves clockwise then so does E_2 .

This implies that G is a graph (above its projection), with the exception to an at most countable numbers of “plateaux” and “cliffs”:



Geometrical Lemma \Rightarrow Main Proposition

Recall the Main Proposition

Proposition

$\text{NOC}^+ \Rightarrow E_1$ determines E_2 almost surely with respect to any λ_1 -maximizing or -minimizing measure.

Let μ be an ergodic non-periodic (and so non-atomic) measure supported in K^\top . (The periodic case is trivial.)

Then the (countable) union of plateaux and cliffs in G is the image under (E_1, E_2) of a set of zero μ -measure. (Here we need the NOC^+ .)

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The case of K^\perp is similar (but extra care is needed: monotonicity is only local).

Summary

As explained before, we obtain zero entropy since **the past** ξ_- **uniquely the future** ξ_+ μ -**a.e.**:

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Barabanov functions



Geometrical Lemma (cross-ratios, forbidden configurations)



Main Proposition

THE END (?)

PROOF OF THE GEOMETRICAL LEMMA

Some important ideas in the proof come from the 2002 paper by Bousch and Mairesse (counter-examples to the finiteness conjecture).

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Lemma (Geometrical Lemma)

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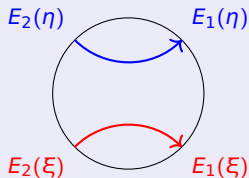
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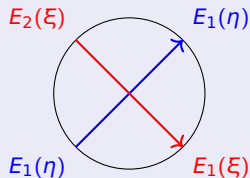
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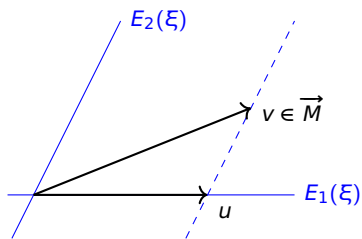
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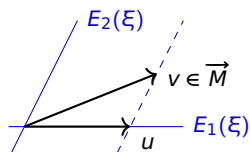
An important estimate

Lemma

Let $\xi \in K^\top$, $u \in E_1(\xi)$. Let $v \in \vec{M}$ be such that $u - v \in E_2(\xi)$.
Then $\|u\| \leq \|v\|$.

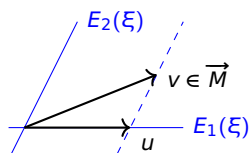


Proof of the “important estimate” Lemma



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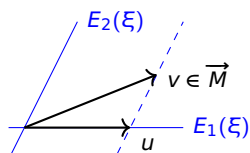
$$u_n := A^{(n)}(\xi)(u) \Rightarrow \|u_n\| = e^{n\lambda_1^T} \|u\|$$

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and so:

$$\frac{\|v\|}{\|u\|} \geq \frac{\|v_n\|}{\|u_n\|} =: Q_n$$

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
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To prove the Lemma we show that $\boxed{Q_n \rightarrow 0}$ as $n \rightarrow +\infty$.

That's easy, using that that $\angle(u_n, v_n) \rightarrow 0$ exponentially fast and “Lipschitz property” of the Barabanov norms.

Proof of the Geometrical Lemma

Assume for a contradiction that $\xi, \eta \in K^T$ are in co-parallel

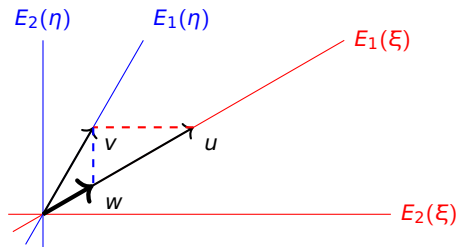
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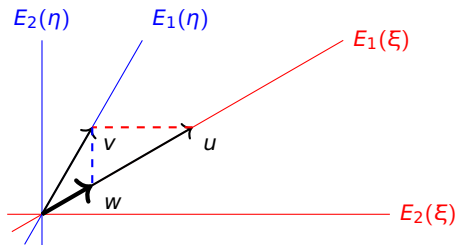
(Rem.: hidden cross-ratio)

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(Rem.: hidden cross-ratio)

Apply the “important estimate” twice:

$$\|u\| \leq \|v\| \leq \|w\|. \quad \text{Contradiction!}$$