

# Path-space information metrics and variational inference for non-equilibrium coarse-grained systems.

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# Coupled Mathematical Models for Physical and Biological Nanoscale Systems, Banff, Aug 28–Sep 1, 2016



## Collaborators:

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  - ▶ V. Harmandaris, E. Kalligiannaki (University of Crete)
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## Funding: Department of Energy, Applied Mathematics

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References: <http://www.math.udel.edu/~plechac>

- ▶ E. Kalligiannaki, A. Chazirakis, M.A. Katsoulakis, P. Plecháč, V. Harmandaris: *Parametrizing coarse-grained models for molecular systems*, Eur. Phys. J. (2016)
- ▶ V. Harmandaris, E. Kalligiannaki, M.A. Katsoulakis, P. Plecháč: *Path-space variational inference for non-equilibrium coarse-grained systems*, J. Comp. Phys. 314 (2016) 355-383
- ▶ P. Dupuis, M.A. Katsoulakis, Y. Pantazis, P. Plecháč *Path-space information bounds for uncertainty quantification and sensitivity analysis of stochastic dynamics*, SIAM/ASA J. Uncertainty Quantification, 4 (2016), 80-111
- ▶ V. Harmandaris, E. Kalligiannaki, M.A. Katsoulakis, P. Plecháč: *The geometry of generalized force matching in coarse-graining and related information metrics* J. Chem. Phys. 143, 084105 (2015)



# Outline

- ▶ Relative entropy, relative entropy rate, duality and bounds
- ▶ Coarse-graining & Parameterization
- ▶ Non-equilibrium steady states & Path Space Relative Entropy
- ▶ Coarse-graining & Parameterization – NESS
- ▶ Data driven coarse-graining
- ▶ Examples

# Coarse-graining, model error and parametrization

Two probabilistic models  $P$  and  $Q$  on the common measurable space  $(\Omega, \mathcal{B})$

## Applications:

- ▶ reaction networks
- ▶ spatially heterogeneous chemical kinetics,
- ▶ molecular systems at equilibrium or  
with non-equilibrium steady states

Goal: extend empirical information theory techniques for path-space application

- ▶ Discrimination between the two models – distance

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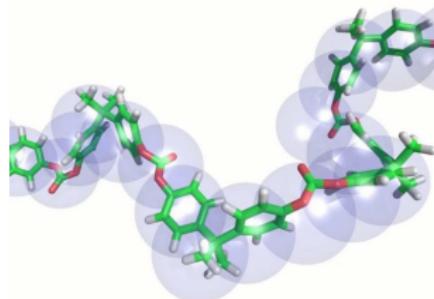
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- ▶ Parameter identifiability in parameterized models  $P^\theta$
- ▶ “Best-fit” for coarse-grained models.

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# Coarse-Graining – Reduced molecular models

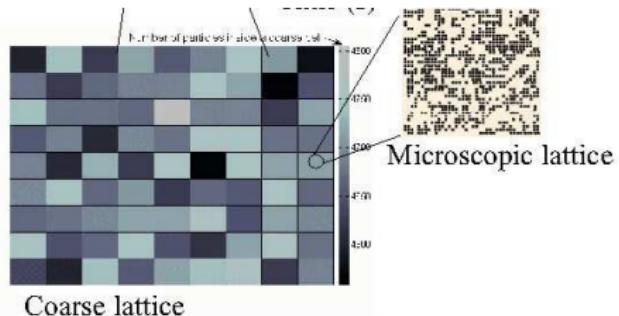
## 1. Coarse-graining of polymers; DPD

Briels, et. al. *J.Chem.Phys.* '01;  
Müller-Plathe *Chem.Phys.Chem* '02;  
Laaksonen et. al. *Soft Matter* '03;  
Kremer et al. *Macromolecules* '06  
Deserno et. al. *Nature* '07;  
Espanol *J Chem. Phys.* '07, '11;  
Shell *J. Chem. Phys.* '12;  
Noid *J Chem. Phys.* '13



## 2. Stochastic lattice dynamics

Katsoulakis, Majda, Vlachos, *PNAS*'03;  
Katsoulakis, P.P., Sopasakis, *SIAM Num. Anal.* '06;  
Are, Katsoulakis, P.P., Rey-Bellet *SIAM J.Sci.Comp.* '08;  
Sinno et al. *J.Chem.Phys.*'08, '13, *PRE* '12



# Coarse-grained models and variational inference

- ▶ coarse-graining map;  $\mathbf{T} : \Sigma \rightarrow \bar{\Sigma}$ ,  $P \mapsto \bar{P} = \mathbf{T}_* P$
- ▶ exactly coarse-grained model  $\bar{P}$  intractable
- ▶  $\bar{P}$  approximated from a tractable, parametrized family  $\bar{Q}^\theta$
- ▶ minimize a “distance” between  $\bar{P}$  and  $\bar{Q}^\theta$

$$\min_{\theta \in \Theta} \text{dist}(\bar{P}, \bar{Q}^\theta)$$

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<sup>1</sup> $P = \mu$  equilibrium distrib.; Shell (2008,2011), Noid, (2011,2013), Bilionis, Koustsourelakis (2012), Zabarasz et al. (2013)

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$$\min_{\theta \in \Theta} \text{dist}(\bar{P}, \bar{Q}^\theta)$$

- ▶ Choice of  $\text{dist}(\cdot, \cdot)$  ?
  - ▶ Model based (information theoretic):  $\text{dist} = \text{relative entropy}$

$$\min_{\theta \in \Theta} \mathcal{R}(P | \mathbf{T}_*^\dagger \bar{Q}^\theta) \quad \text{or} \quad \min_{\theta \in \Theta} \mathcal{R}(\mathbf{T}_* P | \bar{Q}^\theta)$$

- ▶ Observable based (QoI):  $\{\phi_1, \phi_2, \dots, \phi_n\}$

$$\min_{\theta \in \Theta} \sum_i |\mathbb{E}_P[\phi_i] - \mathbb{E}_{\bar{Q}^\theta}[\phi_i]|^2$$

Example: radial distribution function, forces  $f = -\nabla U$

<sup>1</sup> $P$  =  $\mu$  equilibrium distrib.; Shell (2008,2011), Noid, (2011,2013), Bilionis, Koustsourelakis (2012), Zabarás et al. (2013)

# Why information-based methods ?

Relative Entropy and  $\mathcal{R}$ -projections

- Pseudo-distance (Kullback-Leibler divergence)

$$\mathcal{R}(P | Q) = \int \log \left( \frac{dP}{dQ} \right) dP$$

for  $P \ll R, Q \ll R$      $\mathcal{R}(P | Q) = \int p_R \log \left( \frac{p_R}{q_R} \right) dR$

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- $\mathcal{R}$ -geometry of probability distributions  $\mathcal{B}(R, \rho) = \{P | \mathcal{R}(P | R) < \rho\}$   
 $\mathcal{R}$ -projection on  $\mathcal{A}$  convex, TV closed,  $\mathcal{A} \cap \mathcal{B}(R, \rho) \neq \emptyset$  (Kullback, Csiszár)

$$\mathcal{R}(Q | R) = \min_{P \in \mathcal{A}} \mathcal{R}(P | R)$$

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- “Geometry”: tangent hyperplane to  $\mathcal{B}(R, \rho)$  at  $Q$ ,  $\rho = \mathcal{R}(Q | R)$

$$P \text{ s.t. } \int \log \frac{dQ}{dR} dP = \rho, \quad \mathcal{R}(P | R) = \mathcal{R}(P | Q) + \mathcal{R}(Q | R)$$

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- Properties: (i)  $\mathcal{R}(P | Q) \geq 0$  and  
(ii)  $\mathcal{R}(P | Q) = 0$  iff  $P = Q$  a.e.
- The “best fit” in relative entropy:  $\min_{Q \in \mathcal{A}} \mathcal{R}(P | Q)$   
modeling error + numerical error + statistical error  
Modelling error  $\sim \mathcal{R}(P | Q) \sim \epsilon^\alpha$   
Bounds on the weak error:

$$|\mathbb{E}_P[f] - \mathbb{E}_Q[f]| \leq C_f \Phi(\mathcal{R}(P | Q))$$

# Bounding the error

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- ▶ Csiszár  $\phi$ -divergences, convex  $\phi : \mathbb{R}^+ \rightarrow \mathbb{R}$  with  $\phi(1) = 0$

$$\mathcal{R}_\phi(Q | P) = \begin{cases} \int \phi\left(\frac{dQ}{dP}(\omega)\right) P(d\omega), & \text{if } Q \ll P \text{ and } \phi\left(\frac{dQ}{dP}\right) \text{ is } P\text{-integrable} \\ +\infty & \text{otherwise,} \end{cases}$$

- ▶  $\phi(x) = x \log x$  – relative entropy (Kullback-Leibler divergence)
- ▶  $\phi(x) = (x - 1)^2$  –  $\chi^2$ -divergence

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- ▶ Csiszár-Kullback-Pinsker inequality:  $\|P - Q\|_{\text{TV}} \leq \sqrt{2\mathcal{R}(P | Q)}$

$$|\mathbb{E}_P[f] - \mathbb{E}_Q[f]| \leq \|f\|_\infty \sqrt{2\mathcal{R}(P | Q)}$$

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- ▶  $\mathcal{R}(P | Q) \leq \chi^2(P | Q)$

CG: Error Quantification and Parameterization using RE in molecular simulations:

Katsoulakis, P.P. Sopasakis (2006), M.S. Shell (2008), Katsoulakis, P.P., Rey-Bellet, Tsagkarogiannis (07, 08, 09), M.S. Shell (08,12), Bilionis et al (12), Zabararas et al (13), M. Katsoulakis, P.P. (2013) (dynamics, non-equilibrium), Luskin, Simpson, Srolovitz (2015)

# Variational error bounds

Error estimate of the type:

$$|\mathbb{E}_P[f] - \mathbb{E}_Q[f]| \leq C_f \Phi(\mathcal{R}(P | Q))$$

Variational representation of  $\mathcal{R}(P | Q)$  and log-moment generating function

$$\Lambda_{P,f}(c) \equiv \frac{1}{c} \log \mathbb{E}_P[e^{cf}] = \sup_{Q \in \mathcal{P}(\Omega)} \left\{ \mathbb{E}_Q[f] - \frac{1}{c} \mathcal{R}(Q | P) \right\}$$

For  $f - \mathbb{E}_P[f]$  tight variational bounds

$$\begin{aligned} \sup_{c>0} \left\{ -\frac{1}{c} \tilde{\Lambda}_{P,f}(-c) - \frac{1}{c} \mathcal{R}(Q | P) \right\} &\leq \mathbb{E}_Q[f] - \mathbb{E}_P[f] \leq \\ &\leq \inf_{c>0} \left\{ \frac{1}{c} \tilde{\Lambda}_{P,f}(c) + \frac{1}{c} \mathcal{R}(Q | P) \right\} \end{aligned}$$

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$$\inf_{c>0} \left\{ \frac{1}{c} \tilde{\Lambda}_{P,f}(c) + \frac{1}{c} \rho^2 \right\} \equiv (\tilde{\Lambda}_{P,f}^*)^{-1}(\rho^2)$$

$$\text{unique minimizer } c^*(\rho) = c_1^* \rho + \mathcal{O}(\rho^2), \quad c_1^* = \sqrt{\frac{2}{\text{Var}_P[f]}}.$$

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<sup>1</sup>P. Dupuis, M. Katsoulakis, Y. Pantazis, P.P. SIAM JUQ (2016)

# Variational error bounds

Error estimate:

$$|\mathbb{E}_P[f] - \mathbb{E}_Q[f]| \leq (\tilde{\Lambda}_{P,f}^*)^{-1}(\mathcal{R}(Q|P))$$

Asymptotics using  $c^*(\rho) = \sqrt{\frac{2}{\text{Var}_P[f]}}\rho + \mathcal{O}(\rho^2)$

$$|\mathbb{E}_Q[f] - \mathbb{E}_P[f]| \leq \sqrt{\text{Var}_P[f]} \sqrt{2\mathcal{R}(Q|P)} + \mathcal{O}(\mathcal{R}(Q|P)),$$

Stability/Sensitivity estimate:  $Q = P^{\theta+\epsilon}$ ,  $P = P^\theta$

$$|\mathbb{E}_{P^{\theta+\epsilon}}[f] - \mathbb{E}_{P^\theta}[f]| \leq \sqrt{\text{Var}_{P^\theta}[f]} \sqrt{\mathbf{F}(P^\theta)} \epsilon + \mathcal{O}(|\epsilon|^2)$$

Fisher Information Matrix:  $\mathbf{F}(P^\theta)_{ij} = \int \frac{\partial p_R^\theta}{\partial \theta_i} \frac{\partial p_R^\theta}{\partial \theta_j} p_R^\theta dR$

# Path-space error estimates

- Measurable functional  $\mathcal{F}$  of the process  $\{X_t\}_{t \geq 0}$

$$|\mathbb{E}_{Q[0,T]}[\mathcal{F}] - \mathbb{E}_{P[0,T]}[\mathcal{F}]| \leq \sqrt{\frac{1}{T} \text{Var}_{P[0,T]}[T\mathcal{F}]} \sqrt{\frac{2}{T} \mathcal{R}(Q_{[0,T]} | P_{[0,T]})} \\ + \mathcal{O}\left(\frac{1}{T} \mathcal{R}(Q_{[0,T]} | P_{[0,T]})\right)$$

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- ▶ Stationary process ( $T \rightarrow \infty$ )

$$\frac{1}{T} \mathcal{R}(Q_{[0,T]} | P_{[0,T]}) = \mathcal{H}(q | p) + \frac{1}{T} \mathcal{R}(\mu | \nu)$$

$$|\mathbb{E}_{Q_{[0,T]}}[\mathcal{F}] - \mathbb{E}_{P_{[0,T]}}[\mathcal{F}]| \leq \sqrt{\frac{1}{T} \text{Var}_{P_{[0,T]}}[T\mathcal{F}]} \sqrt{2\mathcal{H}(q | p) + \frac{2}{T} \mathcal{R}(\mu | \nu)} + \text{h.o.t.}$$

- ▶ Ergodic-type observables:  $\mathcal{F}(X) = \frac{1}{T} \int_0^T f(X_t) dt$

$$|\mathbb{E}_{Q_{[0,T]}}[\mathcal{F}] - \mathbb{E}_{P_{[0,T]}}[\mathcal{F}]| \leq \sqrt{\tau_T(f)} \sqrt{2\mathcal{H}(q|p) + \frac{2}{T}\mathcal{R}(\mu|\nu) + \text{h.o.t.}}$$

Integrated Autocorrelation Time (IAT)

$$\tau(f) = \lim_{T \rightarrow \infty} \tau_T(f) = \text{Var}_{\mu}^{\theta}[f] + 2 \sum_{k=1}^{\infty} A_f(k)$$

$$A_f(k) = \mathbb{E}_{P_{[0,T]}^{\theta}}[(f(X_0) - \mathbb{E}_{\mu^{\theta}}[f(X_0)])(f(X_k) - \mathbb{E}_{\mu^{\theta}}[f(X_0)])]$$

- ▶ as  $T \rightarrow \infty$   
perturbations  $\epsilon = |\epsilon| e$  of the invariant measure  $\mu^{\theta}$

$$\frac{1}{|\epsilon|} |\mathbb{E}_{\mu^{\theta+\epsilon e}}[f] - \mathbb{E}_{\mu^{\theta}}[f]| \leq \sqrt{\tau(f)} \sqrt{e^T \mathbf{F}_{\mathcal{H}}(p^{\theta}) e} + \mathcal{O}(\epsilon)$$

# Parametrized CG – Equilibrium

- Invariant distribution  $\mu \sim e^{-\beta H(\sigma)}$
- Detailed balance for the coarse-grained process w.r.t.  $\bar{\mu} \sim e^{-\beta \bar{H}(\eta)}$
- Coarse-grained Hamiltonian  $\bar{H}(\eta)$
- Parametrized approximation

$$\min_{\theta} \mathcal{R}(\mu | \mu^{\text{app}}(\theta)) \quad \text{or} \quad \min_{\theta} \mathcal{R}(\mu^{\text{app}}(\theta) | \mu)$$

Gibbs structure allows explicit calculations of  $\mathcal{R}$

$$\mathcal{R}(\bar{\mu} | \bar{\mu}^{(0)}) \sim \mathbb{E}_{\mu}[\beta(\bar{H}^{(0)}(\theta) - H)] + \log \frac{\bar{Z}^0(\theta)}{Z}$$

Optimality condition:  $\nabla_{\theta} \mathcal{R} = 0$

- Solution using typically gradient methods, Newton-Raphson, etc: <sup>1</sup>
- Is the parametric family  $\bar{H}^{(0)}(\theta)$  rich enough? <sup>2</sup>  
Multi-body Hamiltonians, Cluster expansions etc

<sup>1</sup>M.S. Shell (2008, 2012), Bilionis et al (2012), Zabararas et al (2013), Noid (2013)

<sup>2</sup>Katsoulakis, P.P., Rey-Bellet (2008)

# Coarse-graining non-equilibrium systems

- ▶ focus on systems with steady states
- ▶ Non-equilibrium steady state (NESS)  $\neq \text{const. } e^{-\beta H(\sigma)}$ 
  - ▶ systems driven by external fields, boundary conditions etc.
  - ▶ reaction networks
  - ▶ polymer flows
  - ▶ heterogeneous reaction systems with multiple mechanisms:  
reaction-diffusion-adsorption-desorption
- ▶ Find the “best-fit” coarse-grained Markovian approximation  
possibly non-Markovian – estimate memory kernels in Mori-Zwanzig formalism.

# Non-equilibrium steady states

Example: Continuous-time jump process (KMC)

$$\partial_t P(\sigma, t; \zeta) = \sum_{\sigma'} [c(\sigma', \sigma)P(\sigma', t; \zeta) - c(\sigma, \sigma')P(\sigma, t; \zeta)] ,$$

Stationary states:  $\partial_t P = 0 \implies \sum_{\sigma'} \mathbf{j}_s(\sigma', \sigma) = 0$

Current  $\sigma' \rightarrow \sigma$ :  $\mathbf{j}_s(\sigma', \sigma) = c(\sigma', \sigma)\mu(\sigma') - c(\sigma, \sigma')\mu(\sigma)$

Reversible dynamics with the equilibrium  $\mu(\sigma)$

Detailed Balance condition with respect to  $\mu(\sigma)$  (e.g.,  $\mu \sim e^{-\beta H(\sigma)}$ )

$$c(\sigma', \sigma)\mu(\sigma') = c(\sigma, \sigma')\mu(\sigma)$$

Irreversible dynamics  $\implies$  Non-equilibrium steady states

$$\sum_{\sigma'} \mathbf{j}_s(\sigma', \sigma) = \sum_{\sigma'} (c(\sigma', \sigma)\mu(\sigma') - c(\sigma, \sigma')\mu(\sigma)) = 0$$

irreversible rate loops, i.e., a non-zero current at stationary states.

# Relative entropy on the path space

- ▶ Markov chains on  $\Sigma$ :  
 $\{\sigma_n\}_{n \in \mathbb{Z}^+}$ ,  $P^\theta(\sigma, d\sigma)$ ,  $\mu^\theta(\sigma)$
- ▶ Approximating Markov chain  $\{\tilde{\sigma}_n\}_{n \in \mathbb{Z}^+}$ ,  $\tilde{P}^\theta(\sigma, d\sigma)$ ,  $\tilde{\mu}^\theta(\sigma)$
- ▶ Path measures:

$$Q^\theta(\sigma_0, \dots, \sigma_M) = \mu^\theta(\sigma_0) p^\theta(\sigma_0, \sigma_1) \dots p^\theta(\sigma_{M-1}, \sigma_M)$$

- ▶ Radon-Nikodym derivative

$$\frac{dQ^\theta}{d\tilde{Q}^\theta}(\{\sigma_n\}) = \frac{\mu^\theta(\sigma_0) \prod_{i=0}^{M-1} p^\theta(\sigma_i, \sigma_{i+1})}{\tilde{\mu}^\theta(\sigma_0) \prod_{i=0}^{M-1} \tilde{p}^\theta(\sigma_i, \sigma_{i+1})}$$

- ▶ Relative entropy

$$\mathcal{R}(Q^\theta | \tilde{Q}^\theta) = \int_{\Sigma^M} \mu^\theta(\sigma_0) \prod_{i=0}^{M-1} p^\theta(\sigma_i, \sigma_{i+1}) \log \frac{\mu^\theta(\sigma_0) \prod_{i=0}^{M-1} p^\theta(\sigma_i, \sigma_{i+1})}{\tilde{\mu}^\theta(\sigma_0) \prod_{i=0}^{M-1} \tilde{p}^\theta(\sigma_i, \sigma_{i+1})} d\sigma$$

# Relative entropy decomposition and scaling

$$\begin{aligned} \mathcal{R}(Q^\theta | \tilde{Q}^\theta) &= \int_{\Sigma} \cdots \int_{\Sigma} \mu^\theta(\sigma_0) \prod_{i=0}^{M-1} p^\theta(\sigma_i, \sigma_{i+1}) \left( \log \frac{\mu^\theta(\sigma_0)}{\tilde{\mu}^\theta(\sigma_0)} \right. \\ &\quad \left. + \sum_{i=0}^{i=M-1} \log \frac{p^\theta(\sigma_i, \sigma_{i+1})}{\tilde{p}^\theta(\sigma_i, \sigma_{i+1})} \right) d\sigma_0 \dots d\sigma_M \end{aligned}$$

# Relative entropy decomposition and scaling

$$\begin{aligned}\mathcal{R} \left( Q^\theta \mid \tilde{Q}^\theta \right) &= \int_{\Sigma} \cdots \int_{\Sigma} \mu^\theta(\sigma_0) \prod_{i=0}^{M-1} p^\theta(\sigma_i, \sigma_{i+1}) \left( \log \frac{\mu^\theta(\sigma_0)}{\tilde{\mu}^\theta(\sigma_0)} \right. \\ &\quad \left. + \sum_{i=0}^{i=M-1} \log \frac{p^\theta(\sigma_i, \sigma_{i+1})}{\tilde{p}^\theta(\sigma_i, \sigma_{i+1})} \right) d\sigma_0 \cdots d\sigma_M\end{aligned}$$

Using

$$\begin{aligned}\int_{\Sigma} p(\sigma, \sigma') d\sigma' &= 1, \quad \int_{\Sigma} \mu(\sigma) p(\sigma, \sigma') d\sigma = \mu(\sigma') \\ \int_{\Sigma} \mu^\theta(\sigma_0) \log \frac{\mu^\theta(\sigma_0)}{\tilde{\mu}^\theta(\sigma_0)} d\sigma_0 &+ \sum_{i=0}^{M-1} \int_{\Sigma} \int_{\Sigma} \mu^\theta(\sigma_i) p^\theta(\sigma_i) \log \frac{p^\theta(\sigma_i, \sigma_{i+1})}{\tilde{p}^\theta(\sigma_i, \sigma_{i+1})} \\ &= M \mathbb{E}_{\mu}^{\theta} \left[ \int_{\Sigma} p^\theta(\sigma, \sigma') \log \frac{p^\theta(\sigma, \sigma')}{\tilde{p}^\theta(\sigma, \sigma')} d\sigma' \right] + \mathcal{R} \left( \mu^\theta \mid \tilde{\mu}^\theta \right)\end{aligned}$$

# Relative entropy decomposition and scaling

$$\begin{aligned}\mathcal{R}(Q^\theta | \tilde{Q}^\theta) &= \int_{\Sigma} \cdots \int_{\Sigma} \mu^\theta(\sigma_0) \prod_{i=0}^{M-1} p^\theta(\sigma_i, \sigma_{i+1}) \left( \log \frac{\mu^\theta(\sigma_0)}{\tilde{\mu}^\theta(\sigma_0)} \right. \\ &\quad \left. + \sum_{i=0}^{i=M-1} \log \frac{p^\theta(\sigma_i, \sigma_{i+1})}{\tilde{p}^\theta(\sigma_i, \sigma_{i+1})} \right) d\sigma_0 \dots d\sigma_M\end{aligned}$$

Using

$$\begin{aligned}\int_{\Sigma} p(\sigma, \sigma') d\sigma' &= 1, \quad \int_{\Sigma} \mu(\sigma) p(\sigma, \sigma') d\sigma = \mu(\sigma') \\ \int_{\Sigma} \mu^\theta(\sigma_0) \log \frac{\mu^\theta(\sigma_0)}{\tilde{\mu}^\theta(\sigma_0)} d\sigma_0 + \sum_{i=0}^{M-1} \int_{\Sigma} \int_{\Sigma} \mu^\theta(\sigma_i) p^\theta(\sigma_i) \log \frac{p^\theta(\sigma_i, \sigma_{i+1})}{\tilde{p}^\theta(\sigma_i, \sigma_{i+1})} \\ &= M \mathbb{E}_{\mu}^{\theta} \left[ \int_{\Sigma} p^\theta(\sigma, \sigma') \log \frac{p^\theta(\sigma, \sigma')}{\tilde{p}^\theta(\sigma, \sigma')} d\sigma' \right] + \mathcal{R}(\mu^\theta | \tilde{\mu}^\theta)\end{aligned}$$

$$\mathcal{R}(Q^\theta | \tilde{Q}^\theta) = M \mathcal{H}(Q^\theta | \tilde{Q}^\theta) + \mathcal{R}(\mu^\theta | \tilde{\mu}^\theta)$$

# Continuous time Markov chain

$\mathcal{D}_{[0, T]}$  (resp.  $\tilde{\mathcal{D}}_{[0, T]}$ ) is the distribution of the process  $\{\sigma_t\}_{t \in [0, T]}$  (resp.  $\{\tilde{\sigma}_t\}_{t \in [0, T]}$ ) on the path space  $\mathcal{Q}([0, T], \Sigma_N)$

$$\mathcal{R}(\mathcal{D}_{[0, T]} | \tilde{\mathcal{D}}_{[0, T]}) = \int \log \left( \frac{d\mathcal{D}_{[0, T]}}{d\tilde{\mathcal{D}}_{[0, T]}} \right) d\mathcal{D}_{[0, T]},$$

The initial distribution is **the stationary measure**  $\mu$  (resp.  $\tilde{\mu}$ ).

Radon-Nikodym derivative:

$$\frac{d\mathcal{D}_{[0, T]}}{d\tilde{\mathcal{D}}_{[0, T]}} = \frac{\mu(\sigma_0)}{\tilde{\mu}(\sigma_0)} \exp \left\{ - \int_0^T [\lambda(\sigma_s) - \tilde{\lambda}(\sigma_s)] ds + \int_0^T \log \frac{c(\sigma_{s-}, \sigma_s)}{\tilde{c}(\sigma_{s-}, \sigma_s)} dN_s \right\}$$

$$\mathcal{R}(\mathcal{D}_{[0, T]} | \tilde{\mathcal{D}}_{[0, T]}) = T\mathcal{H}(\mathcal{D}_{[0, T]} | \tilde{\mathcal{D}}_{[0, T]}) + \mathcal{R}(\mu | \tilde{\mu})$$

# Langevin dynamics

- ▶ Microscopic dynamics with forcefield  $x \in \mathbb{R}^n \mapsto b(x) \in \mathbb{R}^n$ ,  $\text{rank } \sigma(x) \leq n$

$$dX_t = b(X_t) dt + \sigma(X_t) dB_t, \quad t \geq 0, \quad X_0 \sim \mu_0.$$

- ▶ Approximating dynamics

$$d\tilde{X}_t = \tilde{b}(\tilde{X}_t; \theta) dt + \sigma(\tilde{X}_t) dB_t, \quad t \geq 0, \quad \tilde{X}_0 \sim \nu_0,$$

- ▶ Radon-Nikodym derivative

$$\frac{dP_X^{[0, T]}}{dP_{\tilde{X}}^{[0, T]}}(X_t, t) = \frac{d\mu_0}{d\nu_0}(X_0) \exp \left\{ - \int_0^t \langle u(X_s; \theta), dB_s \rangle - \frac{1}{2} \int_0^t |u(X_s; \theta)|^2 ds \right\}.$$

$$\sigma(X_s)u(X_s; \theta) = b(X_s) - \tilde{b}(X_s; \theta)$$

- ▶ Relative entropy

$$\mathcal{R}(P_X^T | P_{\tilde{X}}^T) = \mathbb{E}_{P_X^T} \left[ \int_0^T \frac{1}{2} |u(X_s; \theta)|^2 ds \right] + \mathcal{R}(\mu_0 | \nu_0)$$

# Relative entropy rate

For stationary process:  $\mathcal{R}(P_X^T | P_{\tilde{X}}^T) = T\mathcal{H}(P_X^T | P_{\tilde{X}}^T) + \mathcal{R}(\mu_0 | \nu_0)$

$$\mathcal{H}(P_X^T | P_{\tilde{X}}^T) = \lim_{T \rightarrow \infty} \frac{1}{T} \mathcal{R}(P_X^T | P_{\tilde{X}}^T)$$

- ▶ RER representation for stationary process

$$\mathcal{H}(P_X | P_{\tilde{X}}) = \mathbb{E}_\mu \left[ \frac{1}{2} \|b(X) - \tilde{b}(X; \theta)\|_\Xi^2 \right],$$

the norm  $\|\cdot\|_\Xi$  defined by  $\Xi(x) = [\sigma^T(x)\sigma(x)]^{-1}\sigma^T(x)$ .

- ▶ RE representation for finite time

$$\mathcal{R}(P_X^T | P_{\tilde{X}}^T) = \mathcal{H}^T(P_X^T | P_{\tilde{X}}^T) + \mathcal{R}(\mu_0 | \nu_0),$$

where

$$\mathcal{H}^T(P_X^T | P_{\tilde{X}}^T) = \mathbb{E}_{P_X^T} \left[ \frac{1}{2} \int_0^T \|b(X_s) - \tilde{b}(X_s; \theta)\|_\Xi^2 ds \right].$$

# Relative Entropy Rate and Dynamics Parametrization

## Langevin dynamics

- ▶ CG map:  $\mathbb{R}^n \rightarrow \mathbb{R}^m$ ,  $x \mapsto \bar{x} = \mathbf{T}x$
- ▶ CG Markovian dynamics

$$d\bar{X}_t = \bar{b}(\bar{X}_t; \theta) dt + \bar{\sigma}(\bar{X}_t; \theta) d\bar{B}_t, \quad \bar{X}_0 \sim \bar{\mu}_0$$

- ▶ Reconstructed process  $\mathbf{T}\tilde{X}_t = \bar{X}_t$  in distribution

$$d\tilde{X}_t = \tilde{b}(\tilde{X}_t; \theta) dt + \tilde{\sigma}(\tilde{X}_t; \theta) dB_t, \quad \tilde{X}_0 \sim \nu_0$$

$$\begin{aligned} \mathbf{T}\tilde{b}(x; \theta) &= \bar{b}(\mathbf{T}x; \theta), \quad \mathbf{T}\tilde{\Sigma}(x; \theta)\mathbf{T}^T = \bar{\Sigma}(\mathbf{T}x; \theta) \quad \text{for all } x \in \mathbb{R}^n \\ \tilde{\Sigma}(x; \theta) &= \tilde{\sigma}(x; \theta)\tilde{\sigma}^T(x; \theta), \quad \bar{\Sigma}(\bar{x}; \theta) = \bar{\sigma}(\bar{x}; \theta)\bar{\sigma}^T(\bar{x}; \theta) \end{aligned}$$

- ▶ Best fit at stationary regime – minimize  $\mathcal{H}$

$$\min_{\theta \in \Theta} \mathbb{E}_{\mu} \left[ \frac{1}{2} \|\mathbf{T}b(X) - \bar{b}(\mathbf{T}X; \theta)\|_{\mathbf{T}^T \Xi}^2 \right]$$

---

$$\text{new metric } \|\bar{b}\|_{\mathbf{T}^T \Xi} \equiv \bar{b}^T \mathbf{T}^T \Xi^{-1} \bar{b}, \quad \mathbf{T}^T \Xi \equiv \mathbf{T}^T (\mathbf{T}\mathbf{T}^T)^{-1}.$$

<sup>1</sup>Kalligianaki, Harmandaris, Katsoulakis, P.P. (2016)

# Relative Entropy Rate and Dynamics Parametrization

## Lattice KMC dynamics

- ▶ Define parametrized CG transition probabilities  $q^{\theta^*}(\sigma, \sigma')$ :
  - ▶ Parametrized CG transition probabilities  $\bar{p}^{\theta}(\eta, \eta')$
  - ▶ Reconstruction scheme:  $\nu(\sigma' | \mathbf{T}\sigma')$ , e.g. uniform:  $\frac{1}{|\{\sigma : \mathbf{T}\sigma = \eta'\}|}$
  - ▶  $q^{\theta}(\sigma, \sigma') = \nu(\sigma' | \mathbf{T}\sigma') \bar{p}^{\theta}(\mathbf{T}\sigma, \mathbf{T}\sigma')$ ,
- ▶  $\mathcal{R}(P | Q^{\theta})$  = Loss of Information (in time-series) due to CG
- ▶ For long times  $M \gg 1$ , RER is dominant:

$$\mathcal{R}(P | Q^{\theta}) = M\mathcal{H}(P | Q^{\theta}) + \mathcal{R}(\mu | \mu^{\theta})$$

$$\mathcal{H}(P | Q^{\theta}) = \sum_{\sigma \in \Sigma} \mu(\sigma) \sum_{\sigma' \in \Sigma} p(\sigma, \sigma') \log \frac{p(\sigma, \sigma')}{q^{\theta}(\sigma, \sigma')}.$$

- ▶ No need for explicit knowledge of NESS: suitable for reaction networks, driven systems, reaction-diffusion, etc.

# Path-space Fisher Information Matrix (FIM)

Under a smoothness assumption wrt  $\theta$ , (checkable, on the rates only!)

$$\mathcal{H}\left(Q_{0,M}^\theta \mid Q_{0,M}^{\theta+\epsilon}\right) = \frac{1}{2} \epsilon^T \mathbf{F}_{\mathcal{H}}(Q_{0,M}^\theta) \epsilon + O(|\epsilon|^3)$$

Path-space Fisher Information Matrix.

Example (Markov chain):

$$\mathbf{F}_{\mathcal{H}}(Q_{0,M}^\theta) = \mathbb{E}_{\mu^\theta} \left[ \int_E p^\theta(\sigma, \sigma') \nabla_\theta \log p^\theta(\sigma, \sigma') \nabla_\theta \log p^\theta(\sigma, \sigma')^T d\sigma' \right]$$

- ▶ Spectral analysis of FIM gives the most/least sensitive directions.
- ▶ Derivative-free sensitivity analysis method.
- ▶ Characterizes robustness under parameter perturbations.
- ▶ Determines parameter identifiability, [e.g. Cramer-Rao Theorems].
- ▶ Sparse structure of the path FIM.

# Cramer-Rao inequalities for time-series

## Identifiability and pFIM

- ▶ a biased estimator  $\hat{\theta} = f(X)$  of the parameter  $\theta$  with bias function  $\psi(\theta)$   
 $\mathbb{E}_{P^\theta}[f] = \psi(\theta)$
- ▶ **Cramer-Rao inequality**

$$\text{Var}_{P^\theta}(\hat{\theta}) \geq \frac{[\psi'(\theta)]^2}{\mathbf{F}(P^\theta)}$$

- ▶ a new Cramer-Rao type inequality for time series stationary statistics  
 $\hat{\theta} = \mathcal{F}_T(X)$  with the path-space observables such as  $\mathcal{F}_T(X) = \frac{1}{T} \sum_i f(X_i)$

$$\tau_{P^\theta}(f) \geq \frac{[\psi'(\theta)]^2}{\mathbf{F}_{\mathcal{H}}(P^\theta)}$$

where  $\psi(\theta) = \mathbb{E}_{P^\theta_{[0, T]}} [\mathcal{F}_T]$  is the bias of the estimator.

# Inverse Dynamic Monte Carlo

- ▶ Best-fit obtained by minimizing RER

$$\theta^* = \arg \min_{\theta} \mathcal{H}(P | Q^\theta),$$

- ▶ Optimality condition  $\nabla_\theta \mathcal{H}(P | Q^\theta) = 0$ ; minimization scheme:

$$\theta^{(n+1)} = \theta^{(n)} - \frac{\alpha}{n} G^{(n+1)},$$

$\alpha > 0$  and  $G^{(n+1)}$  being a suitable approximation of the gradient  $\nabla_\theta \mathcal{H}(P | Q^\theta)$

- ▶ FIM revisited-**Newton-Raphson**:

$$G^n = \text{Hess}(\mathcal{H}(P | Q^{\theta^n}))^{-1} \nabla_\theta \mathcal{H}(P | Q^{\theta^n}).$$

$$\mathbf{F}_{\mathcal{H}}(Q^\theta) = \text{Hess}(\mathcal{H}(P | Q^\theta)) = -\mathbb{E}_\mu \left[ \sum_{\sigma'} p(\sigma, \sigma') \nabla_\theta^2 \log q^\theta(\sigma, \sigma') \right].$$

# Relative Entropy Rate (RER) $\mathcal{H}$

$$\mathcal{R}(Q^\theta | \tilde{Q}^\theta) = M\mathcal{H}(Q^\theta | \tilde{Q}^\theta) + \mathcal{R}(\mu^\theta | \tilde{\mu}^\theta)$$

$$\mathcal{H}(Q^\theta | \tilde{Q}^\theta) = \mathbb{E}_\mu^\theta \left[ \int_{\Sigma} p^\theta(\sigma, \sigma') \log \frac{p^\theta(\sigma, \sigma')}{\tilde{p}^\theta(\sigma, \sigma')} d\sigma' \right]$$

- ▶ **RER** is an observable  $\Rightarrow$  tractable and statistical estimators are available.  
[Pantazis, Katsoulakis, J. Chem. Phys. (2013)]
- ▶ Contains information not only for the invariant measure but also for the dynamics.
- ▶ No need for explicit knowledge of NESS (stationary measure): suitable for reaction networks, driven and/or reaction-diffusion systems, etc.

## Examples: Statistical estimators

$$\mathcal{H}(\mathcal{D}_{[0, T]} | \tilde{\mathcal{D}}_{[0, T]}^\theta) = \mathbb{E}_\mu \left[ \sum_{\sigma'} c(\sigma, \sigma') \log \frac{c(\sigma, \sigma')}{\tilde{c}(\sigma, \sigma'; \theta)} - (\lambda(\sigma) - \tilde{\lambda}(\sigma; \theta)) \right]$$

Estimator I:

$$\widehat{\mathcal{H}}_1^{(n)} = \frac{1}{T} \sum_{k=0}^{n-1} \delta \tau_i \left[ \sum_{\sigma'} c(\sigma_k, \sigma') \log \frac{c(\sigma_k, \sigma')}{\tilde{c}(\sigma_k, \sigma')} - (\lambda(\sigma_k) - \tilde{\lambda}(\sigma_k)) \right]$$

Estimator II:

$$\widehat{\mathcal{H}}_2^{(n)} = \frac{1}{n} \sum_{k=0}^{n-1} \log \frac{c(\sigma_k, \sigma_{k+1})}{\tilde{c}(\sigma_k, \sigma_{k+1})} - \frac{1}{T} \sum_{k=0}^{n-1} \delta \tau_k (\lambda(\sigma_k) - \tilde{\lambda}(\sigma_k))$$

# Data-based parametrization of CG dynamics

- Unbiased estimator for RER,

$$\hat{\mathcal{H}}_N(P \mid Q^\theta) := \frac{1}{N} \sum_{i=1}^N \log \frac{p(\sigma_i, \sigma_{i+1})}{q^\theta(\sigma_i, \sigma_{i+1})},$$

- Minimization of RER:

$$\min_\theta \hat{\mathcal{H}}_N(P \mid Q^\theta) = \max_\theta \frac{1}{N} \sum_{i=1}^N \log q^\theta(\sigma_i, \sigma_{i+1}) - \frac{1}{N} \sum_{i=1}^N \log p(\sigma_i, \sigma_{i+1}),$$

- *Coarse-grained path space log-likelihood* maximization

$$\max_\theta \ell(\theta; \{\sigma_i\}_{i=0}^N) := \max_\theta \frac{1}{N} \sum_{i=1}^N \log \bar{p}^\theta(\mathbf{T}\sigma_i, \mathbf{T}\sigma_{i+1}).$$

- No need for microscopic reconstruction:  $q^\theta(\sigma, \sigma') = \nu(\sigma' \mid \mathbf{T}\sigma') \bar{p}^\theta(\mathbf{T}\sigma, \mathbf{T}\sigma')$

# Fisher Information Matrix

## Parameter identifiability

RER is a relative entropy:  $\mathcal{H}(P | Q) = \mathcal{R}(\mu \otimes p | \mu \otimes q)$  :

- ▶ Asymptotic Gaussianity of the **Maximum Likelihood Estimator**:

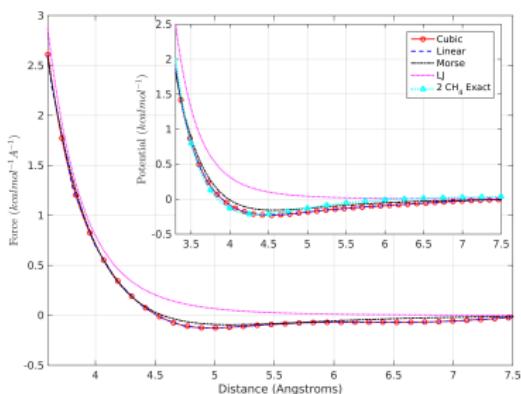
$$\hat{\theta}_N \rightarrow \theta^* \text{ a.s. and } N^{-1/2}(\hat{\theta}_N - \theta^*) \xrightarrow{\text{d}} \mathcal{N}(0, \mathbf{F}_{\mathcal{H}}^{-1}(Q^{\theta^*}))$$

- ▶ Variance determined by the path-space FIM  $\mathbf{F}_{\mathcal{H}}(Q^{\theta^*})$ , or asymptotically by  $\mathbf{F}_{\mathcal{H}}(Q^{\hat{\theta}_N})$ .
- ▶ Estimating the FIM  $\mathbf{F}_{\mathcal{H}}(Q^{\hat{\theta}_N})$  provides rigorous error bars on computed optimal parameter values  $\theta^*$ .

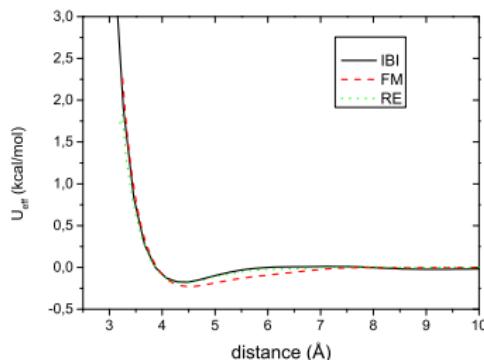
## Examples

## Bulk methane liquid at equilibrium (NVT)

- ▶ CG:  $\text{CH}_4$  in one-site representation with a pair potential (non-bonded only)
  - ▶ micro scale:  $T = 100\text{K}$ , 512  $\text{CH}_4$  molecules,  $\rho = 0.38\text{g/cm}^3$



(a) Dynamic force matching scheme the derived potential.

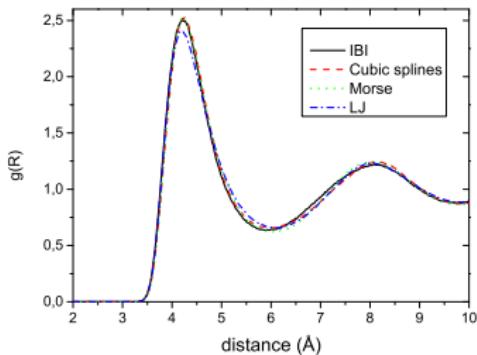


(b) CG effective potentials approximated from different methods

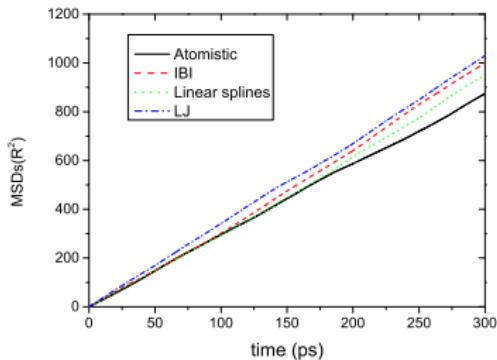
# Examples

Bulk methane liquid at equilibrium (NVT)

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(c) CG pair correlation function.

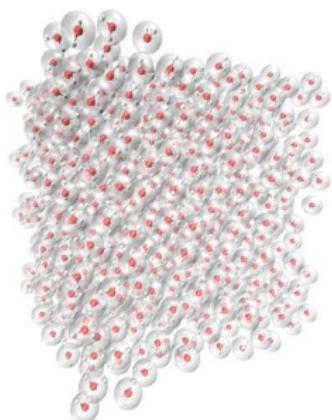


(d) Mean square displacement.

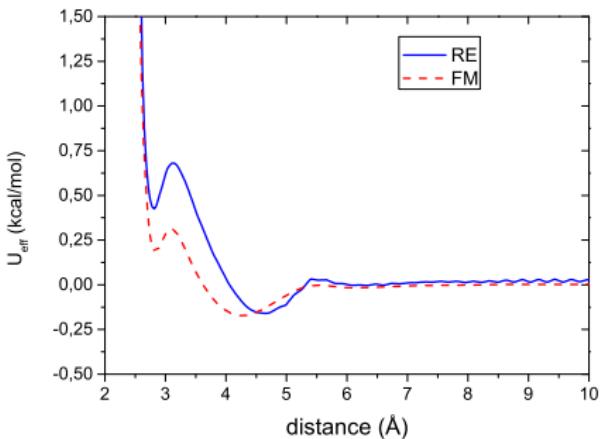
# Examples

## Water

- ▶ CG:  $\text{H}_2\text{O}$  in one-site representation with a pair potential (non-bonded only)
- ▶ micro scale:  $T = 300K$ ,  $p = 1\text{atm}$ , 1192  $\text{H}_2\text{O}$  molecules, SPC/E force-field



(e) Snap shot of micro scale simulation  
Petr Plechac (UDEL)

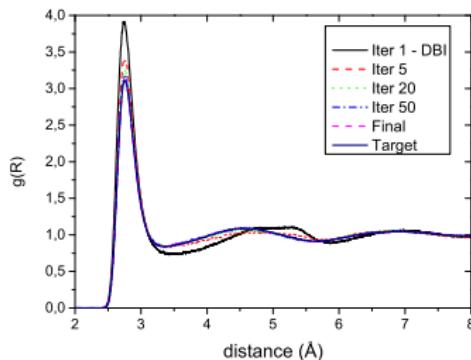


(f) CG effective interactions  
Path-space metrics  
Coupled Mathematical Models for Physics / 1

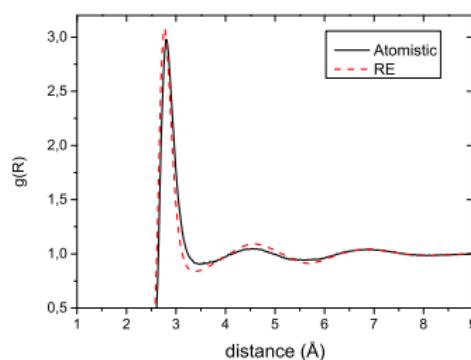
# Examples

## Water

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(g) CG pair distribution function – inverse Monte Carlo

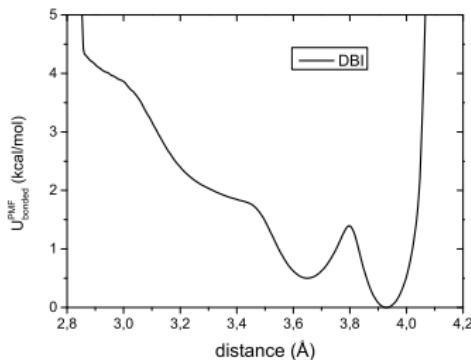


(h) CG pair distribution function – RE based method

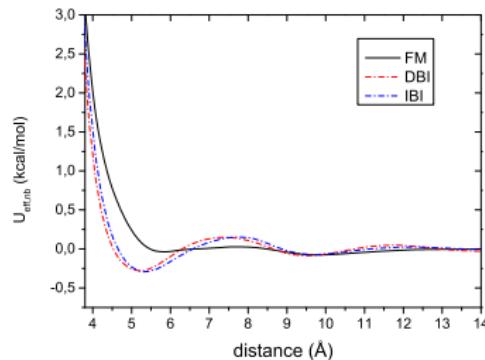
## Examples

## Hexane liquid

- ▶ CG:  $\text{CH}_3(\text{CH}_2)_4\text{CH}_3$  3:1 mapping (3 monomers to 1 CG particle) with a pair potential
  - ▶ micro scale:  $T = 300K$ ,  $p = 1\text{atm}$ , 512  $\text{CH}_3(\text{CH}_2)_4\text{CH}_3$  molecules, OPLS force-field



(i) bonded potential



(j) non-bonded potential

**Figure:** CG effective interactions for hexane molecules.

# Examples

## Driven Arrhenius diffusion

- ▶ Rates: Exchange dynamics with the migration rate to n.n. site  $|x - y| = 1$

$$c(x, y, \sigma) = d e^{-\beta(U(x, \sigma))} [\sigma(x)(1 - \sigma(x + 1)) + \sigma(x)(1 - \sigma(x - 1))]$$

- ▶ Energy barrier:  $U(x, \sigma) = \sum_{z \neq x} J(x - z)\sigma(z) - h$   
 $J(z) = J_0$ , for  $|z| \leq L$  and  $J = 0$  otherwise.
- ▶ Parametrized coarse-grained potential:

$$\bar{U}(k, \eta) = \sum_l \bar{J}(k, l)\eta(k) + \bar{J}(0, 0)(\eta(k) - 1) - \bar{h}$$

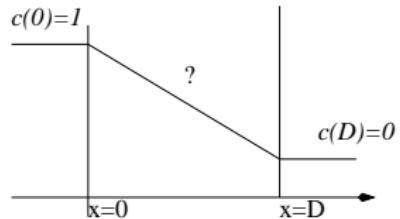
- ▶ Coarse-grained rates: assume *local equilibrium*,  $\sigma(x) \approx q^{-1}\eta(k)$

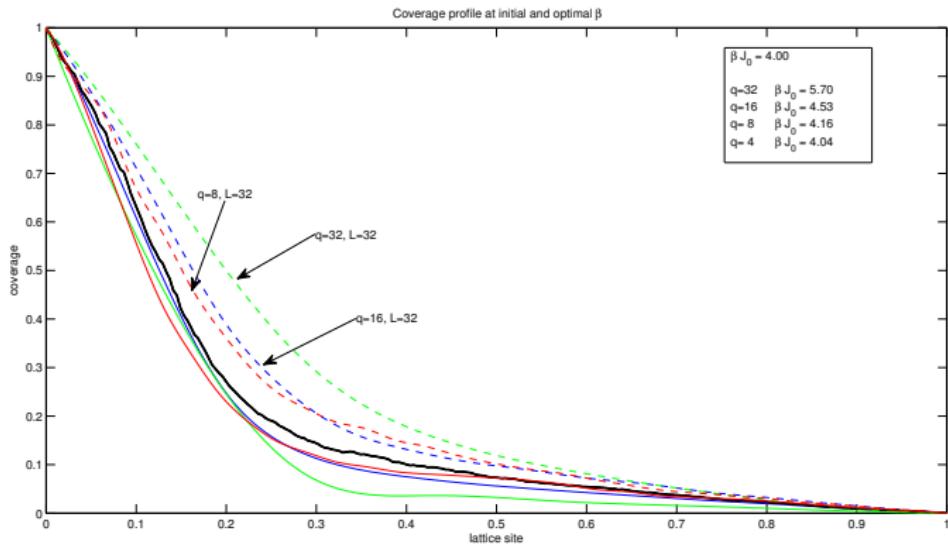
$$\bar{c}(k, l, \eta) = \frac{1}{q}\eta(k)(q - \eta(l))d e^{-\beta\bar{U}(k, \eta)}$$

- ▶  $\theta = (\beta\bar{J}_0, \bar{J}(k, l), \bar{J}(k, l, m) \dots)$

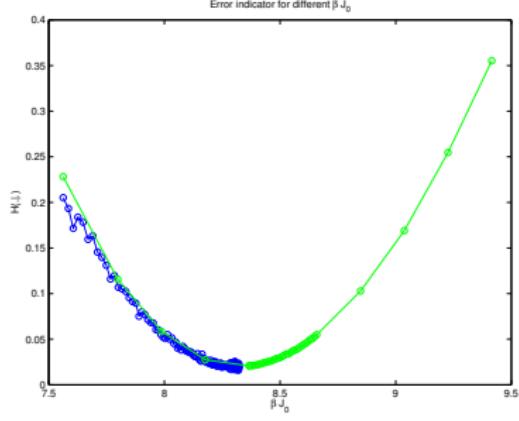
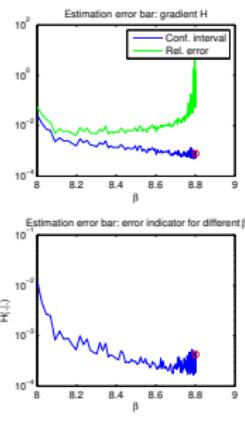
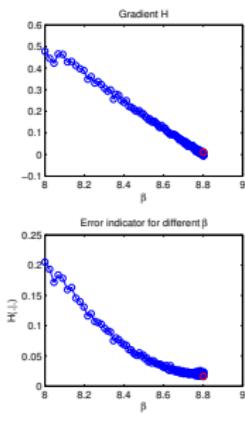
## Non-equilibrium stationary states

Bounded domain with a gradient in concentrations





Stationary concentration profile from CG dynamics with fitted rates using  $\theta = \beta \bar{J}_0$



## CG of systems with NESS and RER

- ▶ Infers information about the path distribution: it contains information not only for the invariant measure but also for the dynamics.
- ▶ No need for explicit knowledge of invariant measure. Thus, it is suitable for reaction networks and **non-equilibrium steady state** systems.
- ▶ **Relative entropy rate  $\mathcal{H}$**  is an observable  $\Rightarrow$  tractable and statistical estimators can provide easily and efficiently its value using KMC solvers.
- ▶ Minimizing the error in  $\mathcal{H}$  gives optimal parametrization similar to max-likelihood parameter estimation.
- ▶ **Fisher information matrix** allows for **parameter identifiability** in parameterization of **dynamics** [analogue to Cramer-Rao Theorems]