Transient dynamics in equilibrium and non-equilibrium communities

Frithjof Lutscher

University of Ottawa

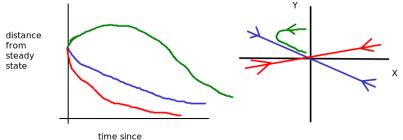
Natural and human disturbances



Transients: How does a system respond to a one-time disturbance?

< 回 > < 三 > < 三 >

Perturbations from a stable steady state



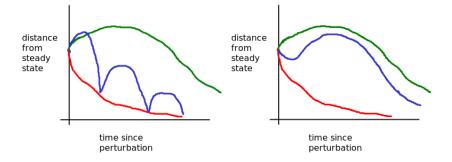
perturbation

- How does an equilibrium community respond to a perturbation?
- How long will it take to return to equilibrium?
- How far from equilibrium will it get along the way?

A .

★ ∃ →

More possibilities



- Eventual decay rate?
- Initial growth or decline?
- Maximal possible deviation?

< ロ > < 同 > < 回 > < 回 >

- Mathematical set-up: Reactivity
 - Reactivity for steady states in ODEs (Neubert and Caswell 1997) > 300 citations
 - Reactivity for steady states of maps (Caswell and Neubert 2005)
 - Reactivity is necessary for diffusion-driven instability (Neubert et al 2002)
- Reactivity for periodically forced models (Vesipa and Rudolfi 2017) + new results
- Reactivity for intrinsically generated cycles new thoughts



Dynamic equations

$$rac{\mathrm{d}\mathbf{x}(t)}{\mathrm{d}t} = \mathbf{F}(\mathbf{x}(t)), \qquad \mathbf{x} \in \mathbb{R}^n.$$

Steady state

$$\mathbf{F}(\mathbf{x}^*) = 0.$$

Linearization

$$\frac{\mathrm{d}\mathbf{y}(t)}{\mathrm{d}t} = D\mathbf{F}(\mathbf{x}^*)\mathbf{y}(t) = \mathbf{A}\mathbf{y}(t), \qquad \mathbf{y}(0) = \mathbf{y}_0,$$

Stability assumption:

 $\Re\lambda_1(\bm{A})<0$

э

Resilience: slowest return rate to steady state (Pimm and Lawton 1977)

$${m R}:=-\Re\lambda_1({f A})>0$$

Return time 1/R

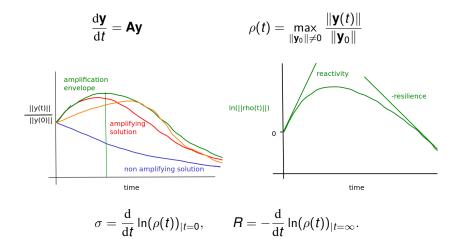
Reactivity: maximal instantaneous growth rate (Neubert and Caswell 1997)

$$\sigma := \max_{\|\mathbf{y}_0\| \neq 0} \left[\left(\frac{1}{\|\mathbf{y}(t)\|} \frac{\mathrm{d}\|\mathbf{y}(t)\|}{\mathrm{d}t} \right) \Big|_{t=0} \right]$$

Amplification envelope: maximum growth at time t (Neubert and Caswell 1997)

$$\rho(t) = \max_{\|\mathbf{y}_0\| \neq 0} \frac{\|\mathbf{y}(t)\|}{\|\mathbf{y}_0\|}$$

(I) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1)) < ((1))



2

イロト イロト イヨト イヨト

- Scalar systems cannot be reactive.
- Reactivity and resilience have no correlation.
- Reactivity depends on chosen norm, stability does not.
- Reactivity depends on scaling!
- In the L^2 norm, we have $\sigma = \lambda_1 (\mathbf{A} + \mathbf{A}^{\top})/2$.
- We also have $\rho(t) = ||| \exp(At) |||$.

< 47 ▶

Examples

Lotka-Volterra type models

 $\dot{N} = rN(1 - N/K) - g(N)P$

$$\dot{P} = eg(N)P - mP$$

Leslie model

$$\dot{N} = rN(1 - N/K) - cNP$$

 $\dot{P} = sP(1 - qP/N)$

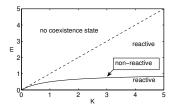
Linearization

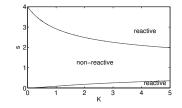
$$A = \begin{bmatrix} a_1 & a_2 \\ a_3 & a_4 \end{bmatrix}$$

Reactivity

 $\sigma > 0 \quad \Leftrightarrow \quad 4a_1$

 $4a_1a_4 < (a_2 + a_3)^2$





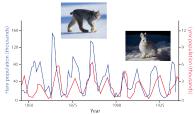
Frithjof Lutscher (University of Ottawa)

BIRS August 2019 10/25

Beyond equilibrium?



- External forcing: seasonality
- Internal generation: predator–prey cycles



Is there a "good" time to perturb an oscillating system?

Seasonally forced systems

Dynamic equations with *T*-periodic forcing $\mathbf{F}(t, \cdot) = \mathbf{F}(t + T, \cdot)$

$$rac{\mathrm{d}\mathbf{x}(t)}{\mathrm{d}t} = \mathbf{F}(t,\mathbf{x}(t)), \qquad \mathbf{x} \in \mathbb{R}^n.$$

T-periodic orbit

$$\gamma(t+T)=\gamma(t)$$

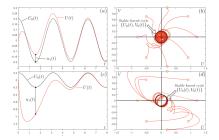
Linearization

$$\frac{\mathrm{d}\mathbf{y}(t)}{\mathrm{d}t} = D\mathbf{F}(\gamma(t))\mathbf{y}(t) = \mathbf{A}(t)\mathbf{y}(t), \qquad \mathbf{y}(t_0) = \mathbf{y}_0, \quad 0 \le t_0 \le T$$

Stability assumption via Poincaré map (independent of t_0)

Transients for seasonally forced systems?

Vesipa and Ridolfi (2017)



- Define σ, ρ as before $\sigma := \max_{\|\mathbf{y}_0\| \neq 0} \left[\left(\frac{1}{\|\mathbf{y}(t)\|} \frac{d\|\mathbf{y}(t)\|}{dt} \right) \Big|_{t=0} \right]$
- Numerical scheme for amplification envelope

Local reactivity

$$\sigma_L(t_0) := \max_{\|\mathbf{y}_0\| \neq 0} \left[\left(\frac{1}{\|\mathbf{y}(t)\|} \frac{\mathrm{d}\|\mathbf{y}(t)\|}{\mathrm{d}t} \right) \Big|_{t=t_0} \right], \quad 0 \leq t_0 \leq T$$

Local amplification envelope

$$\rho_L(t, t_0) = \max_{\|\mathbf{y}_0\| \neq 0} \frac{\|\mathbf{y}(t)\|}{\|\mathbf{y}_0\|}$$

Relations as before:

$$\sigma_L(t_0) = \lambda_1(H(\mathbf{A}(t_0))), \qquad \sigma_L = \sigma_L(t_0) = \frac{\mathrm{d}}{\mathrm{d}t} \ln(\rho_L(t,t_0))_{|t=t_0}.$$

3 → 4 3

The periodically forced logistic equation

$$\frac{\mathrm{d}x(t)}{\mathrm{d}t} = rx(t)[1 - x(t)/K(t)]$$

Explicit expression for $\gamma(t)$

Linearization

$$\frac{\mathrm{d}\mathbf{y}(t)}{\mathrm{d}t} = r[1 - 2\gamma(t)/K(t)]\mathbf{y}(t), \qquad \mathbf{y}(t_0) = \mathbf{y}_0,$$

Explicit solution

$$y(t) = y(t_0) \exp\left(\int_{t_0}^t r[1-2\gamma(s)/K(s)]\mathrm{d}s\right).$$

Local amplification envelope

$$\rho_L(t, t_0) = \max_{|y_0| \neq 0} \frac{|y(t)|}{|y_0|} = \exp\left(\int_{t_0}^t r[1 - 2\gamma(s)/\mathcal{K}(s)] \mathrm{d}s\right)$$

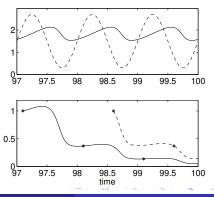
The periodically forced logistic equation II

Local reactivity

$$\sigma_L(t_0) = \frac{d}{dt} \ln(\rho_L(t, t_0))_{|t=t_0} = r[1 - 2\gamma(t_0)/K(t_0)]$$

 $\gamma(t)$ (solid) K(t)/2 (dashed)

Amplification envelope from two initial times



1

Maximum of local reactivity

$$\sigma_M = \max_{0 \le t \le T} \sigma_L(t)$$

In the spirit of "worst cases analysis"

2 Period map
$$\mathbf{z}_n = \mathbf{x}(nT)$$

 \mathbf{z}_n

$$\boldsymbol{z}_{n+1} = \boldsymbol{\mathsf{P}}(\boldsymbol{z}_n)$$

Linearize

$$\mathbf{w}_{n+1} = D\mathbf{P}(\gamma(t_0))\mathbf{w}_n = \mathbf{B}(t_0)\mathbf{w}_n$$

Stability of γ given by eigenvalues of **B** (independent of t_0)

3 > 4 3

For the period map

$$\mathbf{w}_{n+1} = \mathbf{B}(t_0)\mathbf{w}_n$$

Define the period reactivity (as in Caswell and Neubert 2005)

$$\sigma_{\mathcal{P}} := \ln \left(\max_{\|\mathbf{w}_0\| \neq 0} \frac{\|\mathbf{w}_1\|}{\|\mathbf{w}_0\|} \right) = \ln \left(\max_{\|\mathbf{w}_0\| \neq 0} \frac{\|\mathbf{B}\mathbf{w}_0\|}{\|\mathbf{w}_0\|} \right)$$

With L²-norm:

$$\sigma_P$$
: = $\sigma_P(t_0) = \ln\left(\sqrt{\lambda_1(\mathbf{B}^T\mathbf{B})}\right)$.

Largest singular value, depends on t_0 !

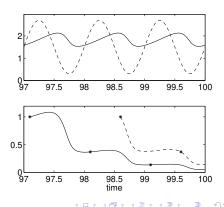
3 > 4 3

Forced logistic equation: continued

$$z_{n+1} = P(z_n) = \frac{z_n e^{rT}}{1 + z_n a(t_0)}, \qquad a(t_0) = \int_{t_0}^{t_0 + T} \frac{r e^{r(s-t_0)}}{K(s)} ds.$$

 $\sigma_P = -rT < 0$

Observation: A periodic orbit of a scalar periodically forced equation cannot be period reactive.

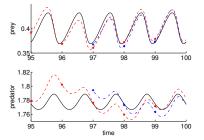


$$\dot{x} = rx[1 - x/K(t)] - cxy$$

 $\dot{y} = ecxy - my$

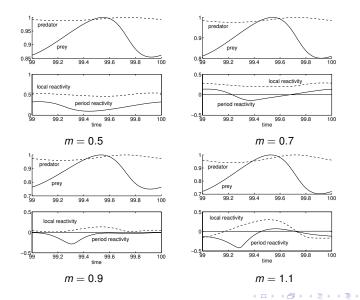
with

 $K(t) = K_m + K_a \sin(2\pi t).$



< 17 ▶

The forced Lotka–Volterra model



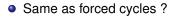
Frithjof Lutscher (University of Ottawa)

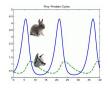
Reactivity

BIRS August 2019 21/25

æ

Reactivity of periodic orbits in autonomous systems





Distance from periodic orbit ?

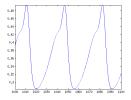




Distance in phase ?

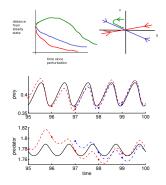
Illustration with Rosenzweig MacArthur model

Period-reactive orbit in a food chain model?



- Locally reactive ! Period reactive ?
- Period reactivity is never negative
- Eliminate the direction of the periodic orbit
- Observation: A planar periodic orbit is not period reactive
- Tri-trophic food chain can be period reactive

- Reactivity of steady states
 - depends on scaling
 - no relationship to resilience
- Reactivity of forced periodic orbits
 - local and period reactivity
 - requires at least 2D
- Reactivity of autonomous periodic orbits
 - Direction of the periodic orbit?
 - requires at least 3D
 - no simple formulas
 - even numerically not easy



Upcoming book:

Upcoming position: Tenure-track position in applied mathematics at University of Ottawa





< ロ > < 同 > < 回 > < 回 >