## One of the models in fractional diffusion

Consider 1-D double-sided fractional diffusion advection reaction equation

$$
\left\{\begin{array}{l}
{[L(u)](x)=f(x), x \in \Omega=(a, b),} \\
u(a)=u(b)=0, \\
{[L(u)](x):=-D k(x)\left(\alpha_{a} D_{x}^{-(1-\mu)}+\beta{ }_{x} D_{b}^{-(1-\mu)}\right) D u} \tag{1}
\end{array}\right.
$$

where $0<\mu<1,0 \leq \alpha, \beta \leq 1, \alpha+\beta=1,{ }_{a} D_{x}^{-(1-\mu)},{ }_{x} D_{b}^{-(1-\mu)}$ represent left- and right-sided Riemann-Liouville integrals.

Model (1) has been used in modeling anomalous diffusion processes such as in underground water, cellular cytoplasm setting, etc.

Meanwhile, some disputes arise on the wellposedness of various models and the challenge of numerical approximations. In the following, we present some recent progress, which partial solves the open questions.

## Structure of solution

[1] Under natural conditions on the coefficents $k(x), p(x), q(x), f(x)$, there exists a unique true solution $u(x)$ in $\widehat{H}_{0}^{(1+\mu) / 2}(\Omega)$ to (1). It can be decomposed into

$$
\begin{align*}
u(x) & =\int_{a}^{x} \int_{a}^{x_{1}} v(t) d t d x_{1}-\frac{c S}{S_{1}} \int_{a}^{x} \int_{a}^{x_{1}}(t-a)^{p}(b-t)^{q} d t d x_{1} \\
& +\frac{c_{1} S}{S_{1}}(x-a)^{p+1}(b-x)^{q+1}  \tag{2}\\
& +C \int_{a}^{x}(t-a)^{p}(b-t)^{q} d t, x \in \Omega
\end{align*}
$$

where $v(x)$ is a certain function in $H^{*}(\Omega) \subset L^{1}(\Omega), C$ is a certain constant, $p, q$ are uniquely determined by

$$
\begin{gathered}
p+q=-(1-\mu) \text { and } \quad \alpha \sin (q \pi)=\beta \sin (p \pi), \\
c=\Gamma(-q)\left(\alpha(b-a)^{1+p+q} \Gamma(p+1) \int_{a}^{b}(t-a)^{-q-1}(b-t)^{-p-1} d t\right)^{-1} \\
S_{1}=\frac{\Gamma(-q) \int_{a}^{b}(t-a)^{p}(b-t)^{q} d t}{\alpha(b-a)^{1+p+q \Gamma(p+1) \int_{a}^{b}(t-a)^{-q-1}(b-t)^{-p-1} d t},} \\
c_{1}=\frac{(-p-1+\mu)(-p+\mu) \Gamma(1-\mu)}{\mu(1+\mu) \beta \Gamma(2-\mu+p) \Gamma(q+2)}, \quad S=\int_{a}^{b} v(t) d t,
\end{gathered}
$$

and it is representable by

$$
\begin{equation*}
u(x)={ }_{a} D_{x}^{-(1+\mu)} J, \quad x \in \Omega, \text { for a certain } J(x) \in H^{*}(\Omega) \subset L^{1}(\Omega) . \tag{3}
\end{equation*}
$$

## Equivalent models

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Based on the structure of solution, we can prove that the following models actually equivalent:
\[
\begin{aligned}
& \left\{\begin{array}{l}
{[L(u)](x)=f(x), x \in \Omega=(a, b),} \\
u(a)=u(b)=0, \\
{[L(u)](x):=-D k(x)\left(\alpha_{a} D_{x}^{-(1-\mu)}+\beta{ }_{x} D_{b}^{-(1-\mu)}\right) D u} \\
\quad+p(x) D u+q(x) u(x),
\end{array} \Longleftrightarrow\right. \\
& \left\{\begin{array}{l}
{[L(u)](x)=f(x), x \in \Omega=(a, b),} \\
u(a)=u(b)=0, \\
{[L(u)](x):=-D k(x) D\left(\alpha_{a} D_{x}^{-(1-\mu)}+\beta{ }_{x} D_{b}^{-(1-\mu)}\right) u} \\
\quad+p(x) D u+q(x) u(x),
\end{array} \Longleftrightarrow\right. \\
& \left\{\begin{aligned}
& {[L(\tilde{u})](x)=f(x), x \in \Omega, } \\
& \tilde{u}(x)=0, x \in \mathbb{R} \backslash \Omega \\
& {[L(\tilde{u})](x) }:=-k(x)\left((\alpha-\beta){ }_{a} D_{x}^{(1+\mu)}+2 \beta \cos ((1+\mu) \pi / 2)(-\Delta)^{(1+\mu) / 2)} \tilde{u}\right. \\
& \quad-k^{\prime}(x)\left({ }_{a} D_{x}^{\mu}-2 \beta \cos (\mu \pi / 2)(-\Delta)^{\mu / 2}\right) \tilde{u} \\
& \quad+p(x) D \tilde{u}+q(x) \tilde{u}(x),
\end{aligned}\right.
\end{aligned}
\]
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where $\tilde{u}(x)$ denotes the zero extension of $u(x)$ outside $\Omega$.

$$
\begin{aligned}
& \text { Novel numerical scheme } \\
& \text { What does the structure of solution tell us? Observe that } \\
& u(x)={ }_{a} D_{x}^{-(1+\mu)} \psi+C_{1}(x-a)^{t_{1}+1}(b-x)^{t_{2}+1}+C_{2} \int_{a}^{x}(t-a)^{t_{1}}(b-t)^{t_{2}} d t,
\end{aligned}
$$

for $x \in(a, b)$, where $\psi, C_{1}, C_{2}$ are unknonwn and everything else is known. Due to the last two "bad" terms, it is usually inaccurate to make a priori assumption on the smoothness of $u$ to allow for an optimal convergence rate in the analysis of numerical approximations.

What is the novel numerical scheme? Rather than approximating $u$ directly, which is usually challenging and can be tough, we approximate $\psi$ and the constants $C_{1}, C_{2}$, which in turn gives the approximation of $u$ after doing back substitution.
what is the chief merit of this method?Unlike standard numerical approximations, his approach poses no necessity to directly approximate the less regular components of the solution. What is mainly left is to approximate $\psi$. Once approximation of $\psi$ is available, then the constants $C_{1}, C_{2}$ can be calculated, and approximation of $u$ can be directly constructed from (4). Moreover, the error of this construction is only due to the approximation of $\psi$, and thus is free from the nonsmoothness effects inherent in $u$.

## One-sided case

To test the philosophy and provide for a manageable set of tasks in successfully de veloping, analyzing, and implementing the above approach, we first try the specia case, $\beta=0$ :

$$
\left\{\begin{array}{l}
{[L(u)](x)=f(x), \quad x \in \Omega=(a, b),} \\
u(a)=u(b)=0, \\
{[L(u)](x):=-D\left(k(x){ }_{a} D_{x}^{-(1-\mu)} D u\right)+p(x) D u+q(x) u}
\end{array}\right.
$$

The corresponding solution is reduced to

$$
u(x)={ }_{a} D_{x}^{-(1+\mu)} \psi+C_{\psi}(x-a)^{\mu}, x \in \bar{\Omega}, C_{\psi}=-\left.(b-a)^{-\mu}{ }_{a} D_{x}^{-(1+\mu)} \psi\right|_{x=b} .
$$

Algorithm: instead directly approximating solution $u$, we approximate the unknown $\psi$ and $C_{\psi}$

Step 1: convert the fractional differential equation into integral equation

$$
\psi+\mathcal{I} \psi=F(x)-C_{\psi} G(x), \text { a.e. in } \bar{\Omega},
$$

where

$$
\begin{aligned}
& {[\mathcal{I} \psi](x):=-\frac{1}{k(x)}\left(p(x){ }_{a} D_{x}^{-\mu} \psi+q(x)_{a} D_{x}^{-(1+\mu)} \psi-k^{\prime}(x){ }_{a} D_{x}^{-1} \psi\right),} \\
& G(x):=-\frac{1}{k(x)}\left(\mu p(x)(x-a)^{\mu-1}+q(x)(x-a)^{\mu}-\Gamma(\mu+1) k^{\prime}(x)\right), \\
& F(x):=-f / k .
\end{aligned}
$$

Step 2: Use Two-Step Method to approximate $\psi_{F}$ and $\psi_{G}$ that are governed by

$$
\left\{\begin{array}{l}
\psi_{F}+\mathcal{I} \psi_{F}=F(x), x \in \Omega, \\
\psi_{G}+\mathcal{I} \psi_{G}=G(x), x \in \Omega .
\end{array}\right.
$$

Step 3:

$$
\psi=\psi_{F}-C_{\psi} \psi_{G} \Rightarrow\left\{\begin{array}{l}
\text { calculate } C_{\psi} \\
\text { by } u(b)=0
\end{array}\right.
$$

Step 4: Do error analysis and related convergence analysis. (Numerical experi ments can be found in [2] )

## References

[1] Yulong Li. "On the decomposition of solutions: from fractional diffusion to fractional Laplacian". In: Fract. Calc. Appl. Anal. 24.5 (2021), pp. 1571-1600. ISSN: 1311-0454.
[2] Yulong Li and Ginting Victor. "On the Dirichlet BVP of fractional diffusion advection reaction equation in bounded interval: structure of solution, integral equation and approximation". In: (sub

