

Using Process Control Theory to Estimate Sea Spray Emissions in GEOS-Chem

Banff Workshop: Mathematical approaches of atmospheric constituents data assimilation and inverse modeling

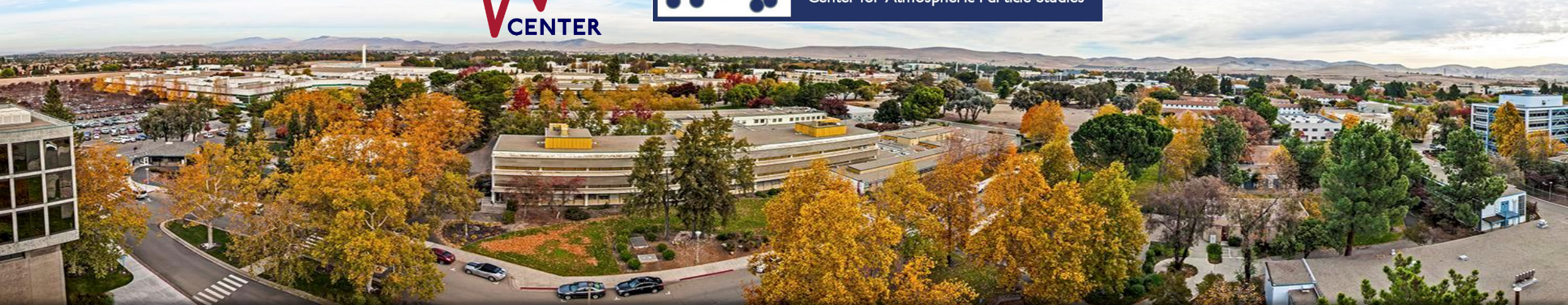
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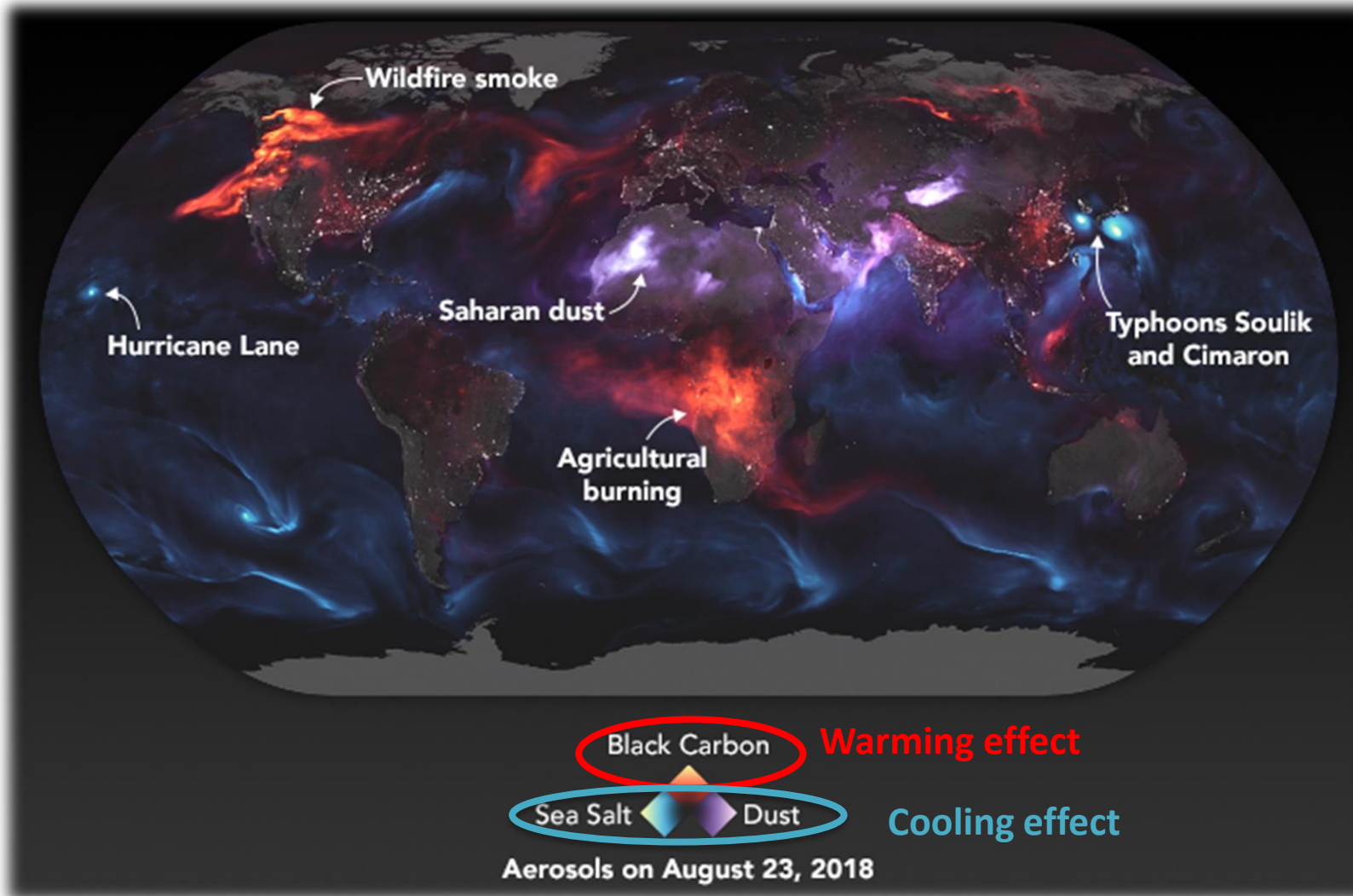


March 21, 2023



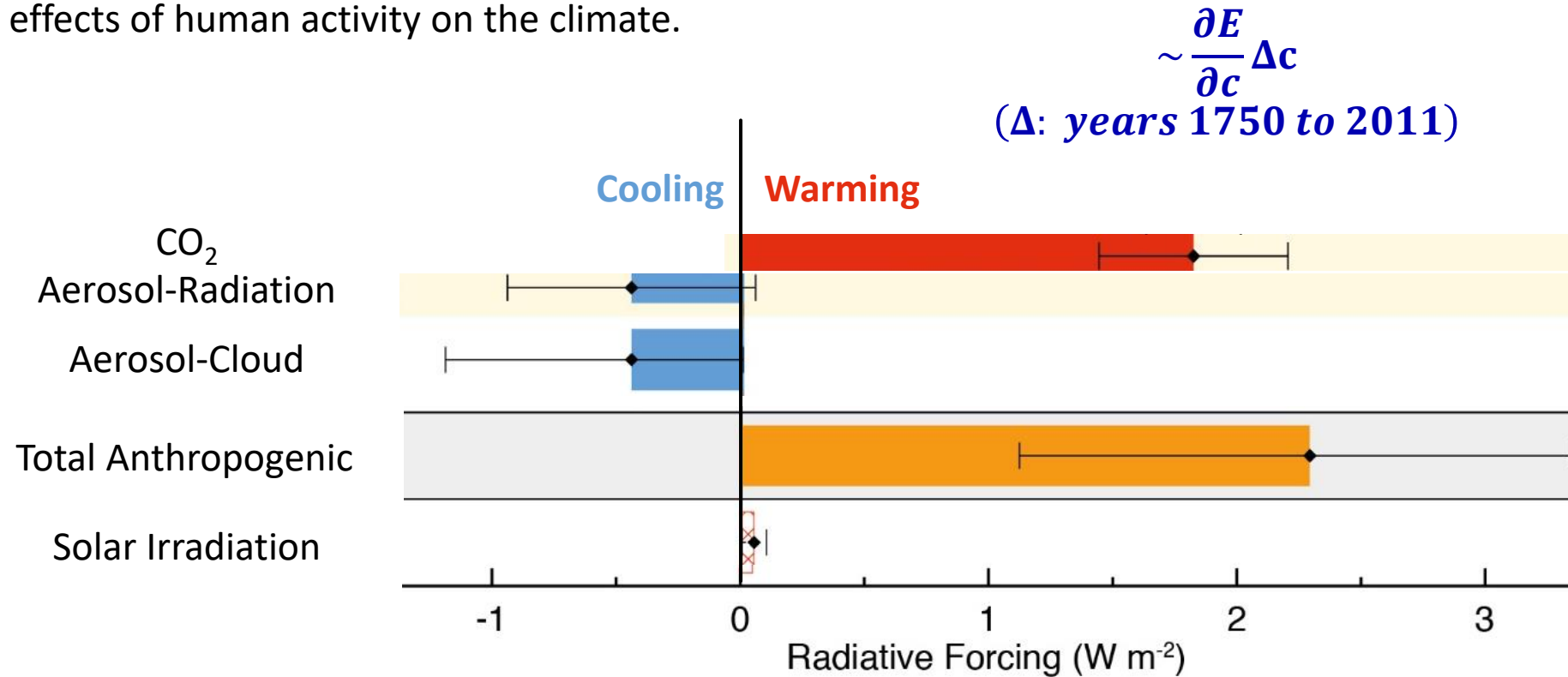
A day in the life of atmospheric aerosol

Sea spray generates sea salt aerosol



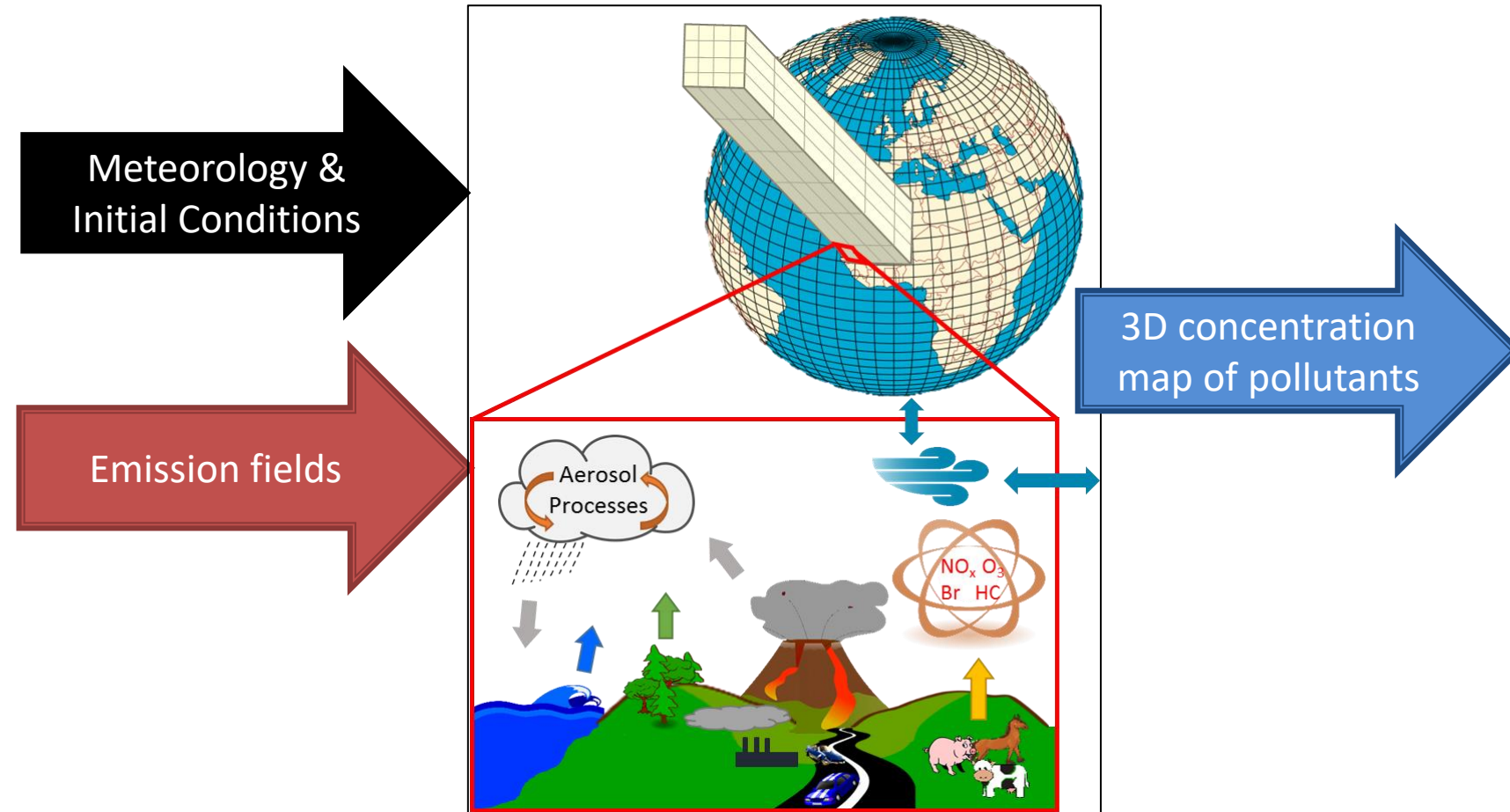
Improved atmospheric aerosol predictions lead to better predictions of climate change

The Intergovernmental Panel on Climate Change estimates **radiative forcing** to assess the effects of human activity on the climate.



Chemical transport models predict gas and particle concentration fields

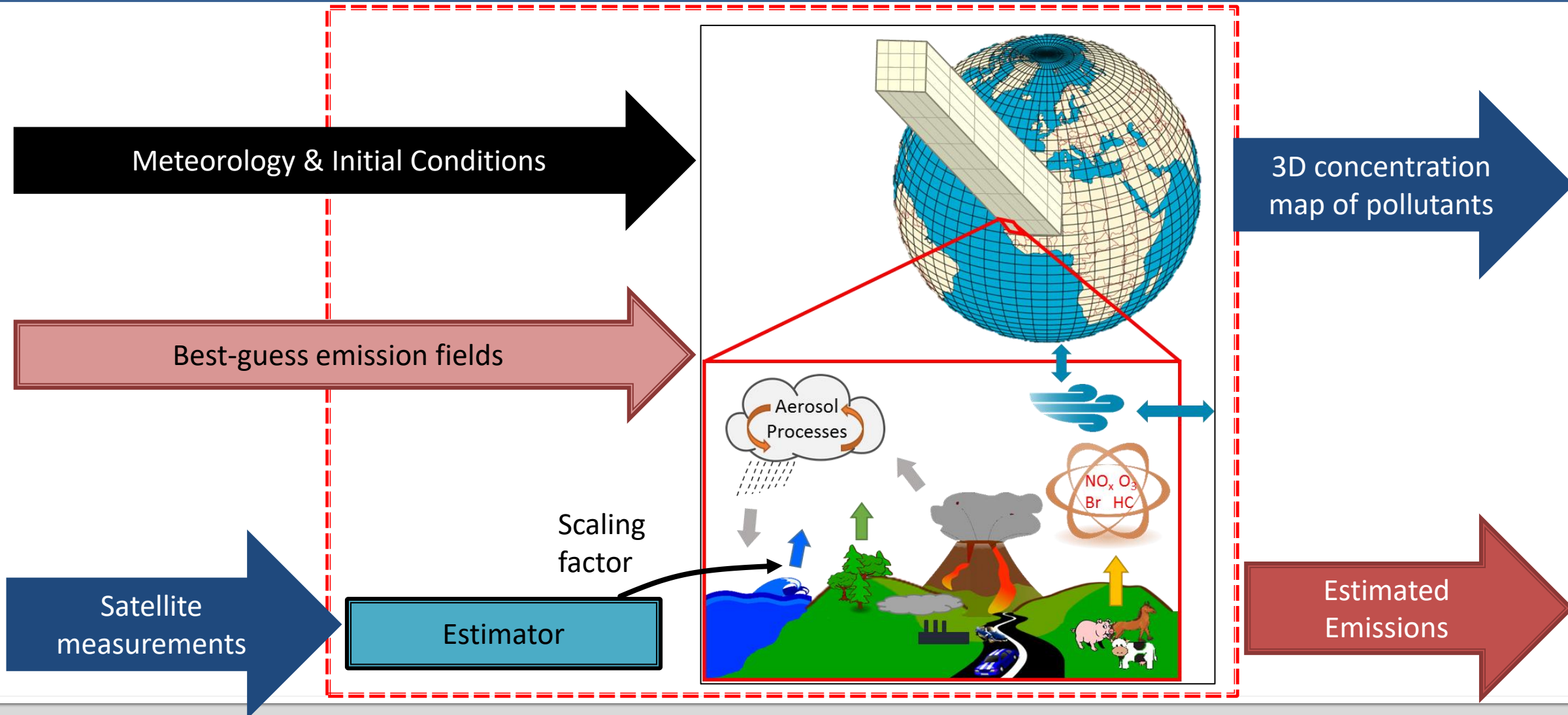
- GEOS-Chem is driven by NASA's MERRA2 meteorological reanalysis fields
- TwO-Moment Aerosol Sectional (TOMAS) algorithm used for aerosol processes
- Soot and organic carbon emissions from input data
- Dust and sea salt emission from parameterizations based on wind data
 - $E_{SSA}(D_p) \propto U_{10}^{3.41}$
 - Parameterization for sea spray from breaking waves based on field measurements on Hawaiian coast (Clarke, 2006)



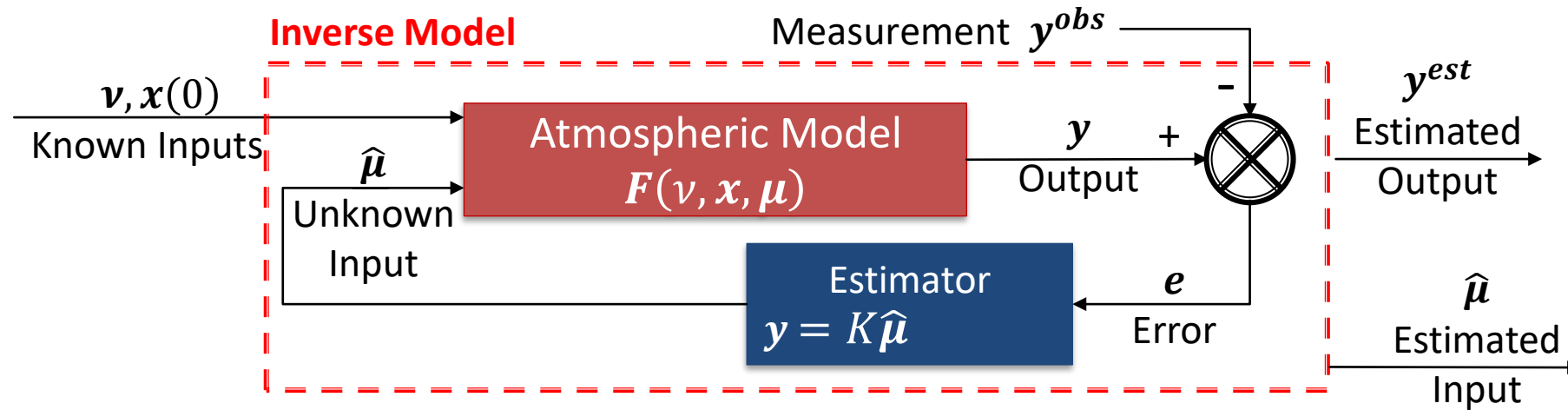
We can use satellites measurements of aerosol optical depth (AOD) to estimate aerosol emissions



Inverse modeling uses observations to estimate emissions



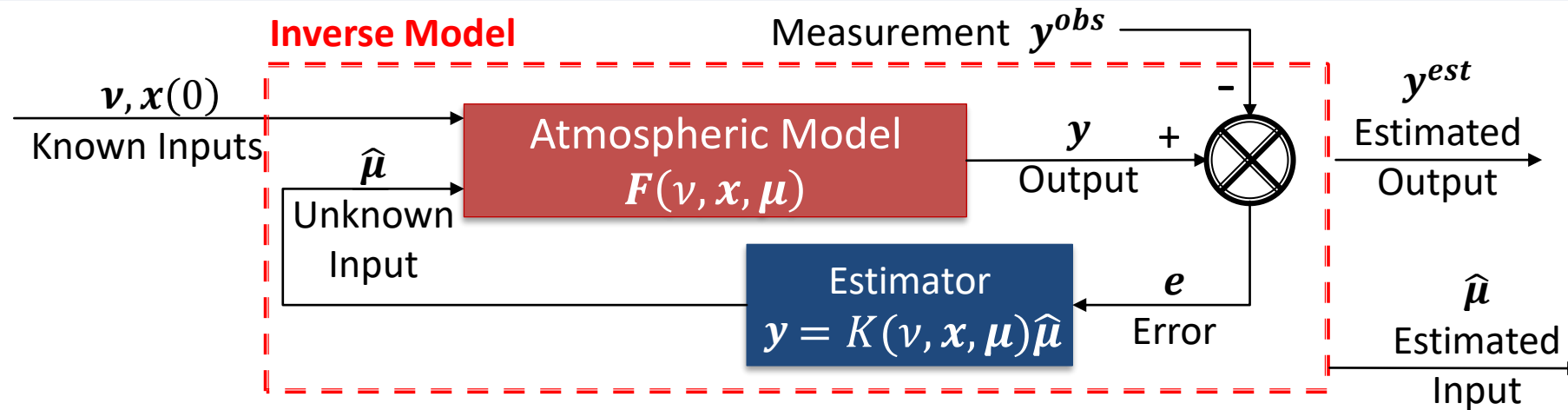
Process control can provide an improved atmospheric inverse modeling technique



Common methods based on least-square minimization:

- Kalman Filter: analytical solution (i.e. [1])
 - Requires reduced model or assumption of linear model: simplifications

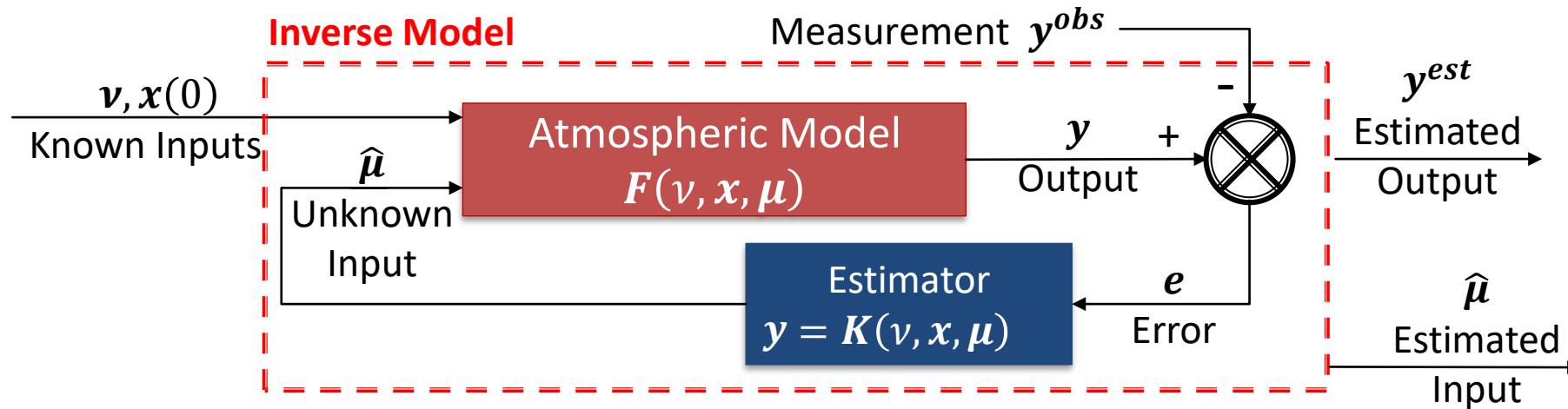
Process control can provide an improved atmospheric inverse modeling technique



Common methods based on least-square minimization:

- Kalman Filter: analytical solution (i.e. [1])
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- “Adjoint method”: numerically solve for Maximum A Posteriori (MAP) solution to inverse problem (i.e. [2])
 - Adjoint is a similar scale to atmospheric model: expensive
 - Calculation of model jacobian with adjoint model: obsolete after model updates

Process control can provide an improved atmospheric inverse modeling technique



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This work formulates an input observer:

- Design an input observer based on passivity theory that estimates model inputs [3]
 - Need derivative of measurements; use available differentiation methods [4, 5]

Passivity-Based Input Observer (PBIO) is based on dynamics of “inventory variables” (\mathbf{z})

$\mathbf{x}(t)$: concentration fields
 \mathbf{v} : Known parameters
 $\boldsymbol{\mu}(t)$: Unknown parameters

Dynamics of inventory variables ($\mathbf{z} \in \mathbb{R}^{N \times 1}$):

All other processes ($\mathbb{R}^{N \times 1}$)

Uncertain processes that we want to estimate ($N \times K$), i.e. \mathbf{E}_{SSA}

$$\frac{d\mathbf{z}}{dt} = \mathbf{f}(\mathbf{x}, \mathbf{v}, t) + \mathbf{G}(\mathbf{v}, t)\boldsymbol{\mu}(t)$$

$$\mathbf{y}_1(t) = \mathbf{z}(t)$$

$$\mathbf{y}_2(t) = \dot{\mathbf{z}}(t)$$

Scaling factors applied to uncertain processes ($K \times 1$)

The model error is defined as deviation between the estimated and measured inventory:

$$\mathbf{e}(t) = \mathbf{y}_1(t) - \mathbf{y}_1^{obs}(t) \qquad \frac{d\mathbf{e}}{dt} = \mathbf{y}_2(t) - \mathbf{y}_2^{obs}(t)$$

The goal is to find $\hat{\boldsymbol{\mu}}$ that decreases the error, so we force the model error to exponentially decay.

$$\frac{d\mathbf{e}}{dt} = -\mathbf{K}_c \mathbf{e}(t)$$

Tuning parameter $\in \mathbb{R}^{N \times N}$

$$K_{c_{i,i}} = \frac{1}{\tau_i}$$

Convergence timescale (hr)

Solve $N \times K$ system of linear equations!

$$\mathbf{f} + \mathbf{G}\hat{\boldsymbol{\mu}}(t) - \mathbf{y}_2^{obs}(t) = -\mathbf{K}_c \left(\mathbf{z}^{est}(t) - \mathbf{y}_1^{obs}(t) \right)$$

$$\Rightarrow \hat{\boldsymbol{\mu}}(t) = \mathbf{A}^{-1} \mathbf{b}$$

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Uncertain processes that we want to estimate ($N \times K$), i.e. E_{SSA}

$$\frac{dz}{dt} = f(x, v, t) + G(v, t)\mu(t)$$

$$y_1(t) = z(t)$$

Scaling factors applied to uncertain processes ($K \times 1$)

The

✓ Computationally efficient & scalable

The

✓ Does not simplify model equations

exp

✓ Independent of model updates

Solve $N \times K$ system of linear equations!

$$f + G\hat{\mu}(t) - y_2^{obs}(t) = -K_c(z^{est}(t) - y_1^{obs}(t))$$

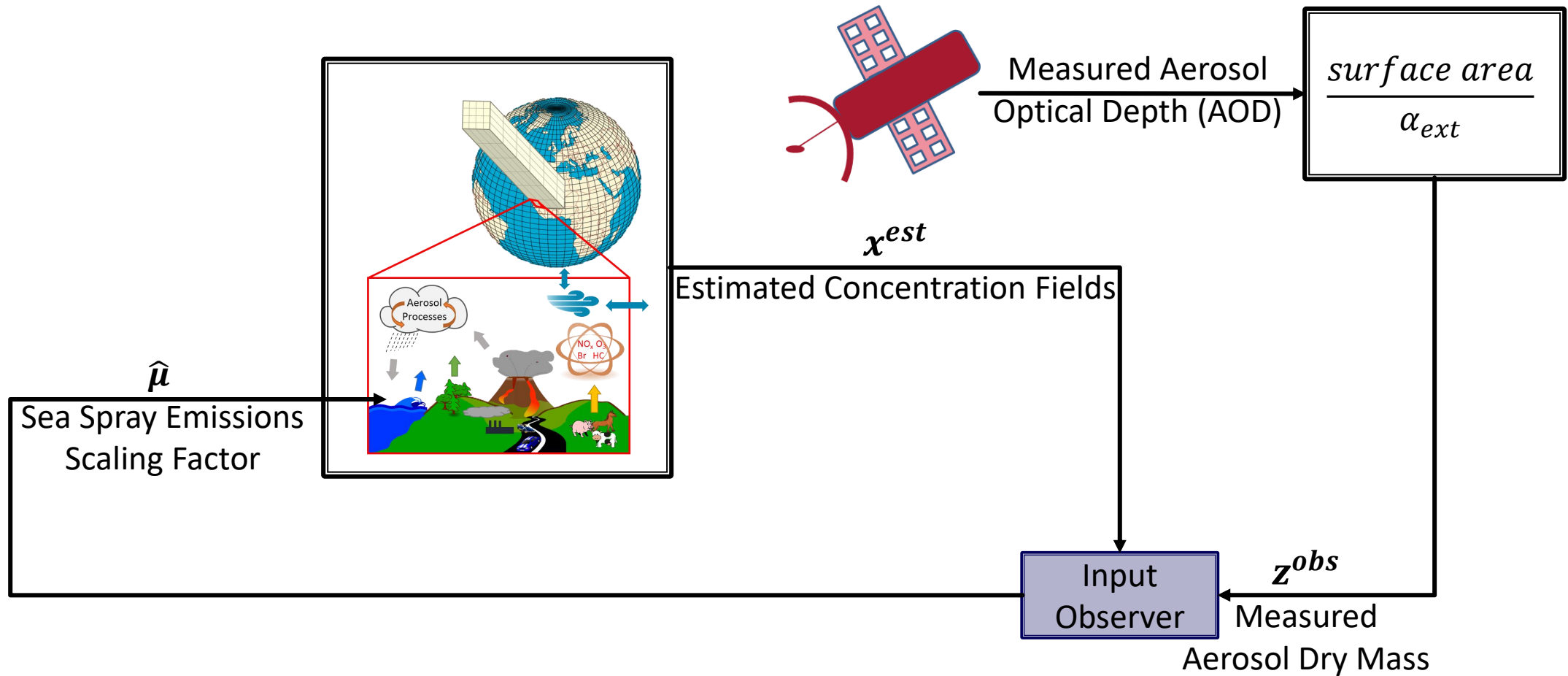
$$\Rightarrow \hat{\mu}(t) = A^{-1}b$$

Tatiraju, S. and Soroush, M., “Parameter Estimator Design with Application to a Chemical Reactor”, *Ind. & Eng. Chem. Res.*, 37 (1998)

Zhao, Z. and Ydstie, B. E., “Passivity-based Input Observer”, *10th IFAC International Symposium ADCHEM* (2018)

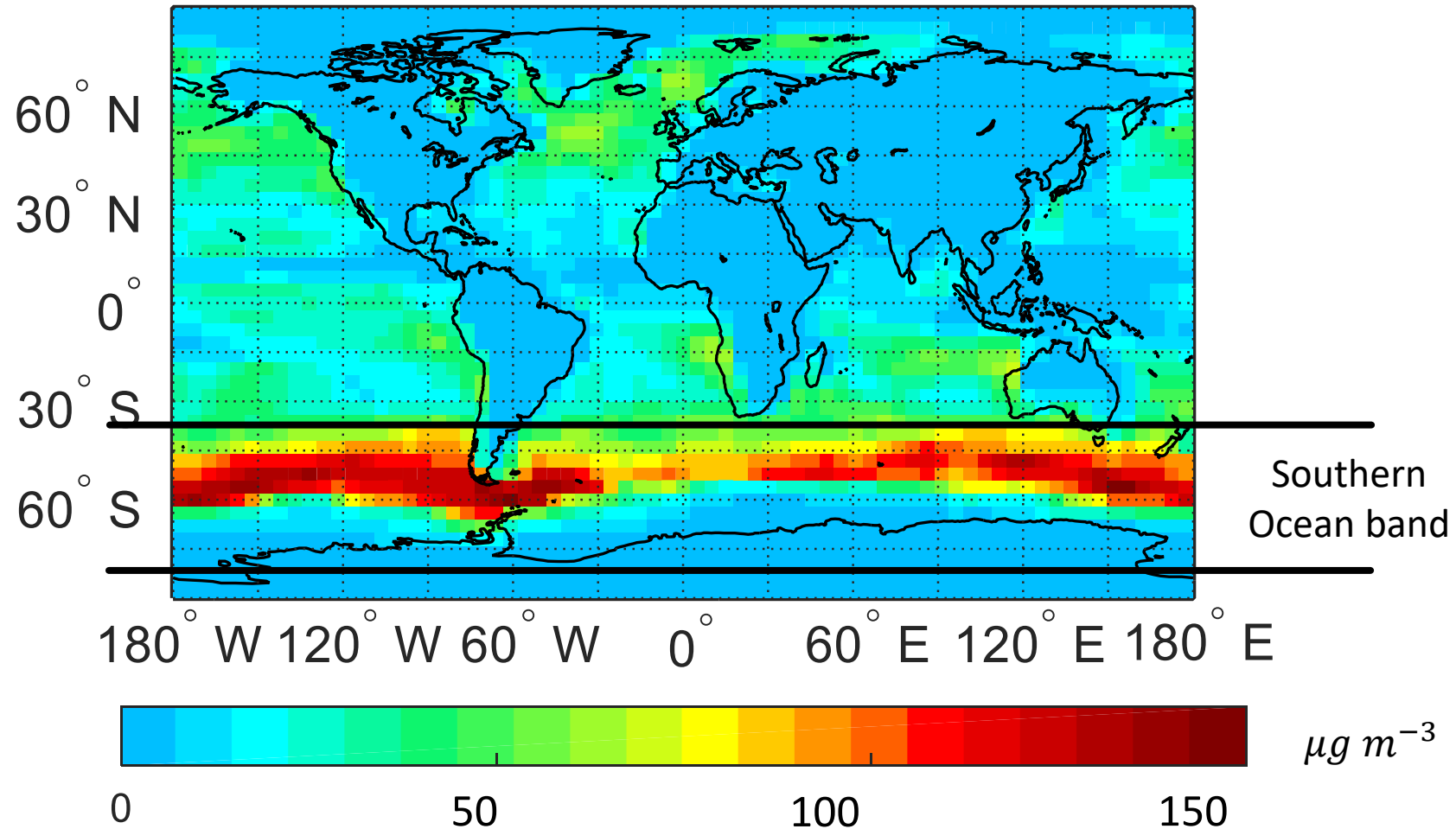
McGuffin, D. et al., “Integrating atmospheric models and measurements using passivity-based input observers”, *Comp. Chem. Eng.*, 129 (2019)

Use total aerosol mass inventory to estimate sea spray emissions with satellite data



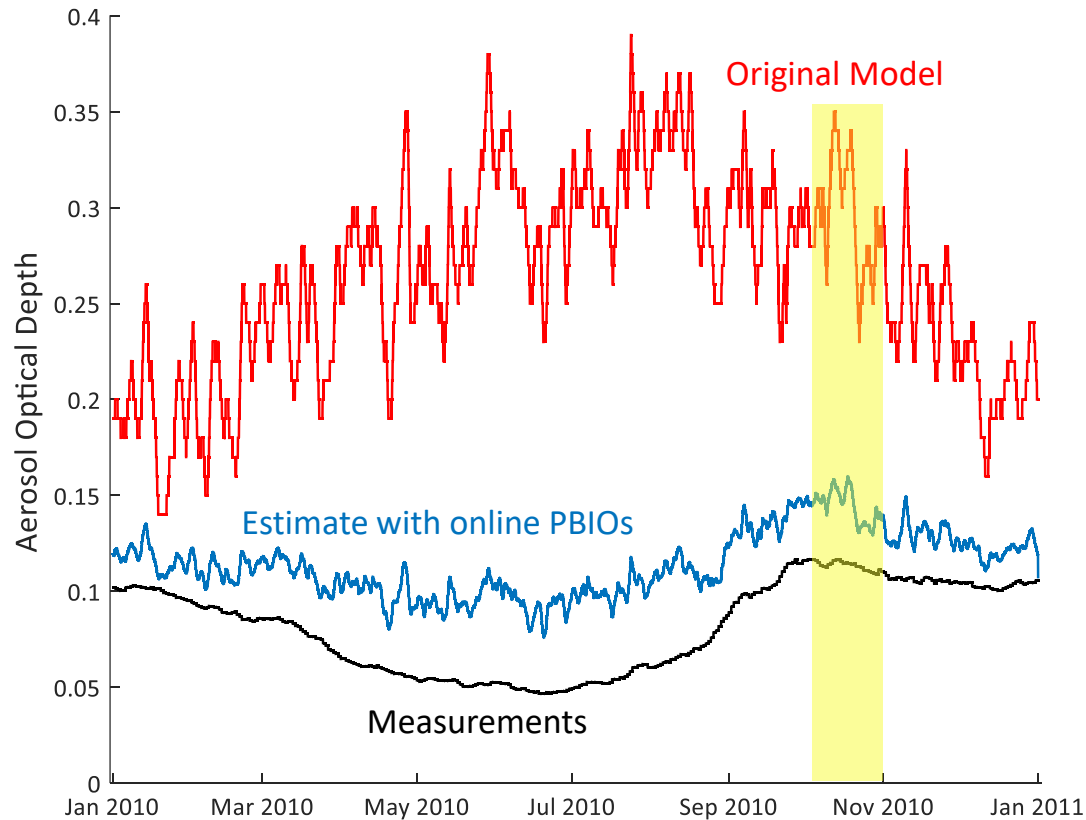
Global model over-predicts sea salt concentration over the Southern Ocean band

- October 2010: Surface NaCl aerosol concentration
- Predicted by GEOS-Chem TOMAS v9-02 at 4°x5° horizontal resolution
- Sea spray over-predicted in Southern Ocean due to high winds
- Use daily AOD measurements to scale sea salt emissions over Southern Ocean band

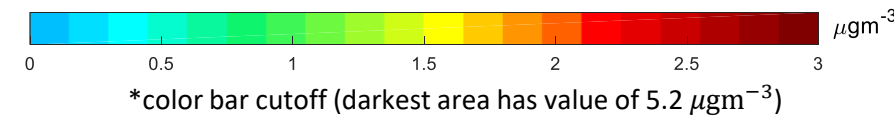
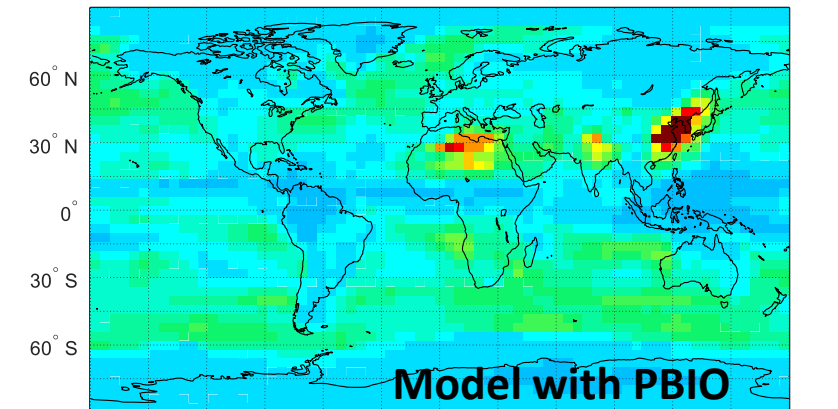
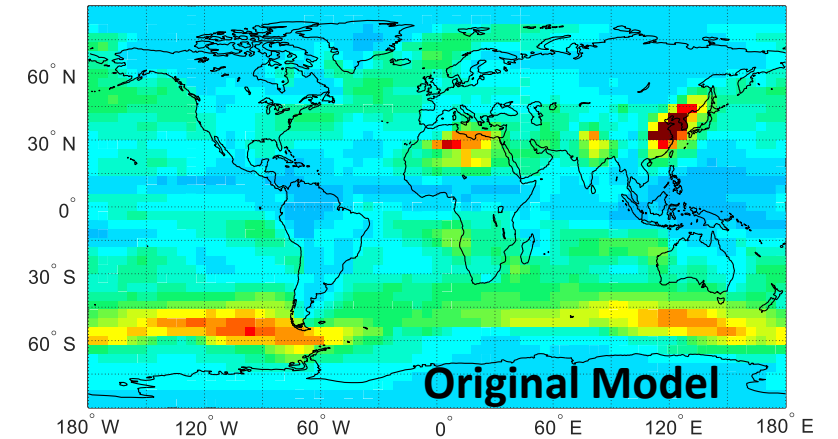


Model with online observers matches measurements

PBIO convergence
timescale = 2 hr
(inverse gain)

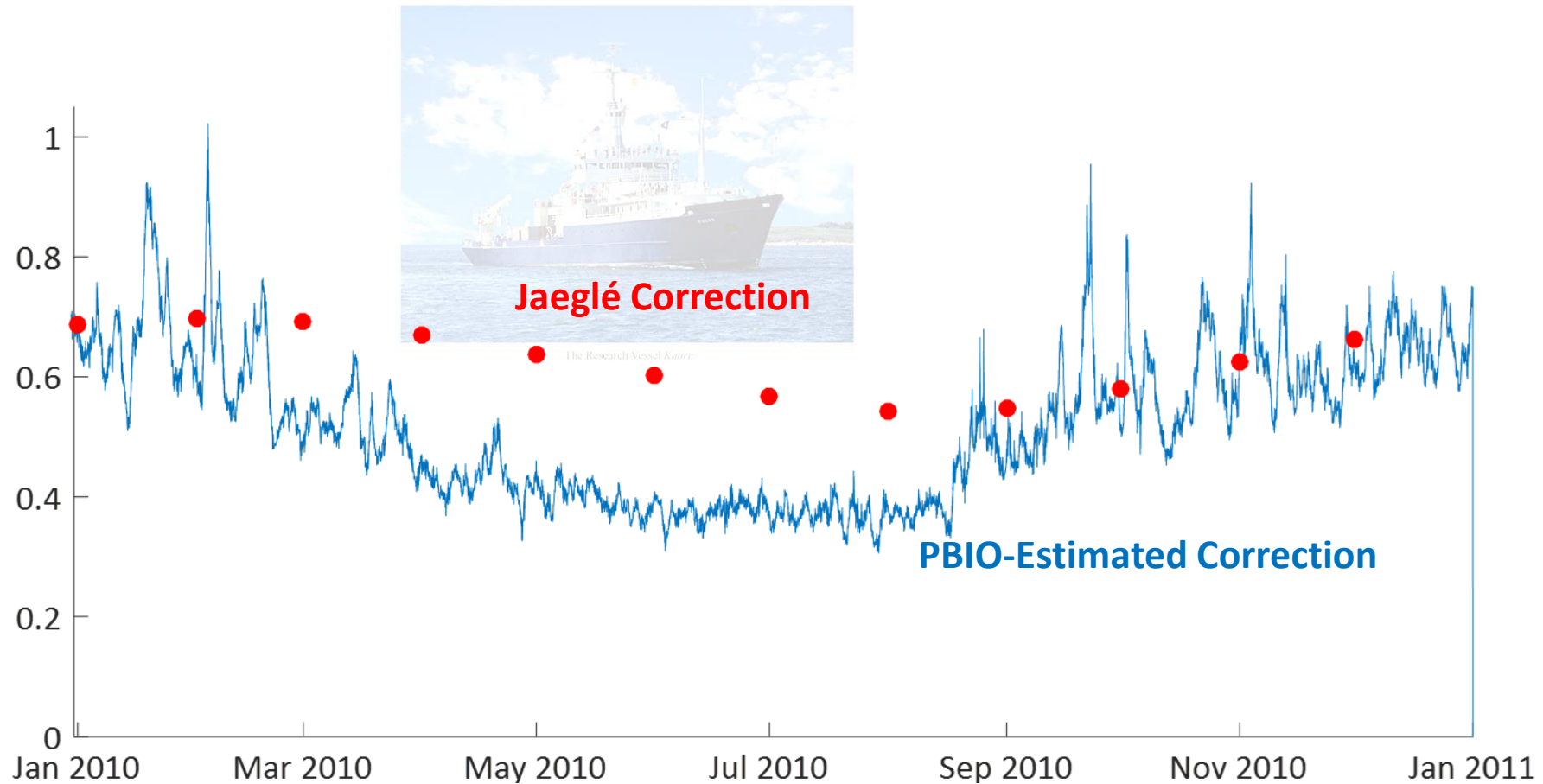


Column Dry Aerosol Mass Concentration



Emission scaling factor trend aligns with sea surface temperature correction in updated model (GEOS-Chem v10-01)

Sea Spray
Emissions
Scaling Factor
 $\hat{\mu}$



Jaeglé, L. et al. "Global distribution of sea salt aerosols: new constraints from in situ and remote sensing observations". *Atmospheric Chemistry and Physics* (2011)

Summary

- Formulated a passivity-based input observer (PBIO) from process control for atmospheric inverse modeling
 - Can be applied to many other applications, but requires finding ideal inventory variables for unknown input parameters
- Application to sea spray emissions **recovers model update** implemented in later version of chemical transport model
- Estimates of sea spray emission can be improved
 - Improve model prediction of AOD by using **radiative transfer calculations**
 - **Investigate other uncertainties** in sea salt loss terms (e.g. deposition velocity or precipitation fields)
 - Use a combination of other satellite observations for **better data coverage**
- Promising technique for estimating nonlinear aerosol physics with **minimal additional computational effort**



Methods Paper



Sea Spray Paper

Thank you!

Questions?



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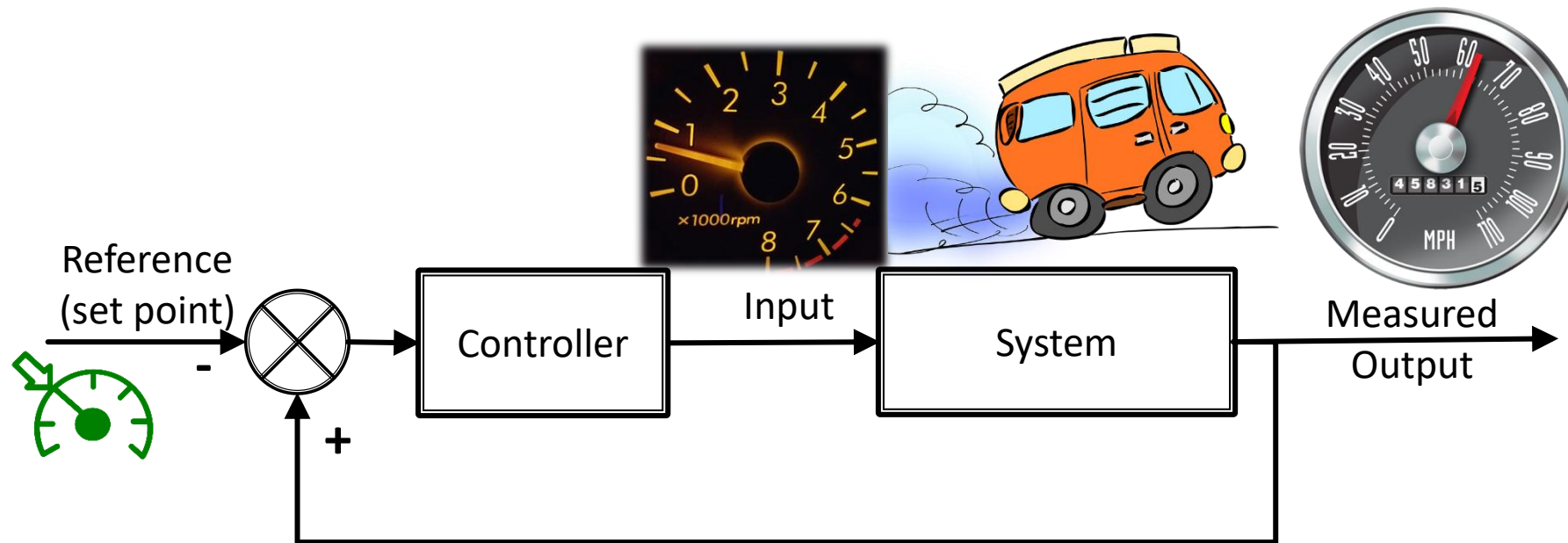
Back up slides

Aerosols affect air quality

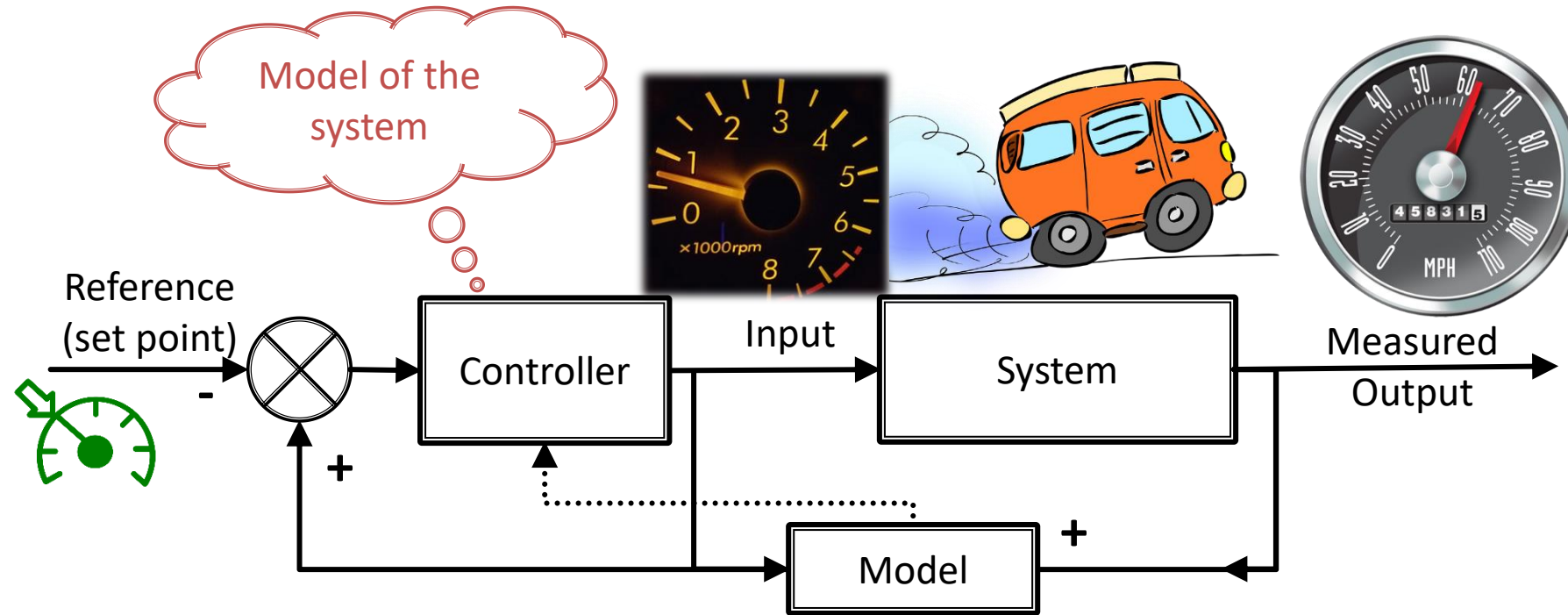
Hazardous pollution vs. COVID-19 lockdowns in New Delhi, India



Input Observers are online estimation tools

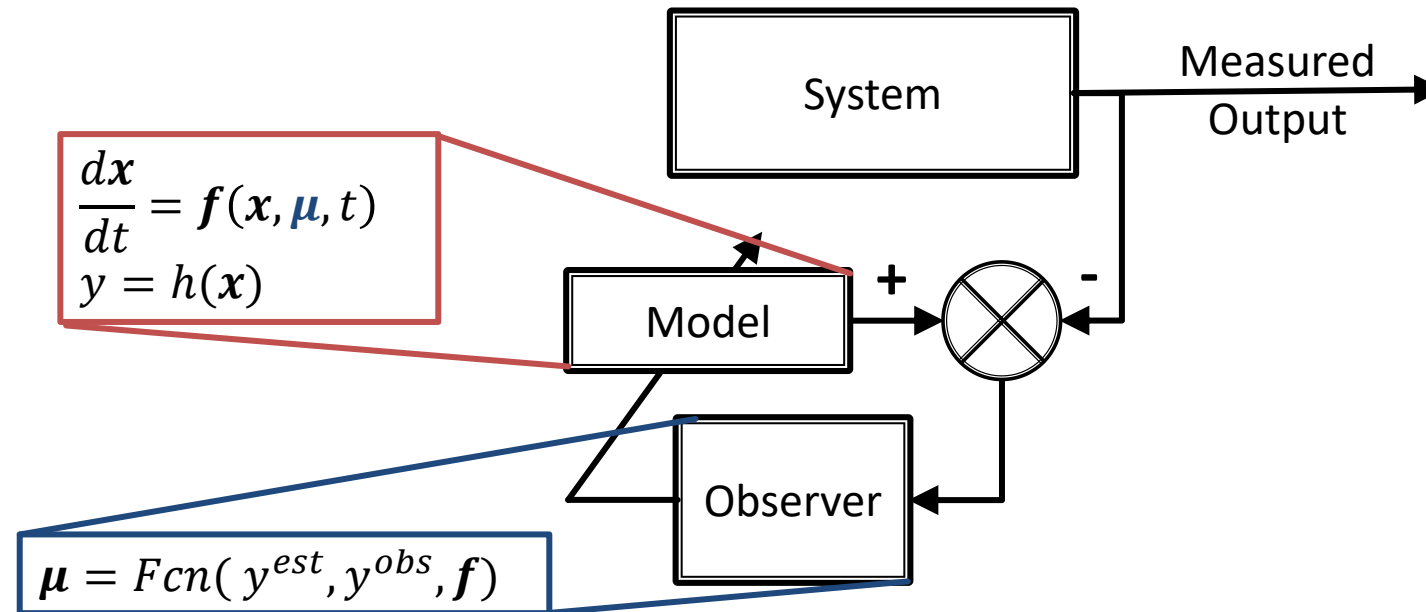


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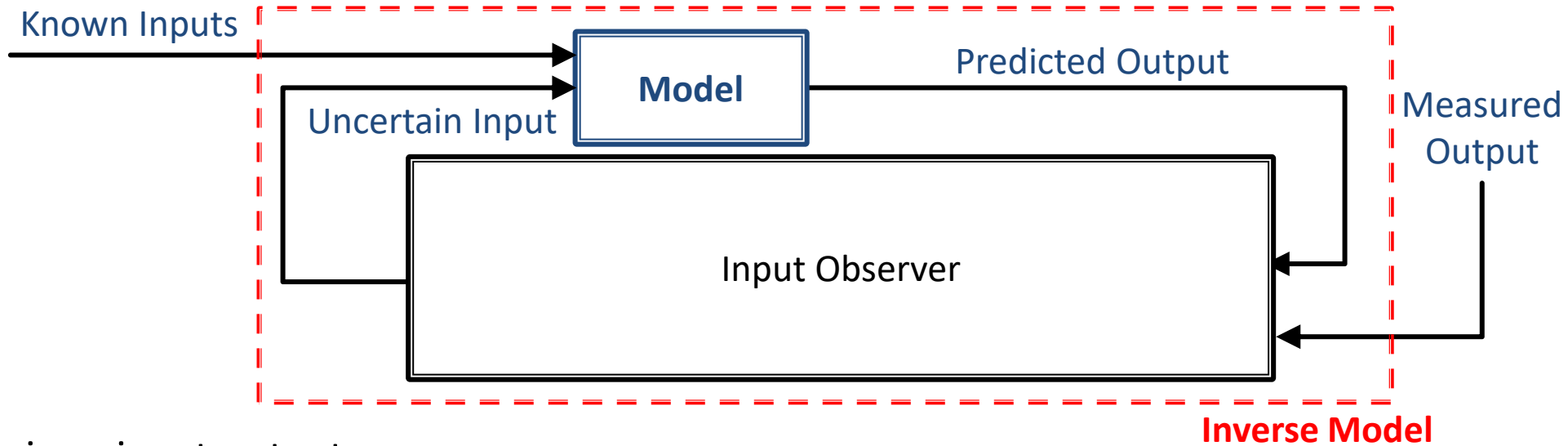


Input Observers are online estimation tools

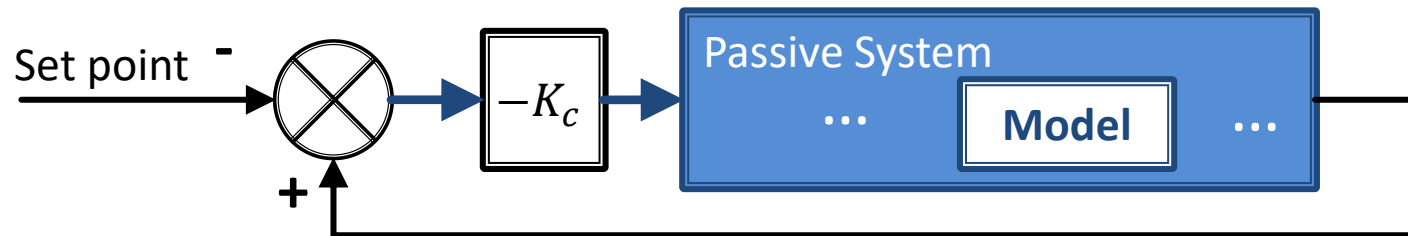
$x(t)$: differential variables
 μ : input variables/parameters
 y : output variables (measurable)



A passivity-based input observer is desirable



- Passivity is an input-output property
- Proportional feedback to any passive system results in a stable system!

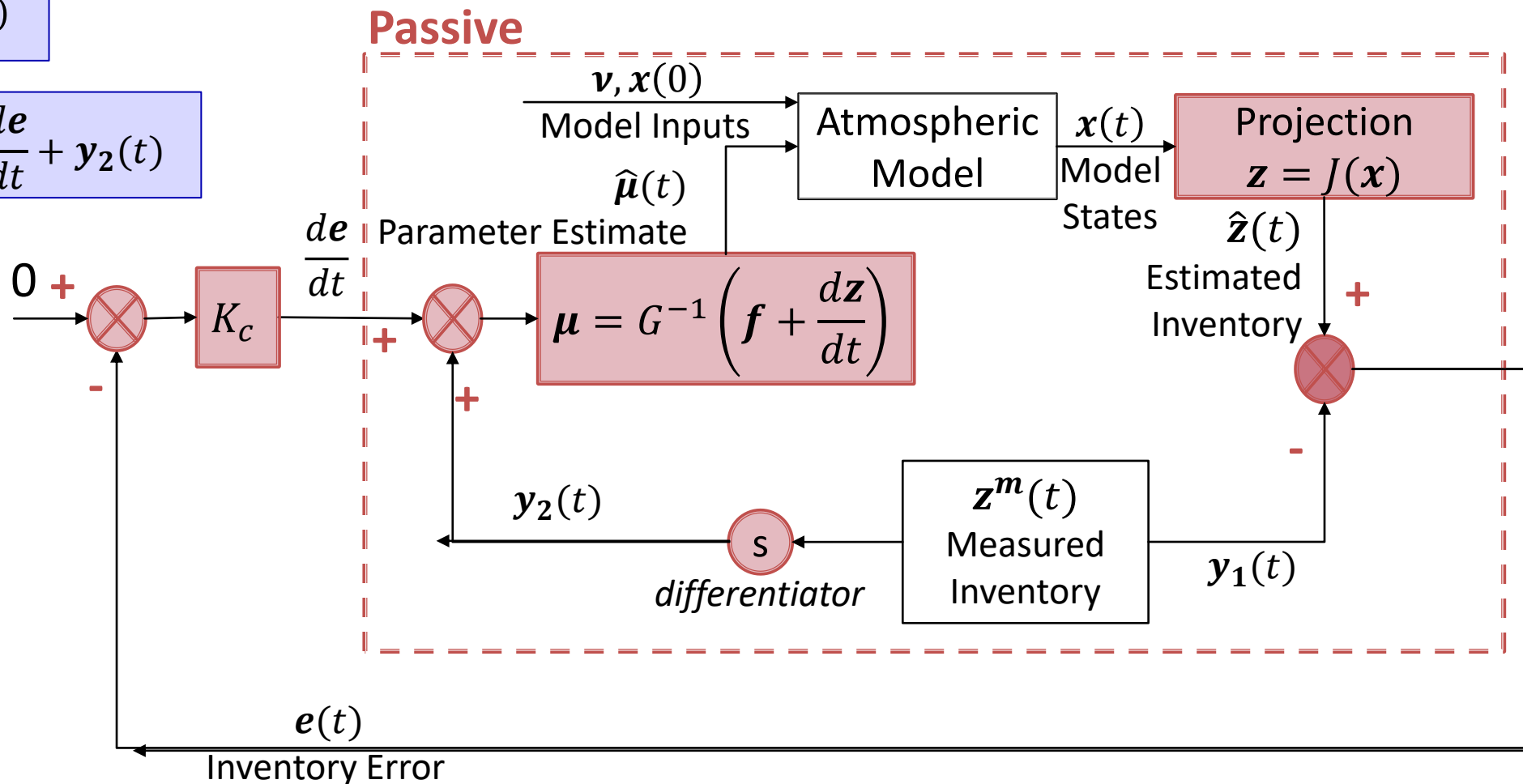


Passivity-based input observer applies proportional feedback to the passive system's output

PBIO block diagram

$$\frac{de}{dt} = -K_c e(t)$$

$$\frac{d\hat{z}}{dt} = \frac{de}{dt} + y_2(t)$$



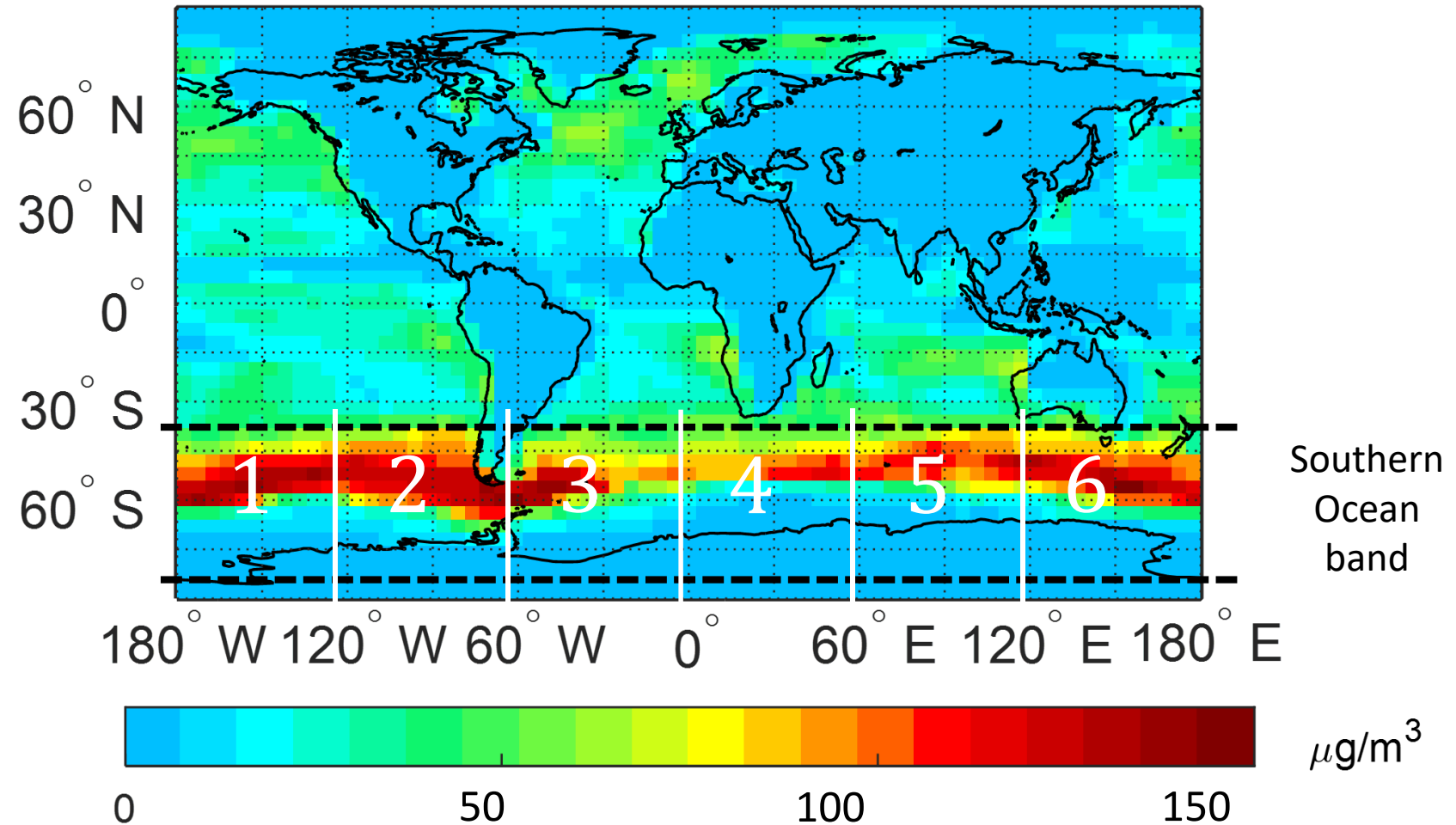
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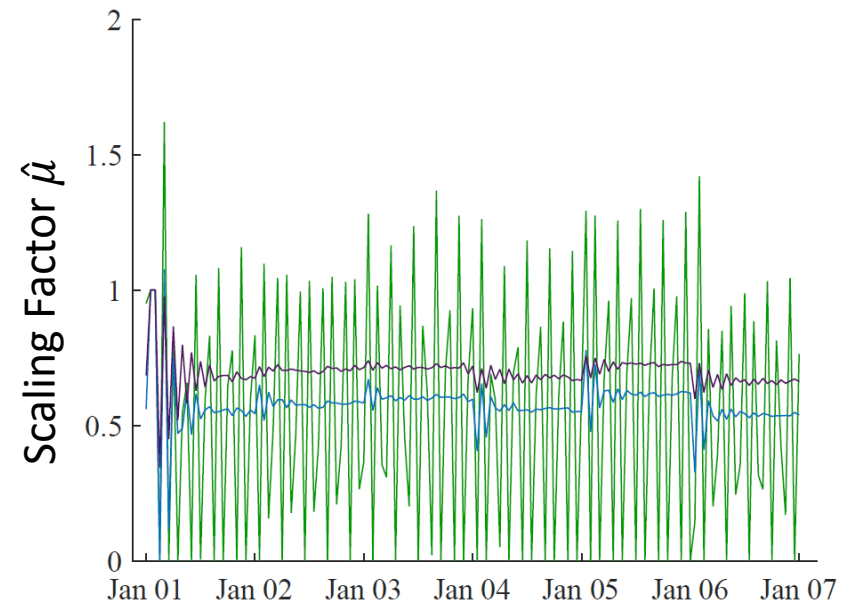
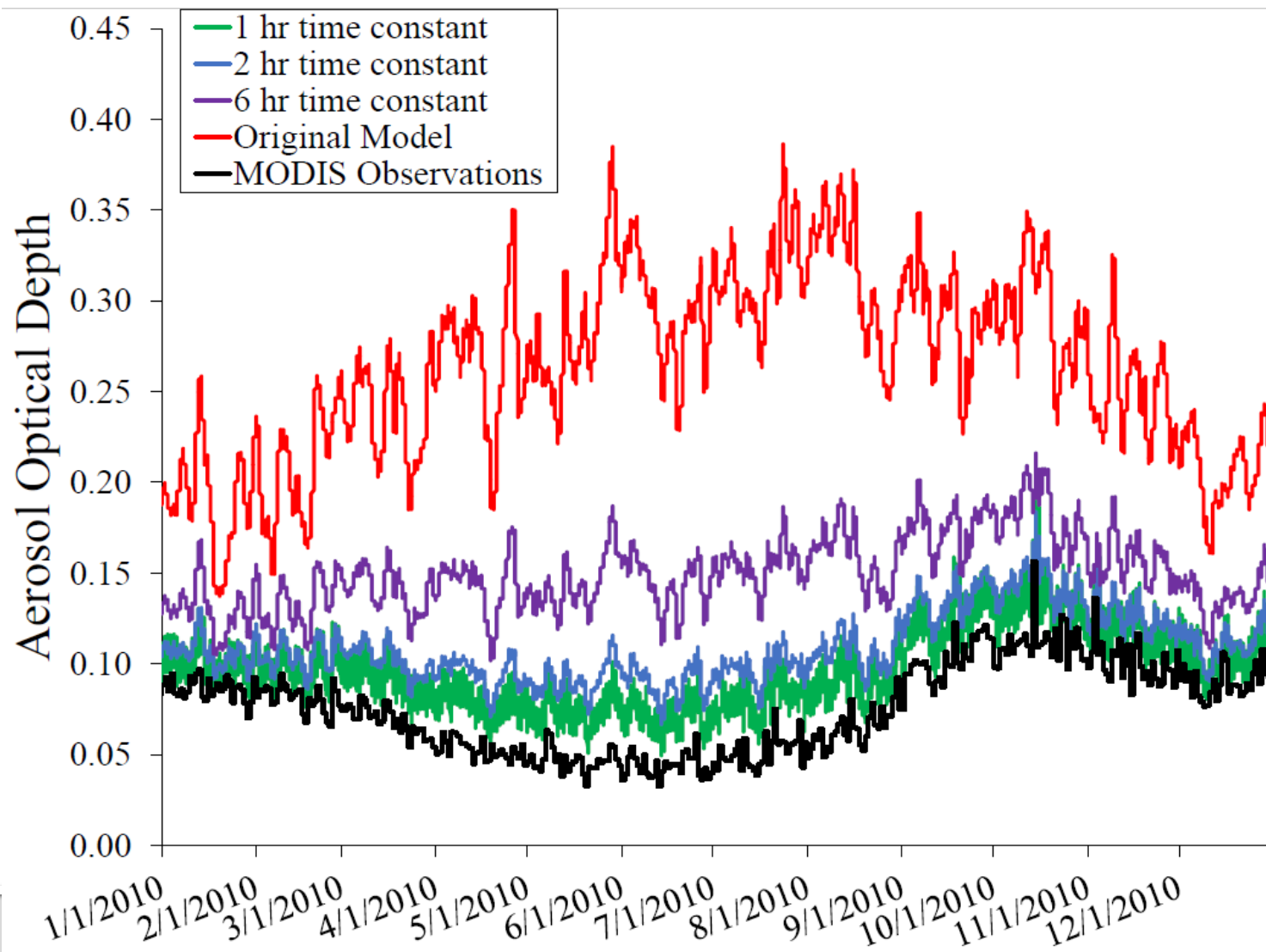
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Global model over-predicts sea salt concentration over the Southern Ocean band

- October 2010: Surface NaCl aerosol concentration
- Predicted by GEOS-Chem TOMAS v9-02 at 4°x5° horizontal resolution
- 6 estimators distributed throughout Southern Ocean band



PBIO Tuning

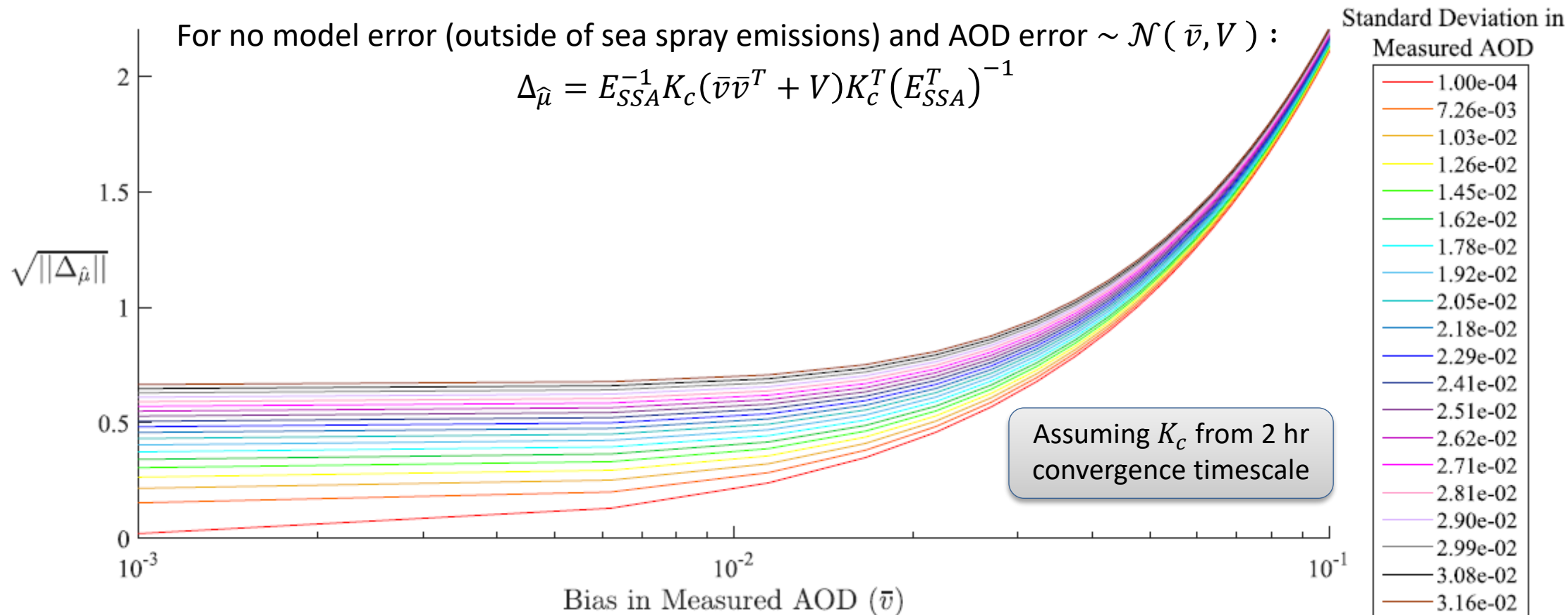


Scaling factor uncertainty depends on measured AOD variance and bias

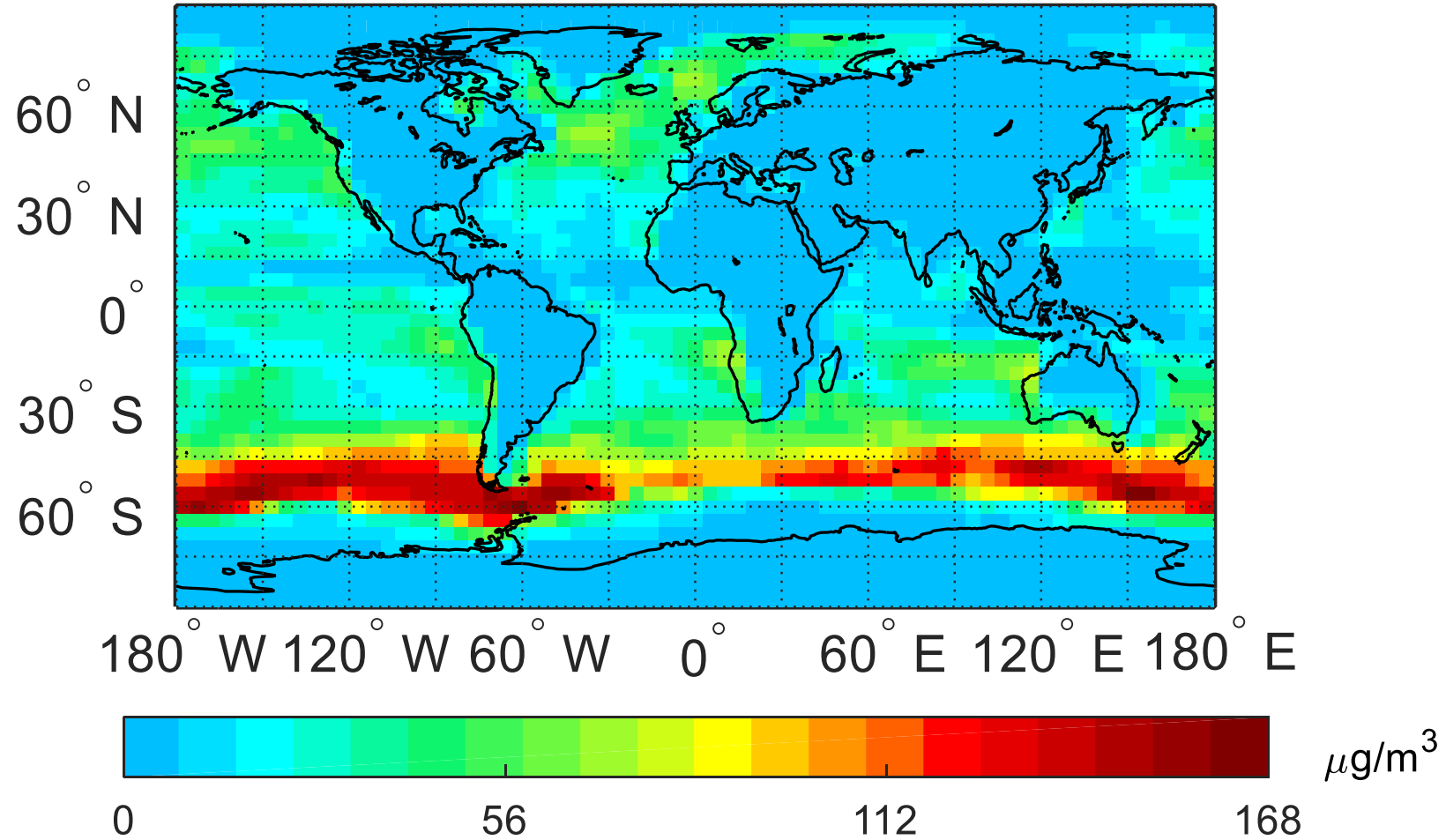
Scaling factor mean-squared error : $\Delta_{\hat{\mu}}$

For no model error (outside of sea spray emissions) and AOD error $\sim \mathcal{N}(\bar{v}, V)$:

$$\Delta_{\hat{\mu}} = E_{SSA}^{-1} K_C (\bar{v}\bar{v}^T + V) K_C^T (E_{SSA}^T)^{-1}$$



Original GEOS-Chem Predicted Sea Salt Aerosol at Surface



Estimated Sea Salt Aerosol at Surface

