

From Monge Transport to Skorokhod Embeddings

Aaron Zeff Palmer
with N. Ghoussoub and Y.H. Kim

University of British Columbia

April 9, 2018

Monge Transport and Skorokhod Embedding

Move snow from μ



to ν , optimally!



$$\inf_{T_{\#}\mu=\nu} \int c(y, T(y))\mu(dy)$$

Given $W_0 \sim \mu$



find a stopping-time with $W_\tau \sim \nu$



as a barrier, $\tau = \inf\{t; W_t \in R\}$.

Tour of Dynamic Problems

① Fixed end-time: $c^L(y, z) = \inf_{\gamma} \int_0^1 \left\{ L(t, \gamma, \dot{\gamma}) dt; \gamma(0) = y, \gamma(1) = z \right\}$.

$$\text{E.g. } L(t, x, v) = \frac{1}{2}|v|^2 \Rightarrow c^L(y, z) = \frac{1}{2}|z - y|^2.$$

Benamou-Brenier, Bernard-Buffoni, Fathi-Figalli

Tour of Dynamic Problems

① Fixed end-time: $c^L(y, z) = \inf_{\gamma} \int_0^1 \left\{ L(t, \gamma, \dot{\gamma}) dt; \gamma(0) = y, \gamma(1) = z \right\}.$

E.g. $L(t, x, v) = \frac{1}{2}|v|^2 \Rightarrow c^L(y, z) = \frac{1}{2}|z - y|^2.$

Benamou-Brenier, Bernard-Buffoni, Fathi-Figalli

② * Free end-time: $c_L(y, z) = \inf_{\gamma, \tau} \int_0^{\tau} \left\{ L(t, \gamma, \dot{\gamma}) dt; \gamma(0) = y, \gamma(\tau) = z \right\}.$

Tour of Dynamic Problems

① Fixed end-time: $c^L(y, z) = \inf_{\gamma} \int_0^1 \left\{ L(t, \gamma, \dot{\gamma}) dt; \gamma(0) = y, \gamma(1) = z \right\}.$

E.g. $L(t, x, v) = \frac{1}{2}|v|^2 \Rightarrow c^L(y, z) = \frac{1}{2}|z - y|^2.$

Benamou-Brenier, Bernard-Buffoni, Fathi-Figalli

② * Free end-time: $c_L(y, z) = \inf_{\gamma, \tau} \int_0^{\tau} \left\{ L(t, \gamma, \dot{\gamma}) dt; \gamma(0) = y, \gamma(\tau) = z \right\}.$

③ Controlled Dynamics: $t \mapsto A \in \mathbb{A}, \dot{\gamma} = f(\gamma, A)$

Minimize $\int_0^{\tau} L(t, \gamma, A) dt.$ Lee-Agrachev (Fixed end-time)

Tour of Dynamic Problems

- ① Fixed end-time: $c^L(y, z) = \inf_{\gamma} \int_0^1 \left\{ L(t, \gamma, \dot{\gamma}) dt; \gamma(0) = y, \gamma(1) = z \right\}$.

E.g. $L(t, x, v) = \frac{1}{2}|v|^2 \Rightarrow c^L(y, z) = \frac{1}{2}|z - y|^2$.

Benamou-Brenier, Bernard-Buffoni, Fathi-Figalli

- ② * Free end-time: $c_L(y, z) = \inf_{\gamma, \tau} \int_0^{\tau} \left\{ L(t, \gamma, \dot{\gamma}) dt; \gamma(0) = y, \gamma(\tau) = z \right\}$.

- ③ Controlled Dynamics: $t \mapsto A \in \mathbb{A}, \dot{\gamma} = f(\gamma, A)$

Minimize $\int_0^{\tau} L(t, \gamma, A) dt$. Lee-Agrachev (Fixed end-time)

- ④ Add Diffusion: $dX_t = f(X_t, A_t) dt + \sigma(X_t, A_t) dW_t$,

$$\inf_{A, \tau} \left\{ E \left[\int_0^{\tau} L(t, X_t, A_t) dt \right]; X_0 \sim \mu, X_{\tau} \sim \nu \right\}.$$

Mikame-Theullen, Gentil-Léonard-Ripani (Fixed end-time)

Tour of Dynamic Problems

- ① Fixed end-time: $c^L(y, z) = \inf_{\gamma} \int_0^1 \left\{ L(t, \gamma, \dot{\gamma}) dt; \gamma(0) = y, \gamma(1) = z \right\}$.

E.g. $L(t, x, v) = \frac{1}{2}|v|^2 \Rightarrow c^L(y, z) = \frac{1}{2}|z - y|^2$.

Benamou-Brenier, Bernard-Buffoni, Fathi-Figalli

- ② * Free end-time: $c_L(y, z) = \inf_{\gamma, \tau} \int_0^{\tau} \left\{ L(t, \gamma, \dot{\gamma}) dt; \gamma(0) = y, \gamma(\tau) = z \right\}$.

- ③ Controlled Dynamics: $t \mapsto A \in \mathbb{A}, \dot{\gamma} = f(\gamma, A)$

Minimize $\int_0^{\tau} L(t, \gamma, A) dt$. Lee-Agrachev (Fixed end-time)

- ④ Add Diffusion: $dX_t = f(X_t, A_t) dt + \sigma(X_t, A_t) dW_t$,

$$\inf_{A, \tau} \left\{ E \left[\int_0^{\tau} L(t, X_t, A_t) dt \right]; X_0 \sim \mu, X_{\tau} \sim \nu \right\}.$$

Mikame-Theullen, Gentil-Léonard-Ripani (Fixed end-time)

- ⑤ * Skorokhod Embedding (without control):

$$\inf_{\tau} \left\{ E \left[\int_0^{\tau} L(t, W_t) dt \right]; W_0 \sim \mu, W_{\tau} \sim \nu \right\}.$$

Literature in probability and finance; Beiglböck-Cox-Heusmann

Problems We Consider

- 1 Classical Existence and Uniqueness of Transport.
Gangbo-McCann, Kantorovich, Sudakov, Evans-Gangbo for Monge

Problems We Consider

- 1 Classical Existence and Uniqueness of Transport.
Gangbo-McCann, Kantorovich, Sudakov, Evans-Gangbo for Monge
- 2 Not so Classical: End-Time as a Hitting-Time.
Pontryagin Transversality for Optimal Control
Root/Rost for Skorokhod Embeddings

Problems We Consider

- 1 Classical Existence and Uniqueness of Transport.
Gangbo-McCann, Kantorovich, Sudakov, Evans-Gangbo for Monge
- 2 Not so Classical: End-Time as a Hitting-Time.
Pontryagin Transversality for Optimal Control
Root/Rost for Skorokhod Embeddings
- 3 Eulerian Formulation with Continuity Equation.
Benamou-Brenier, Bernard-Buffoni for Optimal Transport,
Relates to: Fluids, Kinetic Theory, Phase Transitions.

Problems We Consider

- 1 Classical Existence and Uniqueness of Transport.
Gangbo-McCann, Kantorovich, Sudakov, Evans-Gangbo for Monge
- 2 Not so Classical: End-Time as a Hitting-Time.
Pontryagin Transversality for Optimal Control
Root/Rost for Skorokhod Embeddings
- 3 Eulerian Formulation with Continuity Equation.
Benamou-Brenier, Bernard-Buffoni for Optimal Transport,
Relates to: Fluids, Kinetic Theory, Phase Transitions.
- 4 Kantorovich Duality as Free-Boundary PDE.
Bensoussan-Lions for Optimal Stopping
Dupire, Meilijson, Gassiat, Cox-Wang for Skorokhod Embeddings

Problems We Consider

- 1 Classical Existence and Uniqueness of Transport.
Gangbo-McCann, Kantorovich, Sudakov, Evans-Gangbo for Monge
- 2 Not so Classical: End-Time as a Hitting-Time.
Pontryagin Transversality for Optimal Control
Root/Rost for Skorokhod Embeddings
- 3 Eulerian Formulation with Continuity Equation.
Benamou-Brenier, Bernard-Buffoni for Optimal Transport,
Relates to: Fluids, Kinetic Theory, Phase Transitions.
- 4 Kantorovich Duality as Free-Boundary PDE.
Bensoussan-Lions for Optimal Stopping
Dupire, Meilijson, Gassiat, Cox-Wang for Skorokhod Embeddings
- 5 Understanding Regularity; Viscosity Solutions / Weak Solutions.
Everyone here to name a few

Part 1: Free End-Time and Eulerian formulation

Optimal Transport:

$$V(\mu, \nu) := \inf_{T \# \mu = \nu} \int c_L(y, T(y)) d\mu(y)$$

built from dynamic optimization

$$c_L(y, z) := \inf_{\tau, \gamma(\cdot)} \left\{ \int_0^\tau L(t, \gamma(t), \dot{\gamma}(t)) dt; \gamma(0) = y, \gamma(\tau) = z \right\}.$$



Part 1: Free End-Time and Eulerian formulation

Optimal Transport:

$$V(\mu, \nu) := \inf_{T_{\#}\mu = \nu} \int c_L(y, T(y)) d\mu(y)$$

built from dynamic optimization

$$c_L(y, z) := \inf_{\tau, \gamma(\cdot)} \left\{ \int_0^\tau L(t, \gamma(t), \dot{\gamma}(t)) dt; \gamma(0) = y, \gamma(\tau) = z \right\}.$$



Eulerian Formulation:

$$\text{Thm: } V(\mu, \nu) = E(\mu, \nu) := \inf_{\eta, \rho} \int_0^\infty \int_{T\mathbb{R}^n} L(t, x, v) \eta(t, dx, dv) dt$$

Phase-Space Density $\eta : \mathbb{R}^+ \rightarrow \mathcal{M}(T\mathbb{R}^n)$, $\eta \geq 0$, $\int_{T_x\mathbb{R}^n} \eta(0, x, dv) = \mu(x)$

Stopping-Measure $\rho \in \mathcal{M}(\mathbb{R}^+ \times \mathbb{R}^n)$, $\rho \geq 0$, $\int_0^\infty \rho(dt, x) = \nu(x)$

$$\rho(t, x) + \partial_t \int_{T_x\mathbb{R}^n} \eta(t, x, dv) + \nabla_x \cdot \int_{T_x\mathbb{R}^n} v \eta(t, x, dv) = 0$$

Duality Review: Optimal Transport for Fixed End-Time

The general Kantorovich dual problem is

$$W(\mu, \nu) := \sup \left\{ \int \psi d\nu - \int \phi d\mu; \quad \psi(z) - \phi(y) \leq c^L(y, z) \right\}$$

Optimizer satisfies $(c^L(y, z) = \inf_{\gamma} \int_0^1 L(t, \gamma, \dot{\gamma}) dt; \gamma(0) = y, \gamma(1) = z)$

$$\phi(y) = \sup_z \{ \psi(z) - c^L(y, z) \} = \sup_{\gamma} \left\{ \psi(\gamma(1)) - \int_0^1 L(t, \gamma, \dot{\gamma}) dt \right\}.$$

Duality Review: Optimal Transport for Fixed End-Time

The general Kantorovich dual problem is

$$W(\mu, \nu) := \sup \left\{ \int \psi d\nu - \int \phi d\mu; \quad \psi(z) - \phi(y) \leq c^L(y, z) \right\}$$

Optimizer satisfies $(c^L(y, z) = \inf_{\gamma} \int_0^1 L(t, \gamma, \dot{\gamma}) dt; \gamma(0) = y, \gamma(1) = z)$

$$\phi(y) = \sup_z \{ \psi(z) - c^L(y, z) \} = \sup_{\gamma} \left\{ \psi(\gamma(1)) - \int_0^1 L(t, \gamma, \dot{\gamma}) dt \right\}.$$

Bernard-Buffoni, Fathi-Figalli: $\phi = J_{\psi}(0, \cdot)$,

Let $H(t, x, p) = \sup_v \{ p \cdot v - L(t, x, v) \}$

$$\partial_t J_{\psi}(t, x) + H(t, x, \nabla J_{\psi}(t, x)) = 0, \quad J_{\psi}(1, \cdot) = \psi.$$

Hamiltonian flow, $p(t) = \nabla J_{\psi}(t, \gamma(t))$:

$$\dot{\gamma}(t) = D_p H(t, \gamma(t), p(t)), \quad \dot{p}(t) = -D_x H(t, \gamma(t), p(t))$$

Eulerian Duality: Free End-Time

The dual problem via Eulerian formulation:

$$\text{Thm}' : W(\mu, \nu) = D(\mu, \nu) := \sup_{(J, \psi) \in N(L)} \int_{\mathbb{R}^n} \psi(z) \nu(dz) - \int_{\mathbb{R}^n} J(0, y) \mu(dy),$$

$(J, \psi) \in N(L)$ satisfy

$$\begin{aligned} \psi(x) - J(t, x) &\leq 0 \\ \partial_t J(t, x) + v \cdot \nabla J(t, x) - L(t, x, v) &\leq 0. \end{aligned}$$

Eulerian Duality: Free End-Time

The dual problem via Eulerian formulation:

$$\text{Thm}' : W(\mu, \nu) = D(\mu, \nu) := \sup_{(J, \psi) \in N(L)} \int_{\mathbb{R}^n} \psi(z) \nu(dz) - \int_{\mathbb{R}^n} J(0, y) \mu(dy),$$

$(J, \psi) \in N(L)$ satisfy

$$\begin{aligned} \psi(x) - J(t, x) &\leq 0 \\ \partial_t J(t, x) + v \cdot \nabla J(t, x) - L(t, x, v) &\leq 0. \end{aligned}$$

Thm'': Optimal J_ψ satisfies the Hamilton-Jacobi-Bellman inequality:

$$\max \left\{ \begin{array}{l} \psi(t, x) - J_\psi(t, x), \\ \partial_t J_\psi(t, x) + H(t, x, \nabla J_\psi(t, x)) \end{array} \right\} = 0.$$

$H(t, x, p) = \sup_v \{p \cdot v - L(t, x, v)\}$ (proof by Perron's method)

Dynamic programming shows equivalence:

$$\phi(y) = \sup_z \{ \psi(z) - c_L(y, z) \} = \sup_{\gamma, \tau} \left\{ \psi(\gamma(\tau)) - \int_0^\tau L(t, \gamma, \dot{\gamma}) dt \right\}.$$

Monotonicity by Viscosity Solution Methods

Proposition

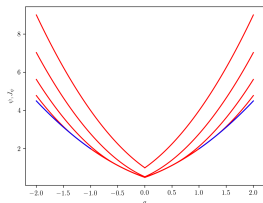
A. $t \mapsto L$ increasing $\Rightarrow t \mapsto J_\psi$ decreasing.

B. $t \mapsto L$ decreasing $\Rightarrow t \mapsto J_\psi$ increasing.

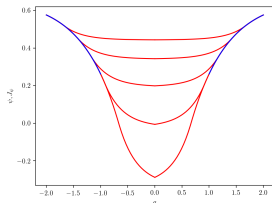
Let $s(x) = \inf\{t; J_\psi(t, x) = \psi(x)\}$ (for A., for B. use sup);

We have the transversality condition:

$$H(s(x), x, \nabla\psi(x)) = 0.$$



A.



B.

Hitting-Time

With A. or B., and good H , μ , ν :

Theorem

Unique optimal $\pi^ \in \Pi(\mu, \nu)$ given by $T(x) := \gamma^x(\tau^x)$.*

Pontryagin transversality

$$H(\tau^x, T(x), \nabla\psi(T(x))) = 0, \quad \text{so } \tau^x = s(T(x)).$$

Hamiltonian flow for $t < \tau^x$, $p(\tau^x) = \nabla\psi(T(x))$:

$$\dot{\gamma}(t) = D_p H(t, \gamma(t), p(t)), \quad \dot{p}(t) = -D_x H(t, \gamma(t), p(t))$$

Hitting-Time

With A. or B., and good H , μ , ν :

Theorem

Unique optimal $\pi^ \in \Pi(\mu, \nu)$ given by $T(x) := \gamma^x(\tau^x)$.*

Pontryagin transversality

$$H(\tau^x, T(x), \nabla\psi(T(x))) = 0, \quad \text{so } \tau^x = s(T(x)).$$

Hamiltonian flow for $t < \tau^x$, $p(\tau^x) = \nabla\psi(T(x))$:

$$\dot{\gamma}(t) = D_p H(t, \gamma(t), p(t)), \quad \dot{p}(t) = -D_x H(t, \gamma(t), p(t))$$

Optimal attainment of Eulerian problem with $\text{supp } \rho \in \{(s(x), x)\}$.

Hitting-Time

With A. or B., and good H , μ , ν :

Theorem

Unique optimal $\pi^* \in \Pi(\mu, \nu)$ given by $T(x) := \gamma^x(\tau^x)$.

Pontryagin transversality

$$H(\tau^x, T(x), \nabla\psi(T(x))) = 0, \quad \text{so } \tau^x = s(T(x)).$$

Hamiltonian flow for $t < \tau^x$, $p(\tau^x) = \nabla\psi(T(x))$:

$$\dot{\gamma}(t) = D_p H(t, \gamma(t), p(t)), \quad \dot{p}(t) = -D_x H(t, \gamma(t), p(t))$$

Optimal attainment of Eulerian problem with $\text{supp } \rho \in \{(s(x), x)\}$.

If $J \in C^1$ then $\hat{\eta} = \int_{T_x \mathbb{R}^n} d\eta$ is determined by (for A.)

$$\partial_t \hat{\eta} + \nabla_x \cdot D_p H(\nabla J) \hat{\eta} = 0, \quad t < s(x)$$

Unresolved: Is η uniquely determined with J Lipschitz?

Relationship to Classical Problems

Suppose

$$L(t, x, v) := \begin{cases} g'(t), & |v| \leq 1 \\ \infty, & |v| > 1 \end{cases}$$

with $g(0) = 0$ and $g'(t) \geq 0$.

If g is convex or concave, characteristics are straight lines, cost is

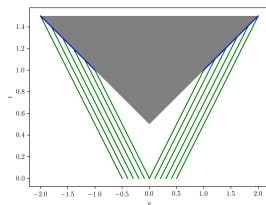
$$c_L(y, z) = g(|z - y|).$$

Gangbo-McCann for Monge Map

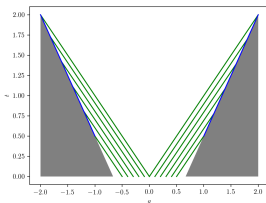
A. $\Leftrightarrow g$ convex

B. $\Leftrightarrow g$ concave

A.



B.



Part 2: Skorokhod Embeddings

Uncontrolled diffusion

$$W_0 \sim \mu$$

Stopping-time to transport

$$W_\tau \sim \nu.$$

28 constructions in 1-D

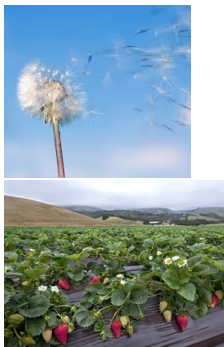
Azéma-Yor, Perkins, Root, Rost ...

Our problem is (multi-D):

$$V(\mu, \nu) := \inf_{\tau} E \left[\int_0^{\tau} L(t, W_t) dt; W_0 \sim \mu, W_{\tau} \sim \nu \right].$$

(Real applications in mathematical finance; options pricing)

Hobson, Obłój, Henry-Labordere ...



Eulerian Formulation and Duality

No optimal transportation cost!

- Eulerian Formulation:

$$E(\mu, \nu) := \inf_{(\eta, \rho) \in \Gamma(\mu, \nu)} \int_0^\infty \int_{\mathbb{R}^n} L(t, x) \eta(t, x) dx dt,$$

$(\eta, \rho) \in \Gamma(\mu, \nu)$ if $\eta \geq 0$, $\rho \geq 0$, and (weakly)

$$\rho + \partial_t \eta = \frac{1}{2} \Delta \eta, \quad \eta(0, \cdot) = \mu, \quad \int_0^\infty \rho(dt, \cdot) = \nu.$$

Eulerian Formulation and Duality

No optimal transportation cost!

- Eulerian Formulation:

$$E(\mu, \nu) := \inf_{(\eta, \rho) \in \Gamma(\mu, \nu)} \int_0^\infty \int_{\mathbb{R}^n} L(t, x) \eta(t, x) dx dt,$$

$(\eta, \rho) \in \Gamma(\mu, \nu)$ if $\eta \geq 0$, $\rho \geq 0$, and (weakly)

$$\rho + \partial_t \eta = \frac{1}{2} \Delta \eta, \quad \eta(0, \cdot) = \mu, \quad \int_0^\infty \rho(dt, \cdot) = \nu.$$

- Dual Problem (via Eulerian Formulation):

$$\text{Thm : } V(\mu, \nu) = E(\mu, \nu) = D(\mu, \nu) := \sup_{(J, \psi) \in \Upsilon(L)} \int \psi d\nu - \int J(0, \cdot) d\mu,$$

$(J, \psi) \in \Upsilon(L)$ if

$$\psi(x) - J(t, x) \leq 0$$

$$\partial_t J(t, x) + \frac{1}{2} \Delta J(t, x) \leq L(t, x)$$

Dual Attainment

Maximize:

$$\int \psi d\nu - \int J_\psi(0, \cdot) d\mu; \quad \max \left\{ \partial_t J_\psi + \frac{1}{2} \Delta J_\psi - L \right\} = 0.$$

Remaining degrees of freedom for (ψ, J_ψ)

- Subtract a positive function from ψ . (Let $\psi = \inf_{t \geq 0} J_\psi$.)
- Subtract a subharmonic function from ψ and J_ψ . (Harder to handle. This shows that $D(\mu, \nu) = \infty$ unless $\mu \leq_{SH} \nu$.)

$$\int h d\mu \leq \int h d\nu \quad \forall h \text{ s.t. } \Delta h \geq 0$$

Theorem (in progress)

Under suitable assumptions the dual problem is attained at regular (ψ, J_ψ) .

Complementary Slackness

- To verify optimality:
 $(\eta, \rho) \in \Gamma(\mu, \nu)$ and $(\psi, J_\psi) \in \Upsilon(L)$ are optimal if and only if

$$\int_0^\infty \int_{\mathbb{R}^n} L(t, x) \eta(t, x) dx dt = \int_{\mathbb{R}^n} \psi d\nu - \int_{\mathbb{R}^n} J(0, \cdot) d\mu.$$

Complementary Slackness

- To verify optimality:

$(\eta, \rho) \in \Gamma(\mu, \nu)$ and $(\psi, J_\psi) \in \Upsilon(L)$ are optimal if and only if

$$\int_0^\infty \int_{\mathbb{R}^n} L(t, x) \eta(t, x) dx dt = \int_{\mathbb{R}^n} \psi d\nu - \int_{\mathbb{R}^n} J(0, \cdot) d\mu.$$

- If (ψ, J_ψ) and (η, ρ) are optimal and regular then:

$$\psi(x) = J_\psi(t, x), \quad \rho \text{ a.e. } (t, x),$$

and

$$\partial_t J_\psi(t, x) + \frac{1}{2} \Delta J_\psi(t, x) = L(t, x), \quad \eta \text{ a.e. } (t, x).$$

Proposition

A. $t \mapsto L$ is increasing $\Rightarrow t \mapsto J_\psi$ is decreasing.

B. $t \mapsto L$ is decreasing $\Rightarrow t \mapsto J_\psi$ is increasing.

$s(x) = \inf\{t; J_\psi(t, x) = \psi(x)\}$ (For B. use sup). We can choose ψ to solve

$$\frac{1}{2}\Delta\psi(x) = L(s(x), x).$$

Proposition

A. $t \mapsto L$ is increasing $\Rightarrow t \mapsto J_\psi$ is decreasing.

B. $t \mapsto L$ is decreasing $\Rightarrow t \mapsto J_\psi$ is increasing.

$s(x) = \inf\{t; J_\psi(t, x) = \psi(x)\}$ (For B. use sup). We can choose ψ to solve

$$\frac{1}{2}\Delta\psi(x) = L(s(x), x).$$

- By complementary slackness, $\eta(t, \cdot) \in H_0^1(\{x; t < s(x)\})$, is unique given s and A. If $s \in C^1$, $\nu(x) = \nabla s(x) \cdot \nabla \eta(s(x), x)$.

Proposition

A. $t \mapsto L$ is increasing $\Rightarrow t \mapsto J_\psi$ is decreasing.

B. $t \mapsto L$ is decreasing $\Rightarrow t \mapsto J_\psi$ is increasing.

$s(x) = \inf\{t; J_\psi(t, x) = \psi(x)\}$ (For B. use sup). We can choose ψ to solve

$$\frac{1}{2}\Delta\psi(x) = L(s(x), x).$$

- By complementary slackness, $\eta(t, \cdot) \in H_0^1(\{x; t < s(x)\})$, is unique given s and A. If $s \in C^1$, $\nu(x) = \nabla s(x) \cdot \nabla \eta(s(x), x)$.
- **Rigidity Theorem:** If s is optimal for increasing L , s is optimal for any increasing \tilde{L} (For B. $t > s(x)$ and $-\nu$).

Proposition

A. $t \mapsto L$ is increasing $\Rightarrow t \mapsto J_\psi$ is decreasing.

B. $t \mapsto L$ is decreasing $\Rightarrow t \mapsto J_\psi$ is increasing.

$s(x) = \inf\{t; J_\psi(t, x) = \psi(x)\}$ (For B. use sup). We can choose ψ to solve

$$\frac{1}{2}\Delta\psi(x) = L(s(x), x).$$

- By complementary slackness, $\eta(t, \cdot) \in H_0^1(\{x; t < s(x)\})$, is unique given s and A. If $s \in C^1$, $\nu(x) = \nabla s(x) \cdot \nabla \eta(s(x), x)$.
- **Rigidity Theorem:** If s is optimal for increasing L , s is optimal for any increasing \tilde{L} (For B. $t > s(x)$ and $-\nu$).
- Martingale Duality of **Beigleböck-Cox-Huesmann:**
Maximize $\int \psi d\nu - E[M_0]$, $W_0 \sim \mu$, M_t martingale,

$$\psi(W_t) - M_t \leq 0 \text{ a.s.} \quad M_t = J_\psi(t, W_t) + E \left[\int_t^T L(s, W_s) ds \right]$$

Stochastic Transportation

General stochastic control with free end-time:

$$V(\mu, \nu) := \inf_{\tau, A(\cdot)} E \left[\int_0^\tau L(t, X_t, A_t) dt \right]$$

with $dX_t = f(X_t, A_t)dt + \sigma(X_t, A_t)dW_t$, $X_0 \sim \mu$, $X_\tau \sim \nu$. Eulerian form:

$$\rho + \partial_t \int_{\mathbb{A}} d\eta + \nabla \cdot \int_{\mathbb{A}} f d\eta = \frac{1}{2} \nabla^2 \cdot \int_{\mathbb{A}} \sigma^2 d\eta.$$

Stochastic Transportation

General stochastic control with free end-time:

$$V(\mu, \nu) := \inf_{\tau, A(\cdot)} E \left[\int_0^\tau L(t, X_t, A_t) dt \right]$$

with $dX_t = f(X_t, A_t)dt + \sigma(X_t, A_t)dW_t$, $X_0 \sim \mu$, $X_\tau \sim \nu$. Eulerian form:

$$\rho + \partial_t \int_{\mathbb{A}} d\eta + \nabla \cdot \int_{\mathbb{A}} f d\eta = \frac{1}{2} \nabla^2 \cdot \int_{\mathbb{A}} \sigma^2 d\eta.$$

Dual problem is

$$W(\mu, \nu) := \sup_{\psi, J} \left\{ \int \psi d\nu - \int J(0, \cdot) d\mu \right\}$$

subject to

$$\begin{aligned} \psi(x) - J(t, x) &\leq 0 \\ \partial_t J + f(\cdot, A) \cdot \nabla J + \frac{1}{2} \sigma^2(\cdot, A) \cdot \nabla^2 J &\leq L(\cdot, \cdot, A). \end{aligned}$$

Many interesting questions!