

Elementary Polytopes, their Lift-and-Project Ranks and Integrality Gaps

Yu Hin (Gary) Au Levent Tunçel

Dept. of Combinatorics and Optimization,
Faculty of Mathematics, University of Waterloo

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$$P_I := \text{conv} \left(P \cap \{0, 1\}^d \right).$$

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$$C_{k+1} \neq C_k \text{ unless } C_k = \text{conv} \left(C_k \cap \{0, 1\}^d \right).$$

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are clear for every j , it makes sense to consider applying this operator iteratively, each time for a new index j .

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Therefore, the notation $BCC_{(J)}(\cdot)$ is justified.

A beautiful, fundamental property of these operators is:

Lemma

For every $J \subseteq \{1, 2, \dots, d\}$, we have

$$BCC_{(J)}(P) = \text{conv}(P \cap \{x : x_j \in \{0, 1\}, \forall j \in J\}).$$

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Theorem

(Balas [1974]) Let P be as above. Then

$$BCC_{(\{1, 2, \dots, d\})}(P) = P_I.$$

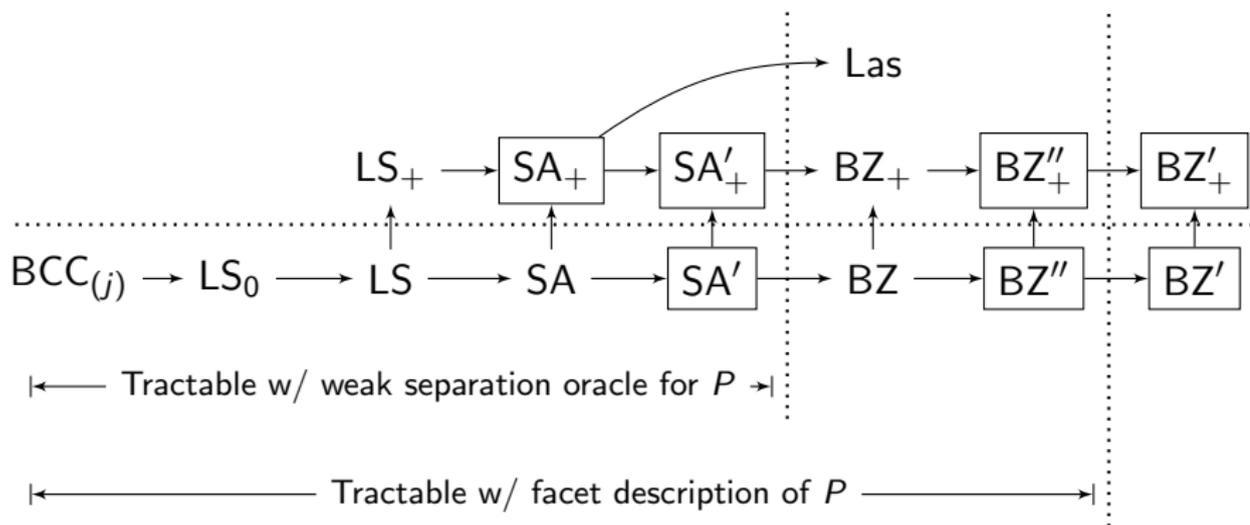


Figure: Various properties of lift-and-project operators (Au and T. [2011, 2013]).

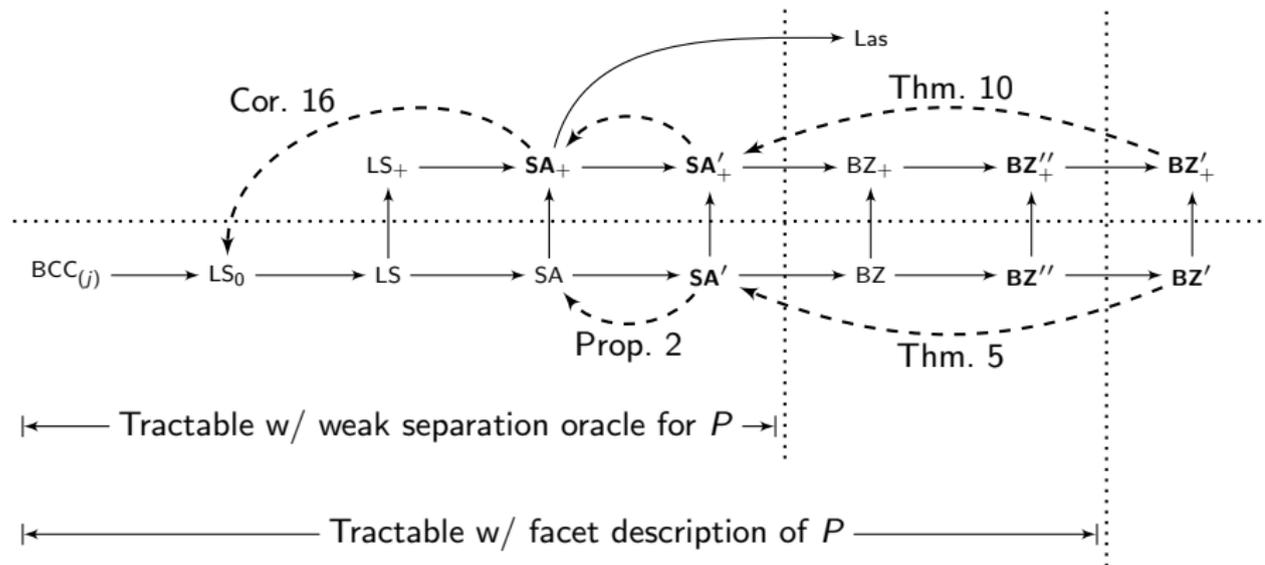


Figure: An illustration of several restricted reverse dominance results (dashed arrows) Au and T. [2013, 2015].

Lovász and Schrijver [1991] proposed:

$$M_0(K) := \left\{ Y \in \mathbb{R}^{(d+1) \times (d+1)} : \begin{array}{l} Y e_0 = Y^T e_0 = \text{diag}(Y), \\ Y e_i \in K, Y(e_0 - e_i) \in K, \\ \forall i \in \{1, 2, \dots, d\} \end{array} \right\}$$

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$$LS_0(K) := \{ Y e_0 : Y \in M_0(K) \}.$$

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Lemma

Let K be as above. Then

$$K_I \subseteq \text{LS}_+(K) \subseteq \text{LS}(K) \subseteq \text{LS}_0(K) \subseteq K.$$

Theorem

(Lovász and Schrijver [1991]) Let P be as above. Then

$$P \supseteq \text{LS}_0(P) \supseteq \text{LS}_0^2(P) \supseteq \cdots \supseteq \text{LS}_0^d(P) = P_I.$$

Similarly for LS as well as LS_+ .

Moreover, the relaxations obtained after a few iterations are still **tractable** if the original relaxation P is.

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There is a wide spectrum of lift-and-project type operators: Balas [1974], Serali and Adams [1990], Lovász and Schrijver [1991], Balas, Ceria and Cornuéjols [1993], Kojima and T. [2000], Lasserre [2001], de Klerk and Pasechnik [2002], Parrilo [2003], Bienstock and Zuckerberg [2004].

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Can it be really good on **any** problem?

Let $G = (V, E)$ be an undirected graph.

We define the *fractional stable set polytope* as

$$\text{FRAC}(G) := \left\{ x \in [0, 1]^V : x_i + x_j \leq 1 \text{ for all } \{i, j\} \in E \right\}.$$

This polytope is used as the initial approximation to the convex hull of incidence vectors of the *stable sets* of G , which is called the *stable set polytope*:

$$\text{STAB}(G) := \text{conv} \left(\text{FRAC}(G) \cap \{0, 1\}^V \right).$$

Let us define the class of *odd-cycle inequalities*. Let \mathcal{H} be the node set of an odd-cycle in G then the inequality

$$\sum_{i \in \mathcal{H}} x_i \leq \frac{|\mathcal{H}| - 1}{2}$$

is valid for $\text{STAB}(G)$. We define

$\text{OC}(G) := \{x \in \text{FRAC}(G) : x \text{ satisfies all odd-cycle constraints for } G\}$.

If \mathcal{H} is an odd-anti-hole then the inequality

$$\sum_{i \in \mathcal{H}} x_i \leq 2$$

is valid for $\text{STAB}(G)$.

If we have an odd-wheel in G with *hub* node represented by x_{2k+2} and the *rim* nodes represented by $x_1, x_2, \dots, x_{2k+1}$, then the *odd-wheel inequality*

$$kx_{2k+2} + \sum_{i=1}^{2k+1} x_i \leq k$$

is valid for $\text{STAB}(G)$.

Based on these classes of inequalities we define the polytopes

$OC(G)$, $ANTI-HOLE(G)$, $WHEEL(G)$.

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Note that this theorem provides a compact lifted representations of the odd-cycle polytope of G (in the spaces $\mathbb{R}(\{0\}^{UV}) \times (\{0\}^{UV})$ and $\mathbb{S}^{\{0\}^{UV}}$). This polytope can have exponentially many facets in the worst case.

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However, $M(G)$ is represented by

$|V|(|V| + 1)/2$ variables and $O(|V|^3)$ linear inequalities.

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Some partial results by Lipták [1999] and by Lipták and T. [2003].

A *clique* in G is a subset of nodes in G so that every pair of them are joined by an edge. The *clique polytope* of G is defined by

$$\text{CLQ}(G) := \left\{ x \in \mathbb{R}_+^V : \sum_{j \in C} x_j \leq 1 \text{ for every clique } C \text{ in } G \right\}.$$

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Optimizing a linear function over $\text{FRAC}(G)$ is **easy!**

Linear optimization over $\text{CLQ}(G)$ (and $\text{STAB}(G)$) is **\mathcal{NP} -hard!**

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$u^{(1)}, u^{(2)}, \dots, u^{(|V|)} \in \mathbb{R}^d$ such that

$$\langle u^{(i)}, u^{(j)} \rangle = 0, \text{ for all } i \neq j, \{i, j\} \notin E,$$

and

$$\langle u^{(i)}, u^{(i)} \rangle = 1, \text{ for all } i \in V.$$

$$\text{TH}(G) := \left\{ x \in \mathbb{R}_+^{|V|} : \sum_{i \in V} (c^T u^{(i)})^2 x_i \leq 1, \right. \\ \left. \forall \text{ ortho. representations and } c \in \mathbb{R}^d \text{ s.t. } \|c\|_2 = 1 \right\}$$

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but **infinitely many linear inequalities!**

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- (v) G does not contain an odd-hole or odd anti-hole
- (vi) the ideal generated by $\{(x_v^2 - x_v), \forall v \in V; x_u x_v, \forall \{u, v\} \in E\}$ is $(1, 1)$ -SoS.

There is a strong connection between $LS_+(G)$ and $TH(G)$:

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Theorem

(Lovász and Schrijver [1991]) Let $G = (V, E)$. Then

$$TH(G) = \left\{ x \in \mathbb{R}^V : \begin{pmatrix} 1 \\ x \end{pmatrix} = Y e_0; Y_{ij} = 0, \forall \{i, j\} \in E; \right. \\ \left. Y e_0 = \text{diag}(Y); Y \succeq 0 \right\}.$$

Theorem

(Lovász and Schrijver [1991]) For every graph G ,

$$LS_+(G) \subseteq OC(G) \cap ANTI\text{-HOLE}(G) \cap WHEEL(G) \cap CLQ(G) \cap TH(G).$$

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Open Problem: Give full, elegant, combinatorial characterizations for $LS_+(G)$.

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Let $G_{\alpha\beta}$ be the graph in the following figure:

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Let $G_{\alpha\beta}$ be the 8-node graph in the following figure, on the board:

A two dimensional cross-section of the compact convex relaxation $LS_+(G_{\alpha\beta})$ has a nonpolyhedral piece on its boundary.

We say that $z \in \mathbb{R}^8$ is an $\alpha\beta$ -point, if α and β are both

nonnegative and $z_i := \begin{cases} \alpha & \text{if } i \in \{1, 2, 3, 4\}, \\ \beta & \text{if } i \in \{5, 6, 7, 8\}. \end{cases}$

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Theorem

(Bianchi, Escalante, Nasini, T. [2014]) An $\alpha\beta$ -point with

$\frac{1}{4} \leq \alpha \leq \frac{1}{2}$ belongs to $LS_+(G_{\alpha\beta})$ if and only if

$$\beta \leq \frac{3 - \sqrt{1 + 8(-1 + 4\alpha)^2}}{8}.$$

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The SDP relaxation $LS_+(G)$ of $STAB(G)$ is stronger than $TH(G)$. By following the same line of reasoning used for perfect graphs, MWSSP can be solved in polynomial time for the class of graphs for which $LS_+(G) = STAB(G)$.

We call these LS_+ -*perfect graphs*.

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A graph is called *near-bipartite* if after deleting the closed neighborhood of *any* node, the resulting graph is bipartite. Let us denote by NB the class of all near-bipartite graphs.

For every graph G ,

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Open Problem: Find a **combinatorial characterization** of **LS₊-perfect** graphs.

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Current best characterization (Bianchi, Escalante, Nasini, T. [2014])

$$LS_+(G) \subseteq NB(G) \cap \hat{TH}(G).$$

What is the smallest graph which is LS_+ -imperfect?

In a related context, Knuth (1993) asked what is the smallest graph for which $STAB(G) \neq LS_+(G)$?

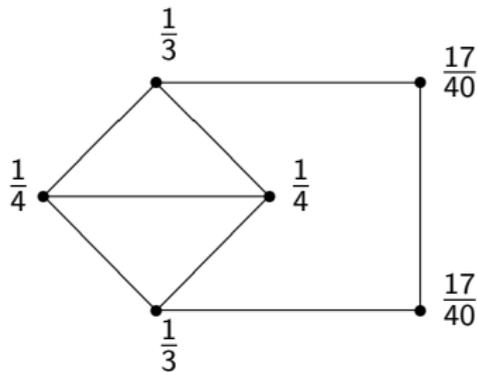


Figure: Little graph that could! G_2 with corresponding weights

Proposition

(Lipták, T., 2003) G_2 is the smallest graph for which $LS_+(G) \neq \text{STAB}(G)$.

The *LS-rank of P* is the smallest k for which $LS^k(P) = P_I$.
Analogously, *LS₀-rank of P* , *LS₊-rank of P_I relative to P ...*
We denote these ranks by $r(G)$, $r_0(G)$, and $r_+(G)$, respectively.

Theorem

(Lipták, T. [2003]) For every graph $G = (V, E)$, $r_+(G) \leq \left\lfloor \frac{|V|}{3} \right\rfloor$.

$$n_+(k) := \min\{|V(G)| : r_+(G) = k\}.$$

Open Problem: What are the values of $n_+(k)$ for every $k \in \mathbb{Z}_+$? In particular,

Conjecture (Lipták, T. [2003]): Is it true that $n_+(k) = 3k$ for all $k \in \mathbb{Z}_+$?

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bipartite graphs, series-parallel graphs, perfect graphs and odd-star-subdivisions of graphs in \mathcal{B} (which contains cliques and wheels, among many other graphs), antiholes and graphs that have N_0 -rank ≤ 2 . Also true for all 8-node graphs, and for 9-node graphs that contain a 7-hole or a 7-antihole as an induced subgraph Au [2008].

Other lower bound results: Stephen and T. [1999], Cook and Dash [2000], Goemans and T. [2001], Laurent [2002], Laurent [2003], Aguilera, Bianchi and Nasini [2004], Escalante, Montelar and Nasini [2006], Arora, Bollobás, Lovász and Turlakis [2006], Cheung [2007], Georgiou, Magen, Pitassi, Turlakis [2007], Schoenebeck, Trevisan and Tulsiani [2007], Charikar, Makarychev and Makarychev [2009], Mathieu and Sinclair [2009], Raghavendra and Steurer [2009], Benabbas and Magen [2010], Karlin, Mathieu and Thach Nguyen [2010], Chan, Lee, Raghavendra and Steurer [2013]. Many of the lower bound proofs have been unified/generalized: Hong and T. [2008].

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Stronger “lower bound” results via study of **extended complexity**.

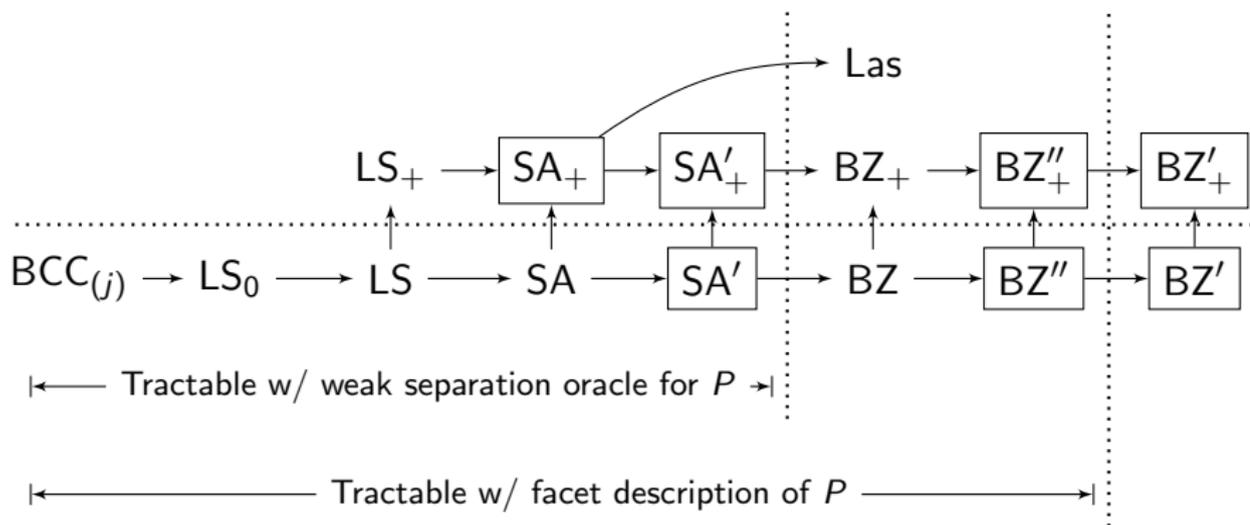


Figure: Various properties of lift-and-project operators (Au and T. [2011, 2013]).

Denote $\{0, 1\}^d$ by \mathcal{F} . Define $\mathcal{A} := 2^{\mathcal{F}}$. For each $x \in \mathcal{F}$, we define the vector $x^{\mathcal{A}} \in \mathbb{R}^{\mathcal{A}}$ such that

$$x_{\alpha}^{\mathcal{A}} = \begin{cases} 1, & \text{if } x \in \alpha; \\ 0, & \text{otherwise.} \end{cases}$$

For any given $x \in \mathcal{F}$, if we define $Y_{\mathcal{A}}^x := x^{\mathcal{A}}(x^{\mathcal{A}})^T$, then, the following must hold:

- $Y_{\mathcal{A}}^x e_0 = (Y_{\mathcal{A}}^x)^T e_0 = \text{diag}(Y_{\mathcal{A}}^x) = x^{\mathcal{A}}$;
- $Y_{\mathcal{A}}^x e_{\alpha} \in \{0, x^{\mathcal{A}}\}$, $\forall \alpha \in \mathcal{A}$;
- $Y_{\mathcal{A}}^x \in \mathbb{S}_+^{\mathcal{A}}$;
- $Y_{\mathcal{A}}^x[\alpha, \beta] = 1 \iff x \in \alpha \cap \beta$;
- If $\alpha_1 \cap \beta_1 = \alpha_2 \cap \beta_2$, then $Y_{\mathcal{A}}^x[\alpha_1, \beta_1] = Y_{\mathcal{A}}^x[\alpha_2, \beta_2]$.

Given $S \subseteq [d]$ and $t \in \{0, 1\}$, we define

$$S|_t := \{x \in \mathcal{F} : x_i = t, \forall i \in S\}.$$

For any integer $i \in [0, d]$, define

$$\mathcal{A}_i := \{S|_1 \cap T|_0 : S, T \subseteq [n], S \cap T = \emptyset, |S| + |T| \leq i\}$$

and

$$\mathcal{A}_i^+ := \{S|_1 : S \subseteq [d], |S| \leq i\}.$$

① Let $\tilde{S}^k(P)$ denote the set of matrices $Y \in \mathbb{R}^{\mathcal{A}_1^+ \times \mathcal{A}_k}$ that satisfy all of the following conditions:

(SA 1) $Y[\mathcal{F}, \mathcal{F}] = 1$;

(SA 2) $\hat{x}(Ye_\alpha) \in K(P)$ for every $\alpha \in \mathcal{A}_k$;

(SA 3) For each $S|_1 \cap T|_0 \in \mathcal{A}_{k-1}$, impose

$$Ye_{S|_1 \cap T|_0} = Ye_{S|_1 \cap T|_0 \cap J|_1} + Ye_{S|_1 \cap T|_0 \cap J|_0}, \quad \forall j \in [n] \setminus (S \cup T).$$

(SA 4) For each $\alpha \in \mathcal{A}_1^+, \beta \in \mathcal{A}_k$ such that $\alpha \cap \beta = \emptyset$, impose $Y[\alpha, \beta] = 0$;

(SA 5) For every $\alpha_1, \alpha_2 \in \mathcal{A}_1^+, \beta_1, \beta_2 \in \mathcal{A}_k$ such that $\alpha_1 \cap \beta_1 = \alpha_2 \cap \beta_2$, impose $Y[\alpha_1, \beta_1] = Y[\alpha_2, \beta_2]$.

② Let $\tilde{S}_+^k(P)$ denote the set of matrices $Y \in \mathbb{S}_+^{\mathcal{A}_k}$ that satisfies all of the following conditions:

(SA₊ 1) (SA 1), (SA 2) and (SA 3);

(SA₊ 2) For each $\alpha, \beta \in \mathcal{A}_k$ such that $\text{conv}(\alpha) \cap \text{conv}(\beta) \cap P = \emptyset$, impose $Y[\alpha, \beta] = 0$;

(SA₊ 3) For any $\alpha_1, \alpha_2, \beta_1, \beta_2 \in \mathcal{A}_k$ such that $\alpha_1 \cap \beta_1 = \alpha_2 \cap \beta_2$, impose $Y[\alpha_1, \beta_1] = Y[\alpha_2, \beta_2]$.

③ Define

$$SA^k(P) := \left\{ x \in \mathbb{R}^d : \exists Y \in \tilde{S}^k(P) : Ye_{\mathcal{F}} = \hat{x} \right\}$$

Given $P := \{x \in [0, 1]^d : Ax \leq b\}$, and an integer $k \in [d]$,

- ① Let $\tilde{\text{Las}}^k(P)$ denote the set of matrices $Y \in \mathbb{S}_+^{A_{k+1}^+}$ that satisfy all of the following conditions:

(Las 1) $Y[\mathcal{F}, \mathcal{F}] = 1$;

(Las 2) For each $j \in [m]$, let A^j be the j^{th} row of A . Define the matrix $Y^j \in \mathbb{S}^{A_k^+}$ such that

$$Y^j[S|_1, S'|_1] := b_j Y[S|_1, S'|_1] - \sum_{i=1}^n A_i^j Y[(S \cup \{i\})|_1, (S' \cup \{i\})|_1]$$

and impose $Y^j \succeq 0$.

(Las 3) For every $\alpha_1, \alpha_2, \beta_1, \beta_2 \in \mathcal{A}_k^+$ such that $\alpha_1 \cap \beta_1 = \alpha_2 \cap \beta_2$, impose $Y[\alpha_1, \beta_1] = Y[\alpha_2, \beta_2]$.

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$$\text{Las}^k(P) := \left\{ x \in \mathbb{R}^d : \exists Y \in \tilde{\text{Las}}^k(P) : \hat{x}(Ye_{\mathcal{F}}) = \hat{x} \right\}.$$

In our setting, the **Las-rank of a polytope** P (the smallest k such that $\text{Las}^k(P) = P$) is equal to the **Theta-rank**, defined by Gouveia, Parrilo, Thomas [2010].

Consider the set

$$P_{n,\alpha} := \left\{ x \in [0, 1]^n : \sum_{i=1}^n x_i \leq n - \alpha \right\}.$$

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Theorem

(Au and T. [2015]) Suppose an integer $n \geq 5$ is not a perfect square. Then there exists $\alpha \in (\lfloor \sqrt{n} \rfloor, \lceil \sqrt{n} \rceil)$ such that the BZ'_+ -rank of $P_{n,\alpha}$ is at least $\lfloor \frac{\sqrt{n+1}}{2} \rfloor$.

Theorem

(Au and T. [2015]) For every $n \geq 2$, the SA_+ -rank of $P_{n,\alpha}$ is n for all $\alpha \in (0,1)$.

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- 1 For every even integer $n \geq 4$, the Las-rank of $P_{n,\alpha}$ is at most $n - 1$ for all $\alpha \geq \frac{1}{n}$;
- 2 For every integer $n \geq 2$, there exists $\alpha \in (0, \frac{1}{n})$ such that the Las-rank of $P_{n,\alpha}$ is n .

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Theorem

(Au and T. [2015]) Suppose $n \geq 2$, and

$$0 < \alpha \leq n \left(\frac{3 - \sqrt{5}}{4n - 4} \right)^n.$$

Then $P_{n,\alpha}$ has Las-rank n .

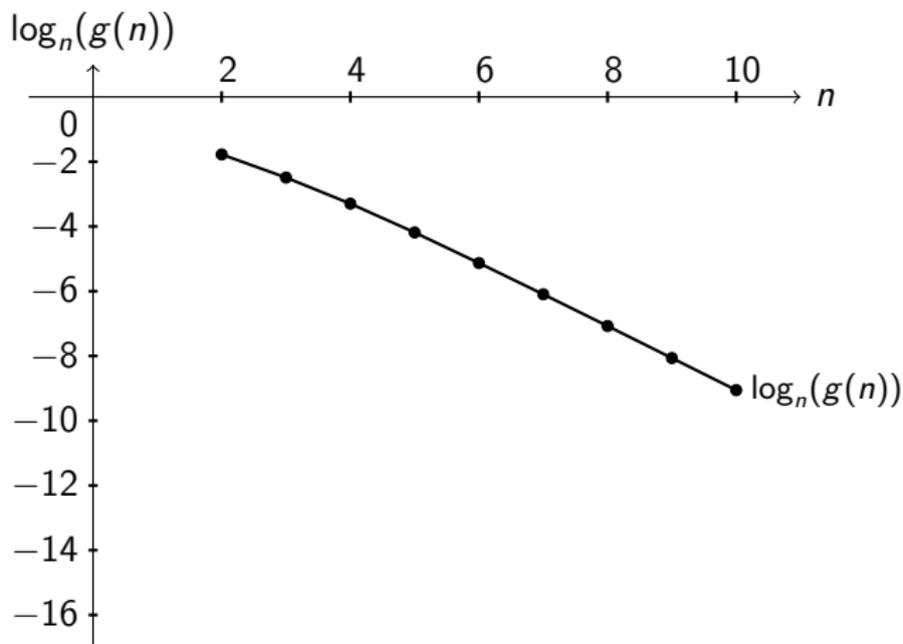


Figure: Computational results and upper bounds for $g(n) := \max \{ \alpha : \text{Las}^{n-1}(P_{n,\alpha}) \neq (P_{n,\alpha})_I \}$ (Au and T. [2015]).

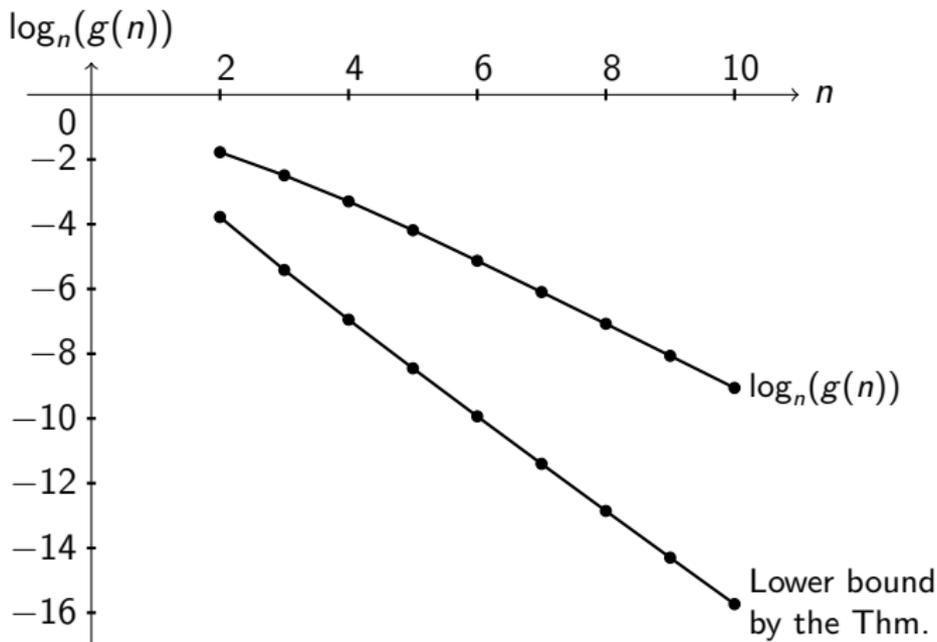


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Given $\alpha > 0$, we define the set

$$Q_{n,\alpha} := \left\{ x \in [0, 1]^n : \sum_{i \in S} (1 - x_i) + \sum_{i \notin S} x_i \geq \alpha, \forall S \subseteq [n] \right\}.$$

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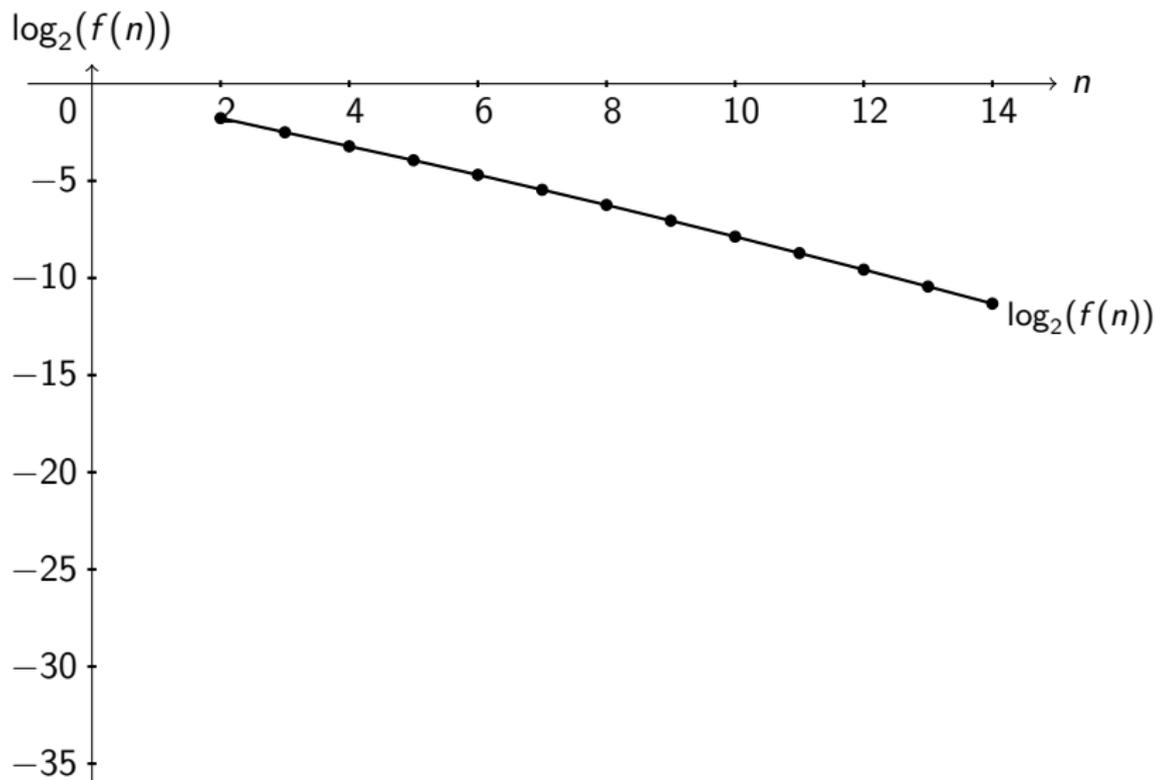


Figure: Computational results and possible ranges for $f(n) := \max \{ \alpha : \text{Las}^{n-1}(Q_n, \alpha) \neq \emptyset \}$ (Au and T. [2015]).

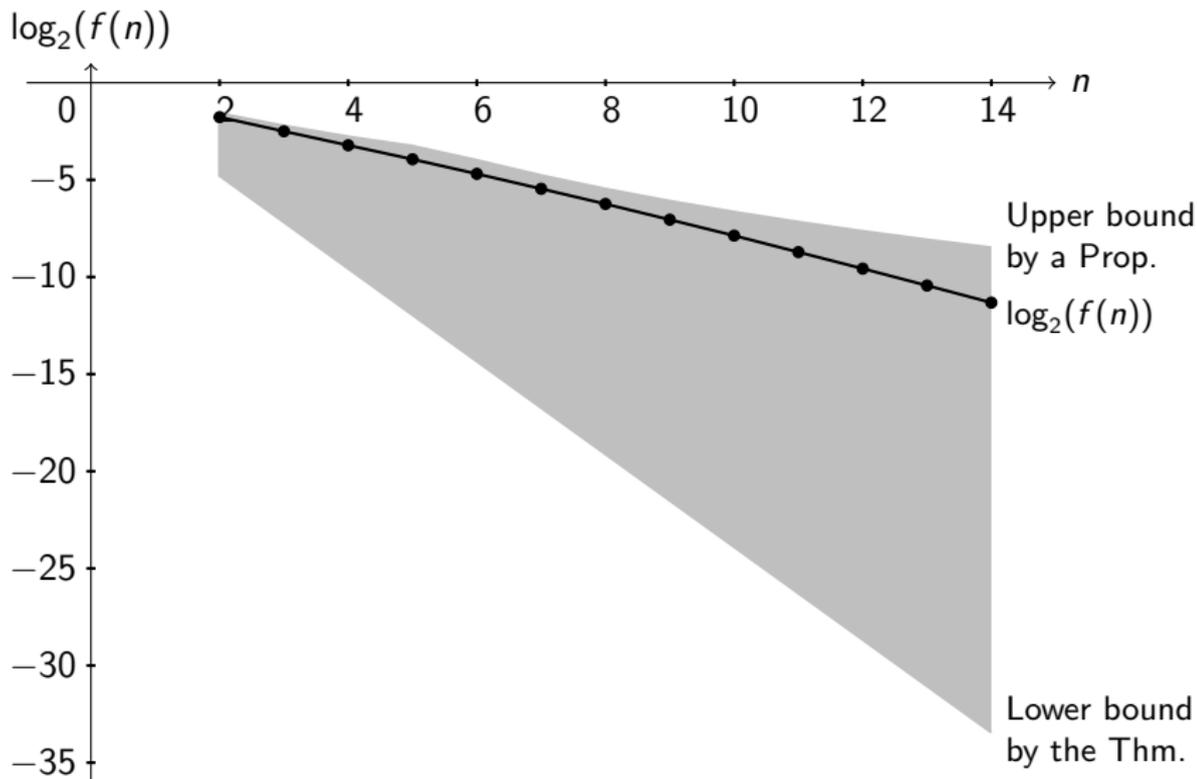


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For the complete graph $G := K_n$, $\text{FRAC}(G)$ has rank 1 with respect to LS_+ , SA_+ and Las operators. However, the rank is known to be $\Theta(n)$ for all other operators that yield only polyhedral relaxations, such as SA and Lovász and Schrijver's LS operator.

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Theorem

(Au and T. [2013]) Suppose G is the complete graph on $n \geq 3$ vertices. Then the BZ' -rank (and the BZ -rank) of $\text{FRAC}(G)$ is between $\lceil \frac{n}{2} \rceil - 2$ or $\lceil \frac{n+1}{2} \rceil$.

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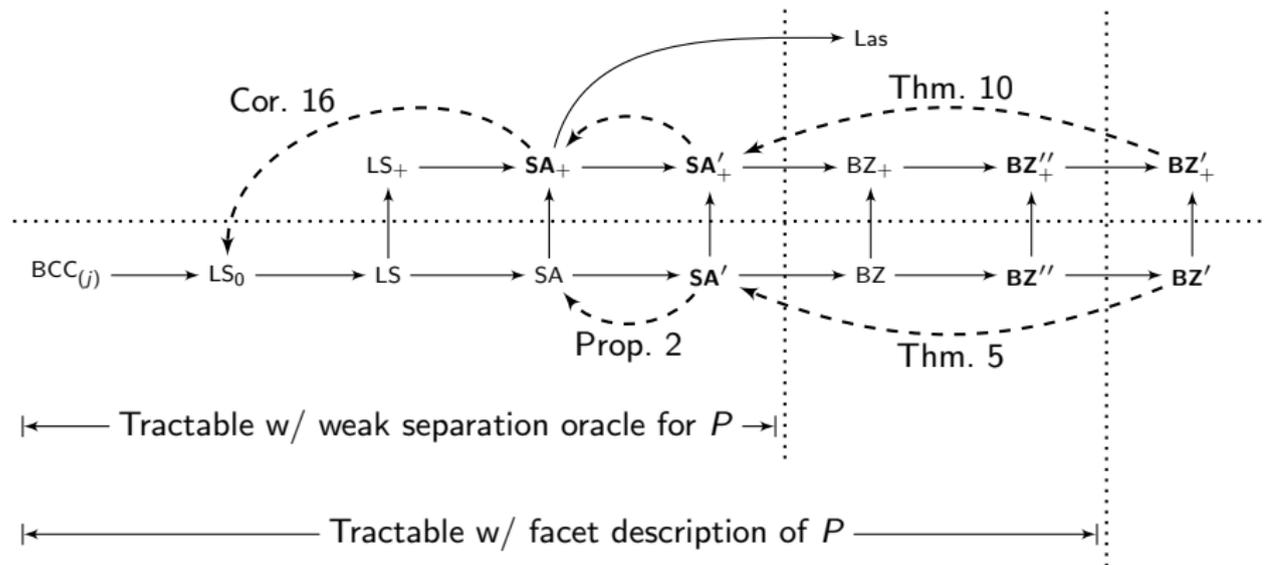


Figure: An illustration of several restricted reverse dominance results (dashed arrows) Au and T. [2013, 2015].