

Advances in QBF Solving

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- 3 Solving QBF by Expansion
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- **SAT** — for a Boolean formula, determine if it is **satisfiable**
- **Example:** $(x \vee y) \wedge (x \vee \neg y)$
 $x \triangleq 1, y \triangleq 0$
- **QBF** — for a *Quantified* Boolean formula, determine if it is true
- **Example:** $\forall x \exists y. (x \leftrightarrow y)$
- Quantifications as shorthands for connectives
($\forall = \wedge, \exists = \vee$)

Example:

- (1) $\forall x \exists y. (x \leftrightarrow y)$
- (2) $\forall x. (x \leftrightarrow 0) \vee (x \leftrightarrow 1)$
- (3) $((0 \leftrightarrow 0) \vee (0 \leftrightarrow 1)) \wedge ((1 \leftrightarrow 0) \vee (1 \leftrightarrow 1))$
- (4) 1 (True)

QBF is a strict subset of Bernays-Schönfinkel (EPR)

- Consider the QBF:

$$(\forall u \exists e)(u \leftrightarrow e)$$

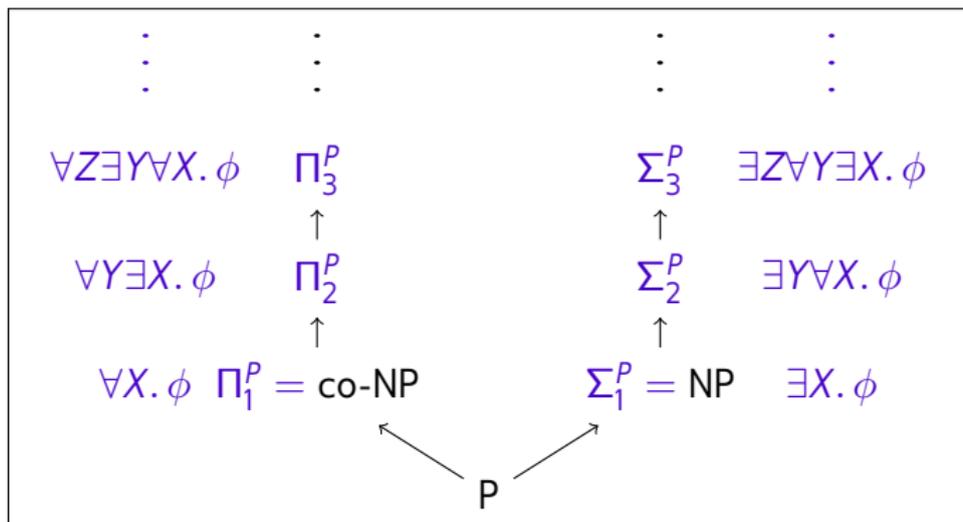
- 1 Introduce a predicate for truth,
- 2 each existential variable replace by a predicate,
- 3 universal variables wrapped by the truth predicate:

$$\text{is-true}(t) \wedge \neg \text{is-true}(f) \wedge \\ (\forall u)(\text{is-true}(u) \leftrightarrow p_e(u))$$

- Alternatively, use equality:

$$t \neq f \wedge (\forall u)((u = t) \leftrightarrow p_e(u))$$

Relation to Complexity Theory



- Deciding QBF is PSPACE complete

Relation to Two-player Games

- In this talk we consider **prenex form**: *Quantifier-prefix. Matrix*

Example $\forall y_1 y_2 \exists x_1 x_2. (\neg y_1 \vee x_1) \wedge (y_2 \vee \neg x_2)$

- A QBF represents a two-player games between \forall and \exists .
- \forall wins a game if the matrix becomes false.
- \exists wins a game if the matrix becomes true.
- A QBF is false iff there exists a **winning strategy** for \forall .
- A QBF is true iff there exists a **winning strategy** for \exists .

Example

$$\forall u \exists e. (u \leftrightarrow e)$$

\exists -player wins by playing $e \triangleq u$.

Why Quantified Boolean Formulas?

- “Fundamental problem”: PSPACE, 2-player games (fin. space)
- Direct applications
 - ▶ model checking (subproblems)
 - ▶ (circuit) synthesis
 - ▶ non-monotonic reasoning
 - ▶ conformant planning
 - ▶ ...
- In other reasoners?
 - ▶ SMT (e.g. Quantified bit vectors)
 - ▶ optimization with quantification (“MaxQBF”)
 - ▶ ...

Example: Smallest MUS

Given a CNF ϕ :

- $\vec{s} = \{s_C \mid C \in \phi\}$ are fresh variables
- \vec{x} are the original variables of ϕ
- $k \in \mathbb{N}$
- construct the following QBF:

$$(\exists \vec{s} \forall \vec{x}) \left(\bigvee_{C \in \phi} (s_C \wedge \neg C) \right) \wedge |\vec{s}| \leq k$$

[Ignatiev et al., 2015]

Framework à la CDCL

- Conceptually backtracking algorithm with
- ... unit propagation
- ... clause learning
- ... order heuristics within the same quantifier block

- run propagation in parallel on ϕ and $\neg\phi$
- ϕ false if \perp derived from ϕ
- ϕ true if \perp derived from $\neg\phi$

[Zhang and Malik, 2002, Klieber et al., 2010, Goultiaeva et al., 2013].

Propagation in QCNF

- remove false **existential** literal (as in SAT)
- remove **universal** literal that is the innermost w.r.t. prefix in the clause

Example: e_1

$(\exists e_1 e_2 \forall u \exists e_3)$

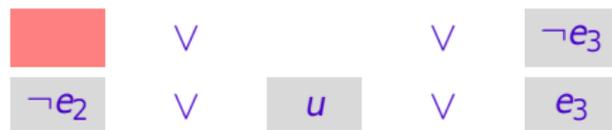
$\neg e_1$	\vee		\vee	$\neg e_3$
$\neg e_2$	\vee	u	\vee	e_3

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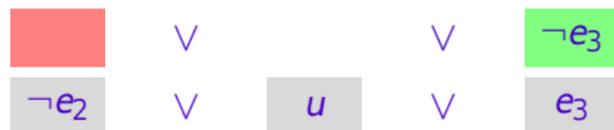


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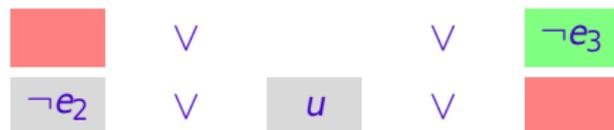


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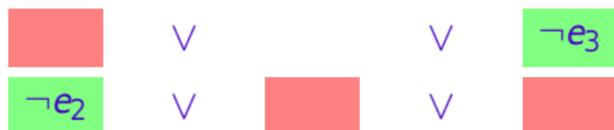


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Propagation and Learning in QCNF

Example: propagate e_1

$(\exists e_1 e_2 \forall u \exists e_3)$

$\neg e_1$	\vee		\vee	$\neg e_3$
$\neg e_2$	\vee	u	\vee	e_3
e_2	\vee	$\neg u$	\vee	e_3

Propagation and Learning in QCNF

Example: propagate e_1

$(\exists e_1 e_2 \forall u \exists e_3)$

	\vee		\vee	$\neg e_3$
$\neg e_2$	\vee	u	\vee	e_3
e_2	\vee	$\neg u$	\vee	e_3

Propagation and Learning in QCNF

Example: propagate e_1

$(\exists e_1 e_2 \forall u \exists e_3)$

	\vee		\vee	 $\neg e_3$
 $\neg e_2$	\vee	 u	\vee	 e_3
 e_2	\vee	 $\neg u$	\vee	 e_3

Propagation and Learning in QCNF

Example: propagate e_1

$(\exists e_1 e_2 \forall u \exists e_3)$

	\vee		\vee	 $\neg e_3$
 $\neg e_2$	\vee	 u	\vee	
 e_2	\vee	 $\neg u$	\vee	 e_3

Propagation and Learning in QCNF

Example: propagate e_1
($\exists e_1 e_2 \forall u \exists e_3$)

	\vee		\vee	 $\neg e_3$
 $\neg e_2$	\vee		\vee	
 e_2	\vee	 $\neg u$	\vee	 e_3

Propagation and Learning in QCNF

Example: propagate e_1
($\exists e_1 e_2 \forall u \exists e_3$)

	\vee		\vee	 $\neg e_3$
 $\neg e_2$	\vee		\vee	
 e_2	\vee	 $\neg u$	\vee	 e_3

Propagation and Learning in QCNF

Example: propagate e_1
($\exists e_1 e_2 \forall u \exists e_3$)

	\vee		\vee	 $\neg e_3$
 $\neg e_2$	\vee		\vee	
 e_2	\vee	 $\neg u$	\vee	

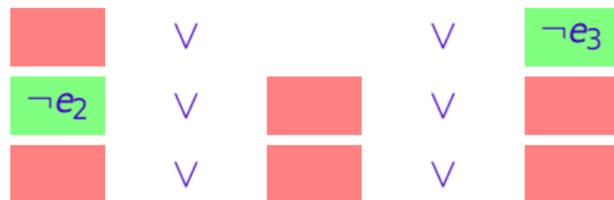
Propagation and Learning in QCNF

Example: propagate e_1
($\exists e_1 e_2 \forall u \exists e_3$)

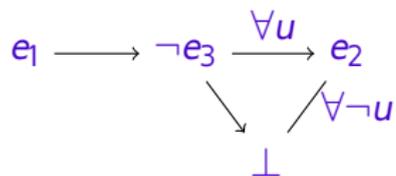
	\vee		\vee	
	\vee		\vee	
	\vee		\vee	

Propagation and Learning in QCNF

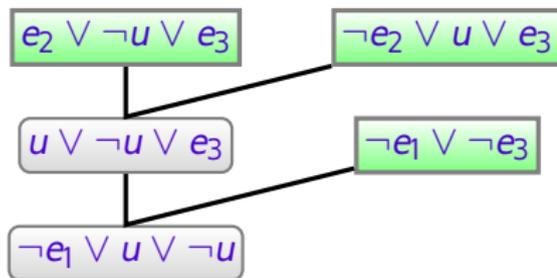
Example: propagate e_1
($\exists e_1 e_2 \forall u \exists e_3$)



Propagation and Learning in QCNF Contd.



$(\exists e_1 e_2 \forall u \exists e_3)$



Long-distance Q-resolution — Remarks

- The clause $\neg e_1 \vee u \vee \neg u$ immediately propagates $\neg e_1$
- resolution with complementary universal literals: long-distance resolution
- as a proof system, long-distance resolution requires a side condition
- ... always sound when obtained in propagation
- for semantics see [Suda and Gleiss, 2018]

Solving by CEGAR Expansion

$$(\exists \vec{E} \forall \vec{U}) \phi \equiv (\exists \vec{E}) \bigwedge_{\mu \in 2^{\vec{U}}} \phi[\mu]$$

Can be solved by SAT $(\bigwedge_{\mu \in 2^{\vec{U}}} \phi[\mu])$. **Impractical!**

Observe:

$$(\exists \vec{E}) (\bigwedge_{\mu \in 2^{\vec{U}}} \phi[\mu]) \Rightarrow (\exists \vec{E}) \bigwedge_{\mu \in \omega} \phi[\mu]$$

for any $\omega \subseteq 2^{\vec{U}}$

$$(\exists \vec{E} \forall \vec{U}) \phi \equiv (\exists \vec{E}) \bigwedge_{\mu \in 2^{\vec{U}}} \phi[\mu]$$

Expand **gradually** instead: [J. and Marques-Silva, 2011]

- Pick τ_0 arbitrary assignment to \vec{E}
- $\text{SAT}(\neg\phi[\tau_0]) = \mu_0$ assignment to \vec{U}
- $\text{SAT}(\phi[\mu_0]) = \tau_1$ assignment to \vec{E}
- $\text{SAT}(\neg\phi[\tau_1]) = \mu_2$ assignment to \vec{U}
- $\text{SAT}(\phi[\mu_0] \wedge \phi[\mu_1]) = \tau_2$ assignment to \vec{E}
- After n iterations

$$(\exists \vec{E}) \bigwedge_{i \in 1..n} \phi[\tau_i]$$

Abstraction-Based Algorithm for a Winning Move

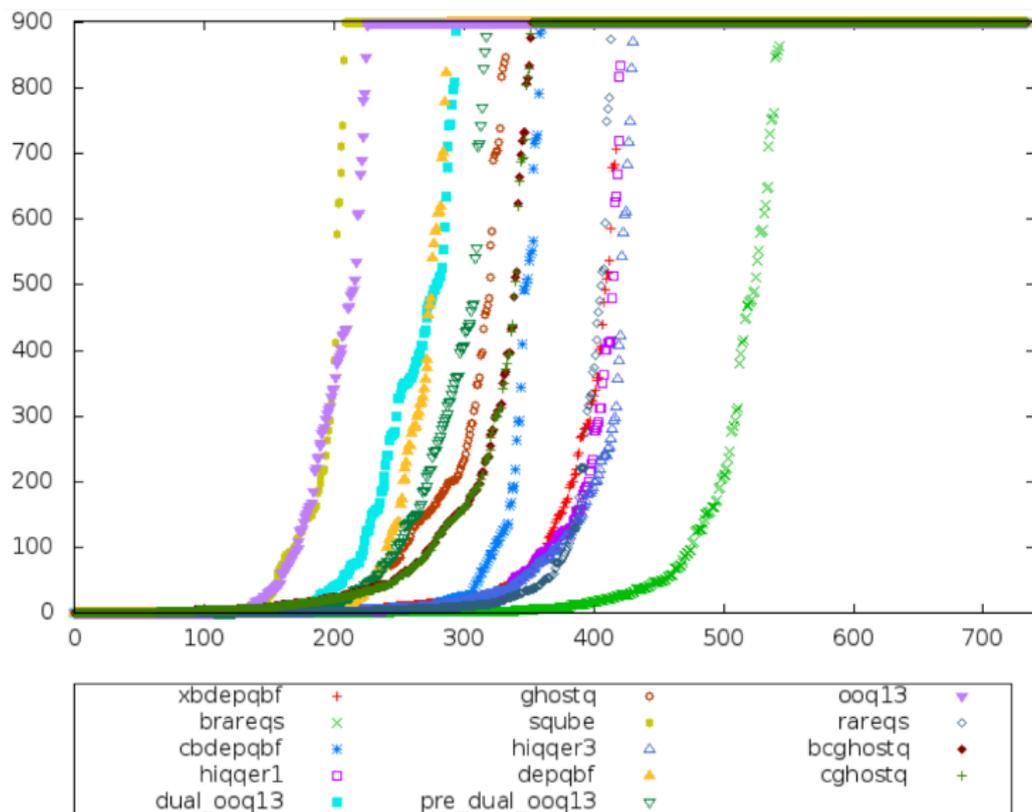
Algorithm for $\exists\forall$ [J. and Marques-Silva, 2011]

```
1 Function Solve( $(\exists\vec{E}\forall\vec{U})\phi$ )
2  $\alpha \leftarrow \text{true}$  // start with an empty abstraction
3 while true do
4    $\tau \leftarrow \text{SAT}(\alpha)$  // find a candidate
5   if  $\tau = \perp$  then return  $\perp$ 
6    $\mu \leftarrow \text{SAT}(\neg\phi[\vec{E} \leftarrow \tau])$  // find a countermove
7   if  $\mu = \perp$  then return  $\tau$ 
8    $\alpha \leftarrow \alpha \wedge \phi[\vec{U} \leftarrow \mu]$  // refine abstraction
```

Expansion Continued

- The algorithm is non-CNF
- The algorithm can be generalized
- ... to arbitrary number of levels by recursion [J. et al., 2012]
- ... non-prenex [J. et al., 2016].

Results, QBF-Gallery '14, Application Track



Careful Expansion: Good Example

$$(\exists x \dots \forall y \dots)(\phi \wedge y)$$

Setting countermove $y \leftarrow 0$ yields false. **Stop.**

$$(\exists x \dots \forall y \dots)(x \vee \phi)$$

Setting candidate $x \leftarrow 1$ yields true (impossible to falsify). **Stop.**

Careful Expansion: Bad Example

$$(\exists x \forall y)(x \leftrightarrow y)$$

1 $x \leftarrow 1$

2 $\text{SAT}(\neg(1 \leftrightarrow y)) \dots y \leftarrow 0$

3 $\text{SAT}(x \leftrightarrow 0) \dots x \leftarrow 0$

4 $\text{SAT}(\neg(0 \leftrightarrow y)) \dots y \leftarrow 1$

5 $\text{SAT}(x \leftrightarrow 0 \wedge x \leftrightarrow 1) \dots$ UNSAT

candidate

countermove

candidate

countermove

Stop

Careful Expansion: Ugly Example

$$(\exists x_1 x_2 \forall y_1 y_2) ((x_1 \leftrightarrow y_1) \vee (x_2 \leftrightarrow y_2))$$

- 1 $x_1, x_2 \leftarrow 0, 0$
- 2 $\text{SAT}(\neg(0 \leftrightarrow y_1 \vee \neg 0 \leftrightarrow y_2)) \dots y_1 \leftarrow 1, y_2 \leftarrow 1$
- 3 $\text{SAT}(x_1 \leftrightarrow 1 \vee x_2 \leftrightarrow 1) \dots x_1, x_2 \leftarrow 0, 1$
- 4 $\text{SAT}(\neg(0 \leftrightarrow y_1 \vee 1 \leftrightarrow y_2)) \dots y_1 \leftarrow 1, y_2 \leftarrow 0$
- 5 $\text{SAT}((x_1 \leftrightarrow 1 \vee x_2 \leftrightarrow 1) \wedge (x_1 \leftrightarrow 1 \vee x_2 \leftrightarrow 0)) \dots$
- 6 \dots

- CEGAR requires 2^n SAT calls for the formula

$$(\exists x_1 \dots x_n \forall y_1 \dots y_n) \bigvee_{i \in 1..n} x_i \leftrightarrow y_i$$

- **BUT:** We know that the formula is immediately false if we set $y_i \leftarrow \neg x_i$.

$$\left(\exists x_1 \dots x_n \forall y_1 \dots y_n. \bigvee_{i \in 1..n} x_i \leftrightarrow \neg x_i \right) \equiv \left(\exists x_1 \dots x_n. 0 \right)$$

- **Idea:** instead of plugging in constants, plug in functions.
- **Where do we get the functions?**

Use Machine Learning

[J., 2018]

- 1 Enumerate some number of candidate-countermove pairs.
- 2 Run a machine learning algorithm to learn a Boolean function for each variable in the inner quantifier.
- 3 Strengthen abstraction with the functions.
- 4 Repeat.

Machine Learning Example

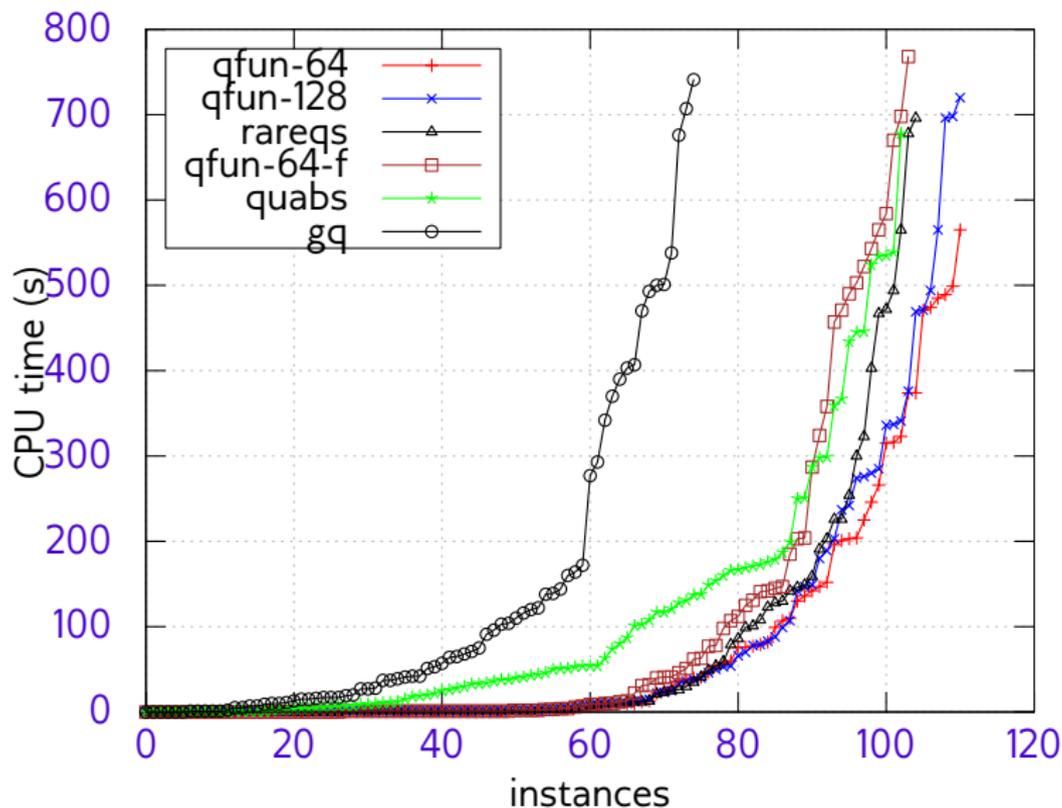
x_1	x_2	...	x_n	y_1	y_2	...	y_n
0	0	...	0	1	1	...	1
1	0	...	0	0	1	...	1
0	0	...	1	1	1	...	0
0	1	...	1	1	0	...	0

- After 2 steps: $y_1 \leftarrow \neg x_1$, $y_i \leftarrow 1$ for $i \in 2..n$.
- $SAT(x_1 \leftrightarrow \neg x_1 \vee \bigvee_{i \in 2..n} x_i \leftrightarrow 1)$
- After 4 steps: $y_1 \leftarrow \neg x_1$ $y_2 \leftarrow \neg x_2 \dots$
- Eventually we learn the right functions.

Current Implementation

- Use CEGAR as before.
- Recursion to generalize to multiple levels as before.
- Refinement as before.
- Every K refinements, learn new functions from last K samples. Refine with them.
- Learning using **decision trees** by ID3 algorithm.
- Additional heuristic: If a learned function still works, keep it.
“Don't fix what ain't broke.”

Current Implementation: Experiments



Challenges

- CNF input harmful because we need to reason about the negation as well
[Ansótegui et al., 2005, J. and Marques-Silva, 2017]
- **but** CNF preprocessing useful [Biere et al., 2011]
- Formulas with sure strategies can be hard to solve
- Approach: Machine learning strategies [J., 2018]
- Approach: **incremental determinization**
[Rabe and Seshia, 2016]
- Since QBF is a subset of FOL, relation to FOL solvers?

Summary

- QBF natural representation for PSPACE or problems at n^{th} level of polynomial hierarchy
- SAT's CDCL can be lifted to QBF
- An alternative approach: gradually expand quantifiers and then call a SAT solver
- Experiments show that expansion tends to be better on small number of quantifier levels and the other way around.
- An important challenge: find good winning strategies
- One way of tackling: machine learning
- Other approaches?

Thank You for Your Attention!

Questions?

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