

# An inexact primal-dual deflected subgradient algorithm with augmented Lagrangians

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# Outline

- 1 Augmented Lagrangian Duality
- 2 Minimizing the Lagrangian
- 3 Deflected Subgradient Method

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# The Primal Problem

$X$  reflexive Banach space,  $H$  a Hilbert space

$$\text{minimize } \varphi(x) \quad \text{s.t. } x \text{ in } X \quad (1)$$

$\varphi : X \rightarrow \mathbb{R}_{+\infty}$  proper, weakly-lsc  
 with weakly compact level sets

For constructing the dual, we need the following ingredients...

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# Building up the Dual

Take a **duality parameterization** for (1), i.e.,

$$g : X \times H \rightarrow \mathbb{R}_{\pm\infty} \quad \text{such that} \quad g(x, 0) = \varphi(x) \quad \forall x \in X.$$

and an **augmenting function**  $\sigma : H \rightarrow \mathbb{R}$

proper, w-lsc, level-bounded, and:

$$\sigma(0) = 0, \quad \sigma(y) \geq \|y\| \quad \forall y, \quad \text{and} \quad \underset{y}{\text{Argmin}} \sigma(y) = \{0\}$$

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# The “augmented” Dual

The **augmented Lagrangian**

$$L : X \times H \times \mathbb{R}_+ \rightarrow \mathbb{R}_{\pm\infty}$$

$$L(x, y, r) := \inf_{z \in H} \{g(x, z) - \langle z, y \rangle + r\sigma(z)\}$$

The **dual function**:  $q : H \times \mathbb{R}_+ \rightarrow \mathbb{R}_{-\infty}$

$$q(y, r) = \inf_{x \in X} L(x, y, r)$$

with **dual problem**:

$$\text{maximize } q(y, r) \text{ s.t. } (y, r) \text{ in } H \times \mathbb{R}_+ \quad (D)$$

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# Duality Properties

Augmented Lagrangians proposed by Rockafellar and Wets, 1997:

- Strong duality: dual optimal value = primal optimal value
- Saddle point properties: get primal solution using dual one
- Dual problem is convex: use known solution techniques

Also true in infinite dimensions [Burachik-Rubinov, 2007]

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# The subproblem

Fix  $(y, r)$  a dual variable, and  $\epsilon \geq 0$ , find:

$$(\tilde{x}, \tilde{z}) \in X_\epsilon(y, r)$$

where

$$X_\epsilon(y, r) := \{(x, z) \in X \times H : g(x, z) - \langle z, y \rangle + r\sigma(z) \leq q(y, r) + \epsilon\}$$

Fact:  $(-\tilde{z}, \sigma(\tilde{z})) \in \partial_\epsilon q(y, r)$

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# $\epsilon$ -solutions

Let  $M_P := \inf_{x \in X} \varphi(x)$  → optimal primal value

and  $M_D := \sup_{(y,r) \in H \times \mathbb{R}_+} q(y,r)$  → optimal dual value

Dual solutions =  $D_*$

Fix  $\epsilon_* \geq 0$ :

$x_* \in X$  is  $\epsilon_*$ -primal solution if  $\varphi(x_*) \leq M_P + \epsilon_*$

$(y_*, c_*) \in H \times \mathbb{R}_+$  is  $\epsilon_*$ -dual solution if  $q(y_*, c_*) \geq M_D - \epsilon_*$

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# An $\epsilon$ -subgradient method

**Update rule:** Given current  $w_k := (u_k, c_k)$ , search along  $\epsilon$ -subgradient direction  $g_k \in \partial_\epsilon q(w_k)$ :

$$w_{k+1} = w_k + s_k g_k$$

where step-size  $s_k > 0$ . An  $\epsilon$ -subgradient of  $q$  at  $w_k$  is

$$g_k = (-z_k, \sigma(z_k))$$

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# Deflected Subgradient Method

Let  $\alpha > 0, \delta \in (0, 1), \epsilon_* > 0$

Step 0 Choose  $(u_0, c_0)$  with  $c_0 \geq 0$  and choose  $\epsilon_k \downarrow 0$ .

Step  $k$  Given  $(u_k, c_k)$ :

Find  $(u_{k+1}, c_{k+1}) \in \mathcal{X} \times \mathcal{C}$  such that  $\|u_{k+1} - u_k\| \leq \epsilon_k$ ,  $c_{k+1} \geq 0$  and  $\|c_{k+1} - c_k\| \leq \epsilon_k$ .

$$u_{k+1} = \arg \min_{u \in \mathcal{X}} \left\{ \langle u, \lambda \rangle + \frac{\alpha}{2} \|u - u_k\|^2 \right\}$$

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**Step k.2** If  $z_k = 0$  and  $\epsilon_k > \epsilon_*$ , set  $\epsilon_k = \delta \epsilon_k$  GOTO Step k.1

**Step k.3**

$$\text{Set } \begin{cases} u_{k+1} & := u_k - s_k z_k, \\ c_{k+1} & := c_k + s_k(1 + \alpha_k)\sigma(z_k), \end{cases}$$

where  $s_k > 0, \alpha_k \in (0, \alpha)$

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**Step k.2** If  $z_k = 0$  and  $\epsilon_k > \epsilon_*$ , set  $\epsilon_k = \delta \epsilon_k$  GOTO Step k.1

**Step k.3**

$$\text{Set } \begin{cases} u_{k+1} & := u_k - s_k z_k, \\ c_{k+1} & := c_k + s_k(1 + \alpha_k)\sigma(z_k), \end{cases}$$

where  $s_k > 0, \alpha_k \in (0, \alpha)$

# Deflected Subgradient Method

Let  $\alpha > 0, \delta \in (0, 1), \epsilon_* > 0$

**Step 0** Choose  $(u_0, c_0)$  with  $c_0 \geq 0$  and choose  $\epsilon_k \downarrow 0$ .

**Step k** Given  $(u_k, c_k)$ :

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(Gasimov 2002; Gasimov & Ismayilova 2004)

(Burachik & Gasimov & Ismayilova & Kaya, 2006, Burachik & Kaya 2007,  
 Burachik & Kaya & Mammadov, 2009)

# Basic Result

For every choice of  $\mathbf{s}_k, \alpha_k$

If stops at iteration  $k$ , then

$x_k$  is  $\epsilon_*$ -primal optimal, and

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## Bounded Stepsize

Take  $\beta > \eta > 0$  and  $\eta_k := \min\{\eta, \|z_k\|\}$ ,  $\beta_k := \min\{\beta, \sigma(z_k)\}$

Choose  $s_k \in [\eta_k, \beta_k]$

If  $\epsilon_k \leq M_D - q(u_k, c_k) + R\sigma(z_k)$  and  $D_* \neq \emptyset$ , then

Call  $q_k := q(u_k, c_k)$

- $\{q_k\}$  converges to  $M_D$
- $\{(u_k, c_k)\}$  converges weakly to a dual solution
- If  $0 < \alpha_k < \bar{\alpha}$ ,  $\{x_k\}$  bded and accumulation points are primal solutions
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# Unbounded Stepsize

Take  $\beta > 0$  and a sequence  $\{\theta_k\} \subset [0, \beta)$ ,  $\sum \theta_k = \infty$

Define  $\eta_k := \frac{\theta_k}{\sigma(z_k)}$ ,  $\beta_k := \frac{\beta}{\sigma(z_k)}$

Choose  $s_k \in [\eta_k, \beta_k]$

Assume  $\epsilon_k \leq M_D - q(y_k, c_k) + R\sigma(z_k)$

- Dual sequence bdd iff dual solutions exist
- If  $D_* \neq \emptyset$  we have finite termination, at  $\epsilon_*$ -primal-dual optimal solution
- If the algorithm generates an infinite sequence (which implies  $D_* = \emptyset$ ), then

- $\{y_k\}$  converges to a primal optimal solution
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