

Sublinear Compressive Sensing (CS) and Support Weight Enumerators of Codes: A Matroid Theory Approach

Olgica Milenkovic

Joint work with Wei Dai and Hoa Vinh Pham

Department of Electrical and Computer Engineering
University of Illinois at Urbana-Champaign

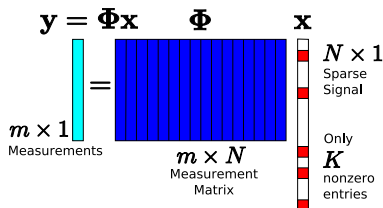
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Outline

- A brief introduction to **CS**;
- Why do support weight enumerators matter?
- **Decoding** of weighted superimposed codes: BP and OMP/SP - **sublinear** complexity reconstruction.
- Many open problems...

Compressive Sensing

CS: a technique that converts high dimensional signals into signals (measurements) with significantly smaller dimension ($m \ll N$).



Recovery problem: decode the signal \mathbf{x} based on the measurement \mathbf{y} .

- Ill conditioned in general.
 - ▶ Φ does not have full column rank. There are many \mathbf{x} such that $\mathbf{y} = \Phi \mathbf{x}$.

When the signal is sparse, ...

When \mathbf{x} is **sufficiently sparse** (K is small), exact reconstruction is possible.
(Kashin, 1977; Bresler et. al., 1999; Donoho et. al., 2004; Candés et. al., 2005)

Exact Reconstruction: iff $\mathbf{y}_1 - \mathbf{y}_2 = \Phi (\mathbf{x}_1 - \mathbf{x}_2) \neq \mathbf{0}$,
 $\forall K\text{-sparse } \mathbf{x}_1 \neq \mathbf{x}_2$.



Any $2K$ -column submatrix of Φ must have full rank.

Reconstruction algorithm (l_0 -minimization):

$$\min \|\hat{\mathbf{x}}\|_0 \text{ s.t. } \mathbf{y} = \Phi \hat{\mathbf{x}}.$$

of measurements: $m = 2K$.

Computational complexity: NP hard \Rightarrow not practical for large N .

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l_1 minimization

$$\min \|\hat{\mathbf{x}}\|_1 \text{ subject to } \mathbf{y} = \Phi \hat{\mathbf{x}}$$

- It is a convex optimization problem, solvable by **linear programming**.
- Complexity: $O(m^2 N^{3/2})$ (Nesterov & Nemirovski, 1994)
- Performance guarantee?

Restricted Isometry Property: Φ satisfies the RIP with $\delta_K \in [0, 1]$ if for all K -sparse signals \mathbf{x} ,

$$(1 - \delta_K) \|\mathbf{x}\|_2^2 \leq \|\Phi \mathbf{x}\|_2^2 \leq (1 + \delta_K) \|\mathbf{x}\|_2^2.$$

Sufficient condition: If Φ satisfies RIP with $\delta_{2K} < \sqrt{2} - 1$, then $\hat{\mathbf{x}} = \mathbf{x}$
(Candès & Tao, 2005 and Candès 2008)

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Number of Measurements

Random matrices satisfying the RIP with constant parameters
(Candès et. al., 2005; Litvak et. al., 2005; Rudelson & Vershynin 2006)

- 1 Random matrices with i.i.d. entries.
 - 1 Gaussian distribution (subGaussian distribution).
 - 2 **Bernoulli distribution.**

$$m \geq O(K \log N)$$

- 2 Random matrices from the Fourier ensemble.
 - 1 choose m rows uniformly at random.

$$m \geq O(K (\log N)^c)$$

This Talk

The **interface** between coding theory and CS

- **Sublinear complexity CS: Iterative decoding (belief propagation (BP)) meets greedy algorithms;**
 - ▶ Constructive methods via low-density parity-check (LDPC) coding;
 - ▶ Reconstruction via **greedy matching pursuit algorithms** (OMP, SP, and CoSaMP) and BP decoding with a “twist”.

Low Complexity Decoding Algorithms from CS

Recent focus on greedy algorithms:

- Orthogonal Matching Pursuit (**OMP**) (Tropp, 2004)
- Regularized OMP (**ROMP**) (Needell & Vershynin, 2007)
- Stagewise OMP (**StOMP**) (Donoho et. al., 2007)
- Subspace Pursuit (**SP**) (Dai & Milenkovic, 2008)
- Compressive Sampling Matching Pursuit (**CoSaMP**) (Needell & Tropp, 2008)

	Complexity	Performance
l_0 minimization	$O(N^K)$	$\delta_{2K} < 1$
l_1 minimization	$O(m^2 N^{3/2})$	$\delta_{2K} < \sqrt{2} - 1$
OMP	$O(KmN)$	$\delta_K < \frac{1}{2K}$
SP	$O(KmN)$ or less	$\delta_{3K} < 0.16$

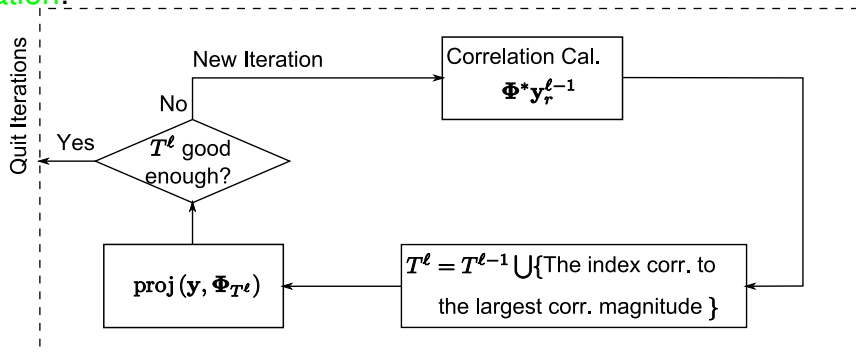
Orthogonal Matching Pursuit (OMP) Algorithm

Input: Φ, \mathbf{y}, K

Initialization:

$$T^0 = \emptyset, \mathbf{y}_r^0 = \mathbf{y}.$$

Iteration:



Output: solution obtained after K iterations

Subspace Pursuit (SP) algorithm

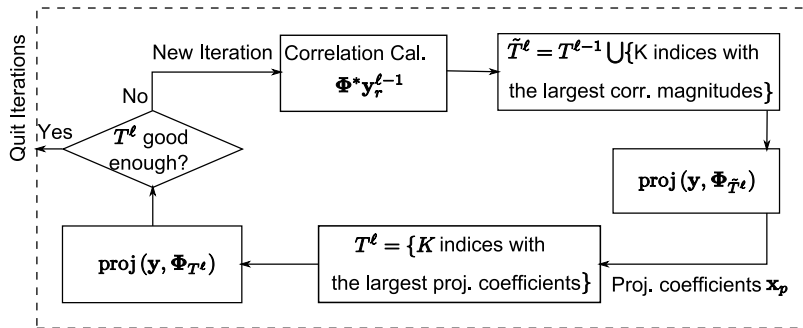
Input: Φ , \mathbf{y} , K

Initialization:

$T^0 = \{K \text{ indices corresponding to the largest magnitudes of } \Phi^* \mathbf{y}\}.$

$\mathbf{y}_r^0 = \text{resid}(\mathbf{y}, \Phi_{T^0}).$

Iteration:



Output:

$\hat{\mathbf{x}}: \hat{\mathbf{x}}_{T^\ell} = \Phi_{T^\ell}^\dagger \mathbf{y}$ and $\hat{\mathbf{x}}_{(T^\ell)^c} = \mathbf{0}.$

LDPC Applications in CS

- Complexity of greedy strategies is dominated by **correlation computation**
 - ▶ Complexity is $O(mN)$.

- Use **LDPC** codebook for sensing matrix design
 - ▶ Mimics the Bernoulli matrix;
 - ▶ Introduce structure for storage saving.

- Correlation computation via **BP**
 - ▶ ML decoding = finding the largest correlation.
 - ▶ **Decoding complexity**: from $O(mN)$ to $O(m)$.

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Incoherence parameter μ

$$\mu \triangleq \max_{i \neq j} |\langle \varphi_i, \varphi_j \rangle|,$$

- **Sufficient** condition of exact reconstruction for OMP (Tropp 2003):

$$\mu \leq \frac{1}{2K}$$

- **Equivalent to Hamming distance requirement** for LDPC codes

$$\frac{1}{2} - \frac{1}{4K} < \frac{d_H(\mathbf{c}_i, \mathbf{c}_j)}{m} < \frac{1}{2} + \frac{1}{4K}, \quad \forall i \neq j.$$

Proposition: A random LDPC code with row sums $d_c \geq 3$ and $m = O(K^2 \log N)$ satisfies

$$\frac{1}{2} - \frac{1}{4K} < \frac{d_H(\mathbf{c}_i, \mathbf{c}_j)}{m} < \frac{1}{2} + \frac{1}{4K}, \quad \forall i \neq j$$

with high probability.

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RIP property

- **Gershgorin Circle Theorem:** For all $\mathbf{A} \in \mathbb{C}^{n \times n}$,

$$\{\lambda_i\} \subset \bigcup_{i=1}^n D \left(a_{i,i}, \sum_{j \neq i} |a_{i,j}| \right).$$

- **RIP** holds!

For all eigenvalues of $\Phi_T^* \Phi_T$,

$$\begin{aligned} |\lambda(\Phi_T^* \Phi_T) - 1| &\leq \max_j \sum_{l \neq j} |\langle \varphi_j, \varphi_l \rangle| \\ &\leq K\mu \leq \frac{1}{2}, \end{aligned}$$

which implies

$$\delta_K \leq 1/2.$$

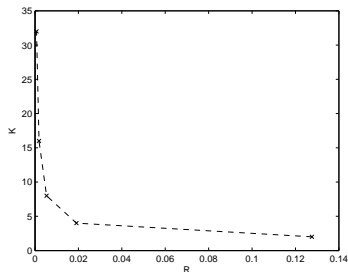
LDPC Code Rate for CS

A necessary condition: Unless the LDPC code family satisfies

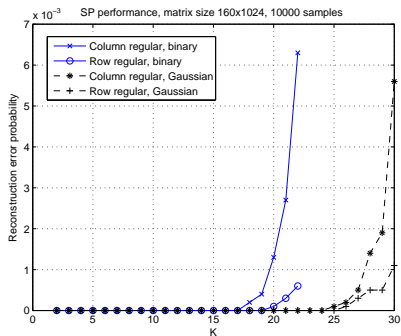
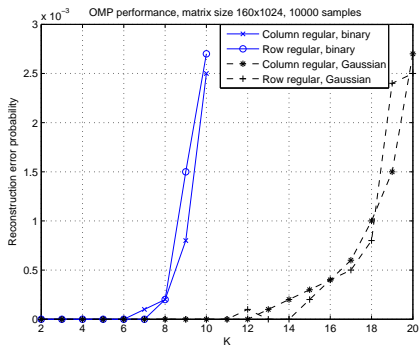
$$R < 1 - \left(1 - \frac{\sqrt{2}}{K}\right) \frac{\log_2(K-1)}{\log_2(K)} - \frac{H(\sqrt{2}/K)}{K},$$

the RIP constant cannot satisfy $\delta_K < \sqrt{2} - 1$.

Proof is based on connection between the RIP and **generalized Hamming weights** of a code.



Performance of standard OMP and SP algorithms



Extensions

- **List-based** BP decoding algorithm.
 - ▶ Motivated by the significant performance improvement of SP compared with OMP.
 - ▶ Instead of outputting the ML codeword, we output **a list of K codewords** that have large likelihood.
- **Multiple basis belief propagation (MBBP)** Algorithm
 - ▶ An LDPC code can have different parity check matrices (bases).
 - ▶ The performance of BP algorithm highly depends on the chosen basis.
 - ▶ We propose to **run BP algorithm on multiple bases and choose the best output codeword.**

Thank you!