### Techniques and estimates to analyze TDBIE

Matt Hassell, 'Tim' Qiu, Tonatiuh Sánchez-Vizuet, Francisco–Javier Sayas Department of Mathematical Sciences University of Delaware

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#### Team Pancho @ Delaware

FJS Thomas Brown Matthew Hassell Allan Hungria Tianyu Qiu Tonatiuh Sánchez-Vizuet



### DMS 1216356



### This paper

FJS Matt Hassell Tianyu 'Tim' Qiu Tonatiuh Sánchez-Vizuet

### Idea behind the talk

- Crash course on Laplace and time domain tools for TDBIE
- Galerkin semidiscretization-in-space perfectly integrated in the theoretical framework
- Equations of the first kind
- Summary of tools

A considerable amount of estimates can be obtained as particular cases of a somewhat exotic transmission problem for the wave equation

**Achtung.** I'm assuming a mathematically motivated audience. This will look like a piece of pure math, but it's just analysis, not algebra or topology. No need to panic.

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# Reframing the framework

- Everything will be done for the acoustic case
- The elastic case is identical
- Maxwell is not 'that' different after all (I used to think it was)
- Actual transmission problems can be dealt with using a two-field formulation
- Coupling with FEM-like discretization is also doable (it's done)
- Wave-structure interaction is doable (also done)
- To be done:
  - regularity theory and approximation theorems
  - equations of the second kind (?)
  - free coupling of FEM and BEM

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# The self-centered mathematician apology playbook

I'm not citing (almost) anyone. However, this work condenses CQ- and Galerkin-TDBIE flavored results from the literature:

- Bamberger-HaDuong and related work (Becache, Bachelot, Terrasse, etc)
- German speaking CQ revival (Sauter, Hackbusch, Banjai, Schanz, López Fdez, Melenk)
- Delaware bunch (Monk, Weile, myself and my students)

A modest goal. Can we find a way to make many techniques real simple so that we can move to more complicated (theoretical) issues without being repetitive? At the end this looks like an exercise. (Of course, once you know the result...) But that's kind of our goal.

A conversation (in the 90s). My adviser (M.C.): make the proof so simple so that it cannot be published. Me (mentally): I kind of want a job.

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### Geometry and notation



- Traces:  $\gamma^{\pm}u$
- Normal traces:  $\gamma_{\nu}^{\pm} \mathbf{v}$
- Normal derivatives:  $\partial_{\nu}^{\pm} := \gamma_{\nu}^{\pm} \nabla$
- Jumps:  $[\gamma u] := \gamma^- u \gamma^+ u$

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etc

Geometrically (analytically) speaking, we only need a fully functioning trace operator (and a normal vector field on the boundary)

#### **Trial-test spaces**

$$X_h \subset H^{-1/2}(\Gamma) = H^{1/2}(\Gamma)^*$$
  $Y_h \subset H^{1/2}(\Gamma) = H^{-1/2}(\Gamma)^*$ 

#### Polar sets = Galerkin observation

For instance

$$\beta \in X_h^{\circ}$$
 means  $\langle \beta, \mu^h \rangle_{\Gamma} = 0 \quad \forall \mu^h \in X_h.$ 

But... admit the chance that  $X_h = H^{-1/2}(\Gamma)$ , or  $X_h = \{0\}$ , or  $X_h = \widetilde{H}^{-1/2}(\Gamma_{scr})$ .

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### A set of compatible transmission conditions

#### You are allowed four data

$$\llbracket \gamma \boldsymbol{u} \rrbracket - \alpha_1 \in \boldsymbol{Y_h} \qquad \gamma^+ \boldsymbol{u} - \alpha_2 \in \boldsymbol{X_h^\circ}$$

 $\llbracket \partial_{\nu} u \rrbracket - \beta_{1} \in X_{h} \qquad \partial_{\nu}^{-} u - \beta_{2} \in Y_{h}^{\circ}$ 

$$\begin{aligned} (\nabla u, \nabla v)_{\mathbb{R}^d \setminus \Gamma} + (\Delta u, v)_{\mathbb{R}^d \setminus \Gamma} &= \langle \partial_{\nu}^- u, \gamma^- v \rangle_{\Gamma} - \langle \partial_{\nu}^+ u, \gamma^+ v \rangle_{\Gamma} \\ &= \langle \partial_{\nu}^- u, \llbracket \gamma v \rrbracket \rangle_{\Gamma} + \langle \llbracket \partial_{\nu} u \rrbracket, \gamma^+ v \rangle_{\Gamma} \end{aligned}$$

**Remark.** You can obviously use  $\gamma^-$  and  $\partial^+_{\nu}$  instead.

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# Some insight: conservation of energy

If for all *t* (the Laplacian is applied in  $\mathbb{R}^d \setminus \Gamma$ )

$$egin{aligned} \ddot{u}(t) &= \Delta u(t), \ & [\![\gamma u]\!](t) \in Y_h \qquad \gamma^+ u(t) \in X_h^\circ \ & [\![\partial_
u u]\!](t) \in X_h \qquad \partial_
u^- u(t) \in Y_h^\circ \end{aligned}$$

then

$$\begin{aligned} \frac{\mathrm{d}}{\mathrm{d}t} \left( \frac{1}{2} \|\nabla u(t)\|_{\mathbb{R}^{d}\setminus\Gamma}^{2} + \frac{1}{2} \|\dot{u}(t)\|_{\mathbb{R}^{d}\setminus\Gamma}^{2} \right) \\ &= (\nabla u(t), \nabla \dot{u}(t))_{\mathbb{R}^{d}\setminus\Gamma} + (\ddot{u}(t), \dot{u}(t))_{\mathbb{R}^{d}\setminus\Gamma} \\ &= (\nabla u(t), \nabla \dot{u}(t))_{\mathbb{R}^{d}\setminus\Gamma} + (\Delta u(t), \dot{u}(t))_{\mathbb{R}^{d}\setminus\Gamma} \\ &= \langle \partial_{\nu}^{-} u(t), [\![\gamma \dot{u}(t)]\!]\rangle_{\Gamma} + \langle [\![\partial_{\nu} u(t)]\!], \gamma^{+} \dot{u}(t)\rangle_{\Gamma} \\ &= 0 \end{aligned}$$

A student after class (in 2012). Was that ... like ... a proof?

## A well-posed elliptic problem

### PDE form

$$U = \Delta U$$

$$\llbracket \gamma U \rrbracket - \alpha_1 \in Y_h \qquad \gamma^+ U - \alpha_2 \in X_h^\circ$$

$$\llbracket \partial_\nu U \rrbracket - \beta_1 \in X_h \qquad \partial_\nu^- U - \beta_2 \in Y_h^\circ$$

#### Its variational formulation

$$U \in H^{1}(\mathbb{R}^{d} \setminus \Gamma)$$

$$\llbracket \gamma U \rrbracket - \alpha_{1} \in Y_{h} \qquad \gamma^{+}U - \alpha_{2} \in X_{h}^{\circ}$$

$$(\nabla U, \nabla V)_{\mathbb{R}^{d} \setminus \Gamma} + (U, V)_{\mathbb{R}^{d}} = \langle \beta_{2}, \llbracket \gamma V \rrbracket \rangle_{\Gamma} + \langle \beta_{1}, \gamma^{+}V \rangle_{\Gamma}$$

$$\forall V \in H^{1}(\mathbb{R}^{d} \setminus \Gamma), \qquad \llbracket \gamma V \rrbracket \in Y_{h} \qquad \gamma^{+}V \in X_{h}^{\circ}$$

**Remark.** This problem is perfectly coercive, right? There's more. You can bound its solution **independently of** *h*.

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### A wave equation in the Laplace domain

### PDE form

$$\begin{aligned} s^2 U &= \Delta U \\ \llbracket \gamma U \rrbracket - \alpha_1 \in Y_h \qquad \gamma^+ U - \alpha_2 \in X_h^\circ \\ \llbracket \partial_\nu U \rrbracket - \beta_1 \in X_h \qquad \partial_\nu^- U - \beta_2 \in Y_h^\circ \end{aligned}$$

#### VF

$$U \in H^{1}(\mathbb{R}^{d} \setminus \Gamma)$$

$$\llbracket \gamma U \rrbracket - \alpha_{1} \in Y_{h} \qquad \gamma^{+}U - \alpha_{2} \in X_{h}^{\circ}$$

$$(\nabla U, \nabla V)_{\mathbb{R}^{d} \setminus \Gamma} + s^{2}(U, V)_{\mathbb{R}^{d}} = \langle \beta_{2}, \llbracket \gamma V \rrbracket \rangle_{\Gamma} + \langle \beta_{1}, \gamma^{+}V \rangle_{\Gamma}$$

$$\forall V \in H^{1}(\mathbb{R}^{d} \setminus \Gamma), \qquad \llbracket \gamma V \rrbracket \in Y_{h} \qquad \gamma^{+}V \in X_{h}^{\circ}$$

**Remark.** Boundary data are now applied as instantaneous impulses at time t = 0.

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$$\begin{split} & U \in H^{1}(\mathbb{R}^{d} \setminus \Gamma) \\ & [\![\gamma U]\!] - \alpha_{1} \in Y_{h} \qquad \gamma^{+} U - \alpha_{2} \in X_{h}^{\circ} \\ & (\nabla U, \nabla V)_{\mathbb{R}^{d} \setminus \Gamma} + s^{2} (U, V)_{\mathbb{R}^{d}} = \langle \beta_{2}, [\![\gamma V]\!] \rangle_{\Gamma} + \langle \beta_{1}, \gamma^{+} V \rangle_{\Gamma} \quad \forall V \dots \end{split}$$

The essential TC are taken care by the **optimal (non-physical) lifting** of Bamberger & HaDuong

$$\begin{split} & U_d \in H^1(\mathbb{R}^d \setminus \Gamma) \\ & [\![\gamma U_d]\!] = \alpha_1 \qquad \gamma^+ U_d = \alpha_2 \\ & (\nabla U_d, \nabla V)_{\mathbb{R}^d \setminus \Gamma} + |s|^2 (U_d, V)_{\mathbb{R}^d} = 0 \qquad \forall V \in H^1_0(\mathbb{R}^d \setminus \Gamma) \end{split}$$

**Remark.** You then study the problem satisfied by  $U_0 = U - U_d$  (which can be used as test function!)

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### Laplace's puzzle: the corner pieces

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$$a(U,V;s):=(
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abla V)_{\mathbb{R}^d\setminus \mathsf{\Gamma}}+s^2(U,V)_{\mathbb{R}^d}$$

and

$$\|\|U\|^2_{|s|}:=a(U,\overline{U};|s|)=\|
abla U\|^2_{\mathbb{R}^d\setminus\Gamma}+\|s\,U\|^2_{\mathbb{R}^d}$$

is the energy norm, then

$$\begin{aligned} |a(U,V;s)| &\leq ||\!| U ||\!|_{|s|} ||\!| V ||\!|_{|s|} \qquad \text{(boundedness)} \\ &\operatorname{Re} a(U,\overline{s\,U};s)| = (\operatorname{Re} s) ||\!| U ||\!|_{|s|}^2 \qquad \text{(coercivity)} \\ &\min\{1,\operatorname{Re} s\} ||U||_{1,\mathbb{R}^d\setminus\Gamma} \leq ||\!| U ||\!|_{|s|} \leq \frac{|s|}{\min\{1,\operatorname{Re} s\}} ||U||_{1,\mathbb{R}^d\setminus\Gamma} \end{aligned}$$

# **Remark.** The coercivity identity is the one telling you to differentiate one of the arguments in the weak TD formulation

### Laplace's puzzle: the impossible blue sky part

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$$-\Delta U + |\boldsymbol{s}|^2 U = 0 \quad \text{in } \mathbb{R}^d \setminus \Gamma, \qquad \gamma^{\pm} U = \alpha_{\pm},$$

then

$$|||U|||_{|s|} \le C_{\Gamma} \max\{1, |s|\}^{1/2} ||\alpha_{\pm}||_{1/2, \Gamma}.$$

Therefore, if

$$-\Delta U + s^2 U = 0 \quad \text{in } \mathbb{R}^d \setminus \Gamma,$$

then

$$\|\partial_{\nu}^{\pm} U\|_{-1/2,\Gamma} \leq C_{\Gamma} \left(\frac{|s|}{\min\{1,\operatorname{Re} s\}}\right)^{1/2} \|\!| U \|_{|s|}$$

Remark. Maxwell differs here

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### The finished image can now be guessed

- You can get Laplace domain bounds for the associated transfer function. With these, use any Inversion of the L.T. theorem to get time domain results.
- You can focus on coercivity results and apply Plancherel. This gives a theoretical basis for some weighted Galerkin methods

**Remark.** We leave Laplace finishing the puzzle and move a more dynamical view

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### A dynamical system

### Second order form. For all t

$$\begin{aligned} \ddot{u}(t) &= \Delta u(t) \\ \llbracket \gamma u \rrbracket(t) - \alpha_1(t) \in Y_h \qquad \gamma^+ u(t) - \alpha_2(t) \in X_h^\circ \\ \llbracket \partial_\nu u \rrbracket(t) - \beta_1(t) \in X_h \qquad \partial_\nu^- u(t) - \beta_2(t) \in Y_h^\circ \end{aligned}$$

#### First order form. For all t

$$\begin{split} \dot{u}(t) &= \nabla \cdot \mathbf{v}(t) \qquad \dot{\mathbf{v}}(t) = \nabla u(t) \\ \llbracket \gamma u \rrbracket(t) - \alpha_1(t) \in Y_h \qquad \gamma^+ u(t) - \alpha_2(t) \in X_h^\circ \\ \llbracket \gamma_\nu \mathbf{v} \rrbracket(t) - \partial^{-1} \beta_1(t) \in X_h \qquad \gamma_\nu^- \mathbf{v}(t) - \partial^{-1} \beta_2(t) \in Y_h^\circ \end{split}$$

**Main advantage.** All TC are now essential. The lifting will take care of all of them at the same time. Note how natural data have been integrated in time

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### The main decomposition

Write

$$(u(t), \mathbf{v}(t)) = (u_d(t), \mathbf{v}_d(t)) + (u_0(t), \mathbf{v}_0(t)),$$

where (elliptic lifting of TCs)

$$\begin{aligned} u_d(t) &= \nabla \cdot \mathbf{v}_d(t) & \mathbf{v}_d(t) = \nabla u_d(t) \\ \llbracket \gamma u_d \rrbracket(t) - \alpha_1(t) \in Y_h & \gamma^+ u_d(t) - \alpha_2(t) \in X_h^\circ \\ \llbracket \gamma_\nu \mathbf{v}_d \rrbracket(t) - \partial^{-1} \beta_1(t) \in X_h & \gamma_\nu^- \mathbf{v}_d(t) - \partial^{-1} \beta_2(t) \in Y_h^\circ \end{aligned}$$

and (non-homogeneous ODE in Hilbert space)

$$\begin{split} \dot{u}_{0}(t) &= \nabla \cdot \mathbf{v}_{0}(t) - \dot{u}_{d}(t) + u_{d}(t) \qquad \dot{\mathbf{v}}_{0}(t) = \nabla u_{0}(t) - \dot{\mathbf{v}}_{d}(t) + \mathbf{v}_{d}(t) \\ & [\![\gamma u_{0}]\!](t) \in Y_{h} \qquad \qquad \gamma^{+} u_{0}(t) \in X_{h}^{\circ} \\ & [\![\gamma_{\nu} \mathbf{v}_{0}]\!](t) \in X_{h} \qquad \qquad \gamma_{\nu}^{-} \mathbf{v}_{0}(t) \in Y_{h}^{\circ} \end{split}$$

And... honestly, that's all it takes to study this problem. (Well, up to a point.)

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# A problem to rule them all



TDBIE

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Let me copy-paste this problem again: for all  $t \ge 0$ 

$$\begin{aligned} \ddot{u}(t) &= \Delta u(t) \\ \llbracket \gamma u \rrbracket(t) - \alpha_1(t) \in Y_h \qquad \gamma^+ u(t) - \alpha_2(t) \in X_h^\circ \\ \llbracket \partial_\nu u \rrbracket(t) - \beta_1(t) \in X_h \qquad \partial_\nu^- u(t) - \beta_2(t) \in Y_h^\circ \end{aligned}$$

We now pick  $X_h$ ,  $Y_h$ , and different choices of data. Quantities of interest:

$$\|u(t)\|_{1,\mathbb{R}^d}, \qquad \|\gamma^{\pm}u(t)\|_{1/2,\Gamma}, \qquad \|\partial_{\nu}^{\pm}u(t)\|_{-1/2,\Gamma} = \|\gamma_{\nu}^{\pm}\dot{\mathbf{v}}(t)\|_{-1/2,\Gamma}$$

**Luckily...** when you obtain bounds for u(t) and v(t), you also produce bounds for their first derivatives

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### Examples galore



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 $X_h = \{0\}, Y_h = \{0\}$  (polar sets do not give any information!)

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$$\ddot{u}(t) = \Delta u(t)$$
$$\llbracket \gamma u \rrbracket(t) = \varphi(t)$$
$$\partial_{\nu} u \rrbracket(t) = \lambda(t)$$

SO

$$\boldsymbol{U} = \boldsymbol{\mathcal{S}} \ast \boldsymbol{\lambda} - \boldsymbol{\mathcal{D}} \ast \boldsymbol{\varphi}$$

and we also gets bounds for all the operators of the acoustic Calderón projector.

# Find the density by looking at the trace

 $X_h = H^{-1/2}(\Gamma)$  (entire space to look into and  $X_h^{\circ} = \{0\}$ ),  $Y_h = \{0\}$  (the polar set is  $H^{-1/2}(\Gamma)$ )

$$\begin{split} \ddot{u}(t) &= \Delta u(t) \\ \llbracket \gamma u \rrbracket(t) &= 0 \\ \gamma^+ u(t) &= \alpha(t) \\ \lambda(t) &:= \llbracket \partial_{\nu} u \rrbracket(t) \in H^{-1/2}(\Gamma) \qquad (\text{unknown}) \end{split}$$

so we are solving

$$\mathcal{V} * \lambda = \alpha, \qquad \mathbf{U} = \mathcal{S} * \lambda$$

(Indirect method for Dirichlet problem. Single layer potential representation.)

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# Same spaces, different data

 $X_h = H^{-1/2}(\Gamma)$  (entire space to look into and  $X_h^{\circ} = \{0\}$ ),  $Y_h = \{0\}$  (the polar set is  $H^{-1/2}(\Gamma)$ )

$$\begin{split} \ddot{u}(t) &= \Delta u(t) \\ \llbracket \gamma u \rrbracket(t) &= \varphi(t) \\ \gamma^+ u(t) &= 0 \\ \lambda(t) &:= \llbracket \partial_{\nu} u \rrbracket(t) \in H^{-1/2}(\Gamma) \qquad (\text{unknown}) \end{split}$$

so we are solving

$$\mathcal{V} * \lambda = \frac{1}{2}\varphi + \mathcal{K} * \varphi, \qquad \mathbf{U} = \mathcal{S} * \lambda - \mathcal{D} * \varphi$$

(Direct formulation for interior Dirichlet problem. Note that  $\gamma^- u = \varphi$ . Small variant for exterior problem.)

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# Find the density by looking at the trace (discretely)

$$\begin{array}{l} X_h \text{ (finite dimensional), } Y_h = \{0\} \\ \\ \ddot{u}(t) = \Delta u(t) \\ [\![\gamma u]\!](t) = 0 \\ \gamma^+ u(t) - \alpha(t) \in X_h^\circ \\ \\ \lambda^h(t) := [\![\partial_\nu u]\!](t) \in X_h \end{array} \qquad (\text{unknown}) \end{array}$$

so we are solving

$$\lambda^h \in \mathbf{X}_h \quad \langle \mathcal{V} \ast \lambda^h - \alpha, \mu \rangle_{\Gamma} = \mathbf{0} \quad \forall \mu \in \mathbf{X}_h$$

and then plugging

$$u = \mathcal{S} * \lambda^h$$

(The discretization of the direct formulation is similar.)

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# Same spaces, different data

 $X_h$  (finite dimensional),  $Y_h = \{0\}$ 

$$\begin{split} \ddot{u}(t) &= \Delta u(t) \\ \llbracket \gamma u \rrbracket(t) &= 0 \\ \gamma^+ u(t) \in X_h^\circ \\ -\lambda^h(t) &:= \llbracket \partial_\nu u \rrbracket(t) - \lambda(t) \in X_h \end{split} \tag{unknown}$$

so we are solving

$$\lambda^h \in X_h \quad \langle \mathcal{V} * \lambda^h - \mathcal{V} * \lambda, \mu \rangle_{\Gamma} = \mathbf{0} \quad \forall \mu \in X_h$$

and then plugging

$$u = \mathcal{S} * (\lambda - \lambda^h)$$

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### I could go on and on and on

- Deactivating  $X_h$  ( $X_h = \{0\}$ ) we obtain double-layer potential related integral equations (Neumann problem) and their Galerkin semidiscretizations
- Activating X<sub>h</sub> and Y<sub>h</sub> at different parts of the boundary we obtain the symmetric Galerkin method for mixed boundary value problems (scatterers with different material properties)
- Activating X<sub>h</sub> in one part of Γ and deactivating Y<sub>h</sub>, we get Dirichlet screens and their discretizations. (And Neumann screens? Guess!)
- Integral equations of the second kind also follow from this theory. However (!!), there doesn't to be any conclusion about their semidiscretization in the pool.

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