### Statistics in BHV Tree Space

#### Megan Owen Lehman College, CUNY Joint with Daniel Brown (U. Waterloo)

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# Overarching Goal

- many examples of tree-shaped data (phylogenies, anatomical trees, etc.)
- parameters:
  - tree shape = tree topology
  - edge lengths
- not Euclidean data!

Goal: develop methods for statistical analysis (i.e. mean, PCA) in a space of metric trees analogous to those for Euclidean space

P. Lo et al. EXACT'09

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## Tree Space Framework

- constructed by Billera, Holmes, and Vogtmann (2001)
- tree space  $T_n$  = set of all trees with *n* leaves and branch lengths
- includes degenerate trees (non-binary)



## Tree Space

(2, 4, 2, 3, 2, 0, 0, 0, 0, 2, 0, 0, ...)

- represent each tree as a vector
- coordinates = splits



## Tree Space

not all sets of splits form a tree
 ⇒ not all vectors are possible
 ⇒ not a Euclidean space



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#### Tree Space Properties

Theorem (Billera, Holmes,Vogtmann, 2001): Tree space has global non-positive curvature. ⇒ unique geodesics (shortest paths)

- $\Rightarrow$  well-defined mid-point tree
- BHV or geodesic distance = length of shortest path between two trees T<sub>1</sub> and T<sub>2</sub>
- polynomial time algorithm to compute geodesic distance (O. and Provan, 2011)

## Mean and Variance

weighted set X in tree space:

Fréchet mean(X) = centre of mass

= argmin 
$$\sum_{\mu} p(\mathbf{x}) d(\mathbf{x}, \mu)^2$$

(tree minimizing sum of square BHV distances)

• variance(X) = 
$$\sum_{x \in X} p(x) d(x, \mu)^2$$

 computable by algorithm based on Law of Large Numbers (Sturm 2003; Miller, O, Provan 2015; Bačák 2014)

































## Measures of Variance

- # of different topologies in sample
- # of different splits in sample
- sum of squared distances between trees

















#### Caveat



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## Other Statistics

- Central Limit Theorem on BHV tree space:
  - special cases: Hotz, O., et al. 2012; Barden, Le, O., 2013, 2014; Huckemann et al. 2015
- Principal Components Analysis (PCA): (Nye 2011, 2014; Feragen, O. et al. 2013; Nye et al. 2016)
- confidence regions: Willis 2016
- multiple techniques: Chakerian and Holmes 2012, Zairis et al. 2016
- and more...

## Thank You

#### • funding: SIMONS FOUNDATION

#### webpage: http://comet.lehman.cuny.edu/owen

- $m_1 = T_1$
- i<sup>th</sup> iteration :
  - randomly choose tree T<sub>i</sub> from tree set with replacement

• 
$$m_i = \frac{1}{i}$$
 (geodesic from  $m_{i-1}$  to  $T_i$ )

Theorem (Sturm, 2003): the following algorithm converges to the mean tree:

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