

Volume product and metric spaces

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Joint work with Matthew Alexander, Matthieu Fradelizi and Artem Zvavitch

Kent State University

Workshop in Geometric Tomography

BIRS

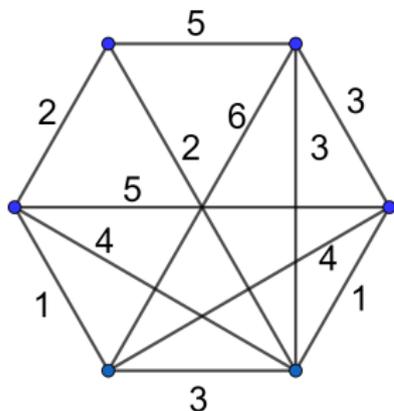
February 13th, 2020

Finite metric spaces and graphs

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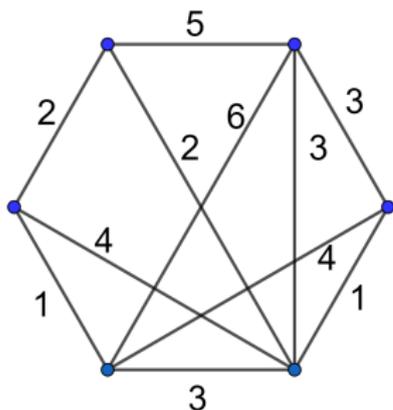
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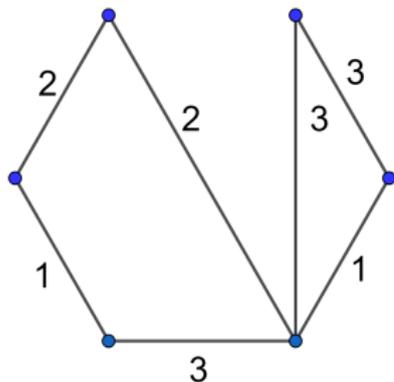
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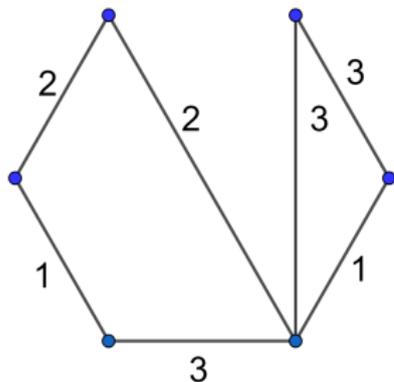
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- (x, y) is an edge of the graph if and only if $d(x, y) < d(x, z) + d(z, y)$ for all $z \in M \setminus \{x, y\}$.

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- We identify $f \equiv (f(a_1), \dots, f(a_n)) \in \mathbb{R}^n$. We denote

$$B_{\text{Lip}_0(M)} := \left\{ f : \frac{f(a_i) - f(a_j)}{d(a_i, a_j)} \leq 1 \quad \forall i \neq j \right\} = \left\{ f : \left\langle f, \frac{e_i - e_j}{d(a_i, a_j)} \right\rangle \leq 1 \quad \forall i \neq j \right\}$$

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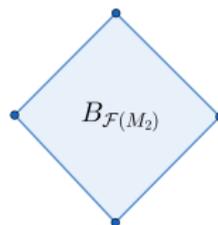
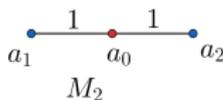
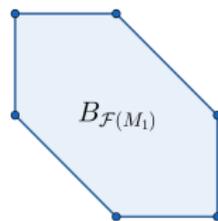
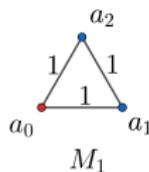
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- $\mathcal{F}(M)$ is called the *Lipschitz-free space over M* (also Arens-Eells, Wasserstein 1, transportation cost, Kantorovich-Rubinstein, ...)

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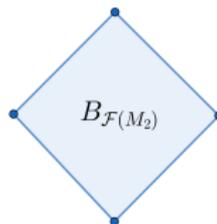
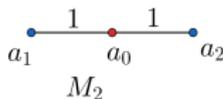
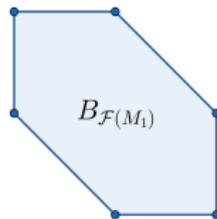
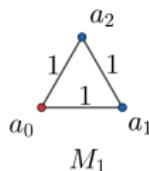


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$\frac{e_i - e_j}{d(a_i, a_j)}$ is a vertex of $B_{\mathcal{F}(M)}$ if and only if $d(x, y) < d(x, z) + d(z, y)$ for all $z \in M \setminus \{x, y\}$.



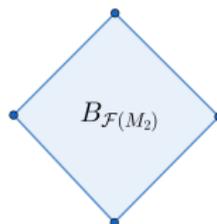
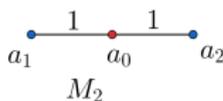
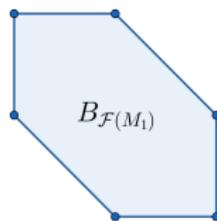
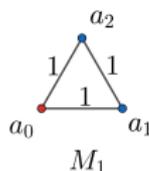
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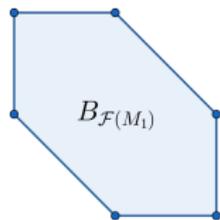
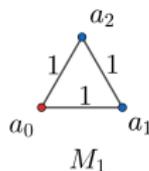
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Indeed, we have shown that $\frac{e_i - e_j}{d(a_i, a_j)}$ belongs to a face of $B_{\mathcal{F}(M)}$ of dimension k precisely if there are k different points $z_1, \dots, z_k \in M \setminus \{x, y\}$ such that $d(x, y) = d(x, z_k) + d(z_k, y)$.



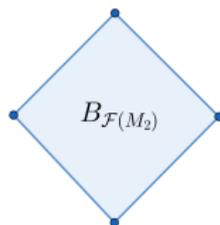
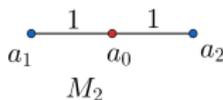
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Theorem (Godard, 2010)

- M is a tree if and only if $B_{\mathcal{F}(M)}$ is a linear image of B_1^n .
- M embeds into a tree if and only if $B_{\text{Lip}_0(M)}$ is a zonoid.

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Blaschke–Santaló inequality

$$\mathcal{P}(K) \leq \mathcal{P}(B_2^n)$$

- (Blaschke, 1923) for $n \leq 3$, (Santaló, 1948) for $n > 3$.
- (Saint-Raymond, 1981), (Petty, 1985) for the equality case.
- Proofs using Steiner symmetrization: (Ball, 1986), (Meyer–Pajor, 1990).
- Harmonic Analysis based proof (Bianchi–Kelly, 2015).
- Stability Results: (Böröczky, 2010), (Barthe–Böröczky–Frédérizi, 2014).
- Functional forms (for log-concave functions): (Ball, 1986), (Artstein-Avidan–Klartag–Milman, 2004), (Frédérizi–Meyer, 2007), (Lehec, 2009).

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- Around Hanner polytopes/Unconditional bodies (Nazarov–Petrov–Ryabogin–Zvavitch, 2010), (Kim, 2013), (Kim–Zvavitch, 2013).
- Body has a point of positive curvature then it is not a minimizer. (Stancu, 2009), (Reisner–Schütt–Werner, 2010), (Gordon–Meyer, 2011).
- Zonoids (Reisner, 1986), (Gordon–Meyer–Reisner, 1988).
- Hyperplane sections of ℓ_p -balls and Hanner polytopes, (Karasev, 2019).
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Shadow Systems

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$$K_t = \text{conv}\{x + \alpha(x)t\vec{\theta}, \text{ over all } x \in B\}$$

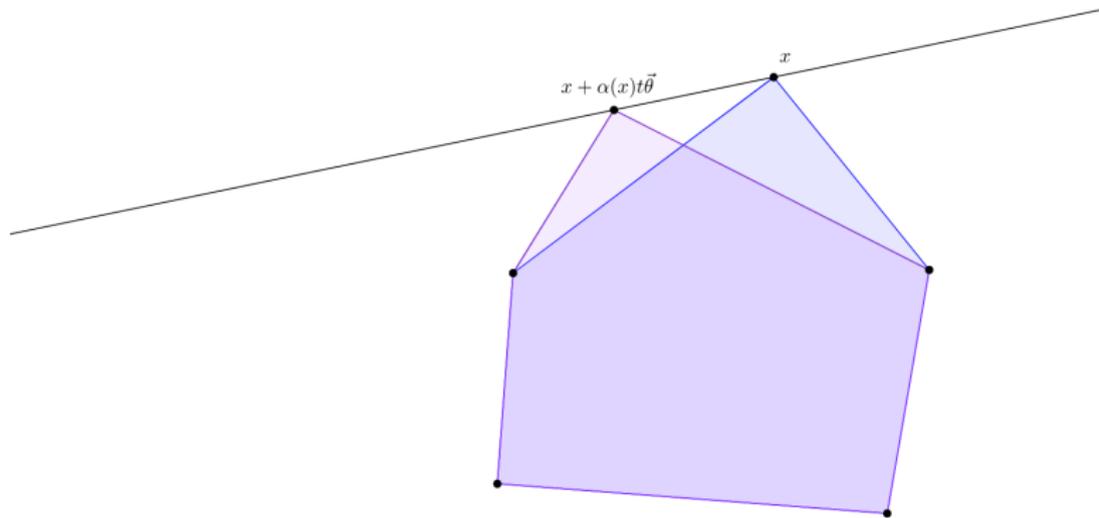
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- If K_t is symmetric for all $t \in [a, b]$, then $t \mapsto |K_t^o|^{-1}$ is convex (Campi–Gronchi, 2006), non-symmetric case by (Meyer–Reisner 2006).

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As a consequence, if $t \mapsto |K_t|$ is affine, then

$$\min_{t \in [a, b]} \mathcal{P}(K_t) = \min\{\mathcal{P}(K_a), \mathcal{P}(K_b)\}$$

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Theorem (Alexander–Fradelizi–G.–Zvavitch, 2019)

Let M be a finite metric space with minimal volume product such that $B_{\mathcal{F}(M)}$ is a simplicial polytope. Then M is a tree (and so $\mathcal{P}(M) = 4^n/n!$).

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- $t \mapsto B_{\mathcal{F}(M_t)}$ is a **shadow system based on the vertices of $B_{\mathcal{F}(M)}$** .
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The volume product of a metric space

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Theorem (Alexander–Fradelizi–G.–Zvavitch, 2019)

Let M be a finite metric space with minimal volume product such that $B_{\mathcal{F}(M)}$ is a simplicial polytope. Then M is a tree (and so $\mathcal{P}(M) = 4^n/n!$).

Proof. Fix an edge (a_i, a_j) of the graph of M and denote $m_{ij} = \frac{e_i - e_j}{d(a_i, a_j)}$. For $|t|$ small enough, consider the metric space M_t with the same graph as M but weight of (a_i, a_j) is replaced by $d_t(a_i, a_j) = \frac{d(a_i, a_j)}{1+t}$. Then,

$$B_{\mathcal{F}(M_t)} = \text{conv} \left\{ (\text{vertices}(B_{\mathcal{F}(M)}) \setminus \{\pm m_{ij}\}) \cup \pm(1+t)m_{ij} \right\}$$

- $t \mapsto B_{\mathcal{F}(M_t)}$ is a **shadow system based on the vertices of $B_{\mathcal{F}(M)}$** .
- $t \mapsto |B_{\mathcal{F}(M_t)}|$ is affine.
- A result by (Fradelizi–Meyer–Zvavitch, 2012) ensures that $B_{\mathcal{F}(M)}$ is a double cone with apex m_{ij} .

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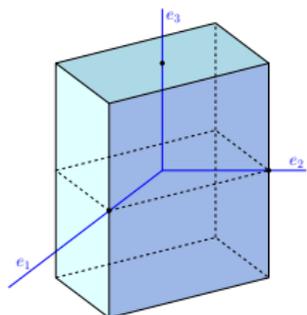
Thus, $B_{\mathcal{F}(M)}$ is a double cone with respect to each one of its vertices. So it is a linear image of B_1^n .

Hanner polytopes

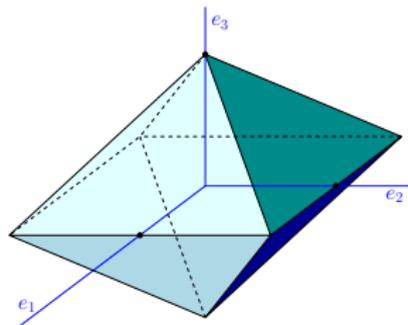
Hanner polytopes

Consider convex symmetric bodies $K \subset \mathbb{R}^m$ and $L \subset \mathbb{R}^n$ denote by:

- $K \oplus_\infty L = K + L$ their ℓ_∞ -sum: $\|(x_1, x_2)\|_{K \oplus_\infty L} = \max\{\|x_1\|_K, \|x_2\|_L\}$
- $K \oplus_1 L = \text{conv}(K \cup L)$ their ℓ_1 -sum: $\|(x_1, x_2)\|_{K \oplus_1 L} = \|x_1\|_K + \|x_2\|_L$



$$(I \oplus_1 I) \oplus_\infty I$$

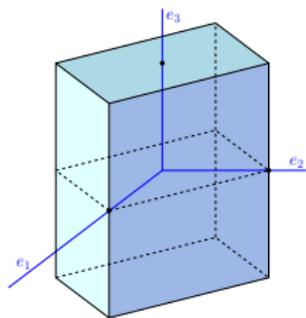


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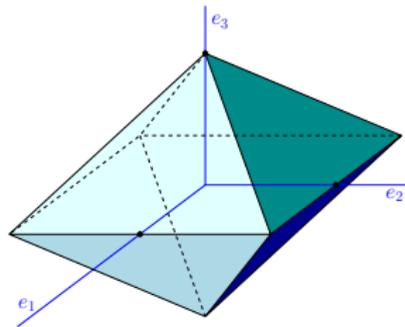
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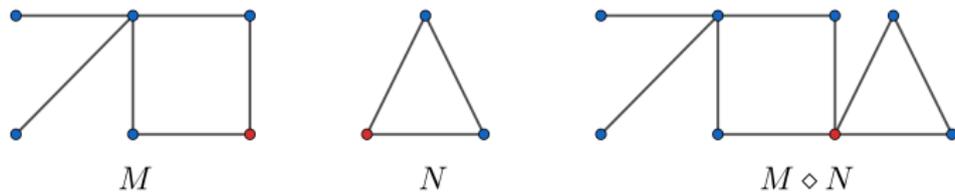
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A symmetric convex body is called a **Hanner polytope** if it is one-dimensional, or the ℓ_1 or ℓ_∞ sum of two (lower dimensional) Hanner polytopes.

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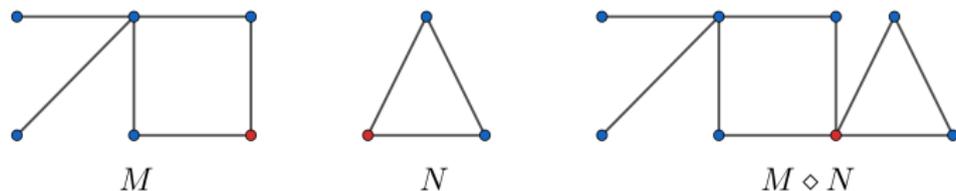
The ℓ_1 -sum of two finite metric spaces M, N is the metric space $M \diamond N$ obtained by identifying the distinguished points of M and N .



Note that $B_{\mathcal{F}(M \diamond N)} = B_{\mathcal{F}(M)} \oplus_1 B_{\mathcal{F}(N)}$.

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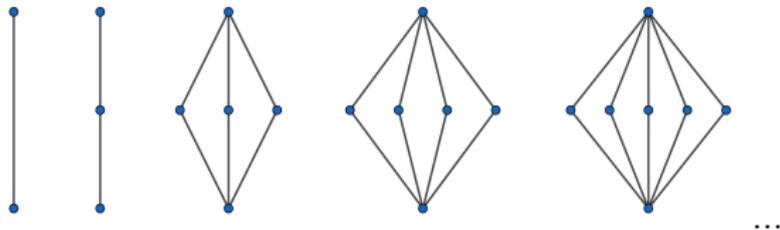
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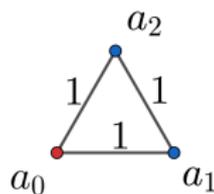
Theorem (Alexander–Fradelizi–G.–Zvavitch, 2019)

$B_{\mathcal{F}(M)}$ is a Hanner polytope if and only if $M = M_1 \diamond \dots \diamond M_r$ and each M_i either contains only two points or it is the complete bipartite graph $K_{2,n}$, where all the edges have the same weight.



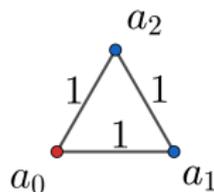
Maximal volume product

For $n = 2$, the metric space with maximum volume product is a complete graph with equal weights.



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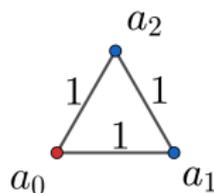
Theorem (Alexander–Fradelizi–G.–Zvavitch, 2019)

Assume that $\mathcal{P}(M)$ is maximal among the metric spaces with the same number of elements. Then

- $d(x, y) < d(x, z) + d(z, y)$ for all different points $x, y, z \in M$, and
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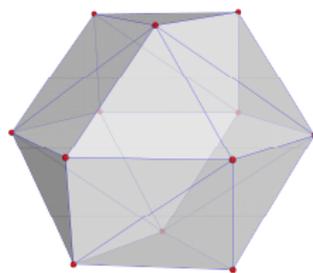


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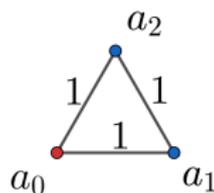
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Thank you for your attention

