

Hard Examples for Common Variable Decision Heuristics

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Banff workshop on Proof Complexity

DPLL

Algorithm 1: DPLL**while** *not solved* **do** **if** *conflict* **then** backtrack() **else if** *unit* **then** propagate() **else**

decide()

State: partial assignment

CDCL

Algorithm 2: CDCL

while *not solved* **do**

if *conflict* **then** **learn**()

else if *unit* **then** propagate()

else

 maybe forget()

 maybe restart()

 decide()

State: partial assignment & learned clauses

CDCL equivalent to Resolution

Theorem

[Beame, Kautz, Sabharwal '04]

Resolution p -simulates CDCL

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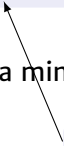
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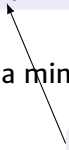
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Wait a minute. Albert says Resolution is NP-hard to automatize.

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Also: CDCL with random decisions simulates bounded-width Resolution
[Atserias, Fichte, Thurley '09].

Separation of CDCL vs Resolution

Theorem

There are formulas such that

- ▶ Resolution refutations of polynomial length
- ▶ Exponential time in CDCL with common decision heuristics

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Decision Heuristics

Which literal do we pick next?

- ▶ Will lead to a conflict quickly.
- ▶ Was involved in conflicts recently.

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VSIDS

- ▶ Give a score $q(x)$ to variable x .
- ▶ At each conflict
 - ▶ Bump $q' = q + 1$ if x involved.
 - ▶ Decay $q' = 0.95 \cdot q$ all variables.
- ▶ Pick variable with largest score

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Sign

- ▶ Last assigned.

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Properties of VSIDS

- ▶ Each conflict
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Observation

A variable involved in a conflict is picked before a variable that never has.

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Fine Print

Not true if finite precision.

Does hold if stable priority queue.

Separation of CDCL vs Resolution

Definition

A decision heuristic **rewards conflicts** if a variable involved in a conflict is picked before a variable that never has.

Theorem

There are formulas such that

- ▶ Resolution refutations of polynomial length
- ▶ Exponential time in CDCL with **conflict-rewarding heuristics**

Intuition

- ▶ Bump $q' = q + 1$ if x involved.
- ▶ Decay $q' = 0.95 \cdot q$ all variables.



Easy

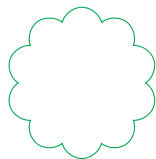
- ▶ **Easy** part + **Hard** part.



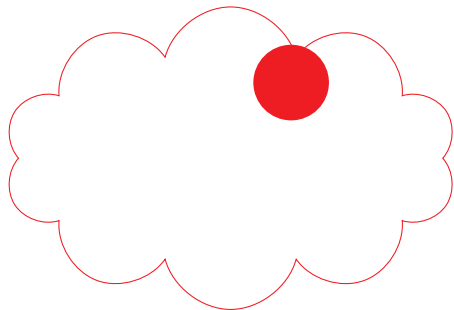
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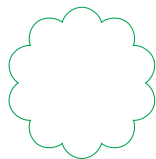


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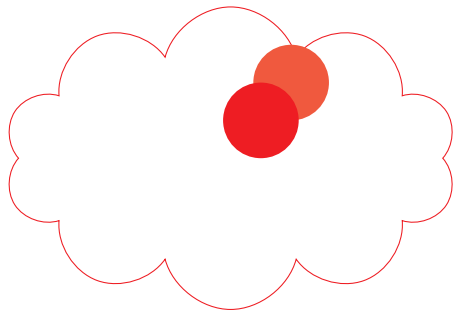
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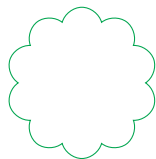
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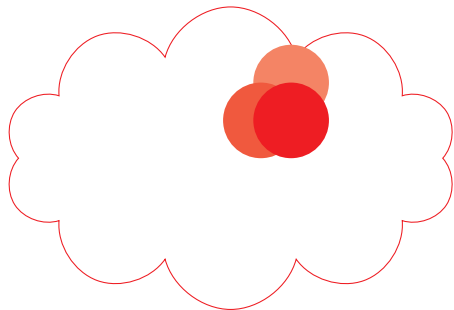
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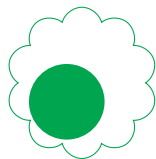
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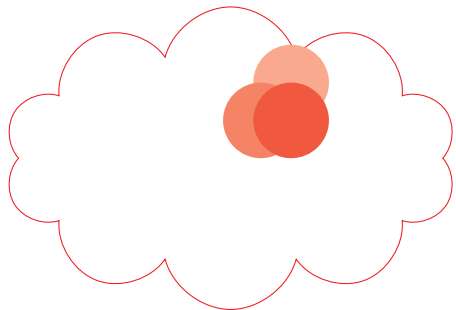


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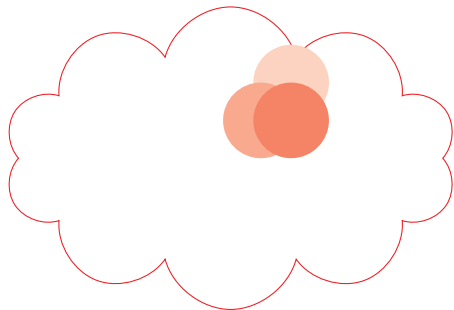


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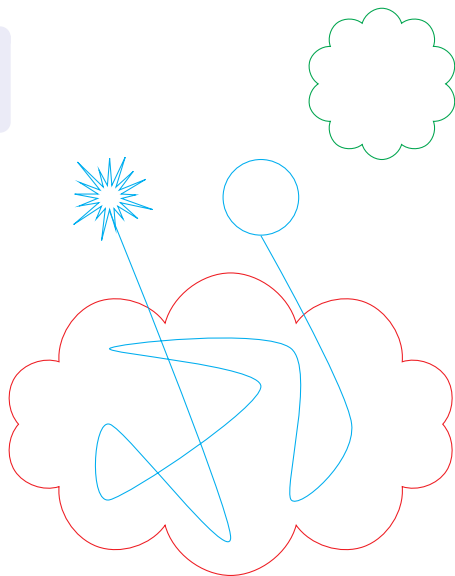


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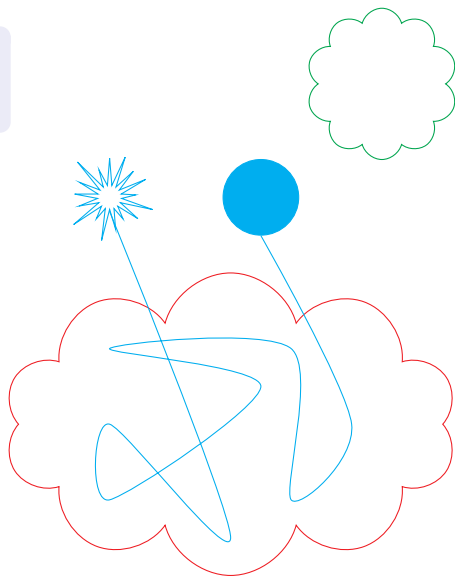
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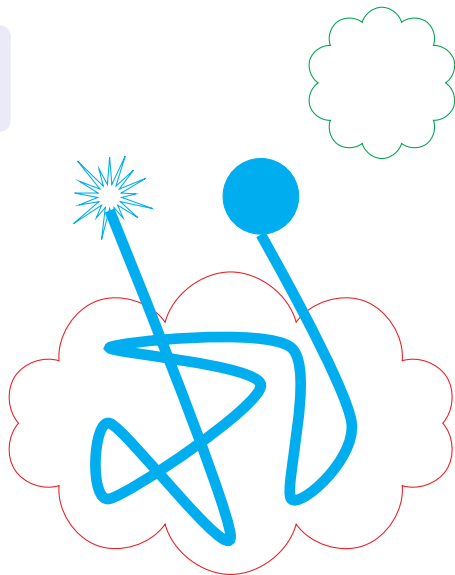
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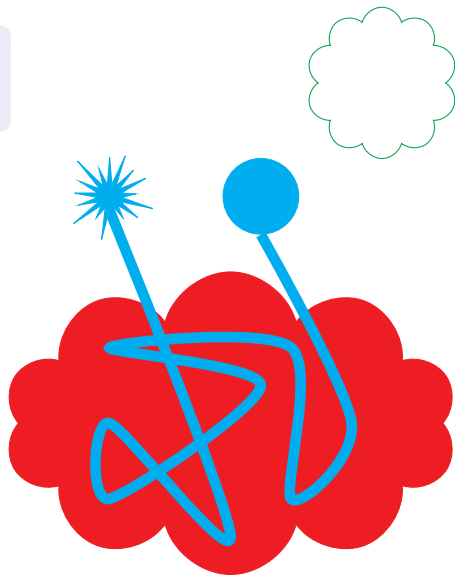
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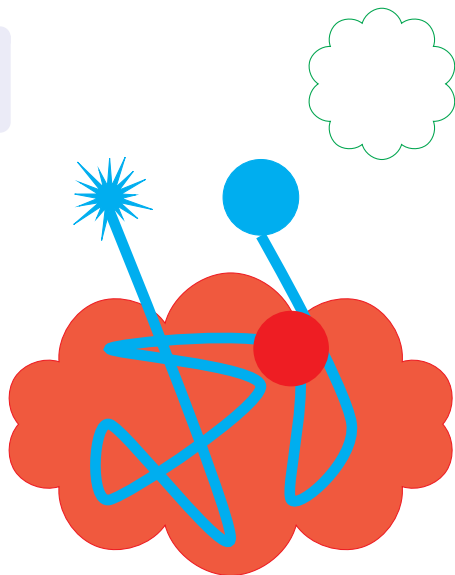
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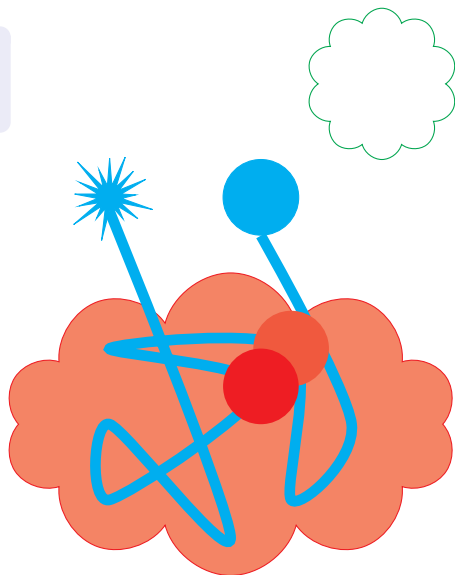
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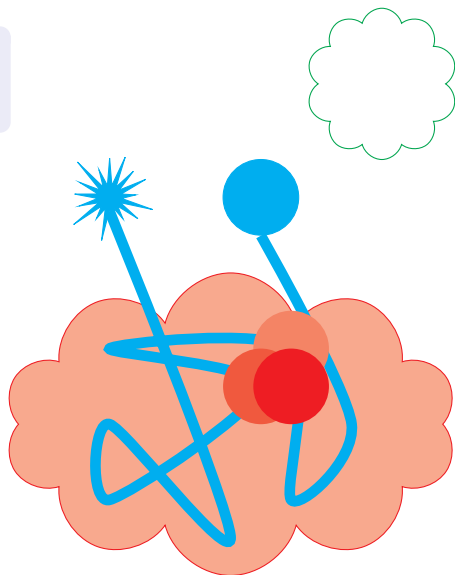
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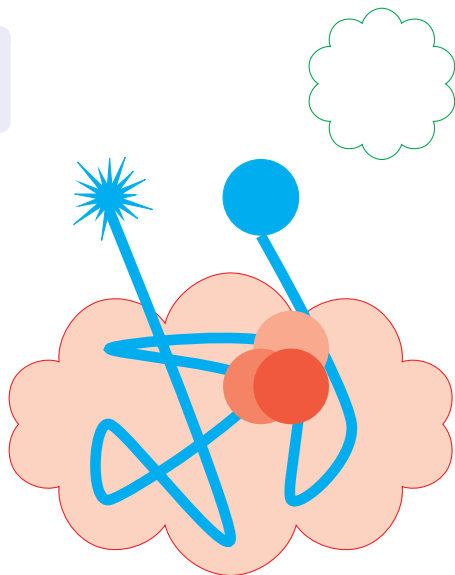
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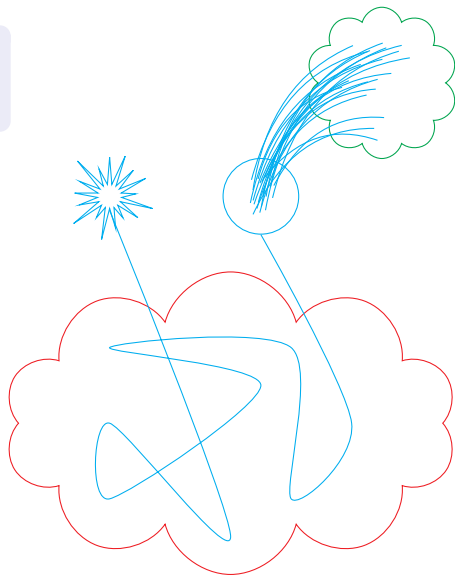
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-
- ▶ But still $1/\text{poly}$ probability of solving easy part first.



Intuition (III)

- ▶ Bump $q' = q + 1$ if x involved.
 - ▶ Decay $q' = 0.95 \cdot q$ all variables.
-
- ▶ Make easy variables lead to **pitfall gadget**.



Formula Description

Pitfall Formula Φ

Variables

X Hard

Y Easy

Z Auxiliary

Gadgets

$Ts(X, Z)$

$\Gamma(Y)$

$\Psi(Y, Z)$ & $\Pi(Z, X)$

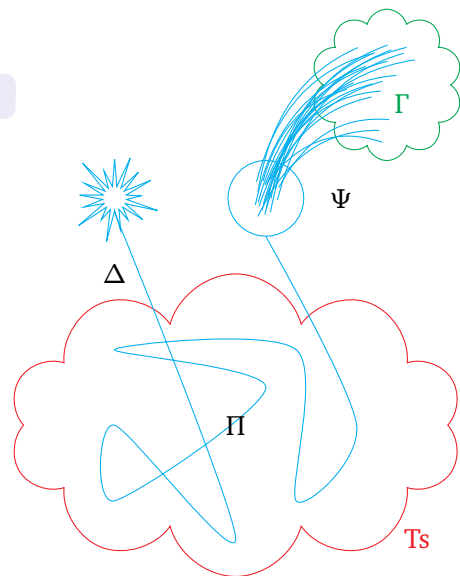
$\Delta(Z)$

Padded Tsetin

Easy

Pitfall

Tail



Proof Sketch

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In other words $\pi \upharpoonright_\rho : \mathbf{T}s \vdash \perp$.
- ▶ Hence π exponential.

Proof Sketch (II)

Need to ensure no conflicts use Γ clauses.
Define following solver states:

(a)

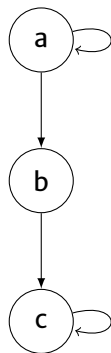
- ▶ No conflict
- ▶ No pair of Y variables assigned
- ▶ Enough Z variables unassigned

(b)

- ▶ (a) + a pair of Y variables assigned

(c)

- ▶ (a) + all X variables involved in a conflict



Take Home

Result

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Open Problems

- ▶ CDCL with VSIDS vs CDCL with random decisions?
- ▶ Lower bound robust wrt score precision?
- ▶ Simpler construction?
- ▶ Abstract proof?

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