Distributions of Multitaper Transfer Function Estimates

Multitaper Spectral Analysis (Online) BIRS 2022 Workshop

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Part 1: Background & Motivation

$$y(t) = \beta(t) x(t) + \varepsilon(t)$$

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Assume error terms are uncorrelated with respect to time.

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Problem: this model can fail to identify temporal trends!

Example: Time-Correlated Errors



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$$\frac{Y(f)}{Y(f)} = H(f) X(f)$$

$$Y_k(f) = H(f) X_k(f)$$
 $k \in \{0, ..., K-1\}$

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Multitaper Transfer Function

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Part 2:

Distributions of Objects in the Frequency Domain

The time series we will consider are signal(s) embedded in noise.

x(t) =

$$x(t) = \xi_x(t)$$

$$x(t) = \frac{\xi_x(t)}{\xi_x(t)} + z_x(t)$$

$$\frac{x(t)}{y(t)} = \frac{\xi_x(t)}{\xi_x(t)} + \frac{\xi_x(t)}{\xi_x(t)}$$

$$\frac{x(t)}{y(t)} = \frac{\xi_x(t)}{\xi_y(t)} + z_x(t)$$

$$\begin{aligned} x(t) &= \xi_x(t) + z_x(t) \\ y(t) &= \xi_y(t) + z_y(t) \end{aligned}$$

The time series we will consider are signal(s) embedded in noise.

$$\begin{aligned} x(t) &= \xi_x(t) + z_x(t) \\ y(t) &= \xi_y(t) + z_y(t) \end{aligned} \qquad z_x(t) \sim \mathcal{N}(0, \sigma_x^2) \\ z_y(t) \sim \mathcal{N}(0, \sigma_y^2) \end{aligned}$$

The noise underlying each time series is Gaussian distributed (zero-mean)

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The noise underlying each time series is Gaussian distributed (zero-mean)

Assume this noise is strongly stationary.

 $X_k(f)$ can be broken down into its deterministic and stochastic parts

 $X_k(f)$

$$\overline{X_k(f)} = \sum_{t=0}^{N-1} v_k(t)$$

$$X_k(f) = \sum_{t=0}^{N-1} v_k(t) \left(\qquad \right)$$

$$X_k(f) = \sum_{t=0}^{N-1} v_k(t) \left(\xi_x(t) \right)$$

$$X_k(f) = \sum_{t=0}^{N-1} v_k(t) \left(\frac{\xi_x(t)}{\xi_x(t)} + \right)$$

$$X_k(f) = \sum_{t=0}^{N-1} v_k(t) \left(\frac{\xi_x(t) + z_x(t)}{\xi_x(t) + z_x(t)} \right)$$

$$X_k(f) = \sum_{t=0}^{N-1} v_k(t) \left(\xi_x(t) + z_x(t) \right) e^{-i2\pi f t}$$

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 $X_k(f) = \frac{\Xi_k(f)}{\Xi_k(f)} + Z_k(f)$
Eigencoefficients: Distribution

 $X_k(f)$ can be broken down into its deterministic and stochastic parts

 $X_k(f) = \frac{\Xi_k(f)}{\Xi_k(f)} + Z_k(f)$

 $X_k(f)$ is Complex Gaussian distributed.

$$Z_k(f) = \sum_{k=0}^{N-1} v_k(t) \quad z_x(t) \quad e^{-i2\pi ft}$$

$$\mathbf{E}\left[Z_k(f)\right] = \sum_{k=0}^{N-1} v_k(t) \mathbf{E}\left[z_x(t)\right] e^{-i2\pi ft}$$

$$\mathbf{E}\Big[Z_k(f)\Big] = \mathbf{0}$$

The stochastic part $Z_{k}(f)$ has a mean of zero.

$$\operatorname{E}\Big[Z_k(f)\Big] = 0$$

 $X_k(f)$'s mean is the eigencoefficient of the response signal, at frequency f

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 $X_k(f)$'s mean is the eigencoefficient of the response signal, at frequency f $E[X_k(f)] = \Xi_k(f)$

$$\operatorname{Var}\left[X_k(f)\right] = \sum_{\substack{s=0\\t=0}}^{N-1} \left($$

$$\operatorname{Var}\left[X_k(f)\right] = \sum_{\substack{s=0\\t=0}}^{N-1} \left(v_k(s)v_k(t)\right)$$

$$\operatorname{Var}\left[X_k(f)\right] = \sum_{\substack{s=0\\t=0}}^{N-1} \left(\frac{v_k(s)v_k(t)}{\gamma_x(s-t)}\right)$$

$$\operatorname{Var}\left[X_k(f)\right] = \sum_{\substack{s=0\\t=0}}^{N-1} \left(\frac{v_k(s)v_k(t)}{\gamma_x(s-t)} \cos\left(2\pi f(s-t)\right)\right).$$

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The variance of $X_k(f)$ is real valued

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$$\operatorname{Var}\left[X_{k}(f)\right] = \sum_{\substack{s=0\\t=0}}^{N-1} \left(\begin{array}{c} v_{k}(s)v_{k}(t) & \gamma_{x}(s-t) & \cos\left(2\pi f(s-t)\right) \\ & \downarrow & \downarrow \\ & & \downarrow \\ & & \downarrow \\ & & v_{k}^{2}(t) & \sigma_{x}^{2} & \cos(0) = 1 \end{array} \right)$$

The variance of $X_k(f)$ is real valued

$$\operatorname{Var}\left[X_k(f)\right] = \sigma_x^2$$

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There is some covariance across Fourier Frequencies

$$\operatorname{Cov}\left[X_k(f), X_k^*(f+\delta)\right] = \sigma_x^2 \sum_{t=0}^{N-1} e^{i2\pi\delta t} v_k(t)^2$$

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There is some covariance across Fourier Frequencies

$$\operatorname{Cov}\left[X_k(f), X_k^*(f+\delta)\right] \neq 0$$

Multitaper Transfer Function Estimates

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$$\hat{H}(f) = \frac{\sum_{j=0}^{K-1} X_j^*(f) Y_j(f)}{\sum_{k=0}^{K-1} |X_k(f)|^2}$$

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Fixed predictor time series

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Fixed predictor time series

Gaussian response time series

$$\hat{H}(f) = \frac{\sum_{j=0}^{K-1} X_j^*(f) Y_j(f)}{\sum_{k=0}^{K-1} |X_k(f)|^2}$$



Multitaper Transfer Function Estimates: Mean

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Multitaper Transfer Function Estimates: Mean

$$E[\hat{H}(f)] = \frac{\sum_{i=0}^{K-1} X_i^*(f) E[Y_i(f)]}{\sum_{j=0}^{K-1} |X_j(f)|^2}$$

Multitaper Transfer Function Estimates: Mean

$$E[\hat{H}(f)] = \frac{\sum_{i=0}^{K-1} X_i^*(f) E[Y_i(f)]}{\sum_{j=0}^{K-1} |X_j(f)|^2}$$

The mean is proportional to the eigencoefficient of the pure response signal

Multitaper Transfer Function Estimates: Variance

$$\hat{H}(f) = \frac{\sum_{j=0}^{K-1} X_j^*(f) Y_j(f)}{\sum_{k=0}^{K-1} |X_k(f)|^2}$$

Multitaper Transfer Function Estimates: Variance

$$\operatorname{Var}\left[\hat{H}(f)\right] = \frac{\sigma_y^2}{\sum_{j=0}^{K-1} |X_j(f)|^2}$$

Multitaper Transfer Function Estimates: Variance

$$\operatorname{Var}\left[\hat{H}(f)\right] = \frac{\sigma_y^2}{\sum_{j=0}^{K-1} |X_j(f)|^2}$$

The variance is inversely proportional to the spectrum of the predictor
Summary





Mean is proportional to the eigencoefficient of the pure response signal



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Real and Imaginary parts are uncorrelated.

The MTFE is not frequency stationary.

MTFEs: Moduli

The Rice distribution describes moduli of circularly symmetric CGRVs.

The Modulus of H(f) is Rice distributed with the following parameters

(EQ: 3.51b)

Part 2:

MTFEs at Signal Frequencies Large variance, zero mean
 Indicates no signal is present.



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- 2. Small variance, zero mean Indicates signal in x(t)



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- Large variance, zero mean Indicates no signal is present.
- 2. Small variance, zero mean Indicates signal in x(t)
- Large variance, non-zero mean Indicates signal in y(t)
- 4. Small variance, nonzero mean Indicates a *common* signal







*T*₁:



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This test is more robust to frequency modulation than the Harmonic F-test.

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 $ilde{H}$ is H, transformed to have uncorrelated entries

Test Statistics: Comparison to MSC

$$MSC_{x,y}^{(m)}(f) = \frac{|\hat{S}_{xy}^{(m)}(f)|^2}{\hat{S}_{xx}^{(m)}(f)\hat{S}_{yy}^{(m)}(f)}.$$

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$$|H(f)|^{2} = \frac{|\hat{S}_{xy}^{(m)}(f)|^{2}}{\left(\hat{S}_{xx}^{(m)}(f)\right)^{2}}.$$

Test Statistics: "Coherent" Noise

$$Y(f_x^*) = \sqrt{\lambda} X(f_x^*) + \sqrt{1-\lambda} Z_y^*(f_x^*)$$

Test Statistics: Comparison to MSC

$$Y(f_x^*) = \sqrt{\lambda} X(f_x^*) + \sqrt{1-\lambda} Z_y^*(f_x^*)$$



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$$y(t) = \cos(2\pi f t) + z_y(t)$$

$$g(t) = f + \cos\left(2\pi A N^{-1}t\right).$$

MTFE: Behaviour under Frequency Modulation



F-Test: Behaviour under Frequency Modulation



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This test is more robust to frequency modulation than the Harmonic F-test.
Test Statistics for Signal Detection

 T_1 : $|E[H(f)]|^2$ detects signals in the response

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Working with Frequency Non-Stationarity



Part 3: Phase

Phase Distribution: Complex Gaussian Random Variables

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$$g(\phi|\mu_x, \mu_y, \sigma_x^2, \sigma_y^2) = \frac{\sigma_x \sigma_y \exp\left\{-\left(\frac{\mu_x^2 \sigma_y^2 + \mu_y^2 \sigma_x^2}{2\sigma_x^2 \sigma_y^2}\right)\right\} \left(1 + \sqrt{\pi} A(\phi) \exp\left\{A(\phi)^2\right\} \operatorname{erfc}\left\{-A(\phi)\right\}\right)}{2\pi \left(\sigma_y^2 \cos^2(\phi) + \sigma_x^2 \sin^2(\phi)\right)}$$

where
$$A(\phi) = \frac{\mu_x \sigma_y^2 \cos(\phi) + \mu_y \sigma_x^2 \sin(\phi)}{\sigma_x \sigma_y \sqrt{\sigma_y^2 \cos^2(\phi) + \sigma_x^2 \sin^2(\phi)}}$$

Phase Distribution: Complex Gaussian Random Variables

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NOTE: The above distribution assumes x and y are uncorrelated.

Phase Distribution: Multitaper Transfer Function Estimates

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$$g_f\left(\phi \mid \mu_x = \operatorname{Re}\left\{E\left[\hat{H}(f)\right]\right\}, \ \mu_y = \operatorname{Im}\left\{E\left[\hat{H}(f)\right]\right\}, \ \sigma_x^2 = \sigma_y^2 = \frac{\operatorname{Var}\left[\hat{H}(f)\right]}{2}\right\}$$

Phase Distribution: Multitaper Transfer Function Estimates

$$g_f\left(\phi \mid \mu_x = \operatorname{Re}\left\{E\left[\hat{H}(f)\right]\right\}, \ \mu_y = \operatorname{Im}\left\{E\left[\hat{H}(f)\right]\right\}, \ \sigma_x^2 = \sigma_y^2 = \frac{\operatorname{Var}\left[\hat{H}(f)\right]}{2}\right\}$$

g() FF = 625





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- 3. A test statistic based on variance structure is *restricted to a frequency band of interest*



4. If the signal amplitude is large in y(t) compared to x(t), it may be difficult to distinguish coherent signals from response-only signals.



Part 4: Conclusion & Future Work

Develop a test statistic (T_3) using MTFE phase

Develop a test statistic (T₃) using MTFE phase

★ Consider the amplitude ratio of signals in predictor vs. response

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- **\star** Compare performance of (T₃) to established methods (eg: MSC and Harmonic F tests)

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Generalize and Explore

★ Multiple signals?

Develop a test statistic (T₃) using MTFE phase

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- ★ Multiple signals?
- ★ Signal frequencies within a small bandwidth?

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- **★** Extend to other distributions of underlying noise in x(t) and y(t)

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- ★ Consider the amplitude ratio of signals in predictor vs. response
- ★ Compare performance of (T₃) to established methods (eg: MSC and Harmonic F tests)

- ★ Multiple signals?
- ★ Signal frequencies within a small bandwidth?
- **★** Extend to other distributions of underlying noise in x(t) and y(t)
- ★ What does the phase distribution imply in the *time* domain?

Thanks for Tuning In, Folks 🔊

References

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