

Tumbling and Spinning of Anisotropic Flat Particles

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UNH Postdoctoral Associate

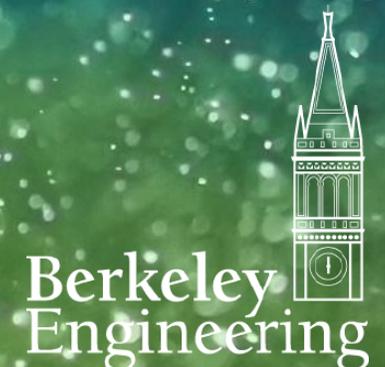
BIRS Microplastic Workshop
February 21, 2022

 @t_oehmke

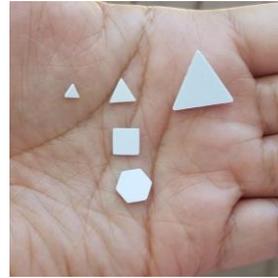
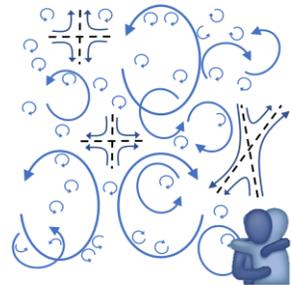


irphé

Institut de Recherche sur les
Phénomènes Hors Equilibre



Outline

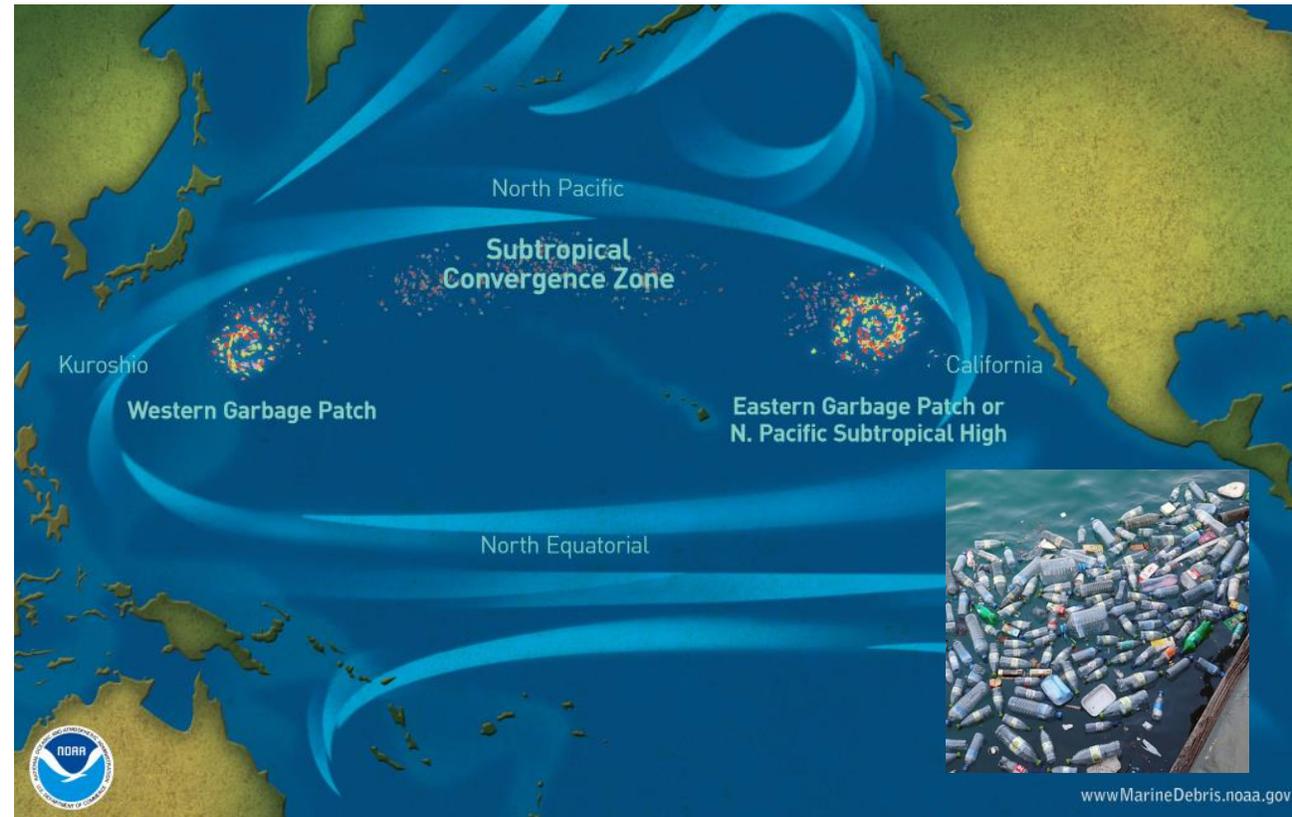


background
and
motivation

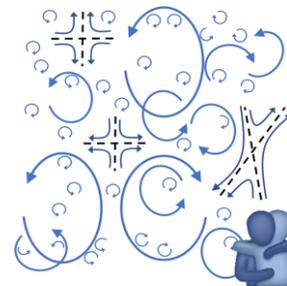
turbulence
and
movement

future
questions

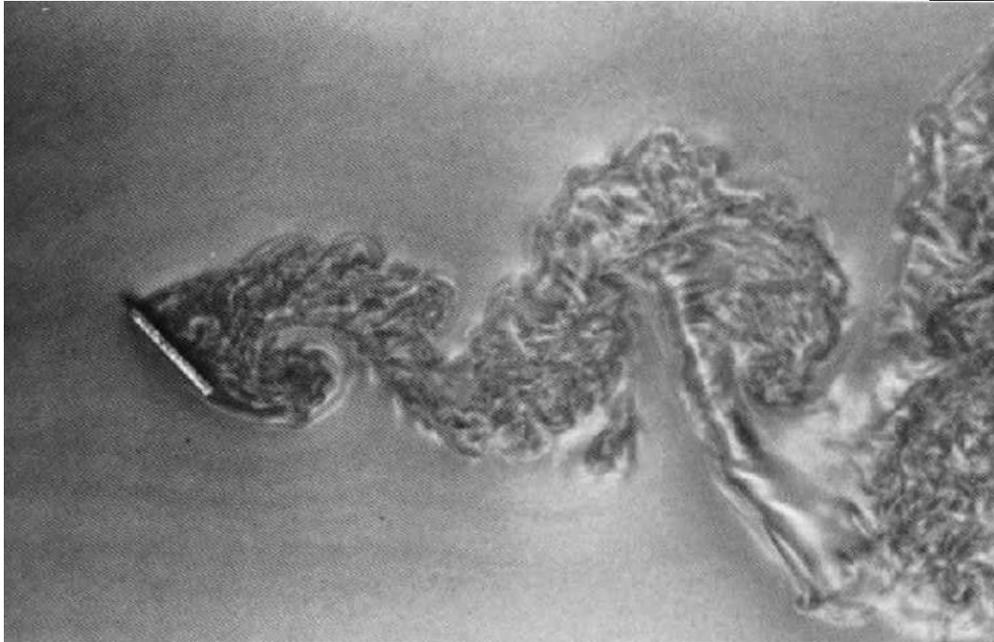
Particle transport in turbulence is an open question



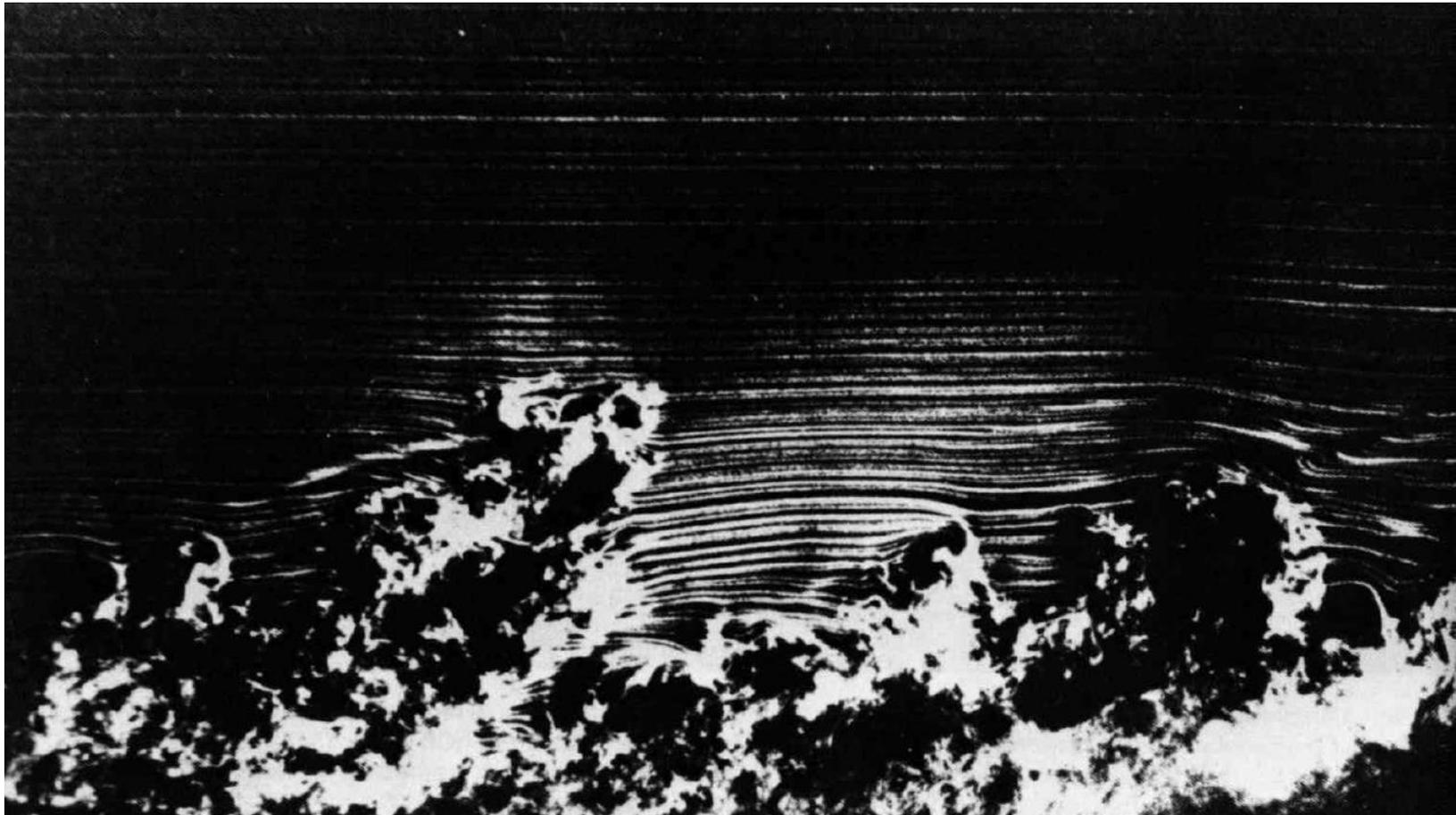
Background



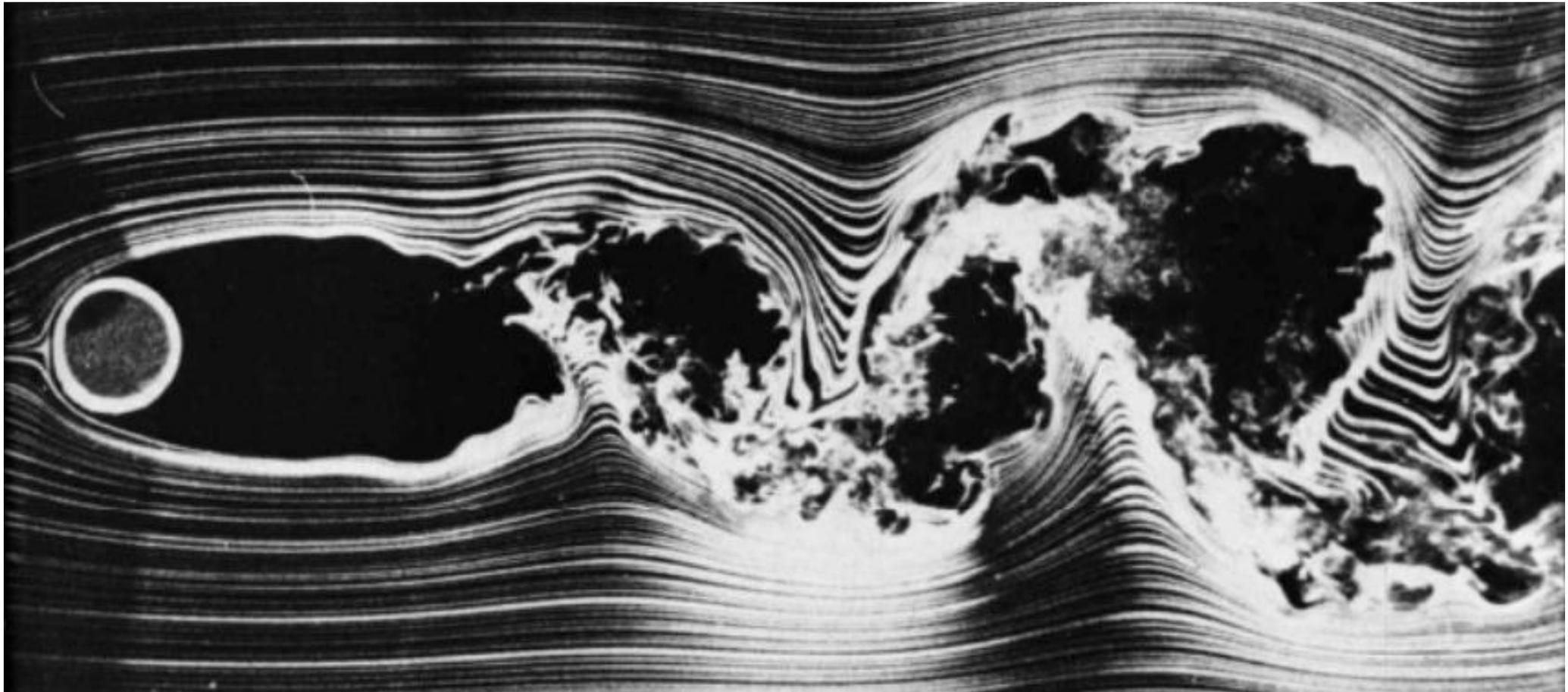
Turbulence is chaotic flow with universal properties



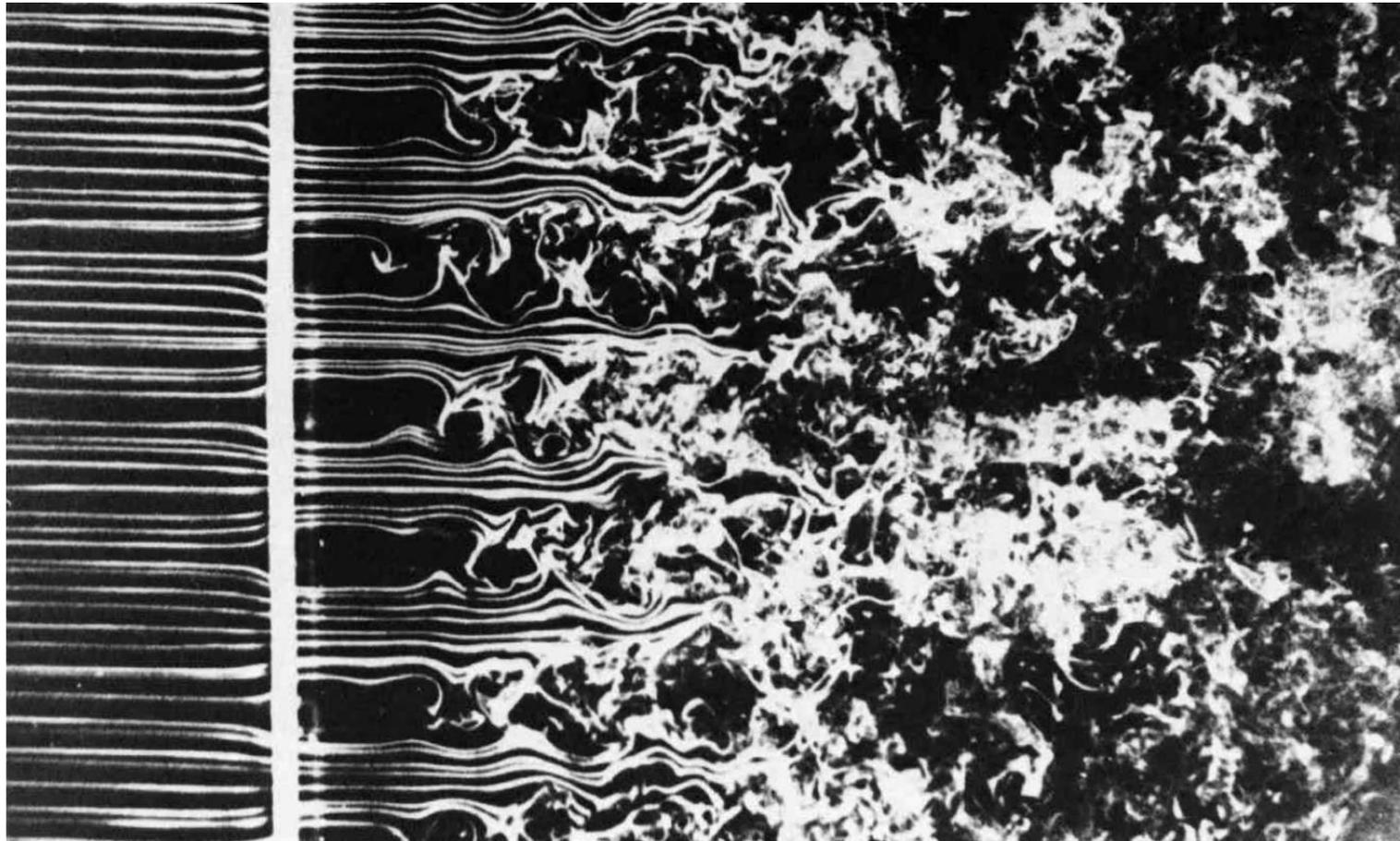
Turbulence is rarely homogeneous (translation invariant) or isotropic (rotation invariant)



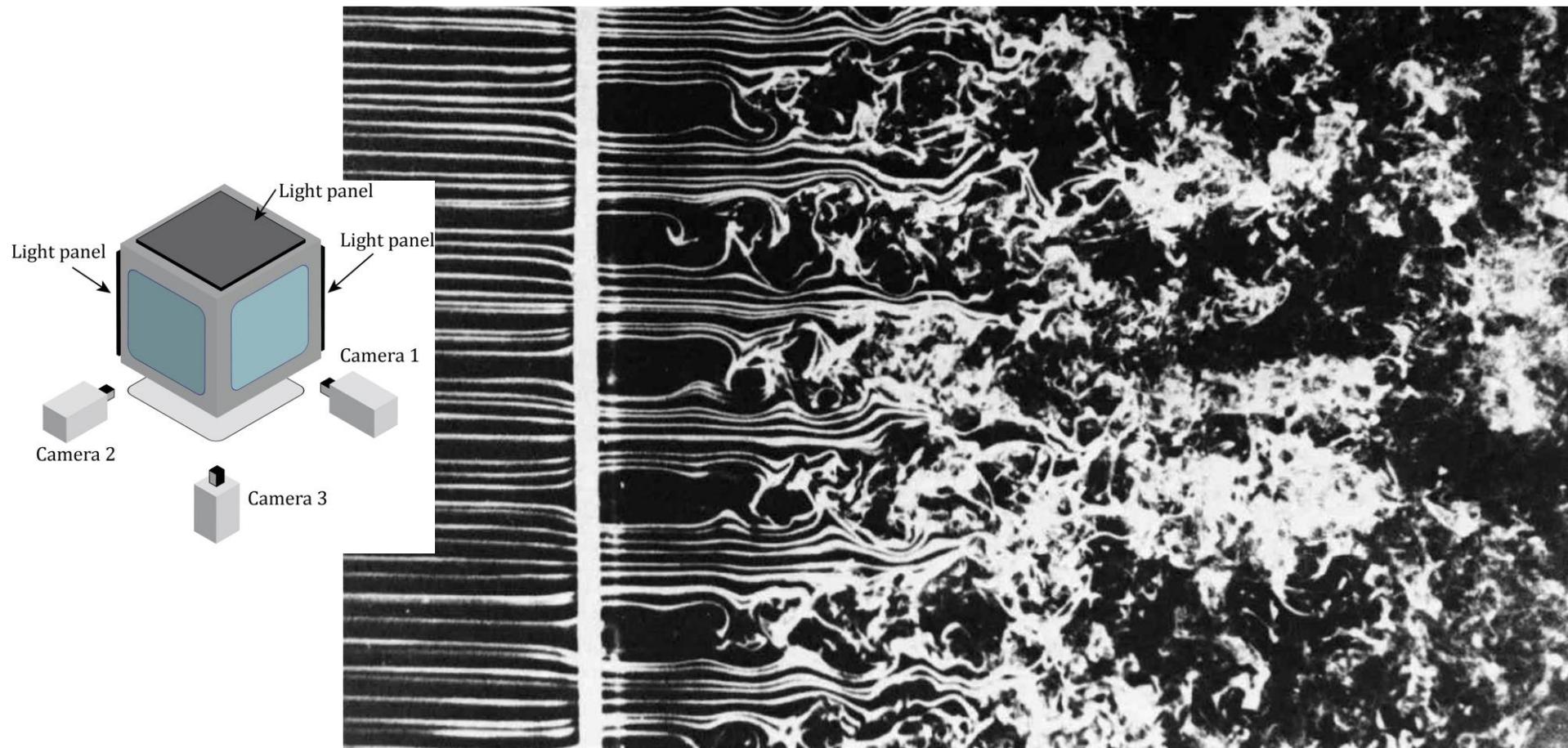
The multiscale chaos of turbulence is superimposed on the geometry of the original flow and instability



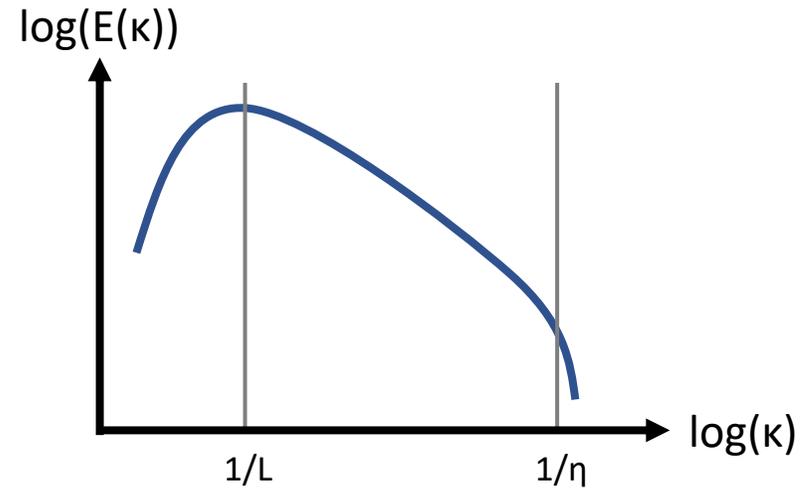
Special laboratory equipment can make homogeneous, isotropic turbulence



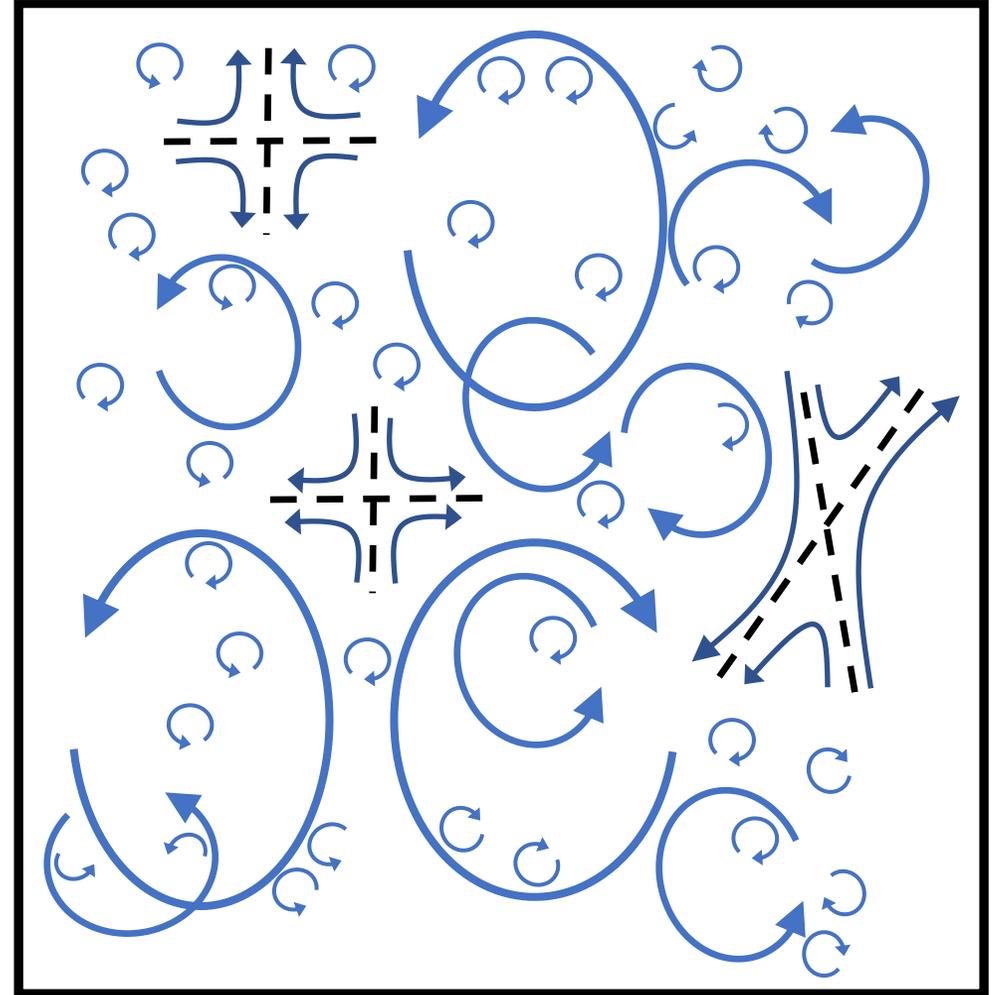
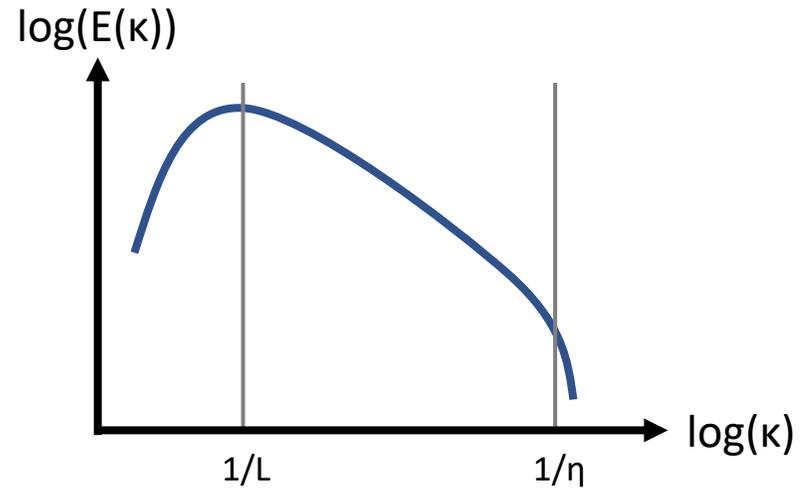
Special laboratory equipment can make homogeneous, isotropic turbulence



Turbulent Length Scales

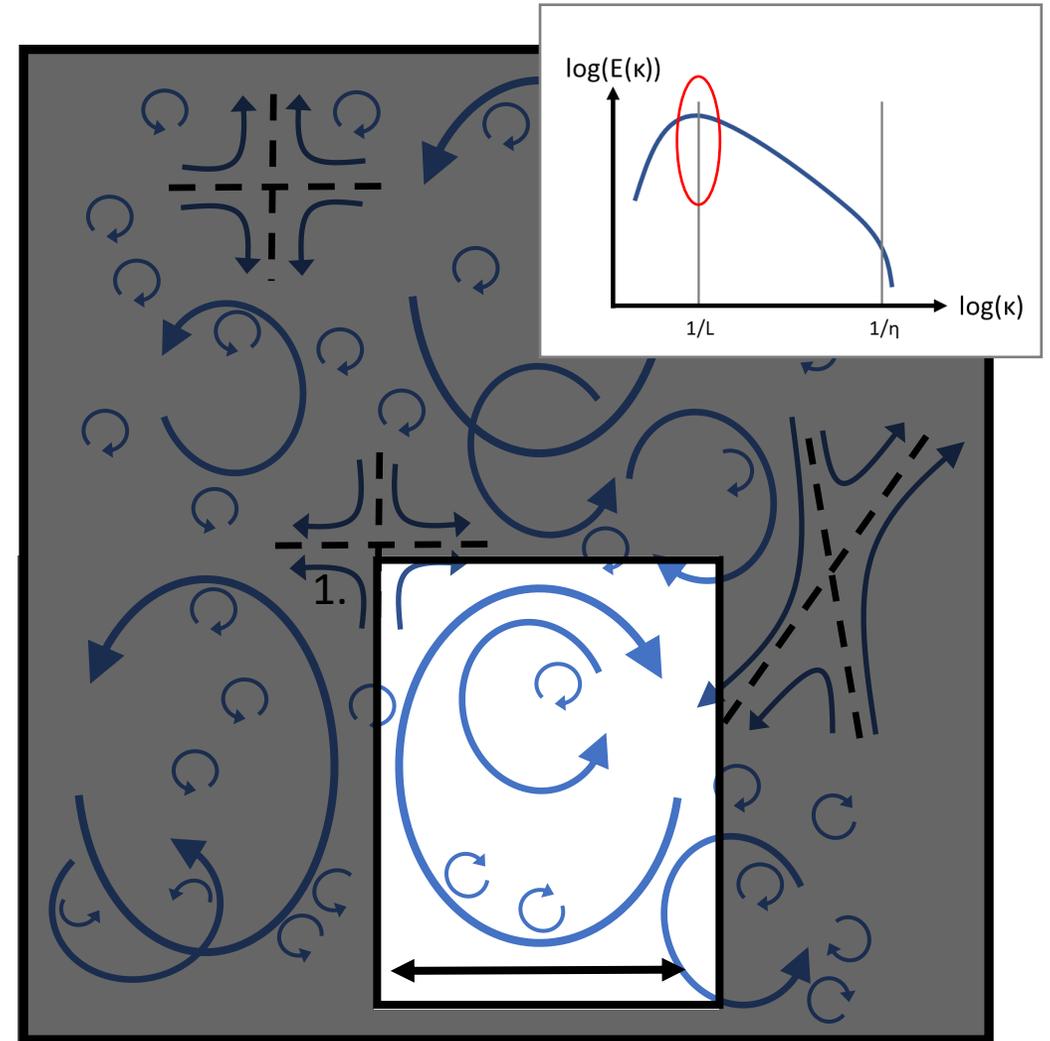


Turbulent Length Scales



Turbulent Length Scales

1. Integral scale
 - Largest eddy

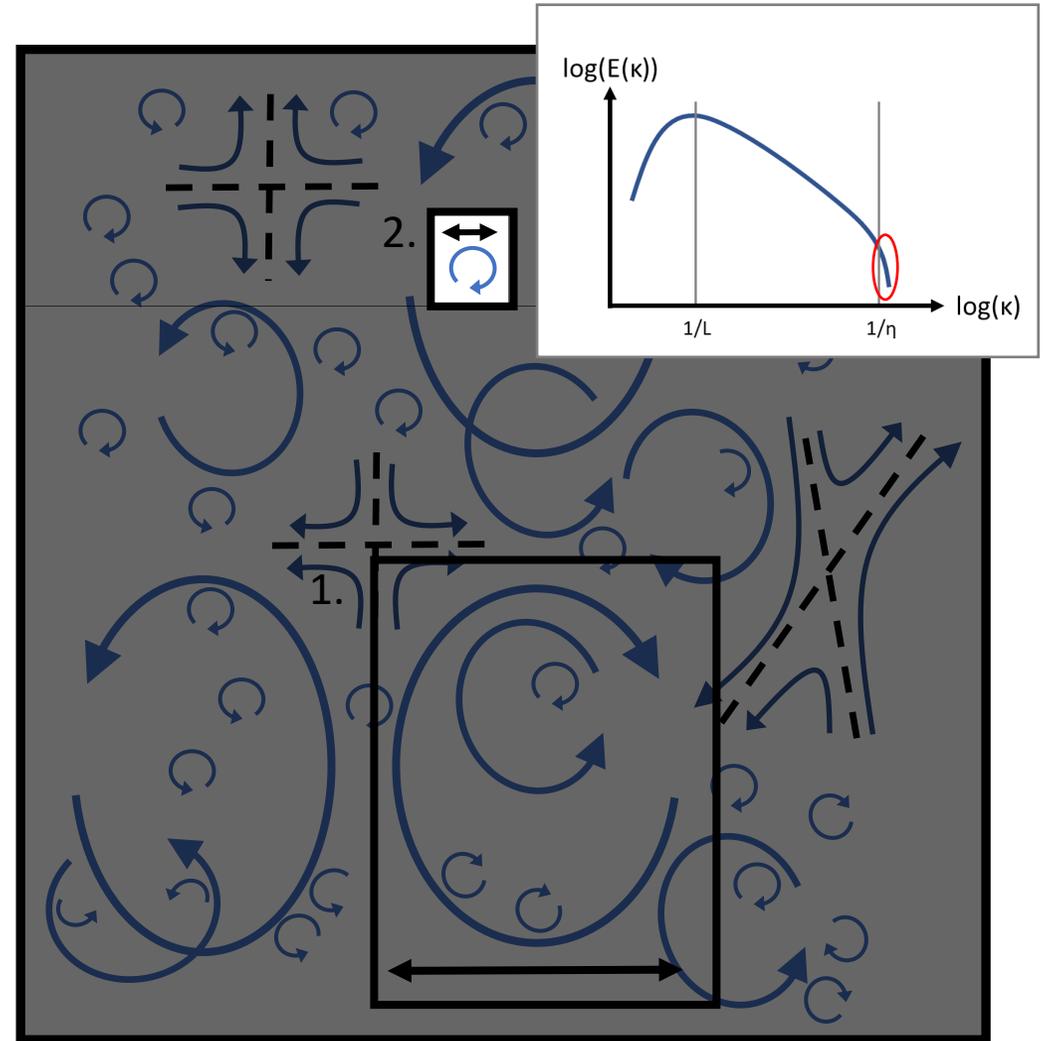


Turbulent Length Scales

1. Integral scale
 - Largest eddy



2. Small scale
 - Passive tracers



Turbulent Length Scales

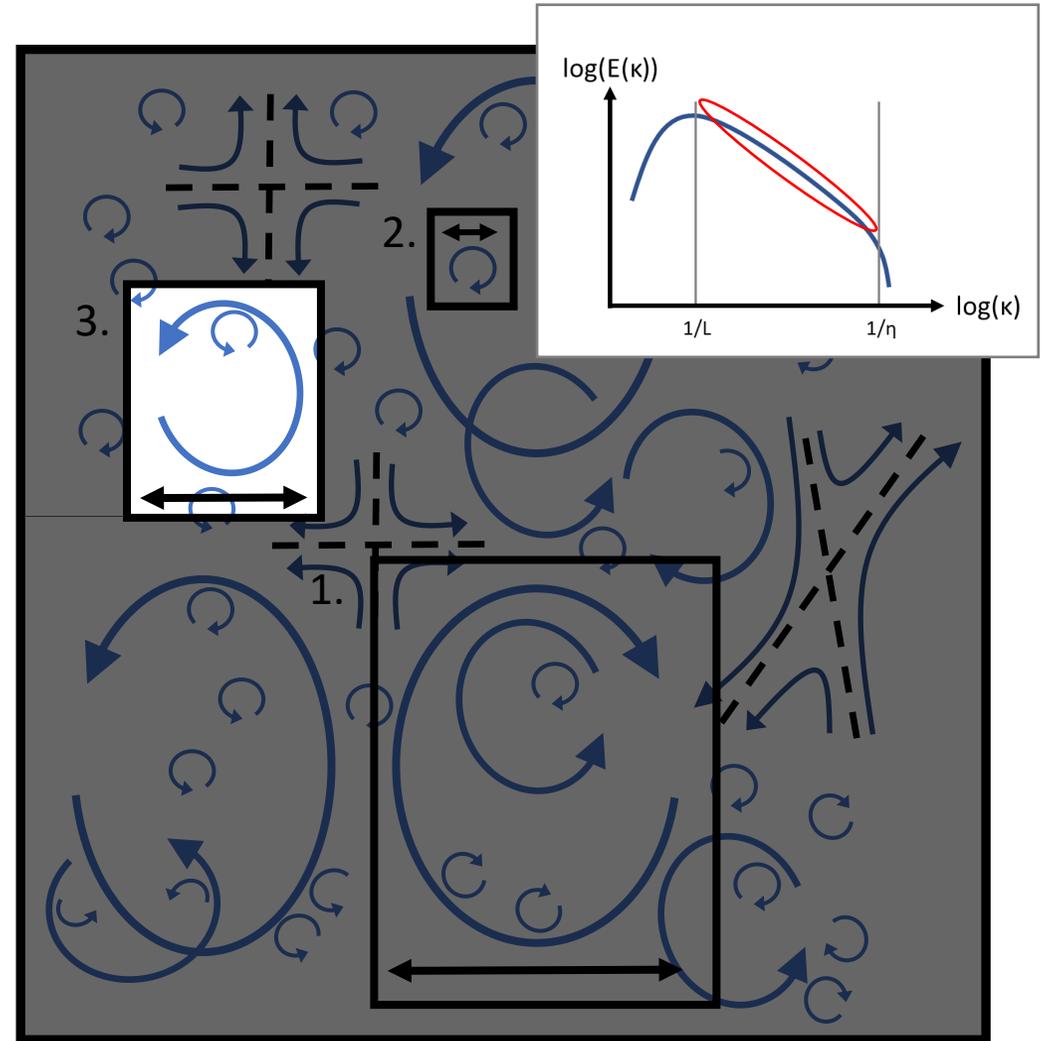
1. Integral scale
 - Largest eddy



2. Small scale
 - Passive tracers



3. Taylor microscale
 - Difficult to model particles numerically



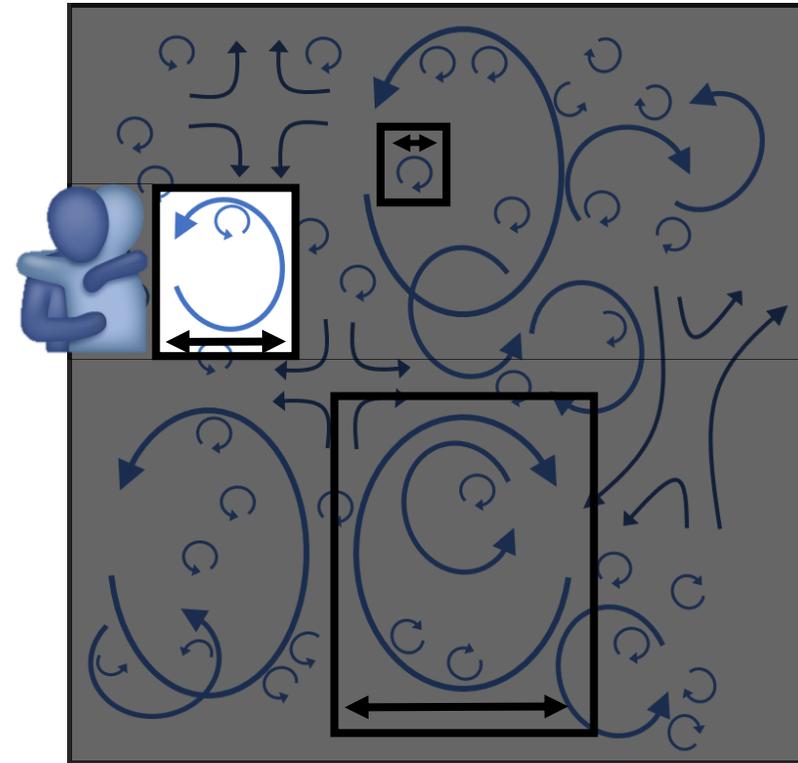
Turbulence makes these projects interesting and difficult

Turbulence



chaotic flow with universal properties

Scale



Particle Rotation



background
and
motivation

turbulence
and
movement

future
questions

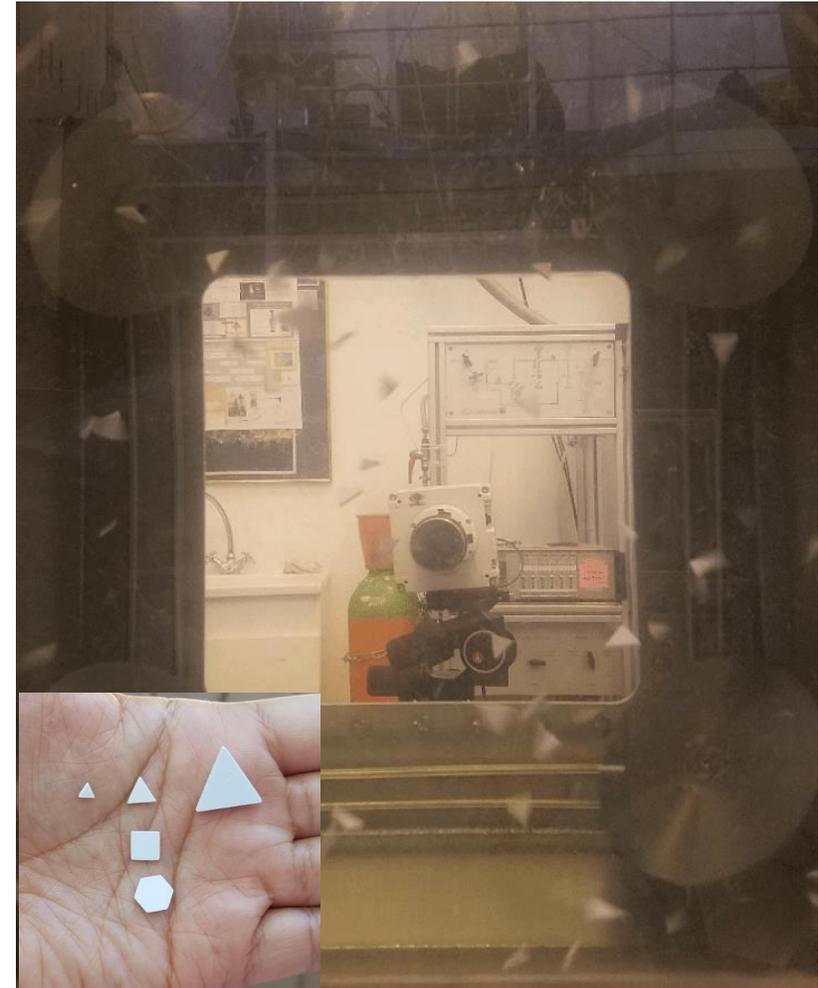
Neutrally buoyant flat particles in five different shapes and sizes were tested in the flow

	Shape	Small d=5mm	Medium d=10mm	Large d=20mm
	Triangle	✓	✓	✓
	Square		✓	
	Hexagon		✓	

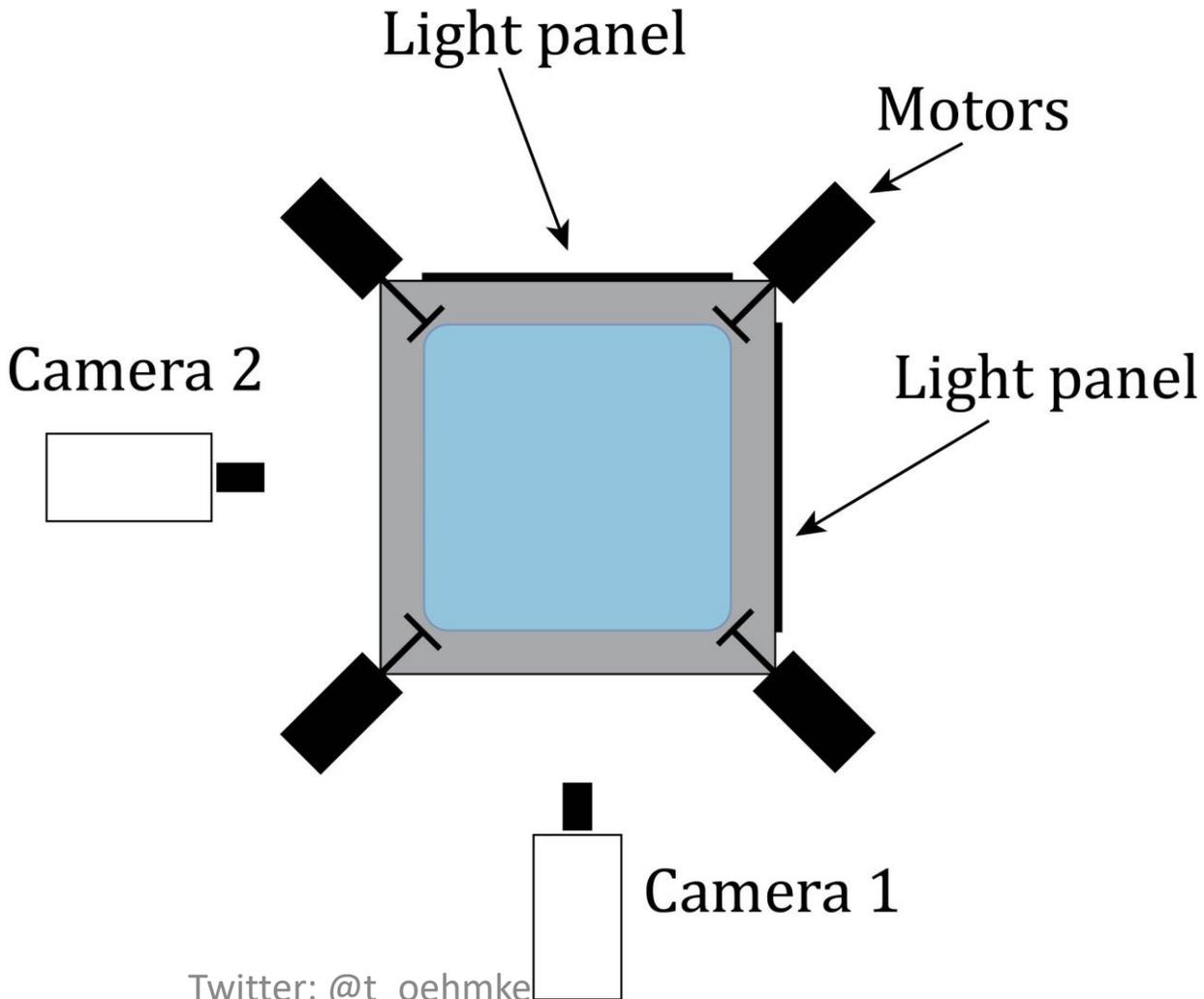


Neutrally buoyant flat particles in five different shapes and sizes were tested in the flow

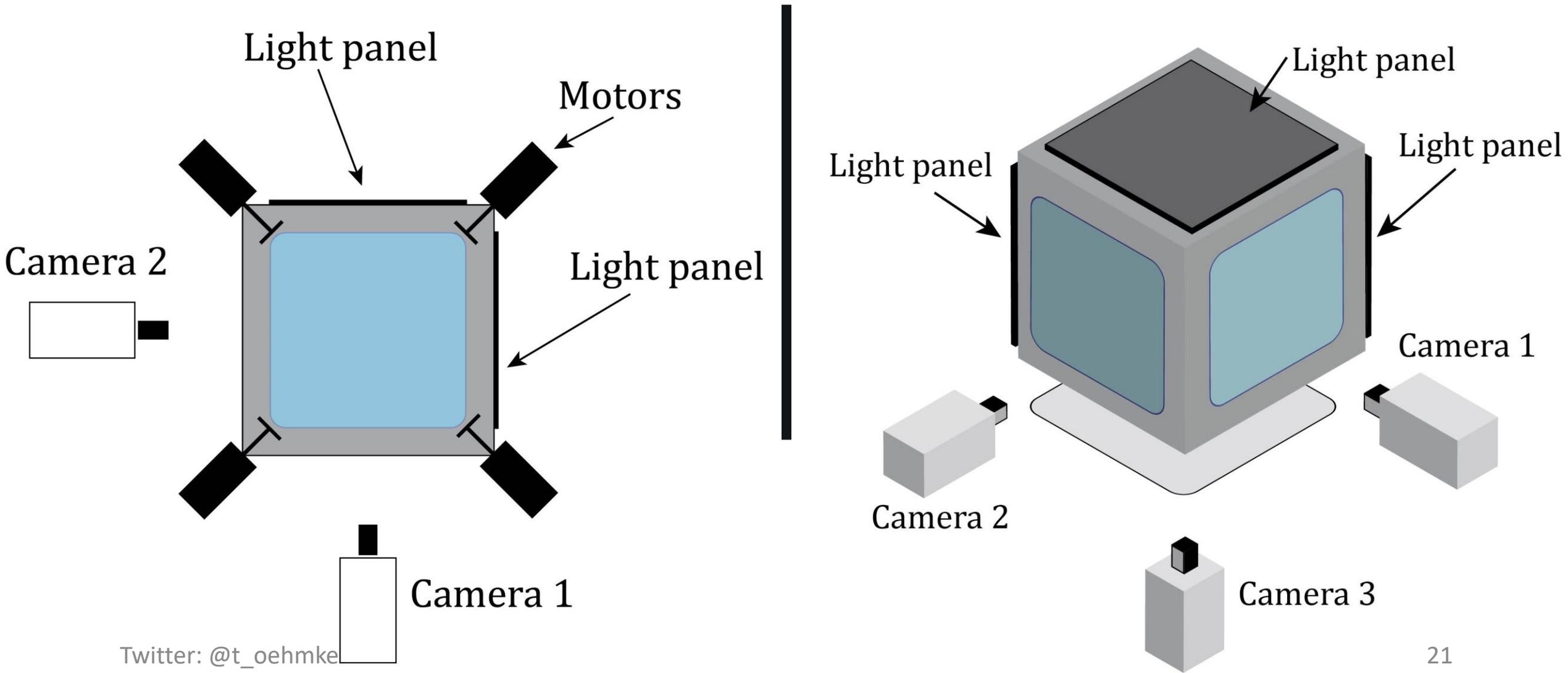
	Shape	Small d=5mm	Medium d=10mm	Large d=20mm
	Triangle	✓	✓	✓
	Square		✓	
	Hexagon		✓	



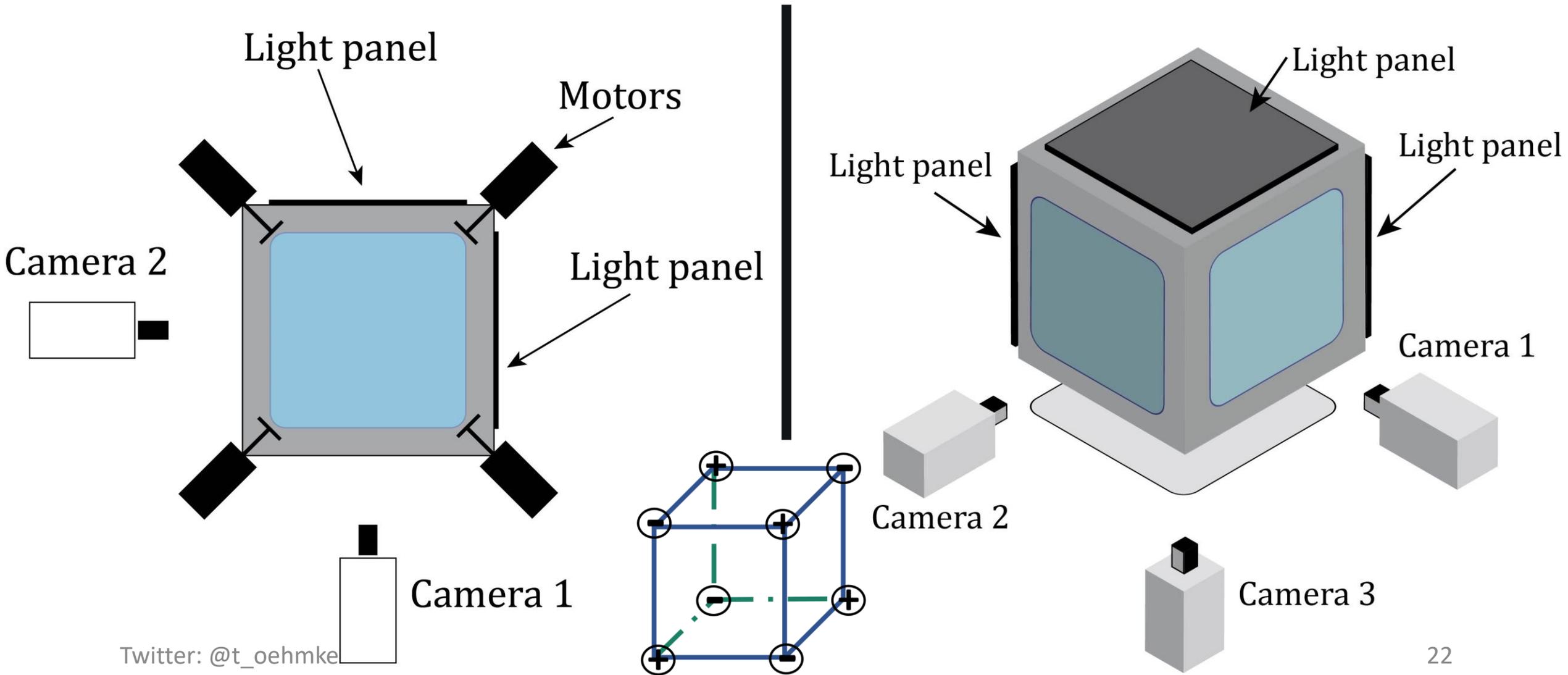
3 cameras were used to capture orthogonal images while motors were rotated in alternating directions

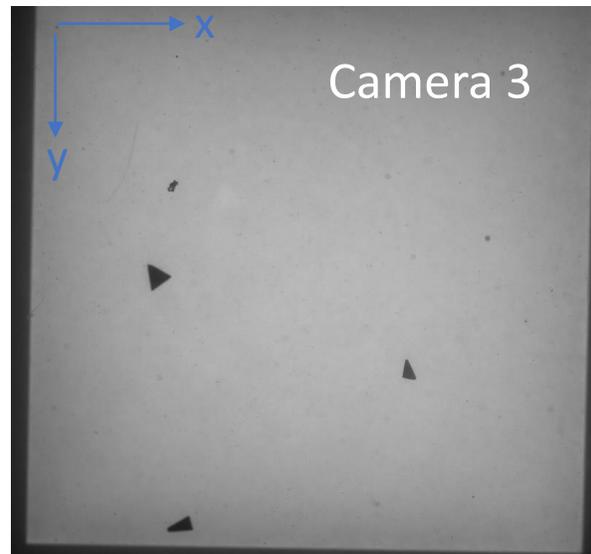
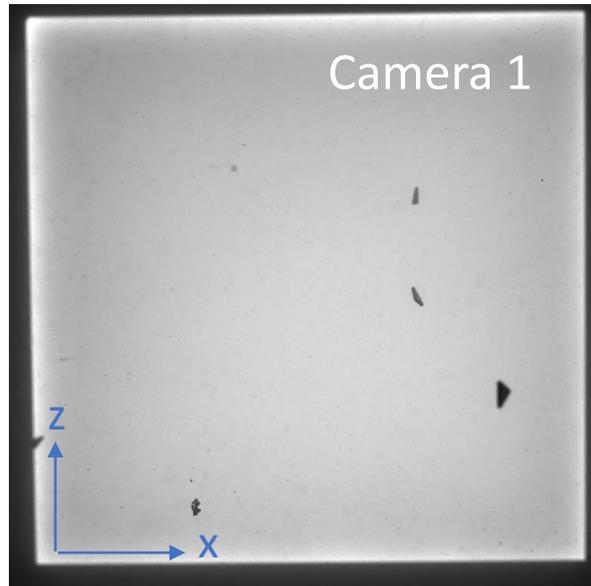
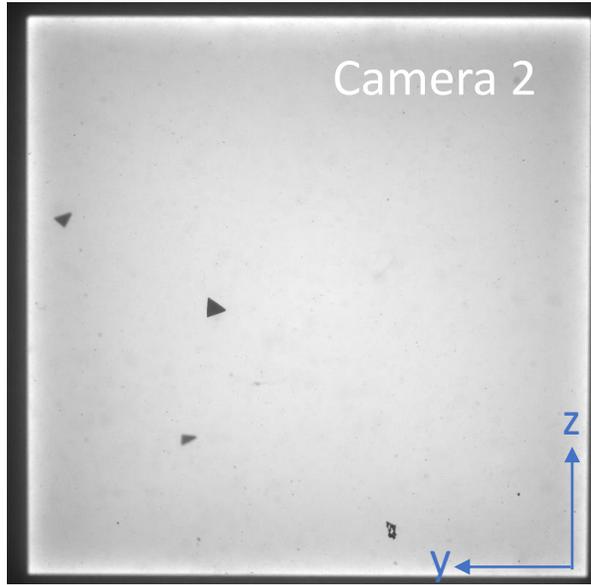


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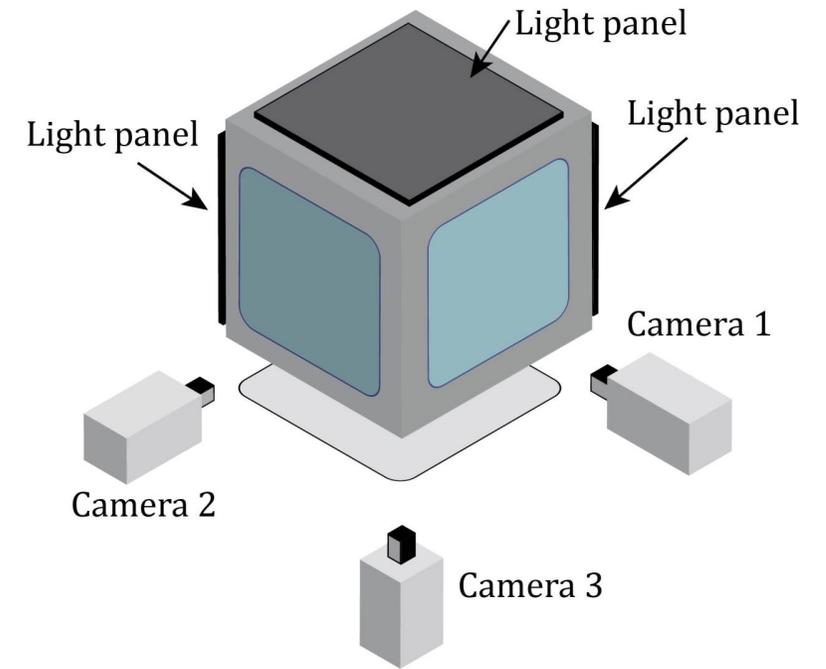


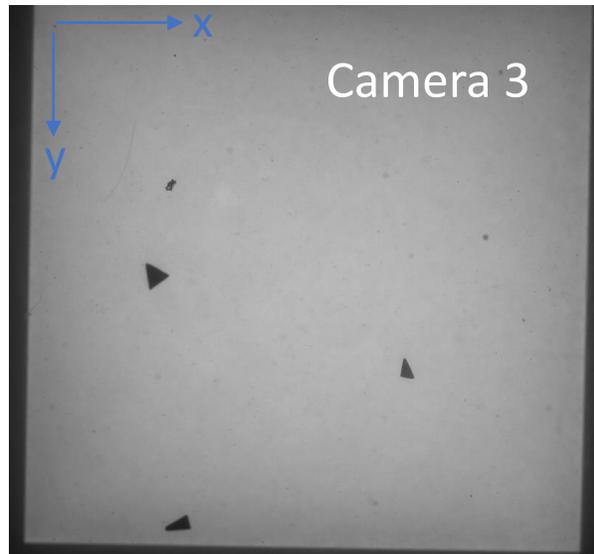
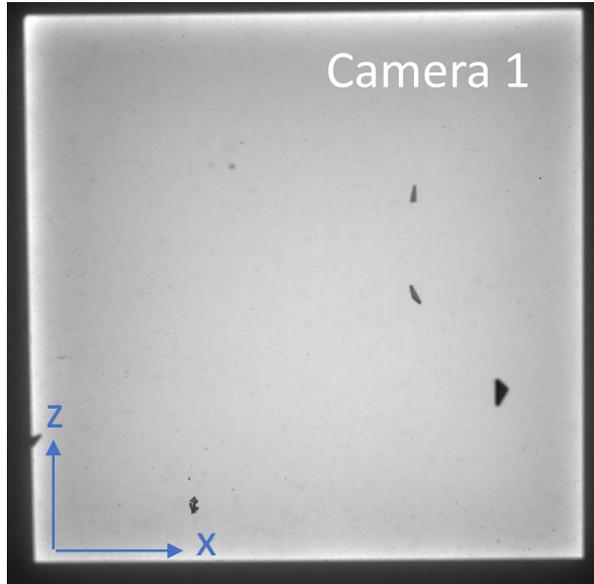
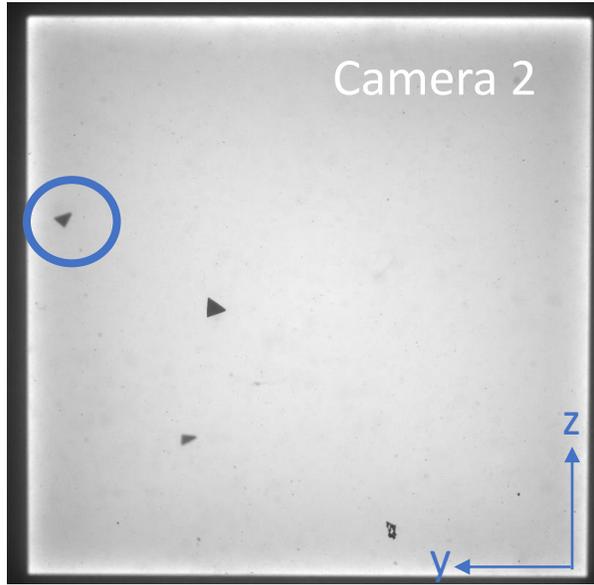
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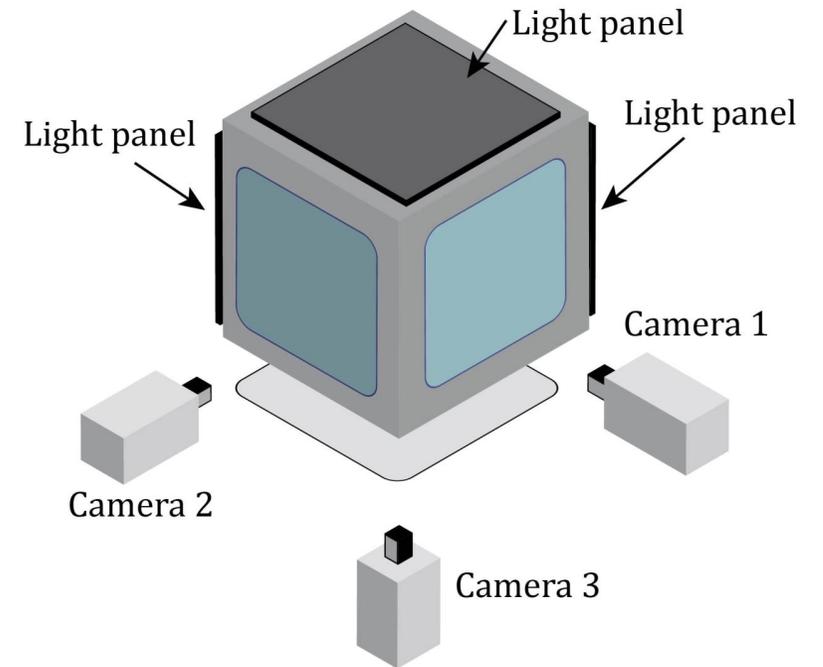


particles are identified in the images and linked to trajectories

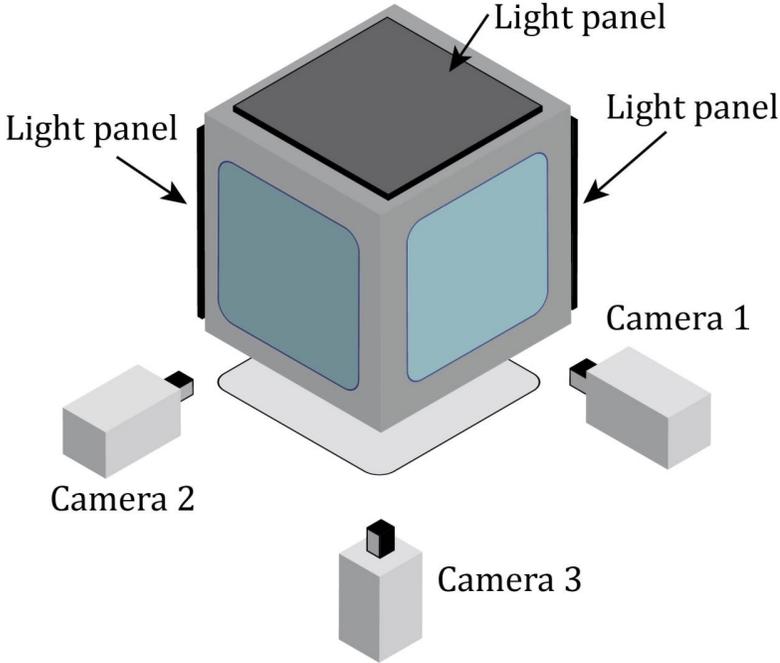
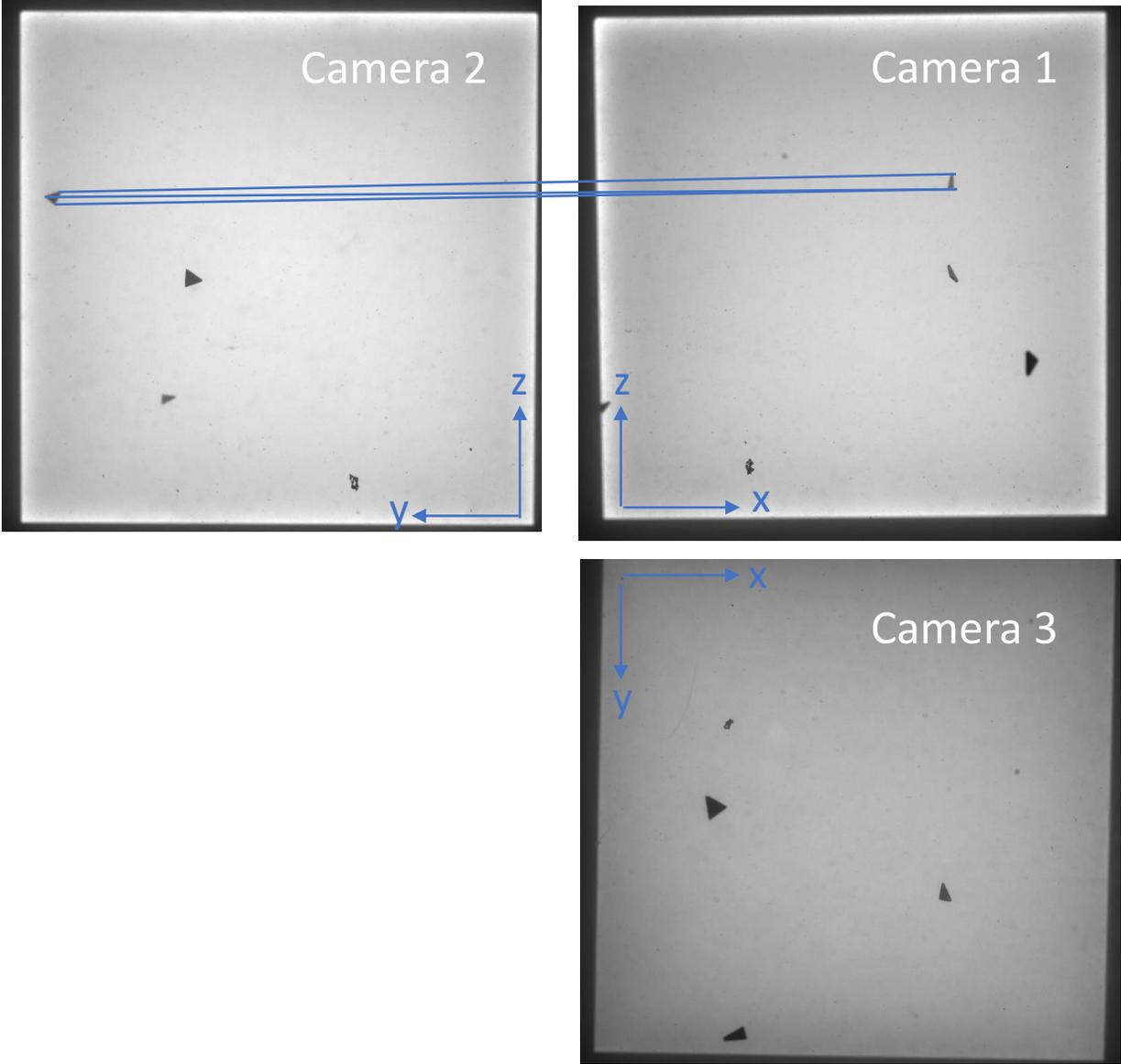




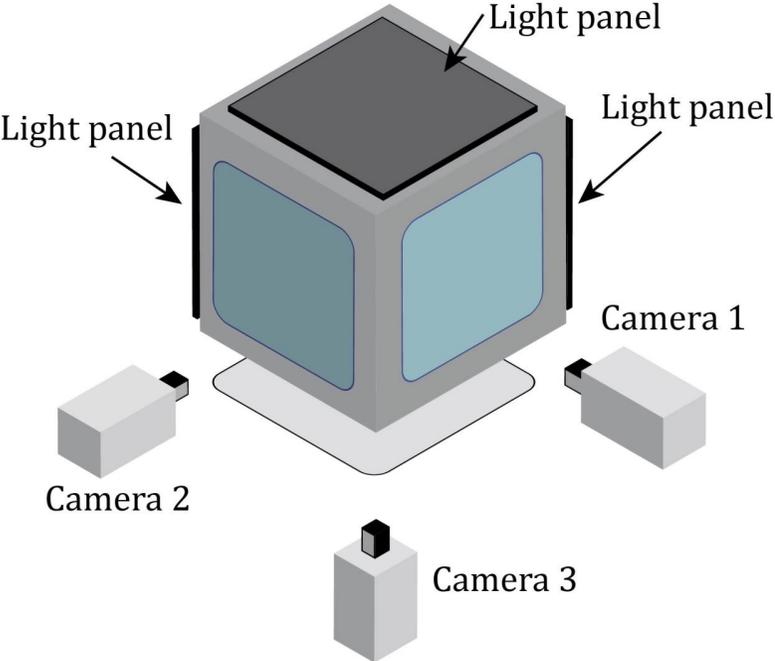
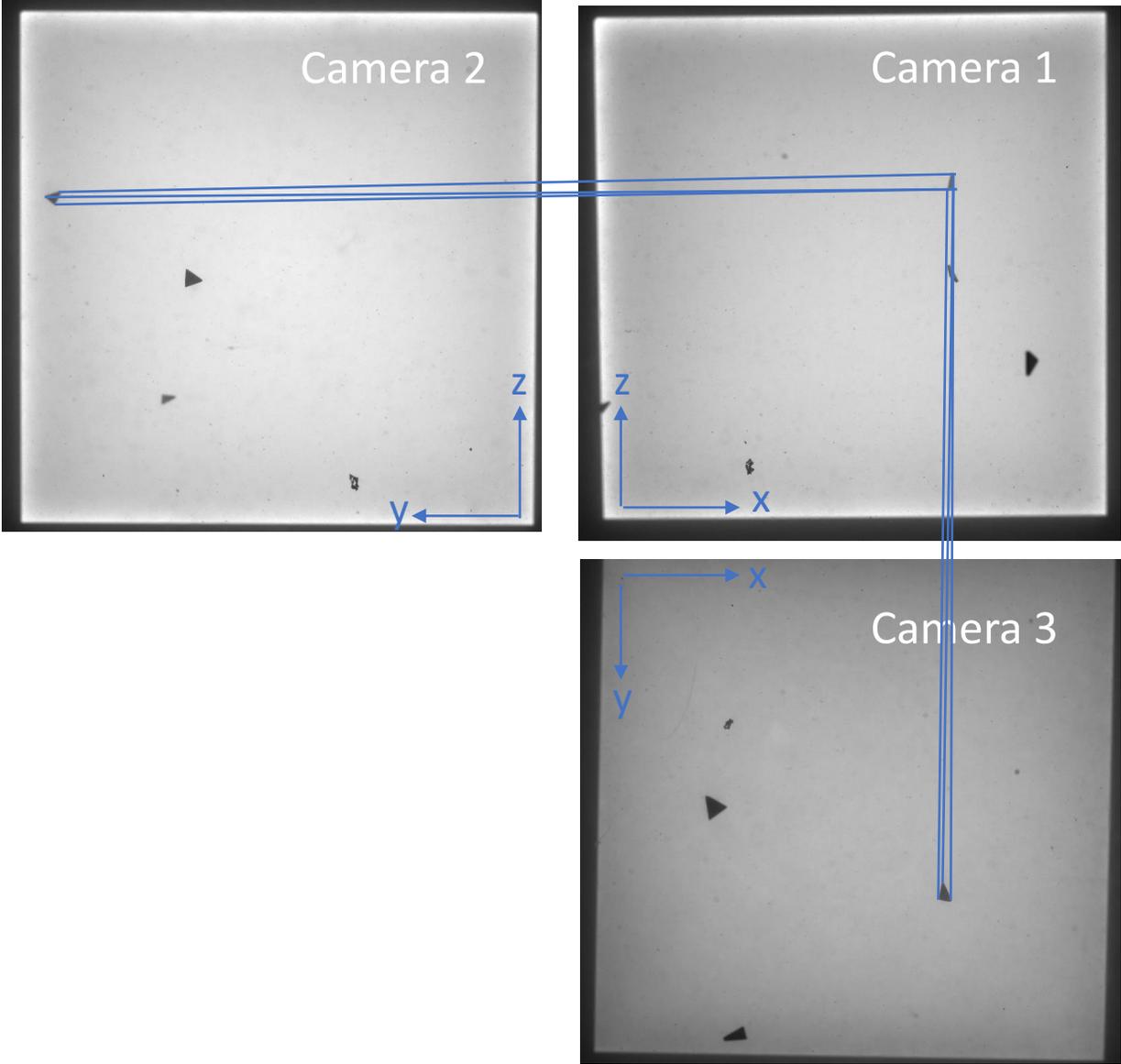
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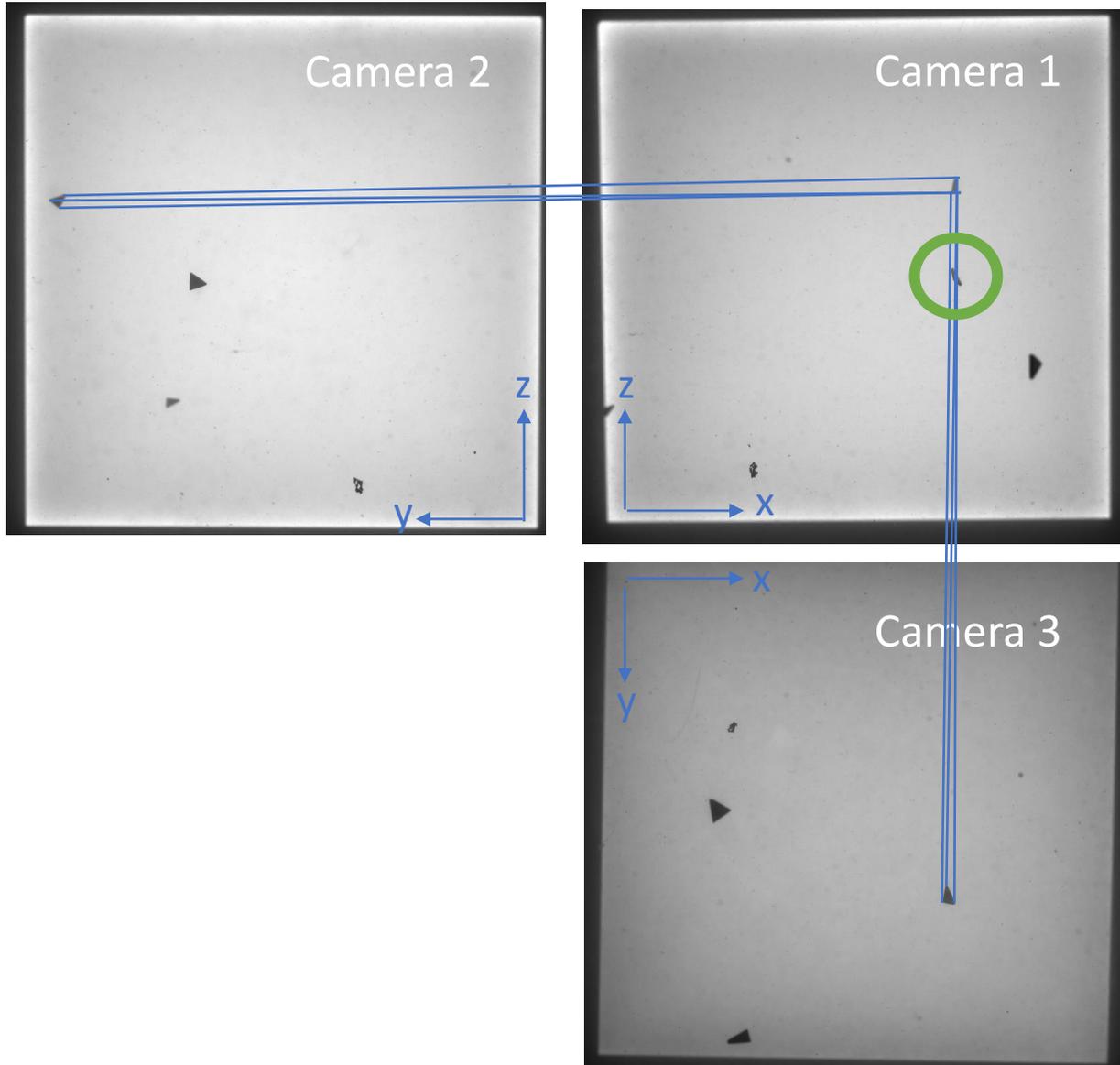


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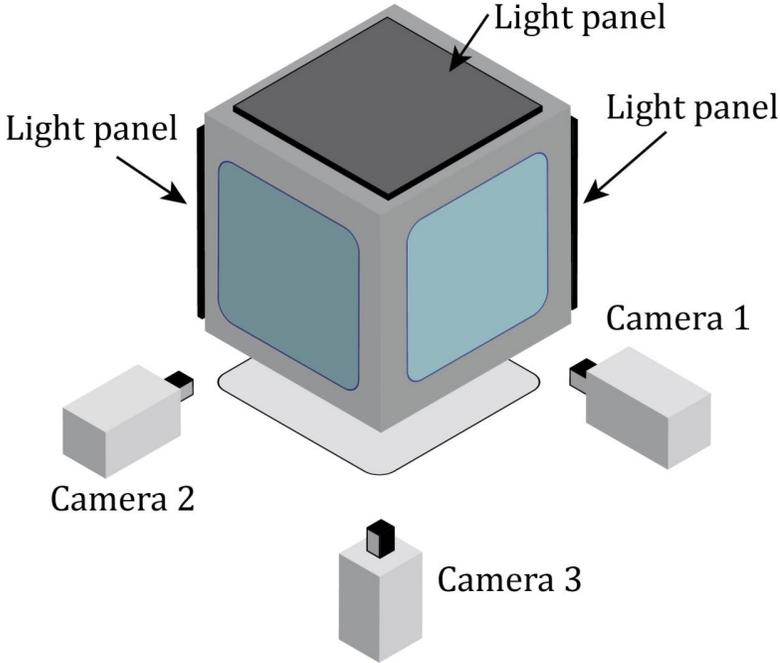


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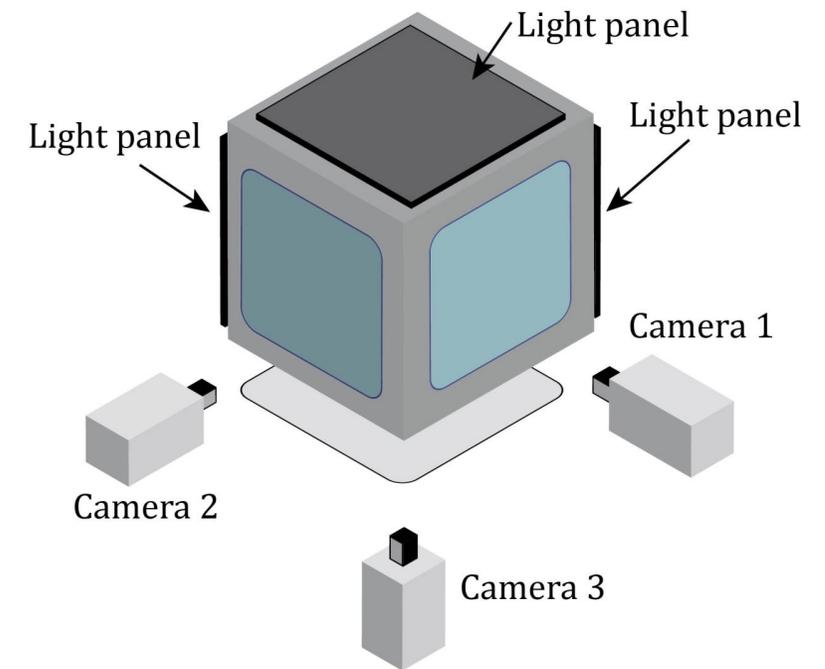
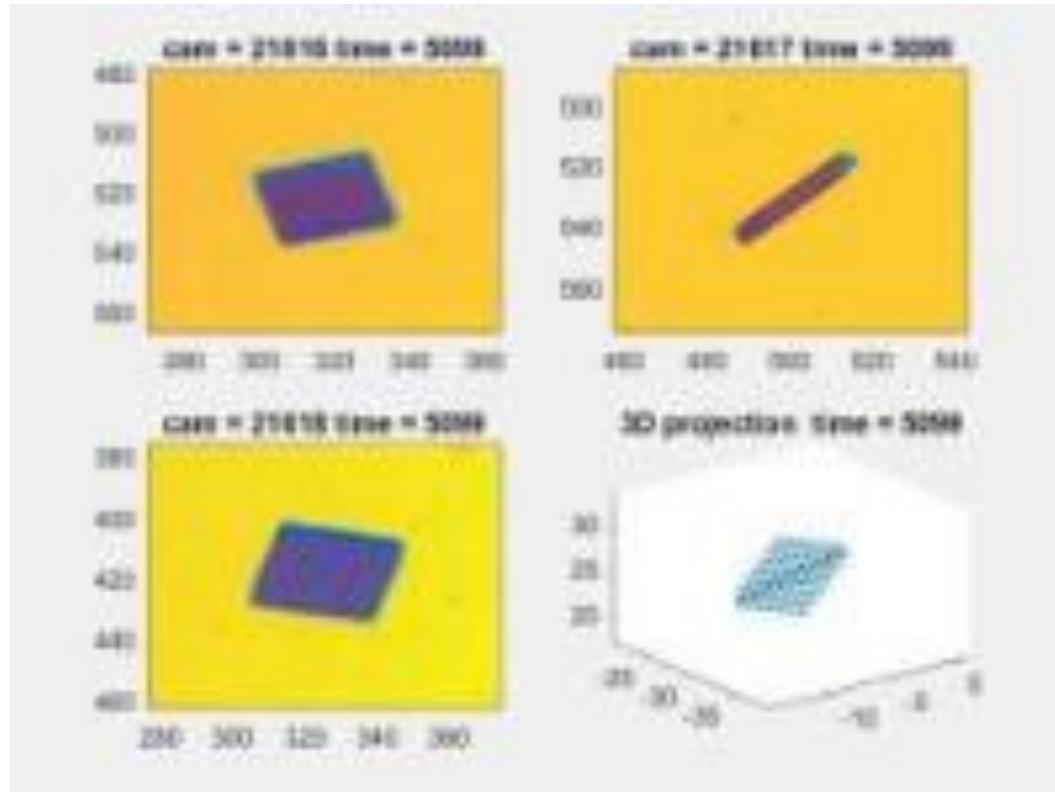




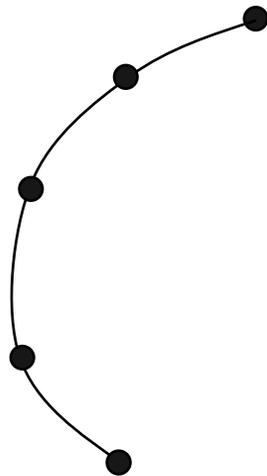
particles are identified in the images and linked to trajectories



After 3D reconstruction, we can project the particles back onto a 2D plane to test our results



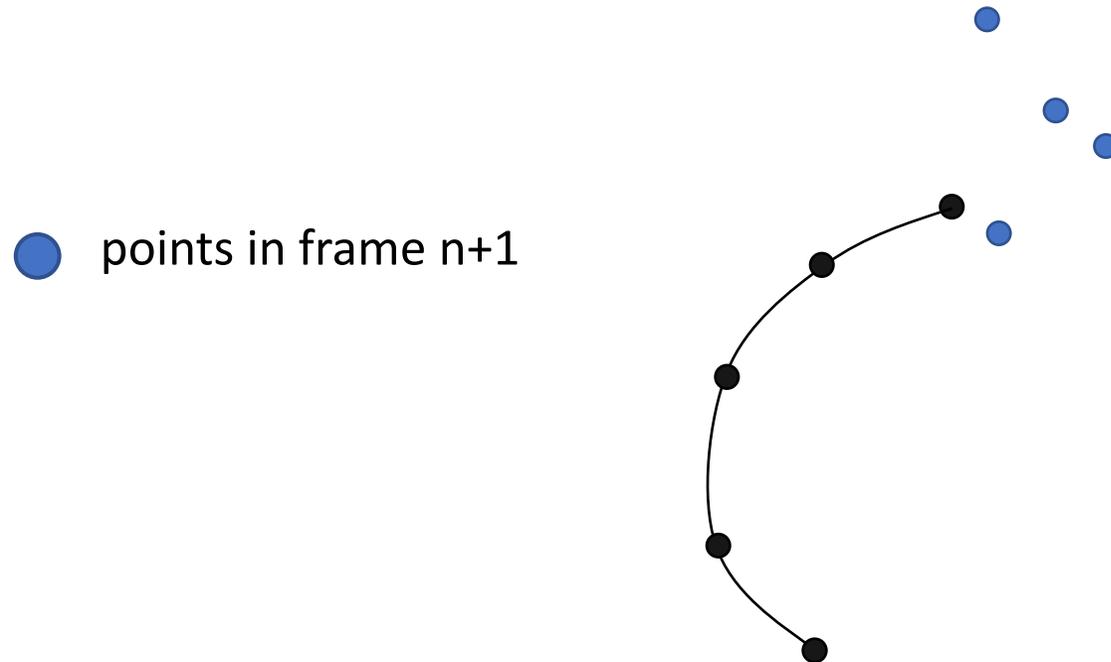
Individual particles were linked together in trajectories using the nearest neighbor method



Nearest neighbor figure adapted from A quantitative study of three-dimensional Lagrangian particle tracking algorithms by Ouellette, Xu, and Bodenschatz (2006)

Twitter: @t_oehmke

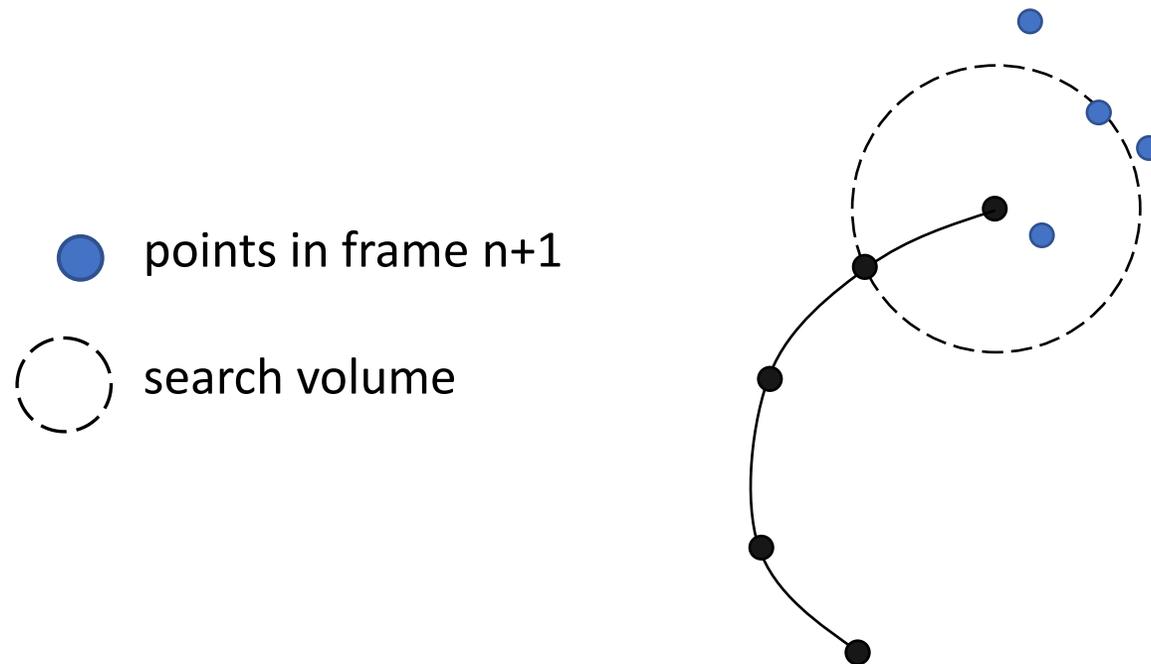
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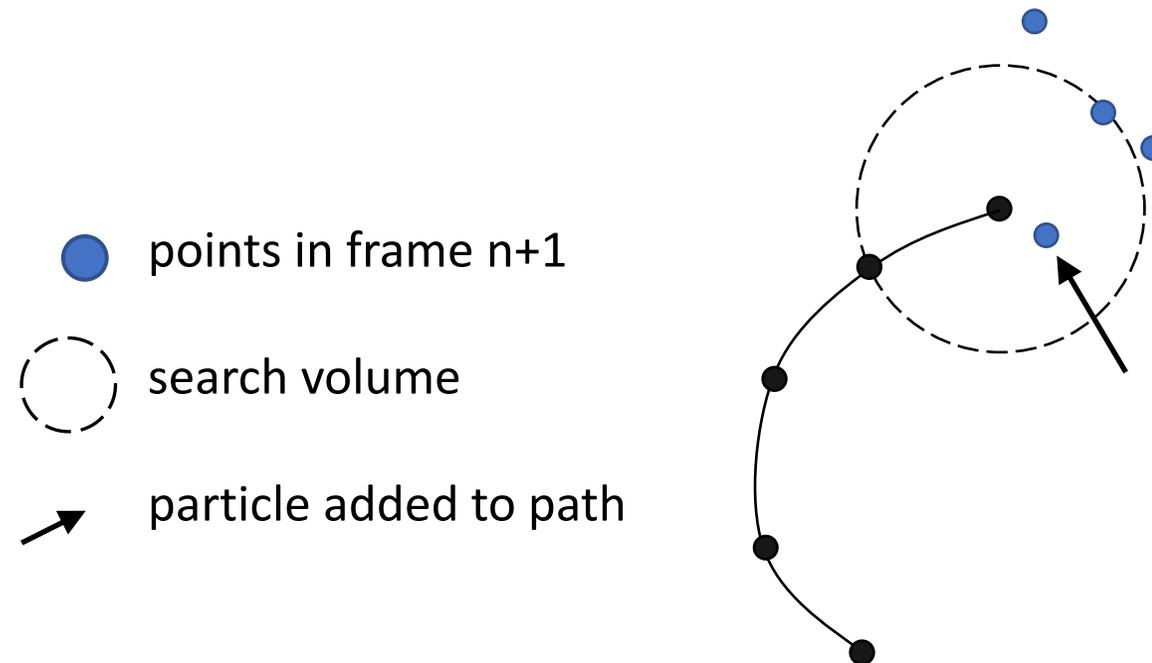
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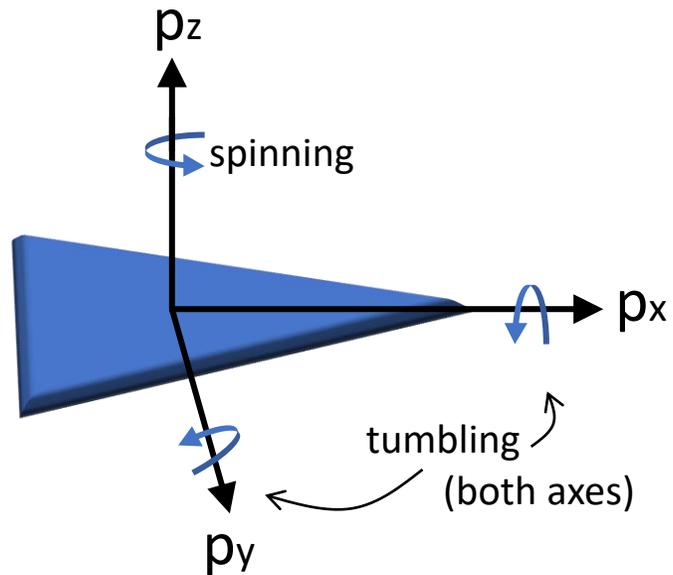
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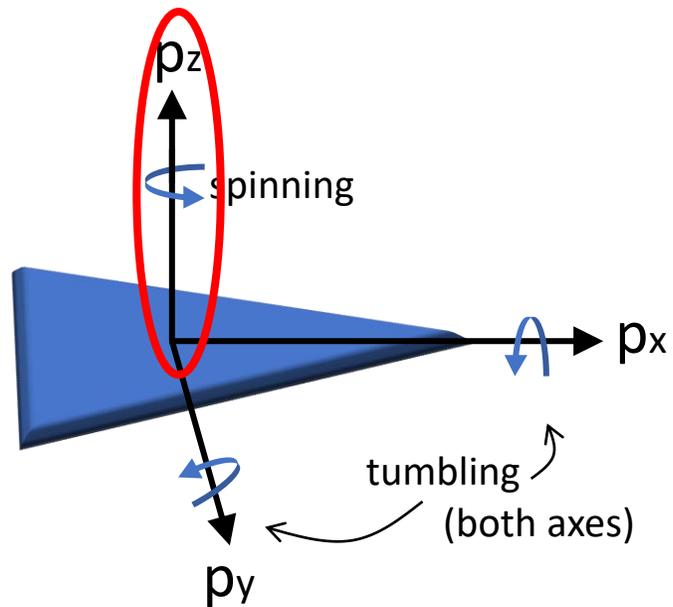
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Particle rotation can be decomposed into tumbling and spinning



reference particle, known
location and orientation

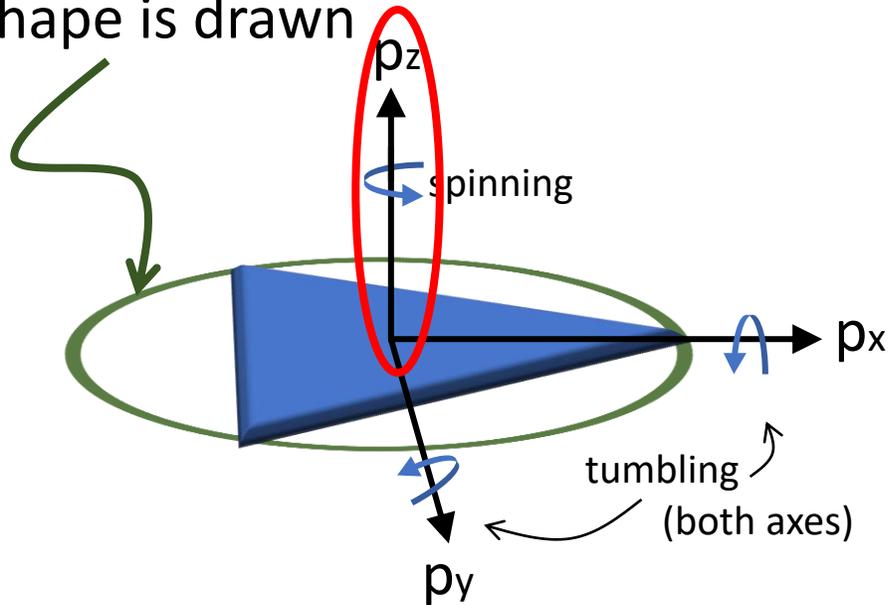
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reference particle, known
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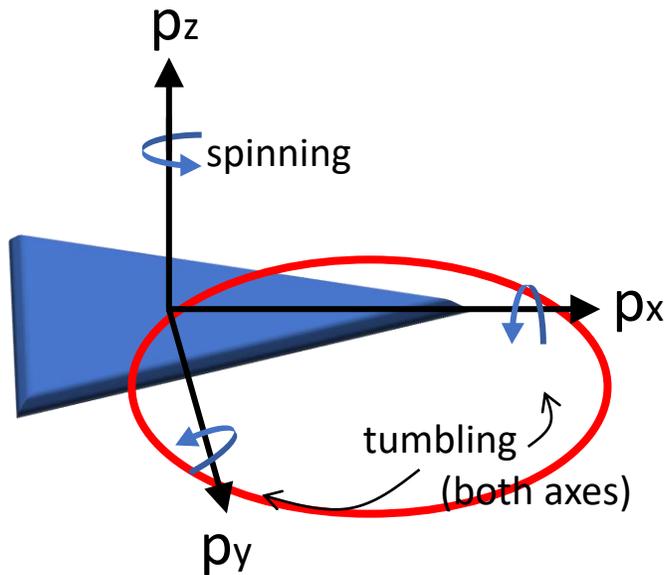
Particle rotation can be decomposed into tumbling and spinning

circle within which the shape is drawn



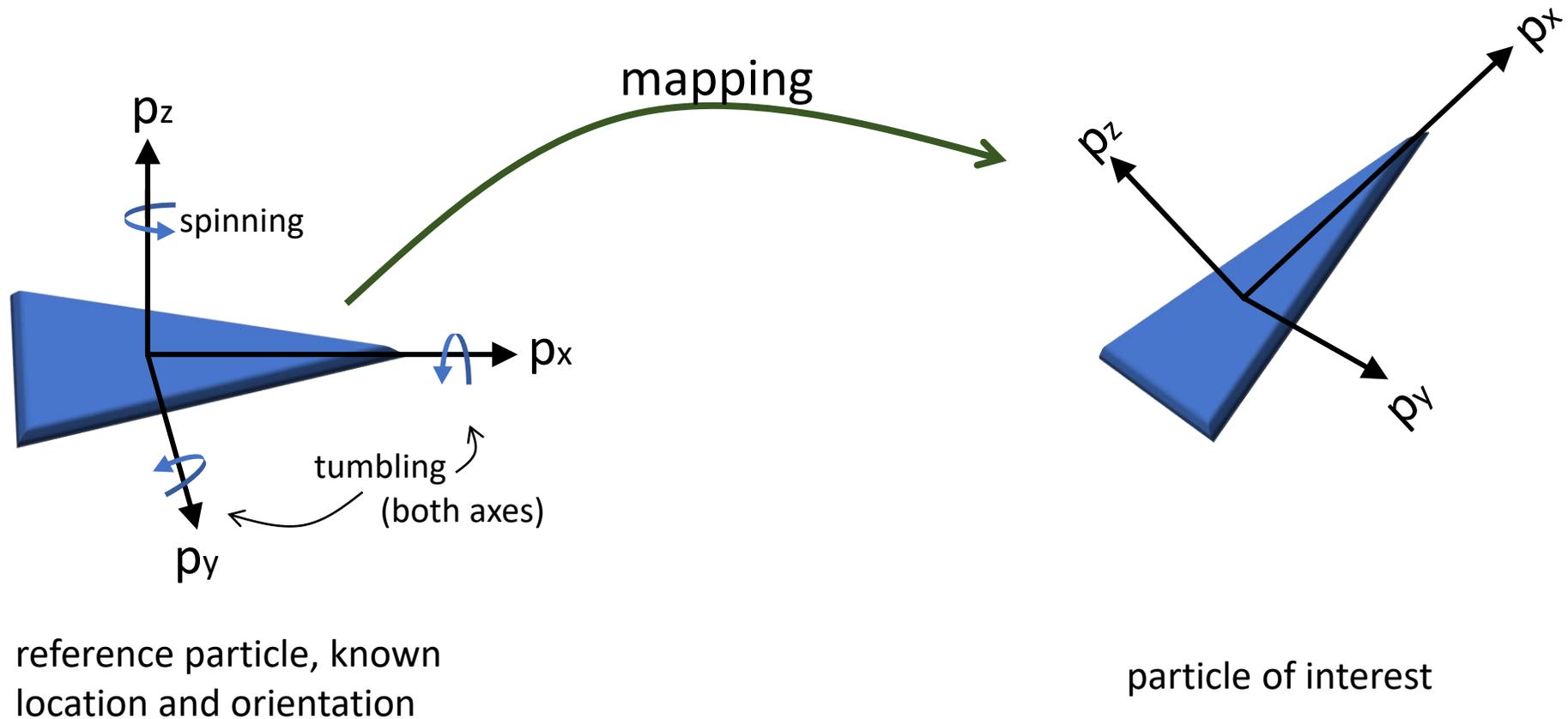
reference particle, known location and orientation

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reference particle, known
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Particle rotation can be decomposed into tumbling and spinning

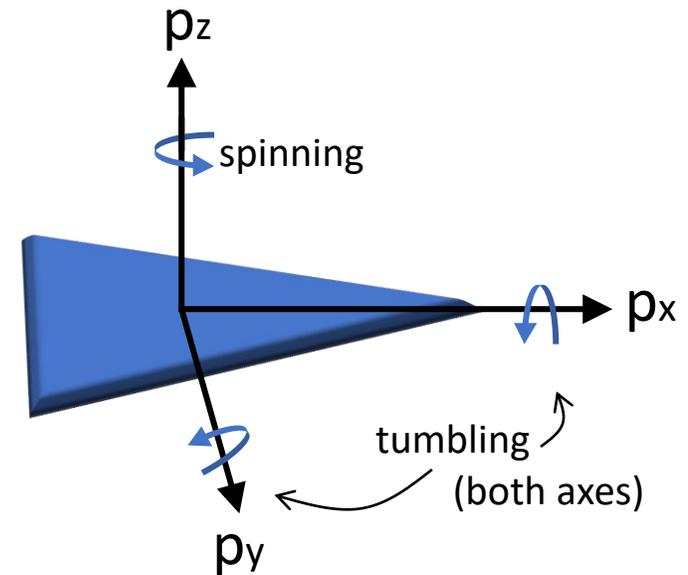


Particle rotation can be decomposed into tumbling and spinning

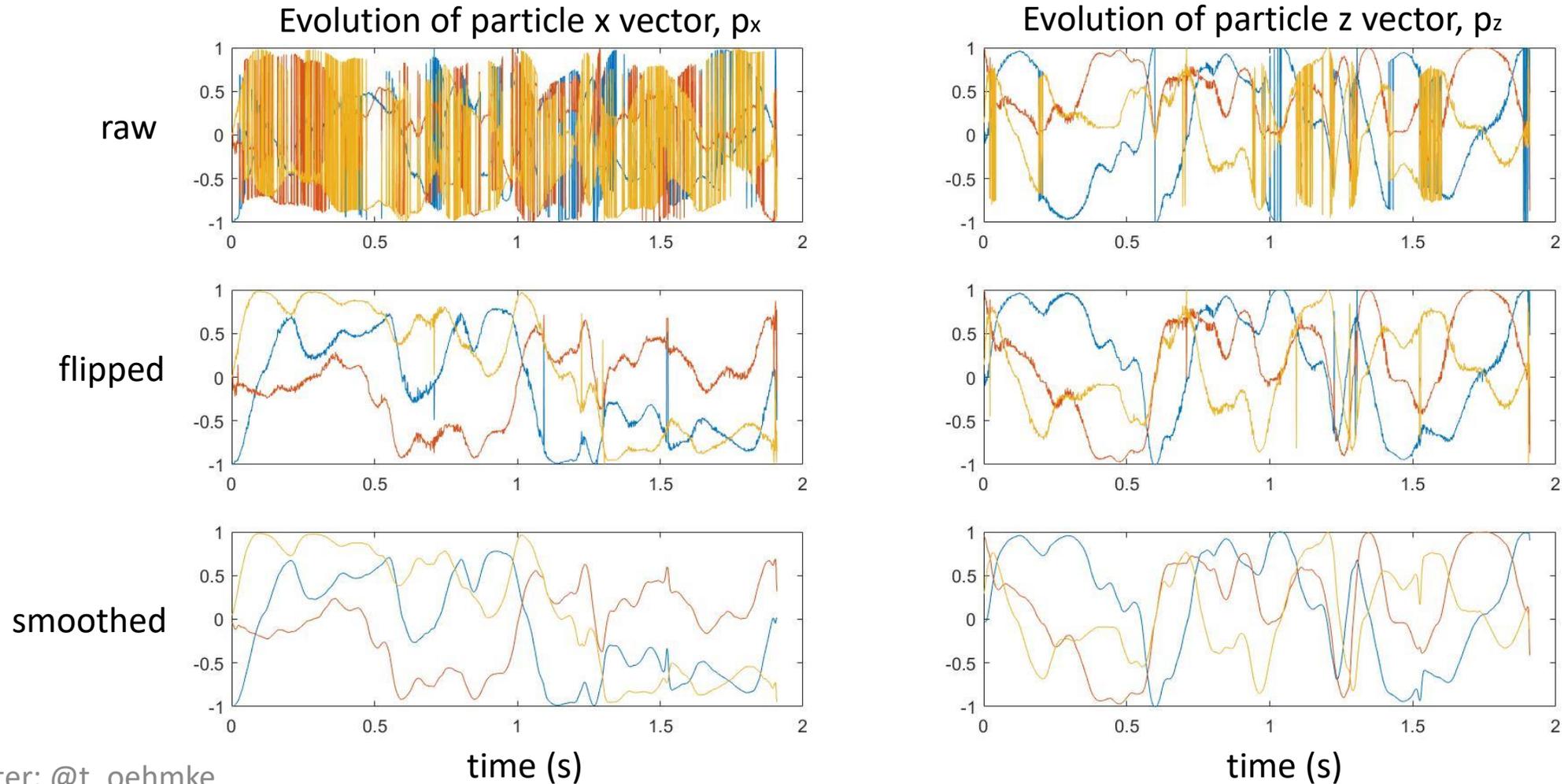
$$R = \begin{bmatrix} \cos\theta & -\sin\theta & 0 \\ \sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$R = R_T R_S$$

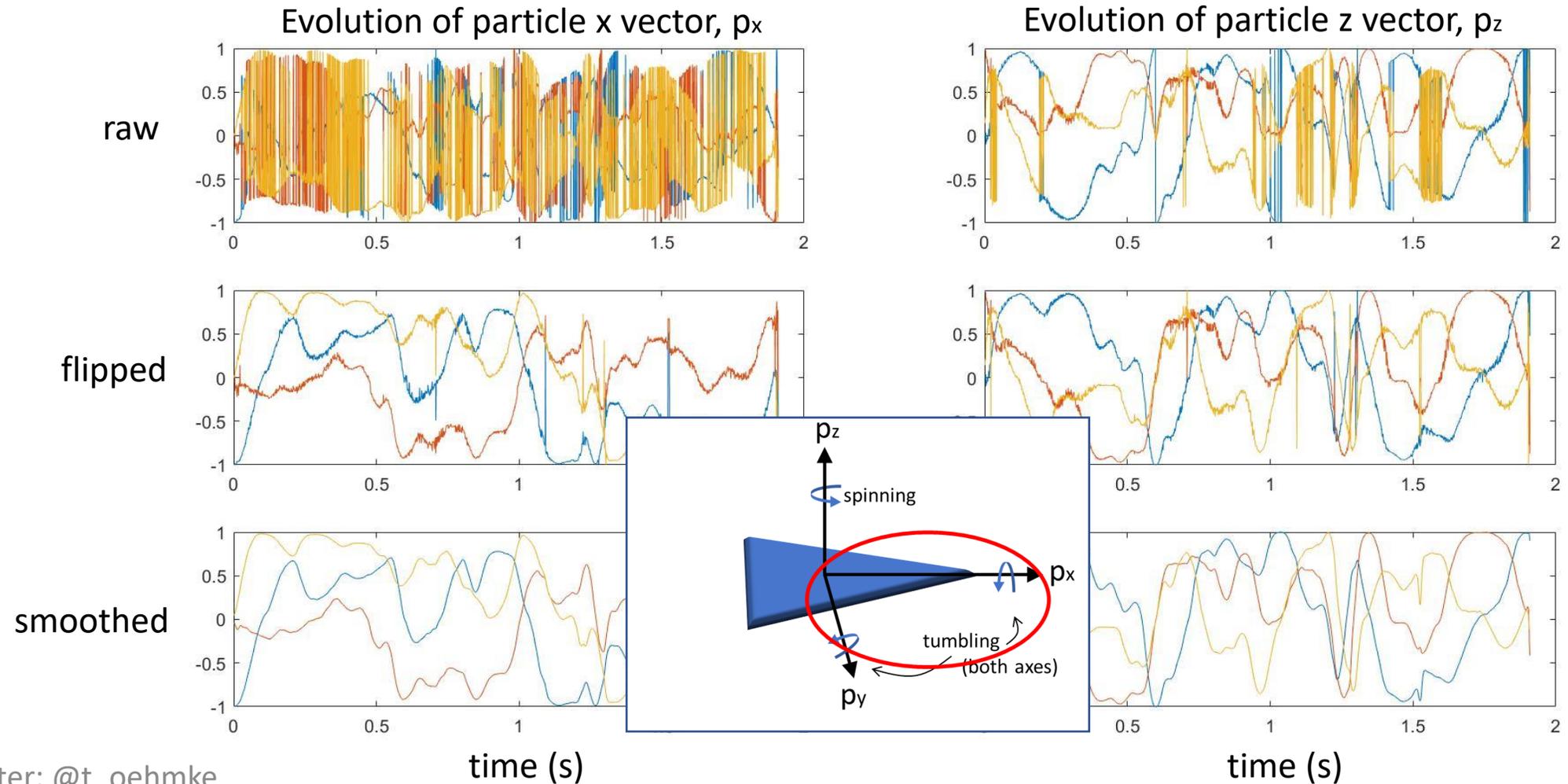
Where R is the rotation matrix
And R_T is the tumbling matrix
And R_S is the spinning matrix



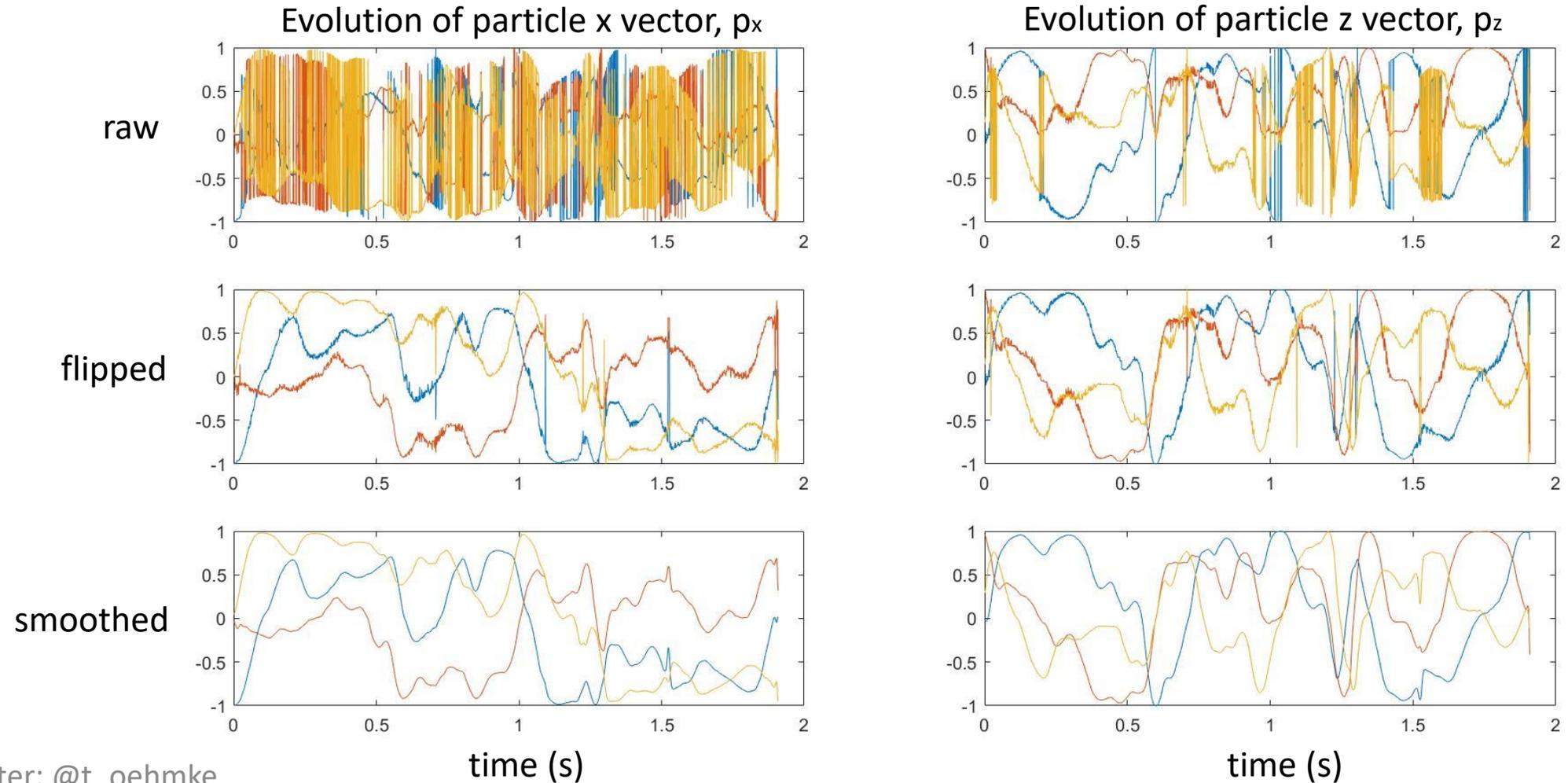
Trajectories were filtered to remove measurement and experimental noise



Trajectories were filtered to remove measurement and experimental noise

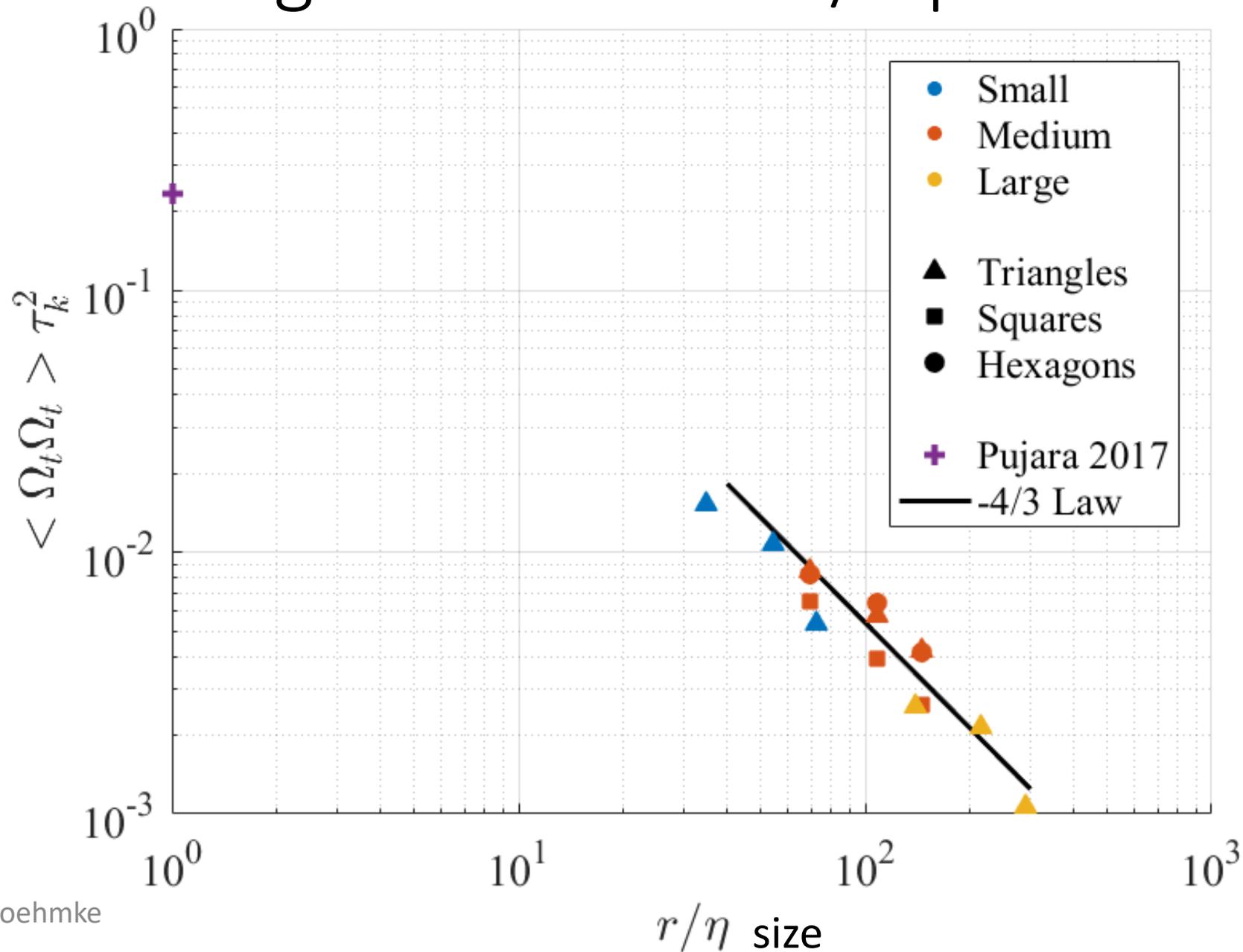


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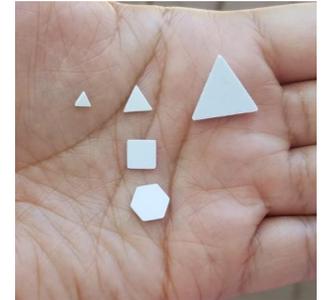
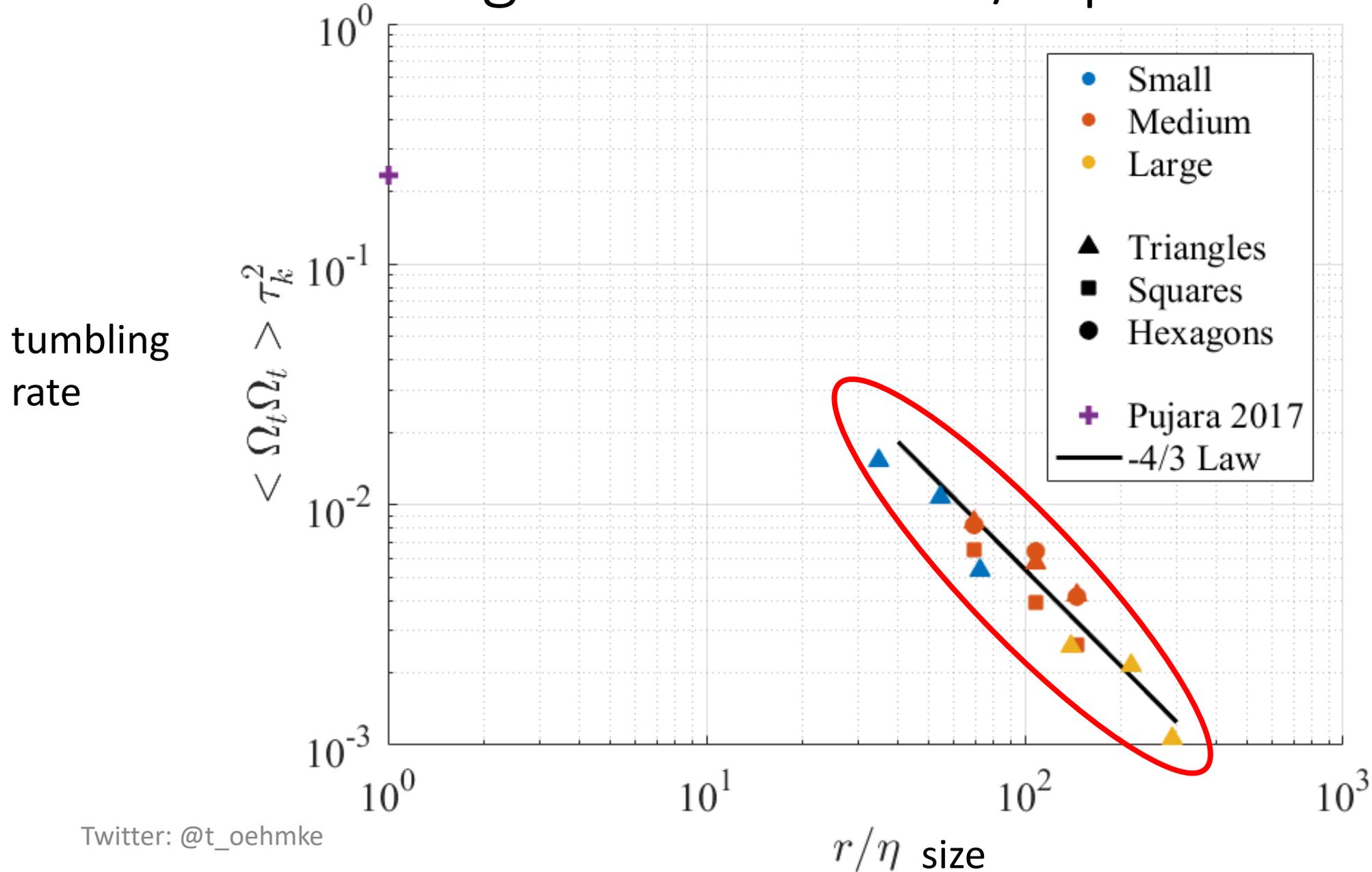


Tumbling rates follow -4/3 power law

tumbling
rate

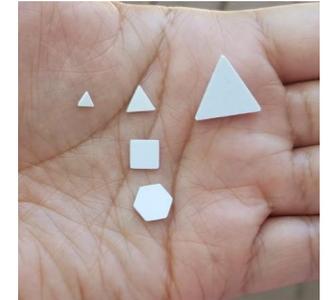
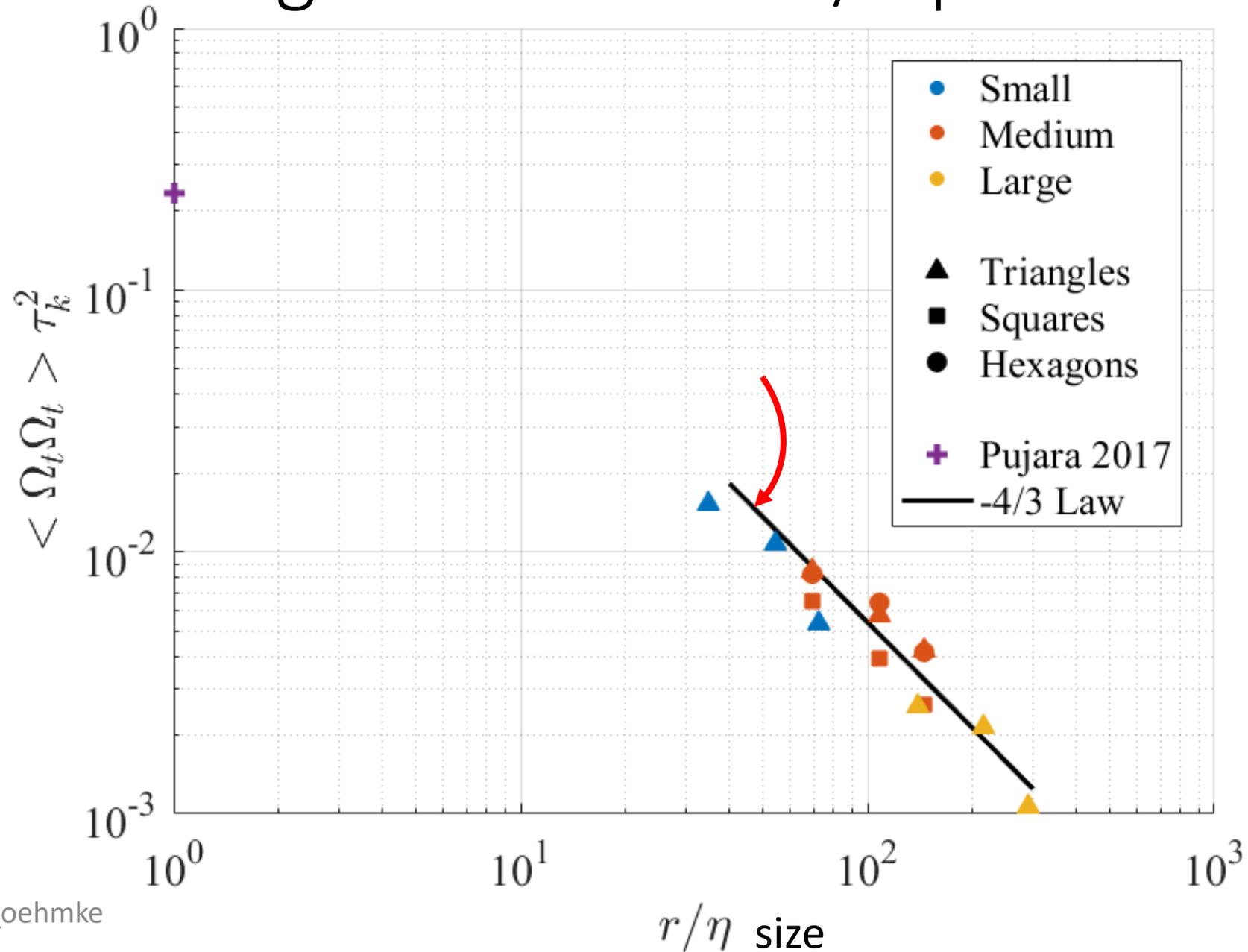


Tumbling rates follow -4/3 power law

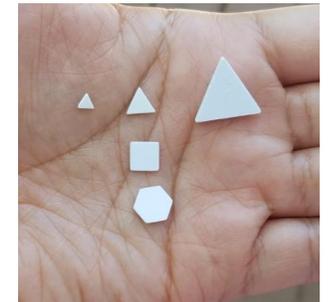
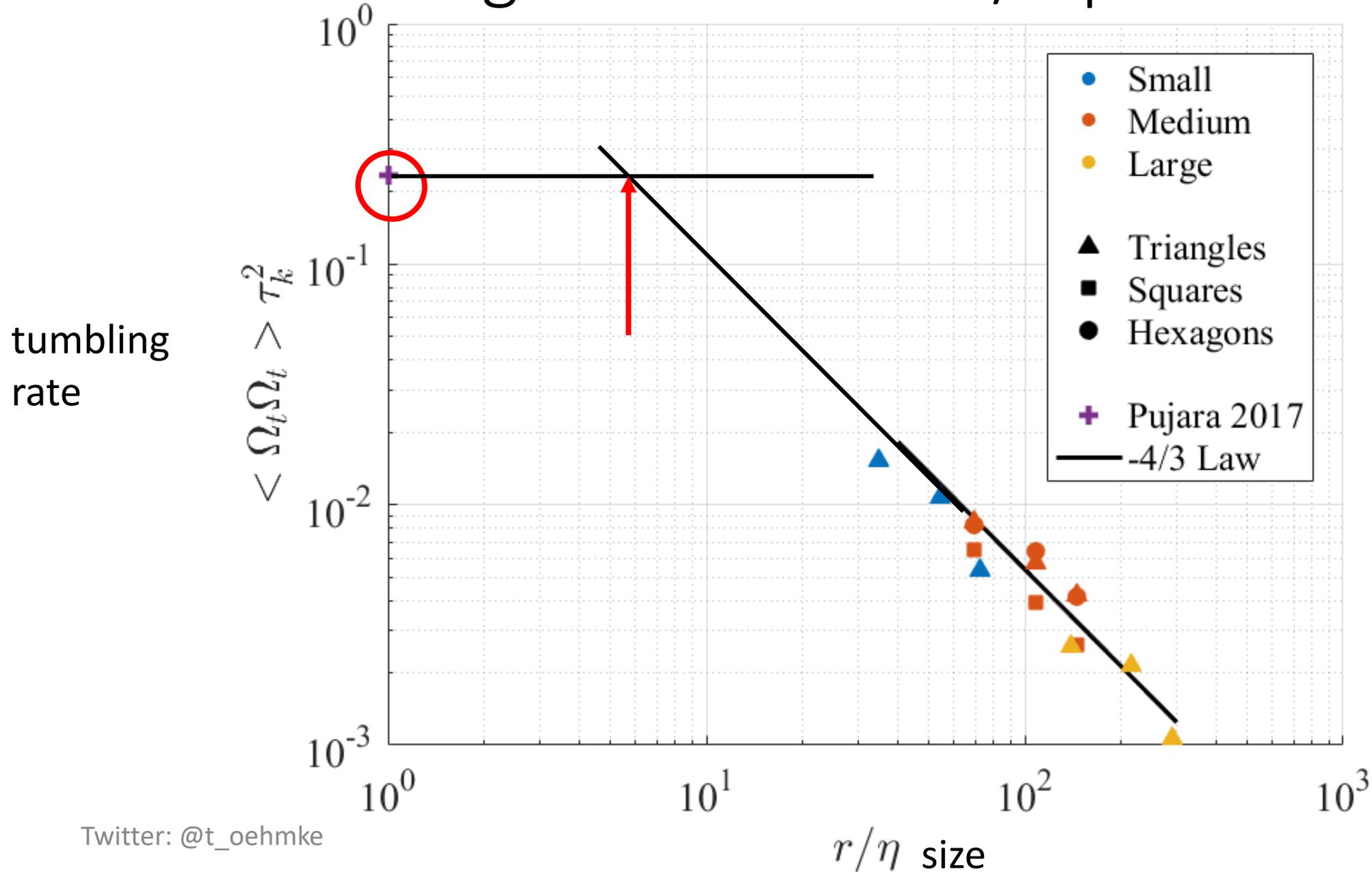


Tumbling rates follow -4/3 power law

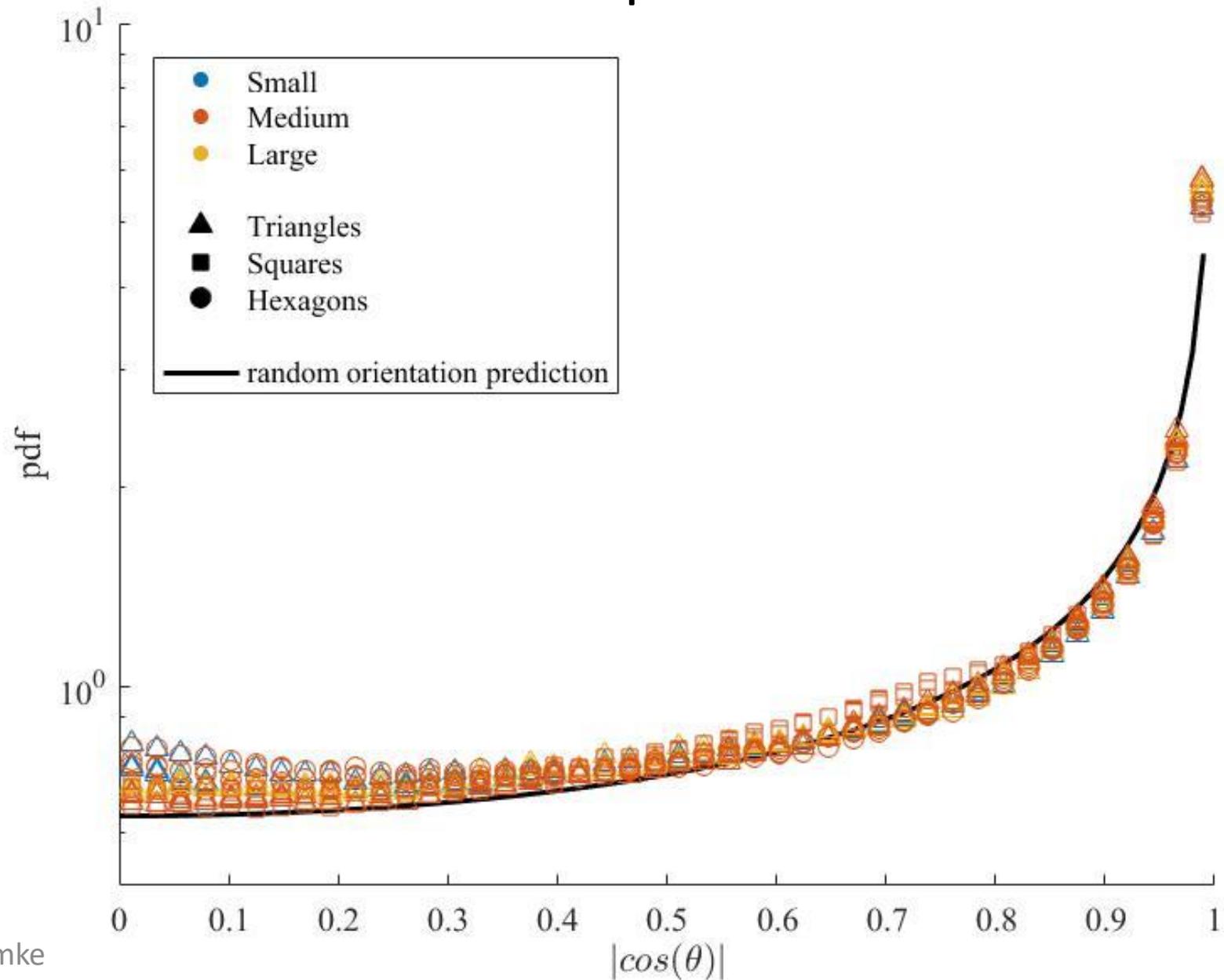
tumbling rate



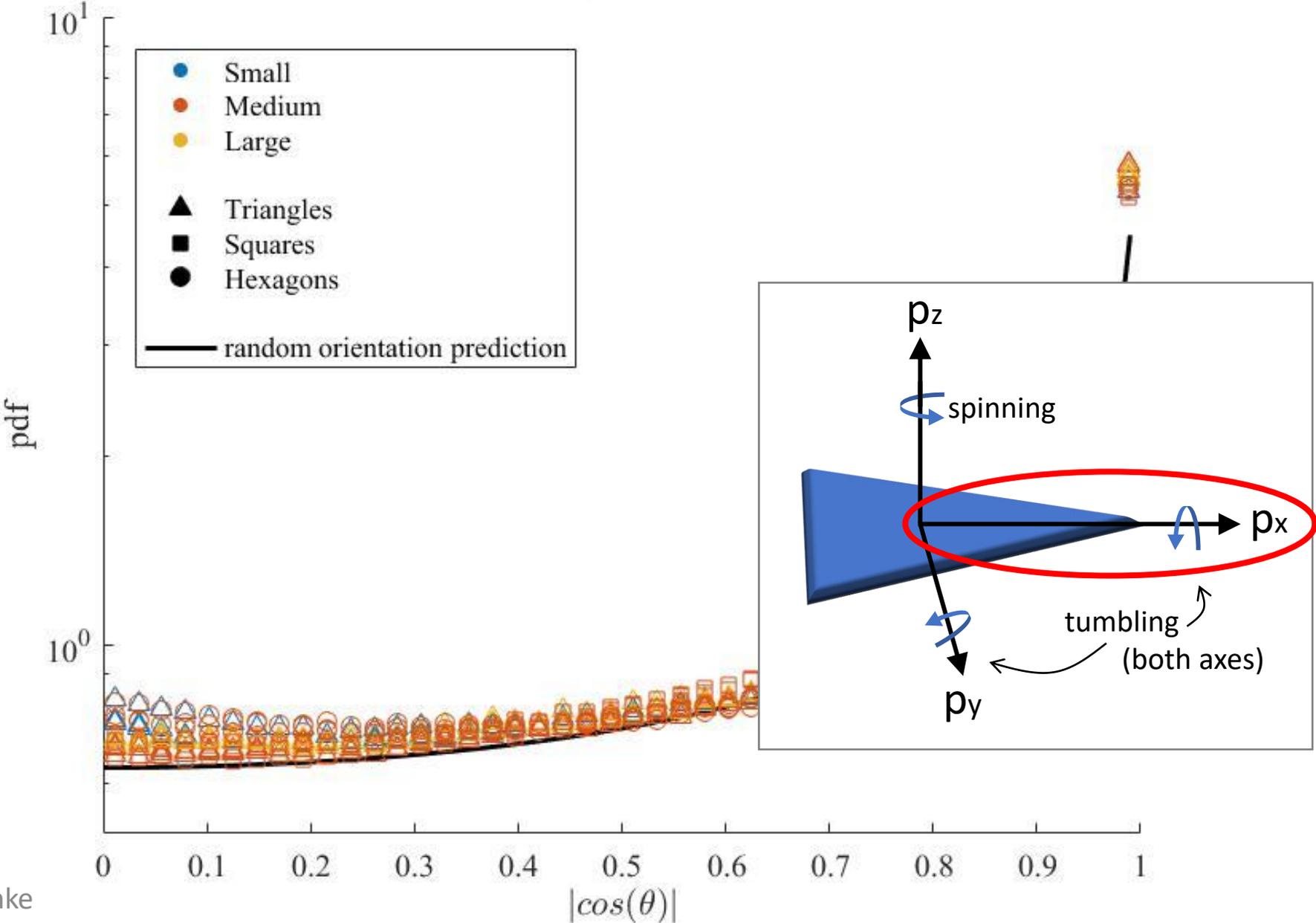
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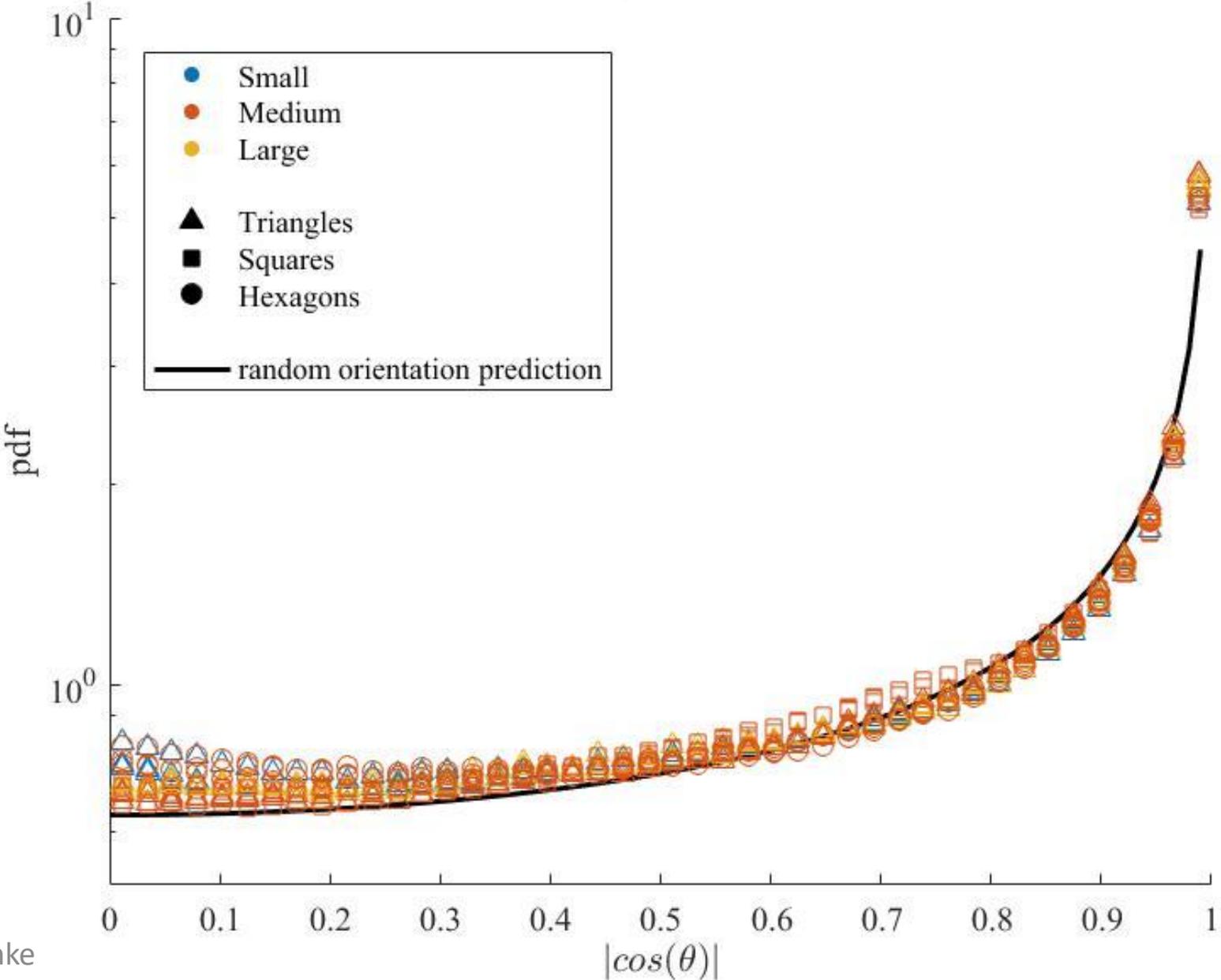
Particles do not show a preferential orientation



Particles do not show a preferential orientation



Particles do not show a preferential orientation



Perspectives: size matters more than shape

- The particles do not show a preferential orientation
- Particles follow a $-4/3$ power law scaling, meaning these particles are rotated and aligned by eddies of their size
 - This means that size matters more than shape
- These findings agree with results for solid, 3D particles as well

Questions to answer



Particle transport in turbulence impacts many aspects of science

- Particle transport prediction
 - Where and how do transported particles eventually settle out of the flow?

Particle transport in turbulence impacts many aspects of science

- Particle transport prediction
 - Where and how do transported particles eventually settle out of the flow?
- Intermittency
 - What is the role of turbulence intermittency on particle kinematics?

Acknowledgements



Professor Evan Variano

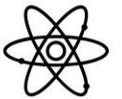


Dr. Gautier Verhille

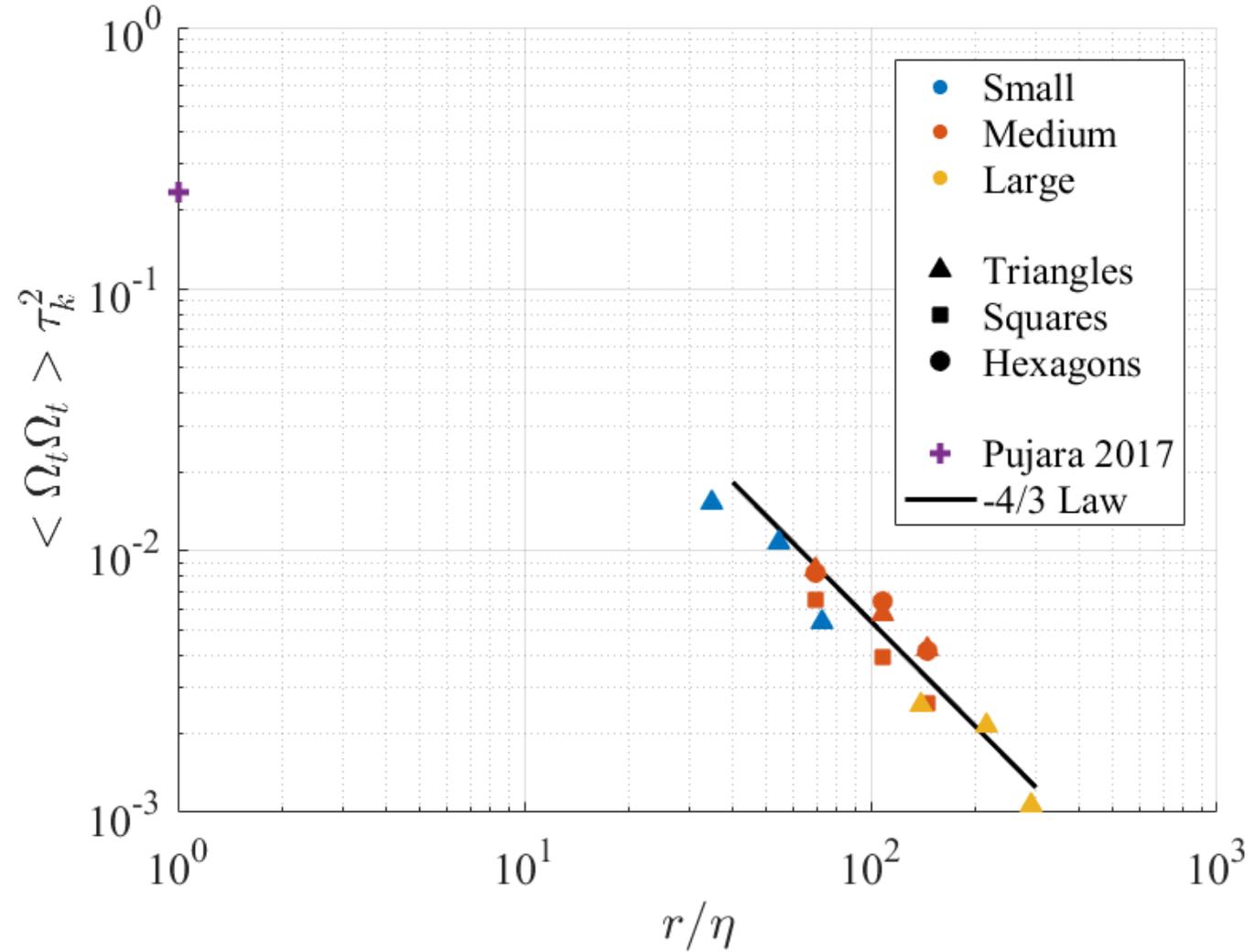
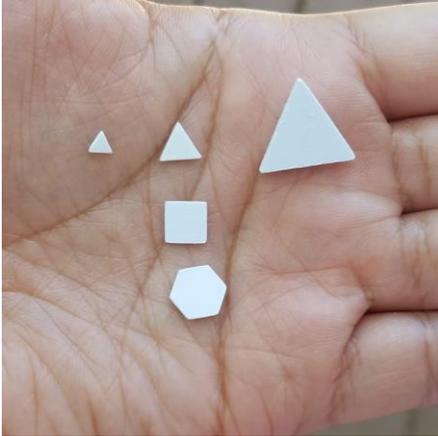


Chateaubriand
Fellowship Program

Science, Technology,
Engineering, Math
& Health



Questions?



Parsa and Voth 2014

rotation rate for tracers : $\langle \dot{p}_i \dot{p}_i \rangle \sim \tau_k^{-2}$

rotation rate for scale l : $\langle \dot{p}_i \dot{p}_i \rangle \sim \tau_l^{-2}$

define τ_l in the inertial range : $\tau_l = l/u_l = l/(l\langle \epsilon \rangle)^{1/3}$

rotation rate for scale l : $\langle \dot{p}_i \dot{p}_i \rangle \sim l^{-4/3}$