# Time periodic solutions near shear/radial flows for 2D Euler

New Trends in Fluids and Collective Dynamics July 23-28, Banff, 2023

# DANIEL LEAR

Joint work with Ángel Castro

# 2D Euler

The incompressible Euler eqn's are the following PDE's for  $(\mathbf{v}, p)$ :

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- Global existence of classical solutions for 2D Euler  $\checkmark$
- Qualitative behaviour of 2D Euler for long times X



# 2D Euler and shear/radial flows

Two important classes of steady states for 2D Euler:

Shear flows in a strip-type domain ( $\mathbb{T} \times \mathbb{R}$  or  $\mathbb{T} \times [0, 1]$ )

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Some remarkable examples:

$$U_C(y) = y, \quad U_P(y) = y^2, \quad U_K(y) = \sin(y)$$
  
 $V_{TC}(|\mathbf{x}|) = |\mathbf{x}| + |\mathbf{x}|^{-1}, \quad V_G(r) = e^{-|\mathbf{x}|^2}$ 

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Arnold's stability (1960's):

$$\begin{array}{c} -\lambda_1(D) < F'(\psi) < 0 \\ 0 < F'(\psi) < +\infty \end{array} \right\} \quad \Longrightarrow \quad$$

nonlinearly (Lyapunov) stable in  $L^2$ 

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Couette and Taylor-Couette flows are stable in  $L^{\infty}$ . Pouseville flow is stable in  $L^2$ .

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 $\partial_t \omega + \nabla^\perp \psi \cdot \nabla \omega + \boldsymbol{U}(\boldsymbol{y}) \partial_{\boldsymbol{x}} \omega - \boldsymbol{U}''(\boldsymbol{y}) \partial_{\boldsymbol{x}} \psi = \boldsymbol{0}, \qquad \Delta \psi = \omega.$ 

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What happens at  $t \to \infty$ ?

 $\|\mathbf{u}_0\|_X \ll 1 \quad \Longrightarrow \quad \lim_{t \to \infty} \|\mathbf{u}(t)\|_Y = ??$ 

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In 1907, Orr predicted the inviscid damping for the Couette flow

shear flow + perturbation  $\rightarrow$  new shear flow

# **Couette flow**

The equation for a perturbation of the Couette flow

$$\mathbf{v}(\mathbf{x},t) = (\mathbf{y},0) + \mathbf{u}(\mathbf{x},t), \qquad \mathbf{w}(\mathbf{x},t) = -1 + \omega(\mathbf{x},t),$$

is given by

$$\partial_t \omega + \nabla^\perp \psi \cdot \nabla \omega + \mathbf{y} \partial_{\mathbf{x}} \omega = \mathbf{0},$$

with

$$\psi = \Delta^{-1}\omega = \int_{\mathbb{T}\times\mathbb{R}} \log \left(\cosh(y - \bar{y}) - \cos(x - \bar{x})\right) \omega(\bar{x}, \bar{y}) d\bar{x} d\bar{y}.$$

# Traveling waves and stationary states

Lin-Zeng (2011). Inviscid dynamical structures near Couette flow

• Existence of nontrivial and smooth **stationary states** arbitrarily close to the Couette flow in the  $H^{<\frac{3}{2}}$  topology.



• Nonexistence of nontrivial smooth **traveling waves** arbitrarily close to the Couette flow in the  $H^{>\frac{3}{2}}$  topology. All steady states near Couette in  $H^{>\frac{3}{2}}$  are shears.

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The above results immediately implies that nonlinear inviscid damping is NOT TRUE in any  $H^s$  (s < 3/2) neighborhood of Couette flow.

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# Inviscid damping in Gevrey spaces

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Gevrey spaces  $\mathcal{G}^s$  :

 $|\partial^m f| \leq K^m (m!)^s \quad \forall m \geq 0.$ 

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## **Our result**

For any  $0 \le s < 3/2$  and  $\epsilon > 0$ , the perturbed 2D Euler system admits a nontrivial smooth traveling wave solution satisfying

 $\|\mathbf{w}+\mathbf{1}\|_{H^{s}(\mathbb{T}\times\mathbb{R})}\equiv\|\omega\|_{H^{s}(\mathbb{T}\times\mathbb{R})}<\epsilon.$ 

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nontrivial smooth traveling wave means...

• Traveling wave:

$$\omega(\mathbf{x},\mathbf{y},t)=\widetilde{\omega}(\mathbf{x}+\lambda t,\mathbf{y}).$$

- Nontrivial: the dependence on *x* is nontrivial.
- Smooth:  $\omega \in C_c^{\infty}$  but its  $H^s$ -norm is large for s > 3/2.

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The support of  $\nabla \omega$  is concentrated around  $y = \pm L$ . The speed of the wave satisfies

$$\lambda = L + O(\epsilon).$$

$$\mathbf{v}(x, y, t) \quad \rightsquigarrow \quad \overline{\mathbf{v}}(x, y, t) = \mathbf{v}(x + \lambda t, y, t) - (\lambda, 0)$$

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From steady states to traveling waves:

$$v_1(x,y) - y = O(\epsilon) \implies \overline{v}_1(x,y,t) - y = O(\epsilon) \text{ if } \lambda = O(\epsilon)$$

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Our traveling waves satisfy  $v_1(x, y) - y = O(\epsilon)$  with  $\lambda = O(1)$ .

# **Taylor-Couette flow**

$$\partial_t \mathbf{w} + \frac{1}{r} (\partial_\theta \psi \partial_r \mathbf{w} - \partial_r \psi \partial_\theta \mathbf{w}) = \mathbf{0}, \qquad -(\partial_r^2 + \frac{1}{r} \partial_r + \frac{1}{r^2} \partial_\theta^2) \psi = \mathbf{w}.$$

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The velocity  $\mathbf{v}(\mathbf{x}) = \mathbf{v}^r(r, \theta)\mathbf{e}_r + \mathbf{v}^{\theta}(r, \theta)\mathbf{e}_{\theta}$  is recovered via  $(\mathbf{v}^r, \mathbf{v}^{\theta}) = (\frac{1}{r}\partial_{\theta}\psi, -\partial_r\psi).$ 

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The velocity  $\mathbf{v}(\mathbf{x}) = v^r(r, \theta)\mathbf{e}_r + v^{\theta}(r, \theta)\mathbf{e}_{\theta}$  is recovered via

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#### **Taylor-Couette flow:**

Let  $0 < r_1 < r_2 < \infty$  and  $\Omega_{r_1, r_2} = \{ \mathbf{x} \in \mathbb{R}^2 : r_1 \le |\mathbf{x}| \le r_2 \}$ 

$$v^{ heta}(r) = Ar + rac{B}{r}, \qquad A, B \in \mathbb{R}$$

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Time-periocic (rotanting) solutions in an annular domain near Taylor-Couette flow can be constructed using a similar strategy.

# (Asymptotic) stability of a steady circular flow

- Bedrosian-Zelati-Vicol (2019): Linear inviscid damping around radially symmetric, strictly monotone decreasing vorticity.
- Ionesuc-Jia (2019): Asymptotic stability of point vortex solutions.
- Gallay-Sverak (2021): Stability of  $w(r) = e^{-r^2/4}$  and  $w(r) = (1 + |r|^2)^{-k}$ , k > 1 for 2D Euler and NS with low regularity.
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Some previous results for the Taylor-Couette:

- Zillinger & Zelati-Zillinger (2017,2019): Linear inviscid damping around Taylor-Couette.
- An-He-Li (2021,2023): Enhanced dissipation and nonlinear asymptotic stability of Taylor-Couette for 2D NS.

The equation for a perturbation of the Taylor-Couette flow

$$\mathbf{v}(r,\theta,t) = \left(0,Ar+\frac{B}{r}\right) + \mathbf{u}(r,\theta,t), \quad w(r,\theta,t) = 2A + \omega(r,\theta,t),$$

is given by

$$\partial_t \omega + \frac{1}{r} (\partial_\theta \psi \partial_r \omega - \partial_r \psi \partial_\theta \omega) \omega + \left( Ar + \frac{B}{r} \right) \partial_\theta \omega = 0, \quad on \quad \Omega_{r_1, r_2}$$

with  $\psi$  solving

$$\begin{cases} -(\partial_r^2 + \frac{1}{r}\partial_r + \frac{1}{r^2}\partial_\theta^2)\psi &= \omega, \quad \text{on} \quad \Omega_{r_1,r_2} \\ \psi|_{r=r_1,r_2} &= 0. \end{cases}$$

# Splitting the domain $\Omega_{r_1,r_2}$

We are looking for a solution with the following structure:



with  $r_1 < R_1 < R_2 < r_2$  and  $|\Omega_{R_i}| = O(\epsilon)$ , for i = 1, 2.

The dynamics of the perturbation occurs only on  $\Omega_{B_1}(t) \cup \Omega_{B_2}(t)$ .

We assume that

 $\Omega_{R_i}(t) = \{(\rho + f(\rho, \theta, t)) (\cos \theta, \sin \theta), \rho \in [R_i - \epsilon, R_i + \epsilon], \theta \in \mathbb{T}\}.$ 

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Using the transport character of the vorticity formulation:

 $\omega(\rho + f(\rho, \theta, t), \theta, t) = \varpi(\rho), \quad (\rho, \theta) \in [\mathbf{R}_i - \epsilon, \mathbf{R}_i + \epsilon] \times \mathbb{T} \quad \forall t \ge \mathbf{0}.$ 



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The problem reduces to study the family of graphs  $(\rho + f(\rho, \theta, t), \theta)$ :

$$(\rho + f(\rho, \theta, t))\partial_t f(\rho, \theta, t) = \partial_\theta \overline{\psi}[f](\rho, \theta, t),$$

with  $\bar{\psi}[f](\rho, \theta, t) := \psi(\rho + f(\rho, \theta, t), \theta, t)$  and  $\psi$  solving

$$\begin{cases} -(\partial_r^2 + \frac{1}{r}\partial_r + \frac{1}{r^2}\partial_\theta^2)\psi = \omega, \quad \text{on} \quad \Omega_{r_1,r_2} \\ \psi|_{r=r_1,r_2} = 0. \end{cases}$$

 $f(\rho, \theta, t) := f(\rho, \theta + \lambda t).$ 

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Therefore, we have to solve the time-independent problem:

 $(\rho + \mathbf{f})\lambda\partial_{\theta}\mathbf{f} = \partial_{\theta}\bar{\psi}[\mathbf{f}].$ 

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This is an equation for  $(\lambda, f)$ . Let us call

$$F_{\varpi}[\lambda, \mathsf{f}] := (\rho + \mathsf{f})\lambda\partial_{\theta}\mathsf{f} - \partial_{\theta}\bar{\psi}[\mathsf{f}].$$

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Important facts:

- Note that  $F_{\varpi}[\lambda, 0] = 0$ , for all  $\lambda \in \mathbb{R}$ .
- Recall that *f* is defined just over  $\bigcup_{i=1,2}(R_i \epsilon, R_i + \epsilon) \times \mathbb{T}$ .

# The function $\varpi_{\epsilon,\kappa} \in C^{\infty}([r_1, r_2])$

$$arpi_{\epsilon,\kappa}(r) := egin{cases} 0 & r_1 \leq r \leq R_1 - \epsilon, \ \epsilon arphi_\kappa \left(rac{R_1 - r}{\epsilon}
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Note that  $\varpi_{\epsilon,0} \in W^{1,\infty}(\mathbb{R}) \cap H^{<3/2}(\mathbb{R})$ . ( $\kappa$  is a regularizing parameter)

Let *X*, *Y* be two Banach spaces,  $\{0\} \in V \subset X$  and let  $F : \mathbb{R} \times V \to Y$  satisfying:

- 1.  $F[\lambda, 0] = 0$  for any  $\lambda \in \mathbb{R}$ .
- 2. The derivatives  $D_{\lambda}F$ ,  $D_{f}F$  and  $D_{\lambda,f}^{2}F$  exist and are continuous.
- 3.  $\mathcal{L}_{\star} = D_f F[\lambda_{\star}, 0]$ :  $\mathcal{N}(\mathcal{L}_{\star})$  and  $Y/\mathcal{R}(\mathcal{L}_{\star})$  are one-dimensional.
- $\text{4. } D^2_{\lambda, f} F[\lambda_\star, 0] h_\star \not\in \mathcal{R}(\mathcal{L}_\star), \text{ where } \mathcal{N}(\mathcal{L}_\star) = \text{span}\{h_\star\}.$

Let *X*, *Y* be two Banach spaces,  $\{0\} \in V \subset X$  and let  $F : \mathbb{R} \times V \to Y$  satisfying:

- 1.  $F[\lambda, 0] = 0$  for any  $\lambda \in \mathbb{R}$ .
- 2. The derivatives  $D_{\lambda}F$ ,  $D_{f}F$  and  $D_{\lambda,f}^{2}F$  exist and are continuous.
- 3.  $\mathcal{L}_{\star} = D_f F[\lambda_{\star}, 0]$ :  $\mathcal{N}(\mathcal{L}_{\star})$  and  $Y/\mathcal{R}(\mathcal{L}_{\star})$  are one-dimensional.
- $\text{4. } D^2_{\lambda, f} F[\lambda_\star, 0] h_\star \not\in \mathcal{R}(\mathcal{L}_\star), \text{ where } \mathcal{N}(\mathcal{L}_\star) = \text{span}\{h_\star\}.$

If *Z* is any complement of  $\mathcal{N}(\mathcal{L}_{\star})$  in *X*, then there is a neighborhood *U* of  $(\lambda_{\star}, 0)$  in  $\mathbb{R} \times X$ , an interval  $(-\sigma_0, \sigma_0)$ , and continuous functions  $\varphi : (-\sigma_0, \sigma_0) \to \mathbb{R}, \psi : (-\sigma_0, \sigma_0) \to Z$  such that  $\varphi(0) = 0, \psi(0) = 0$  and

$$\begin{aligned} F^{-1}(\mathbf{0}) \cap U = & \Big\{ \big( \lambda_{\star} + \varphi(\sigma), \sigma h_{\star} + \sigma \psi(\sigma) \big) \, ; \, |\sigma| < \sigma_0 \Big\} \\ & \cup \Big\{ (\lambda, \mathbf{0}) \, ; \, (\lambda, \mathbf{0}) \in U \Big\}. \end{aligned}$$

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where  $\mathcal{L}_n[\lambda]$  is given by

$$\mathcal{L}_{n}[\lambda]g(r) := \left(\Phi_{\epsilon,\kappa}'(r) + \lambda r\right)g(r) \\ - \frac{\mathcal{S}_{n}(r/r_{1})}{\mathcal{S}_{n}(r_{2}/r_{1})}\frac{1}{n}\int_{r_{1}}^{r_{2}}s\varpi_{\epsilon,\kappa}'(s)\mathcal{S}_{n}(r_{2}/s)g(s) + \frac{1}{n}\int_{r_{1}}^{r}s\varpi_{\epsilon,\kappa}'(s)\mathcal{S}_{n}(r/s)g(s),$$

with  $S_n(\cdot) = \sinh(n \log(\cdot))$  and  $\Phi_{\epsilon,\kappa}$  solving

$$\begin{cases} -(\partial_r^2 + \frac{1}{r}\partial_r)\Phi_{\epsilon,\kappa} = \varpi_{\epsilon,\kappa}, & \text{on} \quad [r_1, r_2] \\ \Phi_{\epsilon,\kappa}|_{r=r_1,r_2} = 0. \end{cases}$$

### The kernel: infinity system ( $n \ge 1$ ) $\mapsto$ m-th mode

Note that

$$\mathcal{L}[\lambda]h = 0 \quad \iff \quad \mathcal{L}_n[\lambda]h_n = 0 \quad \forall n \ge 1.$$

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Fixed  $m \ge 1$ , we consider only  $h \in X$  such that

$$h_n \equiv 0$$
 for  $n \neq m$ 

and

$$h_m(r) = \begin{cases} a(r) & r \in [R_1 - \epsilon, R_1 + \epsilon] =: I_\epsilon(R_1), \\ b(r) & r \in [R_2 - \epsilon, R_2 + \epsilon] =: I_\epsilon(R_2) \end{cases}$$

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We have reduce the problem to study

$$\mathcal{L}_m[\lambda]h_m(r) \equiv \mathcal{L}_m[\lambda] \begin{pmatrix} a \\ b \end{pmatrix} (r) = 0, \qquad r \in I_{\epsilon}(R_1) \cup I_{\epsilon}(R_2).$$

# The problem for $\lambda$ and (a, b)

$$\begin{aligned} \left( \Phi_{\epsilon,\kappa}'(r) + \lambda r \right) \mathbf{a}(r) + \frac{1}{n} \int_{R_1 - \epsilon}^r s \varpi_{\epsilon,\kappa}'(s) \mathcal{S}_n(r/s) \mathbf{a}(s) ds \\ &- \frac{\mathcal{S}_n(r/r_1)}{\mathcal{S}_n(r_2/r_1)} \frac{1}{n} \int_{R_1 - \epsilon}^{R_1 + \epsilon} s \varpi_{\epsilon,\kappa}'(s) \mathcal{S}_n(r_2/s) \mathbf{a}(s) ds \\ &- \frac{\mathcal{S}_n(r/r_1)}{\mathcal{S}_n(r_2/r_1)} \frac{1}{n} \int_{R_2 - \epsilon}^{R_2 + \epsilon} s \varpi_{\epsilon,\kappa}'(s) \mathcal{S}_n(r_2/s) \mathbf{b}(s) ds = 0, \quad r \in I_{\epsilon}(R_1). \end{aligned}$$

$$(\Phi_{\epsilon,\kappa}'(r) + \lambda r) \frac{b(r)}{b(r)} + \frac{1}{n} \int_{R_2 - \epsilon}^{r} s \varpi_{\epsilon,\kappa}'(s) S_n(r/s) \frac{b(s)}{s} ds + \frac{1}{n} \int_{R_1 - \epsilon}^{R_1 + \epsilon} s \varpi_{\epsilon,\kappa}'(s) \left[ S_n(r/s) - \frac{S_n(r/r_1)}{S_n(r_2/r_1)} S_n(r_2/s) \right] a(s) ds - \frac{S_n(r/r_1)}{S_n(r_2/r_1)} \frac{1}{n} \int_{R_2 - \epsilon}^{R_2 + \epsilon} s \varpi_{\epsilon,\kappa}'(s) S_n(r_2/s) \frac{b(s)}{s} ds = 0, \quad r \in I_{\epsilon}(R_2).$$

## **Re-scaling**

We pass from

$$[R_1 - \epsilon, R_1 + \epsilon] \cup [R_2 - \epsilon, R_2 + \epsilon] \rightarrow [-1, 1]$$

We just have to solve

$$A(s) := a(R_1 + \epsilon s), \qquad B(s) := b(R_2 + \epsilon s)$$

$$\begin{aligned} \left(\Phi_{\epsilon,\kappa}'(R_1+\epsilon z)+\lambda(R_1+\epsilon z)\right)A(z) \\ &+\frac{\mathcal{S}_n((R_1+\epsilon z)/r_1)}{\mathcal{S}_n(r_2/r_1)}\frac{\epsilon}{n}\int_{-1}^{+1}(R_1+\epsilon s)\varphi_{\kappa}'(-s)\mathcal{S}_n(r_2/(R_1+\epsilon s))A(s)ds \\ &-\frac{\mathcal{S}_n((R_1+\epsilon z)/r_1)}{\mathcal{S}_n(r_2/r_1)}\frac{\epsilon}{n}\int_{-1}^{+1}(R_2+\epsilon s)\varphi_{\kappa}'(s)\mathcal{S}_n(r_2/(R_2+\epsilon s))B(s)ds \\ &-\frac{\epsilon}{n}\int_{-1}^{z}(R_1+\epsilon s)\varphi_{\kappa}'(-s)\mathcal{S}_n((R_1+\epsilon z)/(R_1+s))A(s)ds = 0. \end{aligned}$$

We have to solve, for  $\lambda$  and (*A*, *B*), the system

$$\begin{pmatrix} \Phi'_{0,\kappa}(R_1) + \lambda R_1 \end{pmatrix} A(z) + O(\epsilon) = 0, \\ \begin{pmatrix} \Phi'_{0,\kappa}(R_2) + \lambda R_2 \end{pmatrix} B(z) + O(\epsilon) = 0. \end{cases}$$

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$$\begin{pmatrix} \Phi_{0,\kappa}'(R_1) + \lambda R_1 \end{pmatrix} A(z) + O(\epsilon) = 0, \\ \begin{pmatrix} \Phi_{0,\kappa}'(R_2) + \lambda R_2 \end{pmatrix} B(z) + O(\epsilon) = 0. \end{cases}$$

Then, we introduce the ansatz

$$\begin{aligned} A(z) &= A_1(z) \,\epsilon + A_2^{\epsilon}(z) \,\epsilon^2 \\ B(z) &= B_0(z) + B_1^{\epsilon}(z) \,\epsilon \end{aligned}$$

together with

$$\lambda = \underbrace{-\frac{\Phi_{0,\kappa}'(R_1)}{R_1}}_{U_{TC}(R_1)} + \lambda_1 \epsilon + \lambda_2^{\epsilon} \epsilon^2$$

At order O(1) we have fixed

 $\lambda_0 = U_{TC}(R_1).$ 

$$\Phi_{\epsilon,\kappa}'(R_i+\epsilon z)+\lambda(R_i+\epsilon z)=\alpha_0^{R_i}[\lambda_0]+\alpha_1^{R_i}[\lambda_0,\lambda_1](z)\epsilon+\alpha_{2,\epsilon}^{R_i}[\lambda_0,\lambda_1,\lambda_2^{\epsilon}](z)\epsilon^2$$

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At order  $O(\epsilon)$  we obtain a closed system for  $\lambda_1$  and  $A_1, B_0$ :

$$lpha_{0}^{R_{1}}[\lambda_{0}]A_{1}(z) - \int_{-1}^{+1} \varphi_{\kappa}'(s)B_{0}(s)ds = 0,$$
  
 $lpha_{1}^{R_{2}}[\lambda_{0},\lambda_{1}](z)B_{0}(z) - \int_{-1}^{+1} \varphi_{\kappa}'(s)B_{0}(s)ds = 0.$ 

$$\Phi_{\epsilon,\kappa}'(R_i+\epsilon z)+\lambda(R_i+\epsilon z)=\alpha_0^{R_i}[\lambda_0]+\alpha_1^{R_i}[\lambda_0,\lambda_1](z)\epsilon+\alpha_{2,\epsilon}^{R_i}[\lambda_0,\lambda_1,\lambda_2^{\epsilon}](z)\epsilon^2$$

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 $lpha_1^{R_2}[\lambda_0,\lambda_1](z)B_0(z) - \int_{-1}^{+1} \varphi'_\kappa(s)B_0(s)ds = 0.$ 

At higher order  $O(\varepsilon^2)$  we have a CONTRACTION for  $\lambda_2^{\epsilon}$  and  $A_2^{\epsilon}, B_1^{\epsilon}$ .

$$\Phi_{\epsilon,\kappa}'(R_i+\epsilon z)+\lambda(R_i+\epsilon z)=\alpha_0^{R_i}[\lambda_0]+\alpha_1^{R_i}[\lambda_0,\lambda_1](z)\epsilon+\alpha_{2,\epsilon}^{R_i}[\lambda_0,\lambda_1,\lambda_2^{\epsilon}](z)\epsilon^2$$

$$\alpha_{0}^{R_{1}}[\lambda_{0}]A_{1}(z) - \int_{-1}^{+1} \varphi_{\kappa}'(s)B_{0}(s)ds = 0 \quad \Longrightarrow \quad A_{1} = \frac{1}{\alpha_{0}^{R_{1}}[\lambda_{0}]} \int_{-1}^{+1} \varphi_{\kappa}'(s)B_{0}(s)ds$$

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Finally, one finds that

$$1\stackrel{(*)}{=}\int_{-1}^{+1}\frac{\varphi_{\kappa}'(s)}{\alpha_{1}^{R_{2}}[\lambda_{0},\lambda_{1}](s)}ds$$

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Fixed  $\lambda_{\epsilon,\kappa,m}$ , we have proved that there exists (unique modulo multiplicative constant)  $h_{\epsilon,\kappa,m} \in X$  such that  $\mathcal{L}[\lambda_{\epsilon,\kappa,m}]h_{\epsilon,\kappa,m} = 0$ .

Using the above argument, we get time-periodic solutions with

 $\lambda \approx U_{TC}(R_1)$  or  $\lambda \approx U_{TC}(R_2)$ .

### The condition on $R_1$ and $R_2$

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 $U_{TC}(R_1) \neq U_{TC}(R_2)$ 



Note that  $U_{TC}(R_1) = \lambda = U_{TC}(R_2) \Longrightarrow \dim(\operatorname{Ker}(\mathcal{L}[\lambda])) > 1$ .

#### The co-kernel

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$$\mathcal{L}[\lambda_{\epsilon,\kappa,m}] = \mathcal{L}_{0}[\lambda_{\epsilon,\kappa,m}] + \mathcal{K}$$

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Then

$$index = dim(\mathcal{N}(\mathcal{L})) - dim(Y/\mathcal{R}(\mathcal{L}))$$

#### Theorem

Fixed  $1 < M < \infty$ . There exist  $\epsilon_0(M)$ ,  $\kappa_0(M)$  such that, for every  $0 < \epsilon < \epsilon_0$ ,  $0 < \kappa < \kappa_0$  and  $m \in \mathbb{N}$ , m < M, there exist  $(\lambda_{\epsilon,\kappa,m}^{\sigma}, \mathbf{f}_{\epsilon,\kappa,m}^{\sigma})$  satisfying,

$$F_{\varpi_{\epsilon,\kappa}}[\lambda^{\sigma}_{\epsilon,\kappa,m},\mathsf{f}^{\sigma}_{\epsilon,\kappa,m}]=\mathsf{0},$$

parameterize by  $\sigma$ . These solutions satisfy:

1. 
$$f^{\sigma}_{\epsilon,\kappa,m}(r,\theta)$$
 is  $\frac{2\pi}{m}$ -periodic on  $\theta$ .

2. The branch

$$\mathsf{f}_{\epsilon,\kappa,m}^{\sigma} = \sigma \mathsf{h}_{\epsilon,\kappa,m}^{\sigma} + o(\sigma),$$

and the speed of the rotation is

$$\lambda_{\epsilon,\kappa,m}^{\sigma} = \lambda_{\epsilon,\kappa,m} + o(1).$$

3.  $f^{\sigma}_{\epsilon,\kappa,m}(r,\theta)$  depends on  $\theta$  in a non-trivial way.

In addition, vorticity  $\omega_{\epsilon,\kappa,m}^{\sigma}$  given implicitly by

$$\omega_{\epsilon,\kappa,m}^{\sigma}(\rho + \mathbf{f}_{\epsilon,\kappa,m}^{\sigma}(\rho,\theta),\theta) = \varpi_{\epsilon,\kappa}(\rho),$$

and extended to  $[r_1, r_2] \times \mathbb{T}$  by  $\epsilon$  and 0, yields a traveling way solution for 2D Euler in the sense that

$$\omega^{\sigma}_{\epsilon,\kappa,m}(\mathbf{r},\theta+\lambda^{\sigma}_{\epsilon,\kappa,m}t)$$

satisfies perturbed 2D Euler. Importantly,  $\omega^{\sigma}_{\epsilon,\kappa,m}(r,\theta)$  depends nontrivially on  $\theta$ .

# **Pouseville flow**

Pouseville flow  $U_P(y) = y^2 - 1$  in  $\mathbb{T} \times [-1, 1]$ :

$$\partial_t \omega + \nabla^{\perp} \psi \cdot \nabla \omega + U(\mathbf{y}) \partial_{\mathbf{x}} \omega - \boxed{U''(\mathbf{y}) \partial_{\mathbf{x}} \psi} = 0, \qquad \Delta \psi = \omega.$$

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## Thank you for your attention!