Quantifying systematic uncertainty in unfolding forward models using optimal transport

Richard Zhu ¹ Mikael Kuusela ¹ Larry Wasserman ¹ Andrea Marini ²

¹Department of Statistics and Data Science, Carnegie Mellon University

²CERN, the European Organization for Nuclear Research

27 April 2023

The unfolding problem: inferring the true particle spectrum from smeared observations

- In measurement analyses, one is interested in the distribution (spectrum) of some physical quantity, e.g., the energy, mass, momentum.
- Due to the finite resolution of the detectors, only a smeared version of the physical quantity is observed.



2/23

Let f be the true distribution. The observed smeared distribution g is given by

$$g(s) = \int_{\mathcal{T}} k(s,t) f(t) dt$$

where the response kernel k represents the response of the detector and is given by

$$k(s,t) = P(Y = s | X = t)$$

X = true collision event and Y = smeared observation.

Uncertainty in the forward model

- The response kernel k(s, t) is usually not available in closed form and needs to be estimated using detector simulation.
- The imperfect knowledge of the detector alignment and calibration as well as the distribution of auxiliary variables can affect the response kernel in different ways.
- This leads to systematic uncertainty in the response kernel and hence the unfolded solution as well.

Using optimal transport to quantify uncertainty

• Given two kernels k_1, k_2 , the 2-Wasserstein distance between k_1 and k_2 is defined as

$$W_2(k_1,k_2) = \left(\int_0^1 \left|F_1^{-1}(q) - F_2^{-1}(q)\right| dq\right)^{1/2}$$

• F_1^{-1} is the quantile function of k_1 and F_2^{-1} is the quantile function of k_2 conditioned on a fixed t.

Using optimal transport to quantify uncertainty

• The Wasserstein barycenter of k_1 and k_2 with weights $\mathbf{t} = (t_1, t_2)$ is given by

$$k_{\mathbf{t}} = \arg\min_{k} \{ t_1 W_2(k_1, k) + t_2 W_2(k_2, k) \}$$

 Varying the weight t defines the geodesic (path) morphing between k₁ and k₂: {kt : t₁, t₂ ≥ 0, t₁ + t₂ = 1}.



Figure: geodesic connecting k_1 and k_2

Discretization

- Let $\{T_j\}_{j=1}^n$ be the partition of the true space T and $\{S_i\}_{i=1}^m$ be the partition of the smeared space.
- Particle-level histogram: x ~ Poisson(λ).
 Detector-level histogram y ~ Poisson(μ).
- True histogram mean: $\lambda = [\int_{T_1} f(t)dt, ..., \int_{T_n} f(t)dt]$. Smeared histogram mean: $\mu = [\int_{S_1} g(s)ds, ..., \int_{S_m} g(s)ds]$. f and g are the intensity functions of the Poisson processes.
- $\mu = \mathsf{K} \lambda$ where the elements of response matrix K are given by

$$\mathbf{K}_{ij} = \frac{\int_{s \in S_i} \int_{t \in T_j} k(s, t) f(t) dt ds}{\int_{t \in T_j} f(t) dt}$$

= P (smeared observation in bin i|true event in bin j)

Goal

Inference on the true histogram mean λ .

Computing confidence interval for the true histogram mean while accounting for the systematic uncertainty in the response kernels

- (1) Given two base kernels k_1, k_2 , compute the geodesic $\{k_t = \arg \min_k \{t_1 W(k_1, k) + t_2 W(k_2, k)\} : t_1, t_2 \ge 0, t_1 + t_2 = 1\}.$
- (2) Compute the corresponding response matrices $\textbf{K}_1, \textbf{K}_2, \{\textbf{K}_t\}.$
- (3) Unfold with One-at-a-time Strict-Bounds (OSB) (Stanley et al. (2022)) using the detector-level histogram \boldsymbol{y} and response matrices $\boldsymbol{K}_1, \boldsymbol{K}_2, \{\boldsymbol{K}_t\}.$
- (4) Obtain a collection of confidence intervals $C_1, C_2, \{C_t\}$ for λ .

Simulate particle-level data using the intensity function

$$f_0\left(p_{\perp}\right) = LN_0\left(\frac{p_{\perp}}{\text{GeV}}\right)^{-\alpha} \left(1 - \frac{2}{\sqrt{s}}p_{\perp}\right)^{\beta} e^{-\gamma/p_{\perp}}, \quad 0 < p_{\perp} \leq \frac{\sqrt{s}}{2}$$

- Number of bins in detector level = 40
- Number of fine bins in particle level = 40
- Number of wide bins in particle level = 10



Figure: LEFT: intensity function; RIGHT: True histogram mean λ

• The detector smearing is modeled using crystal ball function

$$CB(t-s|\mu,\sigma,\alpha,\gamma) \propto \begin{cases} e^{\frac{(t-s-\mu)^2}{2\sigma^2}} & \frac{t-s-\mu}{\sigma} > -\alpha\\ \left(\frac{\gamma}{\alpha}\right)^{\gamma} e^{-\frac{\alpha^2}{2}} \left(\frac{\gamma}{\alpha} - \alpha - \frac{t-s-\mu}{\sigma}\right)^{-\gamma} & \frac{t-s-\mu}{\sigma} \le -\alpha \end{cases}$$

• Two base kernels

$$k_1: \mu = 0, \sigma = 10, \alpha = 1, \gamma = 2$$

 $k_2: \mu = 7, \sigma = 12, \alpha = 1, \gamma = 2$



Figure: k1 and k2 are the base kernels that we might obtain from detector simulation



Geodesic (convex hull) of the base kernels

Figure: Wasserstein geodesic of k1 and k2



Geodesic (convex hull) of the base kernels

Figure: correct kernel represents the actual unknown detector response that generates the smeared observation

• We unfold with the geodesic of the kernels using the OSB intervals on one of the bins.



Figure: OSB confidence intervals for λ for bin 4; x-axis represents the weight that determines the kernel on the geodesic.



- We define *confidence slabs* to be the collection of 2-dimensional confidence sets for the true histogram mean λ of 2 bins unfolded by the geodesic of kernels defined by k₁ and k₂.
- Confidence slabs cover the true histogram mean.



Figure: LEFT: Confidence slabs unfolded by the geodesic of K1 and K2; RIGHT: Interpolation of unfolded boxes by K1 and K2

Confidence slabs — more bins



Figure: Confidence slabs for all bins. Presence of nonlinear patterns.

Confidence slabs have proper coverage



Figure: Coverage for confidence slabs

Extrapolation

• We can allow the weight $t_1, t_2 < 0$ to define extrapolation of the base kernels:

$$\{k_{\mathbf{t}} = \arg\min_{k} \{t_1 W(k_1, k) + t_2 W(k_2, k)\} : t_1 + t_2 = 1\}$$



Figure: Extrapolation of base kernels

More base kernels

• The Wasserstein barycenter of $k_1, k_2, ..., k_m$ with weights $\mathbf{t} = (t_1, t_2, ..., t_m)$ is given by

$$k_{\mathbf{t}} = \arg\min_{k} \{\sum_{i=1}^{m} t_1 W_2(k_i, k)\}$$

• Varying the weight **t** defines the Wasserstein hull of kernels defined by $k_1, k_2, ..., k_m$: $\{k_t : \sum_{i=1}^m t_i = 1\}$.



Summary and Open Problems

- The unfolding problem: Systematic uncertainty in the forward model.
- Method: Use optimal transport to quantify the uncertainty in the response kernel.
- Results: Confidence slabs with proper coverage when the correct kernel is on (or close to) the geodesic of the base kernels.
- Open problems: For a given kernel k_t on the geodesic, we can view the weight t as a nuisance parameter. How can we summarize the collection of confidence intervals into a single confidence interval? Can we do profile likelihood? Can we learn t from the data?

Thank you! Travel support from the NSF AI Planning Institute for Data-Driven Discovery in Physics is gratefully acknowledged.

• The detector smearing is modeled using crystal ball function

$$CB(t-s|\mu,\sigma,\alpha,\gamma) \propto \begin{cases} e^{\frac{(t-s-\mu)^2}{2\sigma^2}} & \frac{t-s-\mu}{\sigma} > -\alpha\\ \left(\frac{\gamma}{\alpha}\right)^{\gamma} e^{-\frac{\alpha^2}{2}} \left(\frac{\gamma}{\alpha} - \alpha - \frac{t-s-\mu}{\sigma}\right)^{-\gamma} & \frac{t-s-\mu}{\sigma} \le -\alpha \end{cases}$$

One correct kernel and two alternative kernels

$$k_{correct}: \mu = 3, \sigma = 11, \alpha = 1, \gamma = 2$$

 $k_1: \mu = 0, \sigma = 10, \alpha = 1, \gamma = 2$
 $k_2: \mu = 10, \sigma = 12, \alpha = 1, \gamma = 2$



Figure: k1 and k2 are the base kernels that we might obtain from detector simulation; correct kernel represents the actual unknown detector response that generates the smeared observation.



Geodesic (convex hull) of the base kernels

Figure: Wasserstein geodesic of k1 and k2

• We use the midpoints of the OSB intervals as the point estimates for λ .



Figure: OSB midpoint solutions for geodesic of two kernels

- We define confidence slabs to be the collection of 2-dimensional confidence sets for the true histogram mean λ of 2 bins unfolded by the geodesic of kernels defined by k₁ and k₂.
- Confidence slabs cover the true histogram mean.
- The interpolation between the two corner confidence boxes (unfolded by k_1 and k_2) fails to cover the true mean.



Figure: LEFT: Confidence slabs unfolded by the geodesic of K1 and K2; RIGHT: Interpolation of unfolded boxes by K1 and K2

Confidence slabs — more bins



Figure: Confidence slabs for all bins. Presence of nonlinear patterns.

Confidence slabs have proper coverage



Figure: LEFT: Coverage for confidence slabs; RIGHT: Coverage for interpolation

• The detector smearing is modeled using Gaussian kernel

$$k_1(s,t) = N(s|\mu = t, \sigma = 10)$$
 (correct)

• Two alternative kernels

$$k_2(s,t) = N(s|\mu = 0.98t, \sigma = 7), k_3(s,t) = N(s|\mu = 1.01t, \sigma = 15)$$



• We use the midpoints of the OSB intervals as the point estimates for λ .



Figure: OSB midpoint solutions for geodesic of two kernels

- We define confidence slabs to be the collection of 2-dimensional confidence sets for the true histogram mean λ of 2 bins unfolded by the geodesic of kernels defined by k₂ and k₃.
- Confidence slabs cover the true histogram mean.
- The range of the confidence slabs is much smaller compared to the span of the confidence sets unfolded by the two corner kernels k_2, k_3 ("two-point" confidence sets).



Figure: Confidence slab for bin 1 and bin 2

Confidence slabs — more bins



Figure: Confidence slabs for the first 5 bins

Confidence slabs have proper coverage



Figure: Coverage for confidence slabs and two-point confidence sets

Confidence slabs have proper coverage



Figure: Coverage for confidence slabs and two-point confidence sets

Applications to simulated LHC data

- Unfold the jet transverse momentum spectrum in Drell-Yan events.
- Generate Monte Carlo events {X_i, Y_i}ⁿ_{i=1} ∈ ℝ²(n = 68180) corresponding to particle and detector level jet p_⊥ respectively.
- To produce alternative kernels, we simulate the effect of a jet energy uncertainty by location shifting and smearing of Y_i.

$$\begin{aligned} Y_i^{(1)} &= 1.02 Y_i + \textit{N}(\mu = 0, \textit{sd} = 10) \\ Y_i^{(2)} &= 1.1 Y_i + \textit{N}(\mu = 0, \textit{sd} = 20) \\ Y_i^{(3)} &= 0.9 Y_i + \textit{N}(\mu = 0, \textit{sd} = 5) \end{aligned}$$
 (correct)

• Obtain kernel estimates $\hat{k}_1, \hat{k}_2, \hat{k}_3$ corresponding to $\{X_i, Y_i^{(1)}\}, \{X_i, Y_i^{(2)}\}, \{X_i, Y_i^{(3)}\}.$

Kernel estimation

- Kernel is the conditional density of smeared Y given true X: k(y,x) = p(y|x).
- We assume

$$Y = m(x) + \sigma(x)\epsilon, \quad \sigma(x) > 0, \epsilon \sim D(\mu = 0)$$

- Regress Y on X to obtain estimates $\widehat{m}(x)$ and residuals $\widehat{r}_i = y_i \widehat{m}(x_i)$.
- Regress \hat{r}_i^2 on x_i to obtain estimates $\hat{\sigma}^2(x)$.
- Estimate the density of ϵ using $\frac{\hat{r}_i}{\hat{\sigma}(\mathbf{x}_i)}$ and obtain \hat{p}_{ϵ} .
- Estimate the conditional density of Y given X by

$$\widehat{p}(y|x) = rac{1}{\widehat{\sigma}(x)}\widehat{p}_{\epsilon}\left(rac{y-\widehat{m}(x)}{\widehat{\sigma}(x)}
ight)$$

Unfolding applied to simulated LHC data

• Perform the same unfolding procedure as in the simulation study, except we have estimated response kernels \hat{k} , particle-level intensity function \hat{f} .



Figure: Confidence slabs for the first 5 bins

Unfolding applied to simulated LHC data

• In some cases, the confidence slabs (and the correct solution) can go outside the two-point confidence sets.



Figure: Confidence slabs for bin 1 and bin2

Unfolding with more kernels



Figure: LEFT: Confidence slabs for bin 0 and bin 1; RIGHT: Confidence slabs for 5 bins