# Quantifying systematic uncertainty in unfolding forward models using optimal transport

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# The unfolding problem: inferring the true particle spectrum from smeared observations

- In measurement analyses, one is interested in the distribution (spectrum) of some physical quantity, e.g., the energy, mass, momentum.
- Due to the finite resolution of the detectors, only a smeared version of the physical quantity is observed.

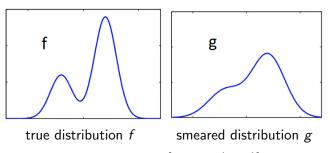


Figure: unfolding [Kuusela (2016)]

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# Forward model for unfolding

Let f be the true distribution. The observed smeared distribution g is given by

$$g(s) = \int_T k(s,t)f(t)dt$$

where the response kernel k represents the response of the detector and is given by

$$k(s,t) = P(Y = s|X = t)$$

X = true collision event and Y = smeared observation.

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# Uncertainty in the forward model

- The response kernel k(s, t) is usually not available in closed form and needs to be estimated using detector simulation.
- The imperfect knowledge of the detector alignment and calibration as well as the distribution of auxiliary variables can affect the response kernel in different ways.
- This leads to systematic uncertainty in the response kernel and hence the unfolded solution as well.

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# Using optimal transport to quantify uncertainty

• Given two kernels  $k_1$ ,  $k_2$ , the 2-Wasserstein distance between  $k_1$  and  $k_2$  is defined as

$$W_2(k_1, k_2) = \left(\int_0^1 \left(F_1^{-1}(q) - F_2^{-1}(q)\right)^2 dq\right)^{1/2}$$

•  $F_1^{-1}$  is the quantile function of  $k_1$  and  $F_2^{-1}$  is the quantile function of  $k_2$  conditioned on a fixed t.

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# Using optimal transport to quantify uncertainty

• The Wasserstein barycenter of  $k_1$  and  $k_2$  with weights  $\mathbf{t} = (t_1, t_2)$  is given by

$$k_{\mathbf{t}} = \arg\min_{k} \{t_1 W_2(k_1, k) + t_2 W_2(k_2, k)\}$$

• Varying the weight **t** defines the geodesic (path) morphing between  $k_1$  and  $k_2$ :  $\{k_t : t_1, t_2 \ge 0, t_1 + t_2 = 1\}$ .

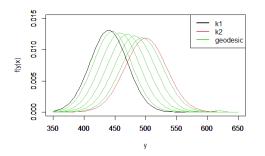


Figure: geodesic connecting  $k_1$  and  $k_2$ 

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#### Discretization

- Let  $\{T_j\}_{j=1}^n$  be the partition of the true space T and  $\{S_i\}_{i=1}^m$  be the partition of the smeared space.
- Particle-level histogram: x ~ Poisson(λ).
   Detector-level histogram y ~ Poisson(μ).
- True histogram mean:  $\lambda = [\int_{T_1} f(t)dt, ..., \int_{T_n} f(t)dt]$ . Smeared histogram mean:  $\mu = [\int_{S_1} g(s)ds, ..., \int_{S_m} g(s)ds]$ . f and g are the intensity functions of the Poisson processes.
- $oldsymbol{eta} \mu = \mathbf{K} oldsymbol{\lambda}$  where the elements of response matrix  $oldsymbol{\mathsf{K}}$  are given by

$$\mathbf{K}_{ij} = \frac{\int_{s \in S_i} \int_{t \in T_j} k(s, t) f(t) dt ds}{\int_{t \in T_j} f(t) dt}$$

= P (smeared observation in bin i|true event in bin j)

#### Goal

Inference on the true histogram mean  $\lambda$ .

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Computing confidence interval for the true histogram mean while accounting for the systematic uncertainty in the response kernels

- (1) Given two base kernels  $k_1, k_2$ , compute the geodesic  $\{k_t = \arg\min_k \{t_1 W(k_1, k) + t_2 W(k_2, k)\} : t_1, t_2 \ge 0, t_1 + t_2 = 1\}.$
- (2) Compute the corresponding response matrices  $\mathbf{K}_1, \mathbf{K}_2, \{\mathbf{K}_t\}$ .
- (3) Unfold with One-at-a-time Strict-Bounds (OSB) (Stanley et al. (2022)) using the detector-level histogram  $\mathbf{y}$  and response matrices  $\mathbf{K}_1, \mathbf{K}_2, \{\mathbf{K}_t\}$ .
- (4) Obtain a collection of confidence intervals  $C_1$ ,  $C_2$ ,  $\{C_t\}$  for  $\lambda$ .

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• Simulate particle-level data using the intensity function

$$f_0\left(p_\perp
ight) = L N_0 \left(rac{p_\perp}{
m GeV}
ight)^{-lpha} \left(1-rac{2}{\sqrt{s}}p_\perp
ight)^{eta} e^{-\gamma/p_\perp}, \quad 0 < p_\perp \leq rac{\sqrt{s}}{2}$$

- Number of bins in detector level = 40
- Number of fine bins in particle level = 40
- Number of wide bins in particle level = 10

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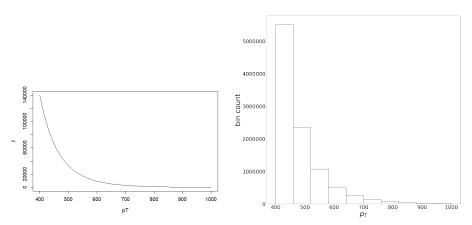


Figure: **LEFT**: intensity function; **RIGHT**: True histogram mean  $\lambda$ 

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• The detector smearing is modeled using crystal ball function

$$\mathit{CB}(t-s|\mu,\sigma,\alpha,\gamma) \propto \begin{cases} e^{\frac{(t-s-\mu)^2}{2\sigma^2}} & \frac{t-s-\mu}{\sigma} > -\alpha \\ \left(\frac{\gamma}{\alpha}\right)^{\gamma} e^{-\frac{\alpha^2}{2}} \left(\frac{\gamma}{\alpha} - \alpha - \frac{t-s-\mu}{\sigma}\right)^{-\gamma} & \frac{t-s-\mu}{\sigma} \leq -\alpha \end{cases}$$

Two base kernels

$$k_1 : \mu = 0, \sigma = 10, \alpha = 1, \gamma = 2$$

$$k_2: \mu = 7, \sigma = 12, \alpha = 1, \gamma = 2$$

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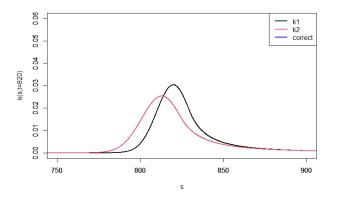


Figure: k1 and k2 are the base kernels that we might obtain from detector simulation

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#### Geodesic (convex hull) of the base kernels

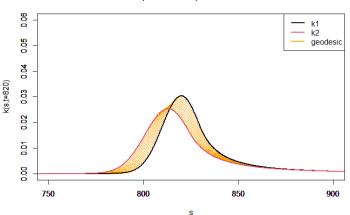


Figure: Wasserstein geodesic of k1 and k2

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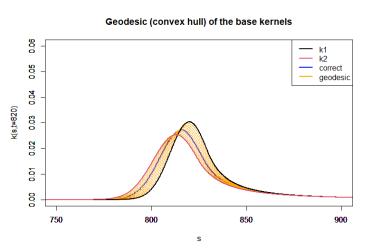


Figure: correct kernel represents the actual unknown detector response that generates the smeared observation

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 We unfold with the geodesic of the kernels using the OSB intervals on one of the bins.

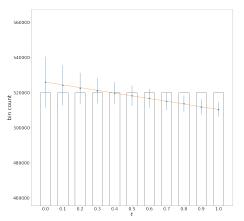


Figure: OSB confidence intervals for  $\lambda$  for bin 4; x-axis represents the weight that determines the kernel on the geodesic.

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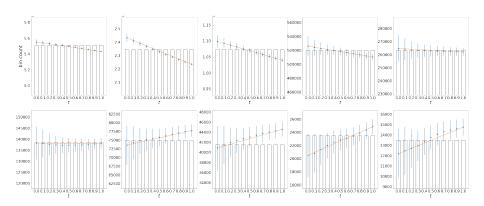


Figure: OSB confidence intervals for  $\lambda$  for 10 bins; each plot corresponds to 1 bin; x-axis represents the weight on the geodesic.

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- We define *confidence slabs* to be the collection of 2-dimensional confidence sets for the true histogram mean  $\lambda$  of 2 bins unfolded by the geodesic of kernels defined by  $k_1$  and  $k_2$ .
- Confidence slabs cover the true histogram mean.

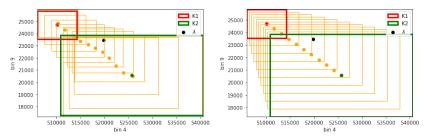


Figure: **LEFT**: Confidence slabs unfolded by the geodesic of K1 and K2; **RIGHT**: Interpolation of unfolded boxes by K1 and K2

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### Confidence slabs — more bins

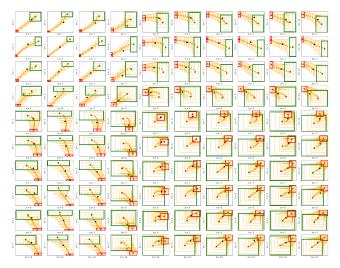


Figure: Confidence slabs for all bins. Presence of nonlinear patterns.

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# Confidence slabs have proper coverage

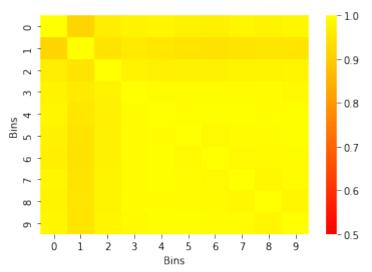


Figure: Coverage for confidence slabs

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### Extrapolation

• We can allow the weight  $t_1, t_2 < 0$  to define extrapolation of the base kernels:

$$\{k_{\mathbf{t}} = \arg\min_{k} \{t_1 W(k_1, k) + t_2 W(k_2, k)\} : t_1 + t_2 = 1\}$$

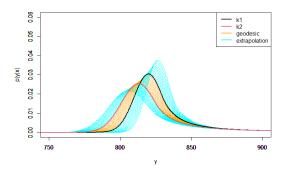


Figure: Extrapolation of base kernels

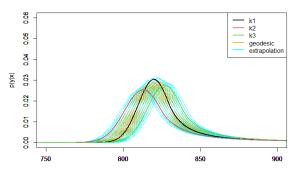
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#### More base kernels

• The Wasserstein barycenter of  $k_1, k_2, ..., k_m$  with weights  $\mathbf{t} = (t_1, t_2, ... t_m)$  is given by

$$k_{t} = \arg\min_{k} \{ \sum_{i=1}^{m} t_{1} W_{2}(k_{i}, k) \}$$

• Varying the weight **t** defines the Wasserstein hull of kernels defined by  $k_1, k_2, ..., k_m$ :  $\{k_t : \sum_{i=1}^m t_i = 1\}$ .



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# Summary and Open Problems

- The unfolding problem: Systematic uncertainty in the forward model.
- Method: Use optimal transport to quantify the uncertainty in the response kernel.
- Results: Confidence slabs with proper coverage when the correct kernel is on (or close to) the geodesic of the base kernels.
- Open problems: For a given kernel k<sub>t</sub> on the geodesic, we can view the weight t as a nuisance parameter. How can we summarize the collection of confidence intervals (dependent on t) into a single confidence interval? Can we do profile likelihood? Can we learn t from the data?

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### Thank you!

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• The detector smearing is modeled using crystal ball function

$$CB(t-s|\mu,\sigma,\alpha,\gamma) \propto \begin{cases} e^{\frac{(t-s-\mu)^2}{2\sigma^2}} & \frac{t-s-\mu}{\sigma} > -\alpha \\ \left(\frac{\gamma}{\alpha}\right)^{\gamma} e^{-\frac{\alpha^2}{2}} \left(\frac{\gamma}{\alpha} - \alpha - \frac{t-s-\mu}{\sigma}\right)^{-\gamma} & \frac{t-s-\mu}{\sigma} \leq -\alpha \end{cases}$$

One correct kernel and two alternative kernels

$$k_{correct}: \mu = 3, \sigma = 11, \alpha = 1, \gamma = 2$$
  $k_1: \mu = 0, \sigma = 10, \alpha = 1, \gamma = 2$   $k_2: \mu = 10, \sigma = 12, \alpha = 1, \gamma = 2$ 

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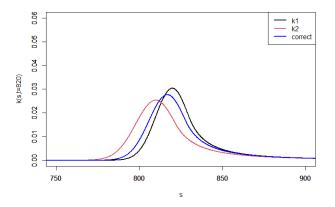


Figure: k1 and k2 are the base kernels that we might obtain from detector simulation; correct kernel represents the actual unknown detector response that generates the smeared observation.

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#### Geodesic (convex hull) of the base kernels

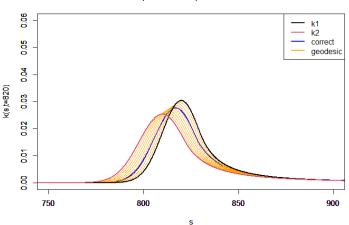


Figure: Wasserstein geodesic of k1 and k2

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ullet We use the midpoints of the OSB intervals as the point estimates for  $oldsymbol{\lambda}.$ 

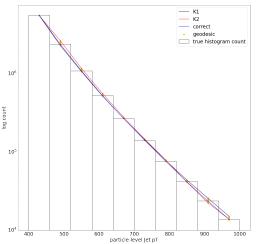


Figure: OSB midpoint solutions for geodesic of two kernels

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- We define *confidence slabs* to be the collection of 2-dimensional confidence sets for the true histogram mean  $\lambda$  of 2 bins unfolded by the geodesic of kernels defined by  $k_1$  and  $k_2$ .
- Confidence slabs cover the true histogram mean.
- The interpolation between the two corner confidence boxes (unfolded by  $k_1$  and  $k_2$ ) fails to cover the true mean.

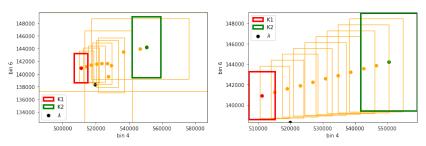


Figure: **LEFT**: Confidence slabs unfolded by the geodesic of K1 and K2; **RIGHT**: Interpolation of unfolded boxes by K1 and K2

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#### Confidence slabs — more bins

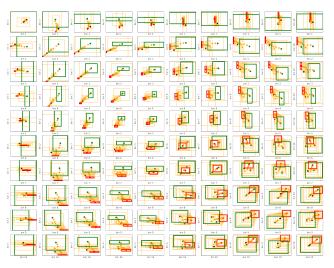


Figure: Confidence slabs for all bins. Presence of nonlinear patterns.

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# Confidence slabs have proper coverage

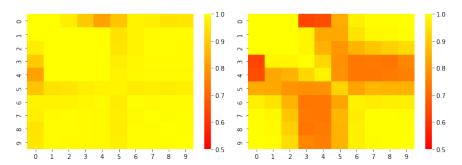


Figure: LEFT: Coverage for confidence slabs; RIGHT: Coverage for interpolation

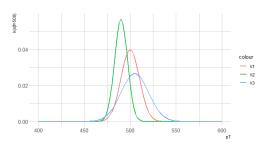
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• The detector smearing is modeled using Gaussian kernel

$$k_1(s, t) = N(s|\mu = t, \sigma = 10)$$
 (correct)

Two alternative kernels

$$k_2(s,t) = N(s|\mu = 0.98t, \sigma = 7), k_3(s,t) = N(s|\mu = 1.01t, \sigma = 15)$$



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 We use the midpoints of the OSB intervals as the point estimates for λ.

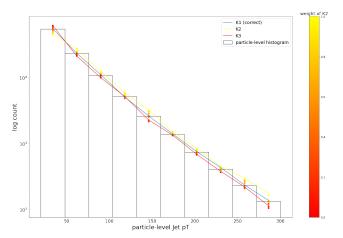


Figure: OSB midpoint solutions for geodesic of two kernels

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- We define *confidence slabs* to be the collection of 2-dimensional confidence sets for the true histogram mean  $\lambda$  of 2 bins unfolded by the geodesic of kernels defined by  $k_2$  and  $k_3$ .
- Confidence slabs cover the true histogram mean.
- The range of the confidence slabs is much smaller compared to the span of the confidence sets unfolded by the two corner kernels  $k_2$ ,  $k_3$  ("two-point" confidence sets).

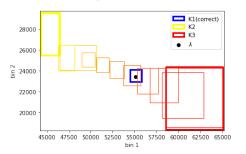


Figure: Confidence slab for bin 1 and bin 2

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#### Confidence slabs — more bins



Figure: Confidence slabs for the first 5 bins

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# Confidence slabs have proper coverage

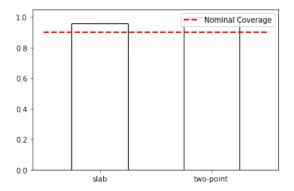


Figure: Coverage for confidence slabs and two-point confidence sets

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# Confidence slabs have proper coverage

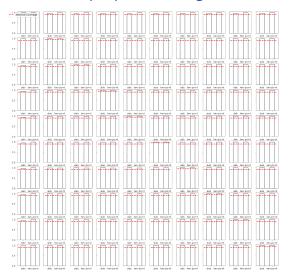


Figure: Coverage for confidence slabs and two-point confidence sets

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### Applications to simulated LHC data

- Unfold the jet transverse momentum spectrum in Drell-Yan events.
- Generate Monte Carlo events  $\{X_i, Y_i\}_{i=1}^n \in \mathbb{R}^2 (n = 68180)$  corresponding to particle and detector level jet  $p_{\perp}$  respectively.
- To produce alternative kernels, we simulate the effect of a jet energy uncertainty by location shifting and smearing of  $Y_i$ .

$$Y_i^{(1)} = 1.02Y_i + N(\mu = 0, sd = 10)$$
 (correct)  
 $Y_i^{(2)} = 1.1Y_i + N(\mu = 0, sd = 20)$   
 $Y_i^{(3)} = 0.9Y_i + N(\mu = 0, sd = 5)$ 

• Obtain kernel estimates  $\hat{k}_1, \hat{k}_2, \hat{k}_3$  corresponding to  $\{X_i, Y_i^{(1)}\}, \{X_i, Y_i^{(2)}\}, \{X_i, Y_i^{(3)}\}.$ 

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#### Kernel estimation

- Kernel is the conditional density of smeared Y given true X: k(y,x) = p(y|x).
- We assume

$$Y = m(x) + \sigma(x)\epsilon$$
,  $\sigma(x) > 0$ ,  $\epsilon \sim D(\mu = 0)$ 

- Regress Y on X to obtain estimates  $\widehat{m}(x)$  and residuals  $\widehat{r}_i = v_i - \widehat{m}(x_i).$
- Regress  $\hat{r}_i^2$  on  $x_i$  to obtain estimates  $\hat{\sigma}^2(x)$ .
- Estimate the density of  $\epsilon$  using  $\frac{\widehat{r}_i}{\widehat{\sigma}(x_i)}$  and obtain  $\widehat{p}_{\epsilon}$ .
- Estimate the conditional density of Y given X by

$$\widehat{p}(y|x) = \frac{1}{\widehat{\sigma}(x)}\widehat{p}_{\epsilon}\left(\frac{y - \widehat{m}(x)}{\widehat{\sigma}(x)}\right)$$

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# Unfolding applied to simulated LHC data

• Perform the same unfolding procedure as in the simulation study, except we have estimated response kernels  $\hat{k}$ , particle-level intensity function  $\hat{f}$ .

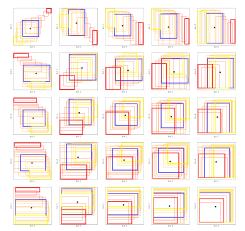


Figure: Confidence slabs for the first 5 bins

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### Unfolding applied to simulated LHC data

• In some cases, the confidence slabs (and the correct solution) can go outside the two-point confidence sets.

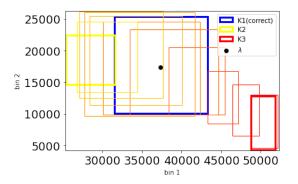


Figure: Confidence slabs for bin 1 and bin2

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# Unfolding with more kernels

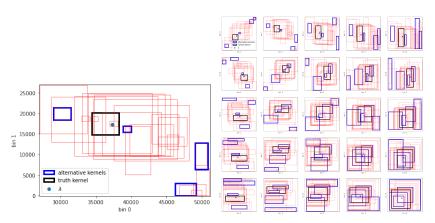


Figure: **LEFT**: Confidence slabs for bin 0 and bin 1; **RIGHT**: Confidence slabs for 5 bins

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