

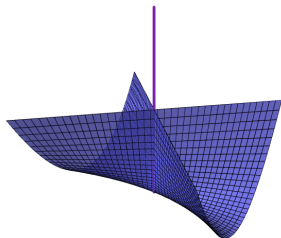
Whitney Stratification of Algebraic Maps and Applications to Kinematic Singularities

Martin Helmer
North Carolina State University

joint work with **Vidit Nanda** (Oxford)

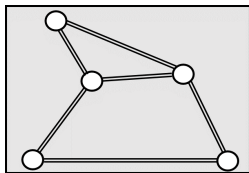
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June 15, 2023



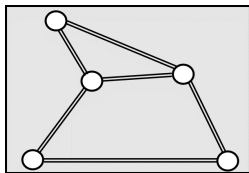
Inverse Kinematics and the Singularities of Kinematic Maps

Think of a **kinematic map** as: a function $f : C \rightarrow S$ where C is the configuration space and S the output state space (workspace).



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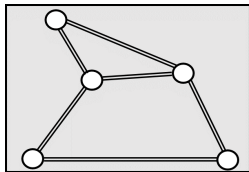
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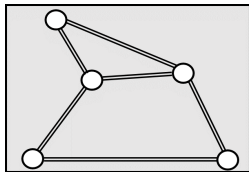
Set $m = \dim(C)$, $n = \dim(S)$. The derivative of f at a point $p \in C$ is a linear map $T_p C \rightarrow T_f(p)S$ between tangent spaces defined by $J(p)$, the $n \times m$ Jacobian matrix of f evaluated at p .

The **singular locus** of f : $\Sigma_f := \{p \in C \mid \text{rank}(J(p)) < \min(m, n)\}$.

At points $p \in \Sigma_f$ the mechanism may lose a degree of freedom causing a loss of control, but this may not happen at all points in Σ_f .

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Goal: understand the global geometry & topology of f , Σ_f , f^{-1} .

Mathematical Tools and Setting

More Precise Goal: stratify the map f , i.e. subdivide C and S into **finitely many** manifold regions so that the fibres $f^{-1}(q)$ and $f^{-1}(q')$ are topologically identical for any two points in a region of S .

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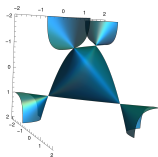
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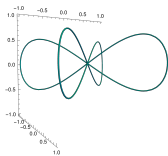
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Setting: To enable effective global computations we restrict to the case where C , S are algebraic varieties and f is a polynomial map.



$$2xyz - x^2 - y^2 - z^2 + 1 = 0$$



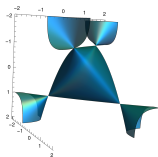
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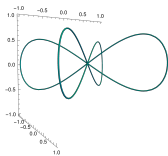
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We can see varieties as a non-linear analogue of v. spaces: we rewrite & solve poly. systems via Gröbner basis instead of linear systems via Gaussian elim.

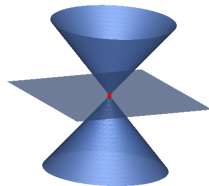
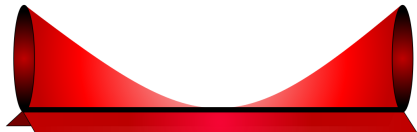
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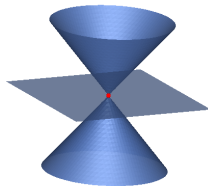
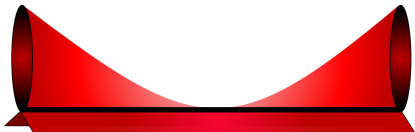
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We seek to **stratify** these spaces by **separating** them into smooth **manifolds** which join in a nice way.

Stratifying Varieties

More precisely, we will (first) consider (complex) algebraic varieties

$$X = \mathbb{V}(I_X) = \mathbb{V}(f_1, \dots, f_r) = \{p \in \mathbb{C}^n \mid f_1(p) = \dots = f_r(p) = 0\}.$$

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A point $p \in X$ is **singular** if the Jacobian matrix of the f_i drops rank at p .

A **stratification** is a filtration, X_\bullet , $\emptyset = X_{-1} \subset X_0 \subset \dots \subset X_n = X$ of X s.t. $X = \cup_i X_i$ and s.t. each strata $\mathcal{M} = X_i - X_{i-1}$ is either empty or smooth, i.e. is a manifold, and has pure dimension.

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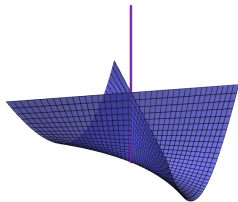
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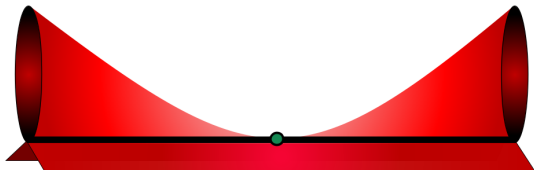
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Additionally: want decomposition $X = \sqcup_i \mathcal{M}_i$ to be **equisingular**; i.e. the neighbourhood in X of any 2 points in a connected comp. of \mathcal{M}_i is “similar”.



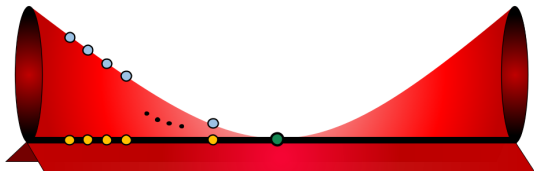
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For X_\bullet to be a **Whitney Stratification** these strata must satisfy **Condition B**: for each pair of strata $\sigma, \tau \subset X$ and a point $y \in \tau$



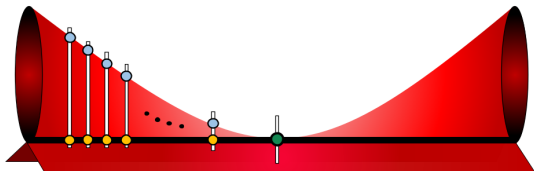
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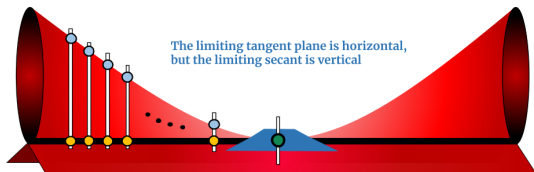
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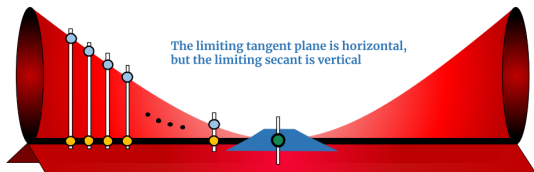
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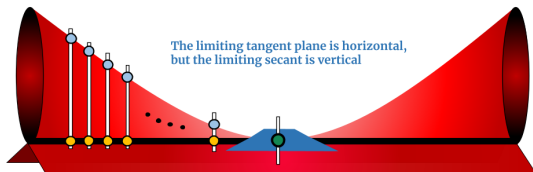


Theorem (H. Whitney, *Annals of Math.*, 1965)

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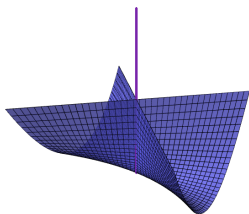
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Goal: given equations defining X **efficiently compute** a Whitney stratification (compute = find equations for each X_i).

Example: Our Algorithm Applied to the Whitney Umbrella

There has long been significant interest in algorithmic computation of Whitney stratifications (e.g. Mostowski & Rannou 1991, Rannou 1998, Dinh & Jelonek 2021); previous methods have proved impractical on even the smallest examples.



```
Macaulay2, version 1.21
with packages: ConwayPolynomials, Elimination

i1 : needsPackage "WhitneyStratifications"

o1 = WhitneyStratifications

i2 : Package

i3 : R=QQ[x..z];

i4 : X=ideal(x^2*z-y^2);

o3 : Ideal of R

i4 : time W=whitneyStratify X;
-- used 0.28765 seconds

i5 : peek W

o5 = MutableHashTable{0 => {ideal (z, y, x)}}
      1 => {ideal (y, x)}
      2 => {ideal (x z - y )}
```

First Ingredients: Conormal Variety

Notation: write X_{reg} = set of all smooth points of a variety $X = \mathbb{V}(f_1, \dots, f_r)$.

The **conormal variety** of X is the subvariety

$$\text{Con}(X) = \overline{\{(p, \xi) \mid p \in X_{\text{reg}}, T_p X_{\text{reg}} \subset \xi\}} \subset X \times (\mathbb{P}^n),$$

given by closing the set of pairs of points $p \in X_{\text{reg}}$ with hyperplanes ξ containing $T_p X_{\text{reg}}$; hyperplanes are represented by their normal vectors.

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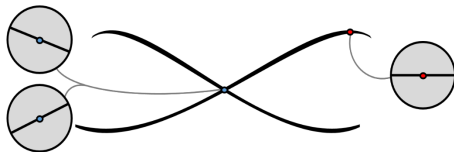
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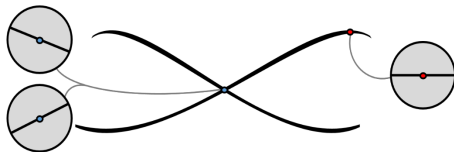
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Eqs. $I_{\text{Con}(X)}$ defining $\text{Con}(X)$ are easily computed from the f_i via Gröbner basis.

One Last Ingredient: Associated Primes

For a polynomial ideal I we can compute a *primary decomposition*:

$$I = Q_1 \cap \cdots \cap Q_\ell$$

where Q_i is a primary ideal (if $ab \in Q_i$, either a or b^n is in Q_i).

The *associated prime* ideals $P_i = \sqrt{Q_i}$ are unique (Q_i need not be) and

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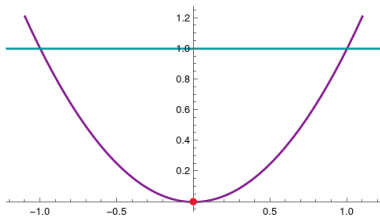
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$$I = \langle x^2y^2 - x^2y - y^3 + y^2, x^3y - x^3 - xy^2 + xy \rangle = \langle y - 1 \rangle \cap \langle y - x^2 \rangle \cap \langle x, y^3 \rangle$$

The associated primes are:

$$\langle y - 1 \rangle, \langle y - x^2 \rangle, \langle x, y \rangle.$$



Our Algebraic Criterion

Let X be a pure dimensional variety and $Y \subset X_{\text{Sing}} = (X - X_{\text{reg}})$ be a nonempty irreducible subvariety.

Goal: find all points in Y where Condition B fails w.r.t. X .

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Set $I_{\kappa_X^{-1}(Y)} := I_{\text{Con}(X)} + I_Y$. Let $\{P_1, \dots, P_s\}$ be the associated primes of $I_{\kappa_X^{-1}(Y)}$, let $\sigma \subset \{1, 2, \dots, s\}$ be the set of indices i with $\dim \kappa_X(\mathbb{V}(P_i)) < \dim Y$ and let

$$A := \left[\bigcup_{i \in \sigma} \kappa_X(\mathbb{V}(P_i)) \right] \cup Y_{\text{sing}}.$$

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Then the pair $(X_{\text{reg}}, Y - A)$ satisfies Condition (B).

Note: this identifies the points of interest and is computable using Gröbner basis calculations only.

Idea of Our Algorithm

Input: An ideal I_X defining a variety X of dimension k .

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Roughly speaking, our algorithm proceeds as follows:

- **Compute** $Y_1 = X_{\text{Sing}}$ by finding the ideal generated by the $(n - k) \times (n - k)$ -minors of the Jacobian of I_X .

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- **Compute associated primes** $\{P_1, \dots, P_s\}$ of $I_{\kappa_X^{-1}(Y_1)}$ and **by our criterion** Condition B fails on $Y_2 = \bigcup_{i \in \sigma} \kappa_X(\mathbb{V}(P_i)) \cup Y_{\text{sing}}$ where σ collects all i with $\dim(\kappa_X^{-1}(\mathbb{V}(P_i))) < \dim Y_1$.

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- **Repeat this with** Y_2 ; **continue until done.**

The above leads to a procedure to construct a stratification where each peice satisfies Whitney's Condition B with respect to the top stratum.

Stratifying Maps

Recall: we wanted to globally understand kinematic maps $f : C \rightarrow S$ via stratification where the configuration and state spaces are varieties.

Exact Map Stratification Definition:

Let X, Y be algebraic varieties and $f : X \rightarrow Y$ an algebraic map. A **stratification of f** , is a Whitney stratification of X and Y so that for every strata S of X there is a strata R of Y such that the restriction $f|_S : S \rightarrow R$ is surjective, with a surjective derivative.

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In our 2022 paper (H.& Nanda, in Found. Comput Math) we construct an effective algorithm to stratify a map $f : X \rightarrow Y$ where $X \subset \mathbb{C}^n$, $Y \subset \mathbb{C}^m$.

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In our 2022 paper (H.& Nanda, in Found. Comput Math) we construct an effective algorithm to stratify a map $f : X \rightarrow Y$ where $X \subset \mathbb{C}^n$, $Y \subset \mathbb{C}^m$.

The key ingredient is the Whitney stratification algorithm presented earlier.

Stratifying Maps between Real Varieties

For planar mechanisms we can use the complex version directly via isotropic coordinates on \mathbb{R}^2 , i.e. represent $(x, y) \in \mathbb{R}^2$ as $x + iy \in \mathbb{C}$.

This introduces unnecessary computational overhead, however, and even more so when generalized to \mathbb{R}^3 .

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This will allow us to compute Whitney stratification of real varieties $V \subset \mathbb{R}^n$ and of polynomial maps $f : X \rightarrow Y$, where $X \subset \mathbb{R}^n$, $Y \subset \mathbb{R}^m$, using Gröbner basis calculations only.

Summary

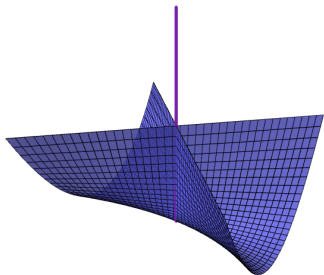
We have described an algorithm to compute a Whitney stratification an algebraic variety $X \subset \mathbb{C}^n$ and of algebraic maps $f : X \rightarrow Y$.

- Ongoing work (funded by AFOSR) gives a similar algorithm to find Whitney stratifications of real varieties $X \subset \mathbb{R}^n$ and to stratify algebraic maps between real varieties.
- This will allow us to stratify kinematic maps $f : C \rightarrow S$, where C and S are real varieties, (eventually) enabling a global study of their singularities using topological techniques.
- There is a M2 package called *WhitneyStratifications* which implements this.

Package Docs: <https://faculty.math.illinois.edu/Macaulay2/doc/Macaulay2/share/doc/Macaulay2/WhitneyStratifications/html/index.html>

Thank You!

Thank you for your attention!



Paper: <https://doi.org/10.1007/s10208-022-09574-8>

Code: <https://faculty.math.illinois.edu/Macaulay2/doc/Macaulay2/share/doc/Macaulay2/WhitneyStratifications/html/index.html>