Attributed Graph Alignment

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Joint work with Ziao Wang (UBC), Ning Zhang (Oxford), and Weina Wang (CMU)

Motivation: Correlated social networks



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Social network de-anonymization (Narayanan and Shmatikov 2008)

- Let A and B be the adjacency matrices of the two (simple) graphs
- Quadratic assignment problem (Koopmans and Beckmann 1957)

$$\hat{\pi} = \arg\max_{\sigma} \sum_{i < j} A_{i,j} B_{\sigma(i),\sigma(j)}$$

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 - Can we solve the problem for most typical practical networks?
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Graph alignment problem















• Exact alignment: Estimation $\hat{\pi}(G_1, G'_2)$ such that for uniform Π ,

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 - Efficient algorithms





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- Converse: Set of (n, p, s_u) s.t. no algorithm achieves exact alignment





- $G \sim \operatorname{ER}(n, p)$
- $G_1 = G_2 = G$
- G'_2 isomorphic to G_1

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Theorem (Babai, Erdős, and Selkow 1980, Czajka and Pandurangan 2008)

Assume $p \leq 1/2$

- If $np \ge \log n + \omega(1)$, \exists a polynomial-time algorithm
- If $np \leq \log n \omega(1)$, no algorithms exist

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Correlated Erdős–Rényi graph alignment

- Information-theoretic limit: Pedarsani and Grossglauser (2011), Cullina and Kiyavash (2016), Cullina and Kiyavash (2017), Wu, Xu, and Yu (2021)
- Polynomial-time algorithm: Lyzinski, Fishkind, Fiori, Vogelstein, Priebe, and Sapiro (2015), Nassar, Veldt, Mohammadi, Grama, and Gleich (2018), Feizi, Quon, Recamonde-Mendoza, Medard, Kellis, and Jadbabaie (2019), Fan, Mao, Wu, and Xu (2020), Onaran and Villar (2020), Barak, Chou, Lei, Schramm, and Sheng (2019a), Mao, Rudelson, and Tikhomirov (2021), Mao, Wu, Xu, and Yu (2022, 2023), Ding and Li (2023)

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Seeded graph alignment

- Information-theoretic limit: converse: Mossel and Xu (2020)
- Polynomial-time algorithm: Yartseva and Grossglauser (2013), Korula and Lattanzi (2014), Lyzinski, Fishkind, and Priebe (2014), Fishkind, Adali, Patsolic, Meng, Singh, Lyzinski, and Priebe (2019), Shirani, Garg, and Erkip (2017), Mossel and Xu (2020)

Bipartite graph alignment

- Information-theoretic limit: Cullina, Mittal, and Kiyavash (2018)
- Polynomial-time algorithm: Hungarian algorithm

• Many others...

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What if graph structure is not enough?











Attributes as vertices



Attributes as vertices



How much benefit can vertex attributes bring?

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• Base graph G generation














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- Achievability: Set of $(n, p, s_u; m, q, s_a)$ s.t. exact alignment is achievable
 - Information-theoretic limits
 - Efficient algorithms
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Result 1: IT limits (simplified)

 $\begin{array}{l} \text{Under mild conditions} \\ 1-p = \Theta(1), 1-q = \Theta(1), \\ s_{\mathrm{u}} = \Omega(\frac{(\log n)^2}{\sqrt{n}}), \\ s_{\mathrm{a}} = \Omega(\frac{(\log n)^{1.5}}{\sqrt{m}}) \end{array}$

Achievability $nps_{u}^{2} + mqs_{a}^{2} > \log n + \omega(1)$

Converse

 $nps_{\rm u}^2 + mqs_{\rm a}^2 \le \log n - \omega(1)$

https://arxiv.org/abs/2102.00665

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Benefit from attribute information





• When m = 0 or $qs_a = 0$, reduces to correlated Erdős–Rényi graph alignment



- When m = 0 or $qs_a = 0$, reduces to correlated Erdős–Rényi graph alignment
- When p = q and $s_u = s_a$, reduces to seeded graph alignment



- When m = 0 or $qs_a = 0$, reduces to correlated Erdős–Rényi graph alignment
- When p = q and $s_u = s_a$, reduces to seeded graph alignment
- When $ps_a = 0$, reduces to bipartite graph alignment





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• For fair comparison, assume *n* unmatched vertices and *m* seeds

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Best-known results

• Achievability: unseeded achievability by Cullina and Kiyavash (2017)

$$(m+n)ps_{\rm u}^2 \ge \log(m+n) + \omega(1)$$

• Converse: Mossel and Xu (2020) for m = O(n)

$$(m+n)ps_{\rm u}^2 \le \log(m+n) + O(1)$$

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$$(m+n)ps_{\rm u}^2 \le \log(m+n) + O(1)$$

Our result: Tight threshold

Achievability: strict improvement

$$(m+n)ps_{\rm u}^2 \ge \log n + \omega(1)$$

• Converse: extension to $m = \omega(n)$

$$(m+n)ps_{\rm u}^2 \le \log n - \omega(1)$$



Studied in the more general setting of database alignment (Cullina et al. 2018)

Best-known results

Achievability:

$$\frac{1}{2}I_2^{\circ}(Q^{\otimes m}) \ge \log n + \omega(1)$$

• Converse: for constant $\epsilon \in (0, 1)$

$$\frac{1}{2}I_2^{\circ}(Q^{\otimes m}) \le (1-\epsilon)\log n$$

where $Q = \begin{pmatrix} q_{00} & q_{01} \\ q_{10} & q_{11} \end{pmatrix}$, $I_2^{\circ}(A) = -\log \operatorname{tr}((ZZ^T)^2)$, $Z_{ij} = \sqrt{A_{ij}}$

• Studied in the more general setting of database alignment (Cullina et al. 2018)

Refined best-known results

Achievability:

$$-\frac{m}{2}\log(1-2\psi_{\mathbf{a}}) \ge \log n + \omega(1)$$

• Converse: for constant $\epsilon \in (0, 1)$

$$-\frac{m}{2}\log(1-2\psi_{\mathbf{a}}) \le (1-\epsilon)\log n$$

where $\psi_{\mathrm{a}} = (\sqrt{q_{11}q_{00}} - \sqrt{q_{01}q_{10}})^2$

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$$\psi_{\rm a} = (\sqrt{q_{11}q_{00}} - \sqrt{q_{01}q_{10}})^2$$

Our result

Achievability: recovers the best

$$-\frac{m}{2}\log(1-2\psi_{\rm a}) \ge \log n + \omega(1)$$

Converse: strict improvement

$$mqs_{\rm a}^2 \le \log n - \omega(1)$$

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Efficient Algorithms

Conjectured information-computation gap in correlated Erdős-Rényi model



• IT limits: Cullina and Kiyavash (2017)

Conjectured information-computation gap in correlated Erdős-Rényi model



- IT limits: Cullina and Kiyavash (2017)
- Poly-time algorithm with correlation at Otter's constant: Mao, Wu, Xu, and Yu (2023)

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https://arxiv.org/abs/2201.10106 https://arxiv.org/abs/2308.09210

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With a tiny bit of attribute information (e.g. $mqs_a^2 = 1/\sqrt{\log n}$), poly-time algorithms can achieve exact alignment with vanishing correlation!

https://arxiv.org/abs/2201.10106 https://arxiv.org/abs/2308.09210



Specialization to seeded graph alignment ($p = q, s_u = s_a$)

Strictly improve the best known achievable region for poly-time algorithms by Shirani, Garg, and Erkip (2017), Mossel and Xu (2020)

https://arxiv.org/abs/2201.10106 https://arxiv.org/abs/2308.09210

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Specialization to bipartite graph alignment ($ps_u = 0$)

Alternative poly-time algorithm for the Hungarian algorithm with a smaller time complexity when m = o(n)

https://arxiv.org/abs/2201.10106 https://arxiv.org/abs/2308.09210

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Efficient algorithms by subgraph counting

- Idea: use the occurrences of a chosen graph structure as vertex feature
 - Identifying clusters in graphs: Mossel et al. (2014)
 - Testing correlation between two graphs: Mao et al. (2022)
 - Graph alignment: Barak et al. (2019b), Mao et al. (2023)

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 - Identifying clusters in graphs: Mossel et al. (2014)
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- For attributed graphs: We identify a *rooted* subgraph involving both attributes and users

Proposed subgraph counting algorithm



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 $W_{1,\{\boldsymbol{A},\boldsymbol{B}\}}(G_1)$

Proposed subgraph counting algorithm



 $W_{1,\{\boldsymbol{A},\boldsymbol{B}\}}(G_1)$












• Construct feature vector for each user vertex



• Construct feature vector for each user vertex e.g.: $X_1 = (W_{1,\{A,B\}}(G_1), W_{1,\{A,C\}}(G_1), W_{1,\{B,C\}}(G_1))$

• Similarity score between user i from G_1 and j from G'_2

$$\Gamma_{ij} \triangleq X_i \cdot X_j = \sum_{\mathcal{T}: |\mathcal{T}|=k} W_{i,\mathcal{T}}(G_1) W_{j,\mathcal{T}}(G'_2).$$

• Key observation: For any wrong pair $j \neq \Pi(i)$,

$$\mathsf{E}[\underbrace{W_{i,\mathcal{T}}(G_1)W_{j,\mathcal{T}}(G_2')}_{\mathsf{H}_i,\mathsf{T}_i}] < \mathsf{E}[\underbrace{W_{i,\mathcal{T}}(G_1)W_{\Pi(i),\mathcal{T}}(G_2')}_{\mathsf{H}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{T}_i,\mathsf{$$

almost independent

positively correlated

• Similarity score between user i from G_1 and j from G'_2

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• Key observation: For any wrong pair $j \neq \Pi(i)$,

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almost independent

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which further implies

 $\mathsf{E}[\Gamma_{ij}] < \mathsf{E}[\Gamma_{i,\Pi(i)}].$

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Similarity score between user i from G₁ and j from G₂'

$$\Gamma_{ij} \triangleq X_i \cdot X_j = \sum_{\mathcal{T}: |\mathcal{T}|=k} W_{i,\mathcal{T}}(G_1) W_{j,\mathcal{T}}(G'_2).$$

• Key observation: For any wrong pair $j \neq \Pi(i)$,



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Summary

- Propose attributed Erdős–Rényi graph pair model
 - Understand the benefit of attributes
 - Unify existing models
- Characterize the information-theoretic limits
 - Improve IT limits for existing models
- Propose polynomial-time algorithms
 - Improve efficient algorithms for existing models
 - Shed new light on information-computation gap

More details: arXiv:2102.006655 arXiv:2201.10106 arXiv:2308.09210

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Thank you!

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Proof Sketch for IT limits

Key ideas in achievability

Correlated Erdős–Rényi model

 $\hat{\pi}_{MAP} = \operatorname{argmin}_{\pi}$ edge misalignment between G_1 and $\pi^{-1}(G'_2)$

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Attributed Erdős–Rényi model

MAP estimator = weighted minimum misalignment

 $\hat{\pi}_{\mathrm{MAP}} = \operatorname{argmin}_{\pi} \{ w_1 \Delta_{\pi}^{\mathrm{u}} + w_2 \Delta_{\pi}^{\mathrm{a}} \},\$

where

 $\begin{array}{l} \Delta^{\mathrm{u}}_{\pi}: \text{user-user edge misalignment between } G_1 \text{ and } \pi^{-1}(G_2') \\ \Delta^{\mathrm{a}}_{\pi}: \text{user-attribute edge misalignment between } G_1 \text{ and } \pi^{-1}(G_2') \\ w_1 = \log\left(\frac{p_{11}p_{00}}{p_{10}p_{01}}\right), w_2 = \log\left(\frac{q_{11}q_{00}}{q_{10}q_{01}}\right) \end{array}$

- Error bounding techniques (Cullina and Kiyavash (2017)):
 - Orbit decomposition
 - Generating functions

•
$$\mathsf{P}(\hat{\pi}_{\mathrm{MAP}} = \Pi) \leq \frac{1}{|\mathrm{Aut}(G_1 \wedge G_2)|}$$

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• Correlated Erdős–Rényi model

 $|\mathrm{Aut}| \geq |\mathrm{Aut}_{\mathrm{iso}}|$



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Correlated Erdős–Rényi model

 $|\mathrm{Aut}| \geq |\mathrm{Aut}_{\mathrm{iso}}|$

Attributed Erdős–Rényi model





i and j are indistinguishable if forall $k \in \mathcal{V} \setminus \{i, j\}, i \sim k \text{ iff } j \sim k$

•
$$\mathsf{P}(\hat{\pi}_{\mathrm{MAP}} = \Pi) \leq \frac{1}{|\mathrm{Aut}(G_1 \wedge G_2)|}$$

Correlated Erdős–Rényi model

 $|Aut| \geq |Aut_{iso}|$

Attributed Erdős–Rényi model





i and j are indistinguishable if forall $k \in \mathcal{V} \setminus \{i, j\}, i \sim k \text{ iff } j \sim k$

Side result: threshold of the existence of indistinguishable pairs in attributed graphs

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Motivation 2: Biomedical image analysis from multiple views



Acquisition 1



Acquisition 2

Brain connectome network analysis (Zhang, He, Chen, Luo, Zhou, and Wang 2018)



Uncover relation and transfer biological knowledge between different species (Kazemi, Hassani, Grossglauser, and Modarres 2016)

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